

MATLAB EXPO 2021

Snow Hazard Index

Using Conditional GAN and Semantic Segmentation

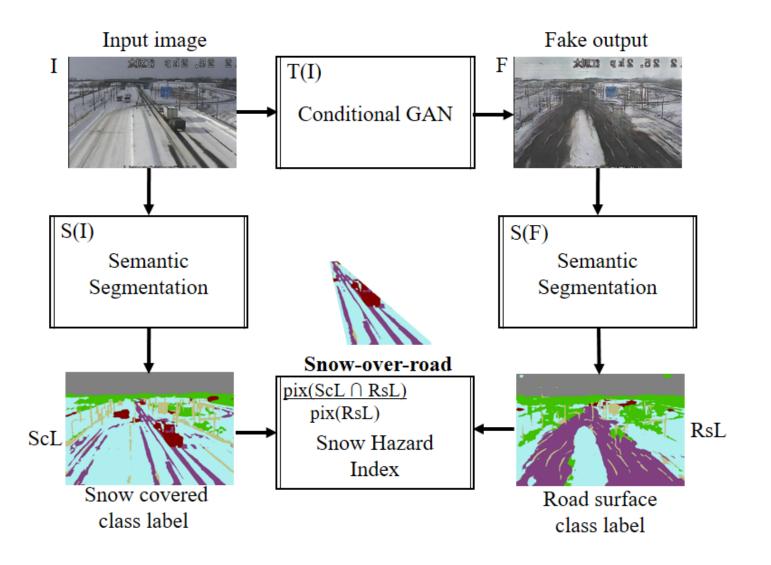
Takato Yasuno, Hiroaki Sugawara, Junichiro Fujii May, 2021



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Today's talk : Snow Hazard Indicator Pipeline







Outline

- 1. Introduction
- 2. Deep Learning Application
- **3. Snow Hazard Indicator Results**
- 4. Snowy Night-to-Day Results
- 5. Concluding Remarks





1. Introduction



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1.1 Background



- January 10, 2021, owing to heavy snowfall on the Hokuriku Expressway, approximately 1,000 cars were stuck.
- This congestion was caused by a slippery accident.
- Road surface monitoring is critical for winter road safety.

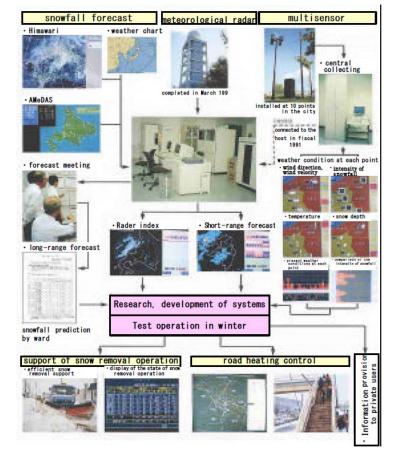


www3.nhk.or.jp/tohoku-news/20210119/6000013183.html

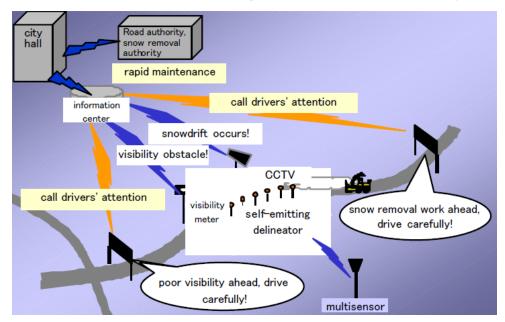


1.2 Intelligent Monitoring Winter Road

 Snowfall forecast / sensing system for road status, comprehensive network



• Required multi-mode observed weather / image data, so costly



Kido et al., Sapporo City (1999) : "Management of Roads in Winter using CCTV camera".

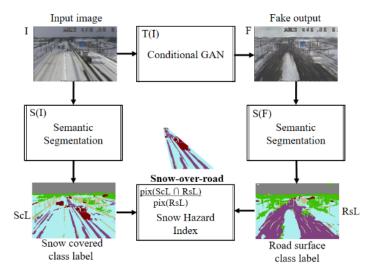


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1.3 Practical Indicator for Winter Road Safety



- Challenges
 - Vision based practical indicator
 - Fewer data, only image input, less cost
 - Provide hazardous measure for road managers/users
- Our proposal
 - Before-snow image translation
 - Snow / road segmentation
 - Live image post-processing
 - Compute a snow hazard indicator.







1.4 Trial steps and Validation

- Trial steps
 - 1) Image translation of the road surface region hidden under snow using a **conditional GAN**
 - 2) Snow-covered /Road surface, per-pixel classification using **semantic segmentation**.
 - 3) Indicate the amount of snow covered on the road
- Apply our pipeline
 - Field study of **snow and cold regions** in Japan.





2. Deep Learning Application

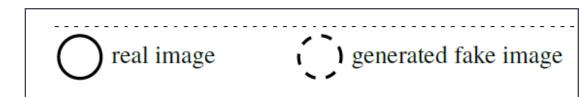


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2.1 Image-to-image Translation for Conditional GAN

- pix2pix framework
- One-to-one Image Translation



• Objective "one-to-one" consistency

$$x_r^a \longrightarrow x_r^b$$
 Aligned training sample
 $||G(x_r^a) - x_r^b||_p$: target consistency



2.2 MATLAB enabler for Conditional GAN

Custom Loop for Deep Learning

- 1) dlarray & dlnetwork: handle data and networks flexibly
- 2) dlfeval : evaluate custom loss & gradient function
- 3) PairedImageDatastore: easy to access paired dataset

MATLAB® (primary tools)

- Deep Learning Toolbox[™], Parallel Computing Toolbox[™]
- Computer Vision Toolbox[™], Image Processing Toolbox[™]

New Released R2021a:

• **pix2pixHD** generator : high-resolution label-to-image translation.



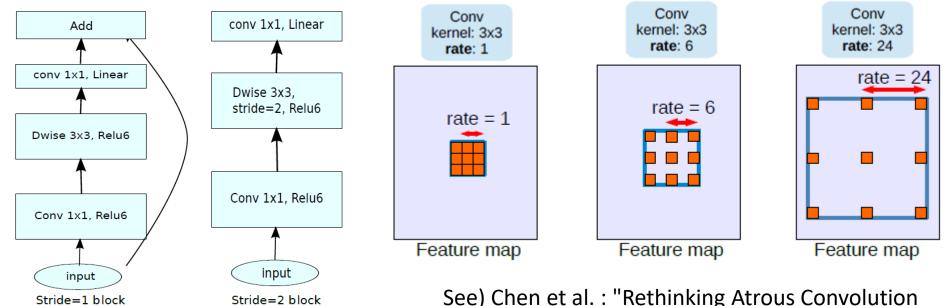
2.3 Semantic Segmentation for Snow and Road

MobileNetv2

- Bottleneck Residual block
- Reduce memory : max. 400K

DeepLabv3+

- Atrous Pyramid Pooling
- Dense convolution



See) Sandler et al. : "MobileNetV2: Inverted Residuals and Linear Bottlenecks" (2018) See) Chen et al. : "Rethinking Atrous Convolution for Semantic Image Segmentation" (2018)







2.4 MATLAB set the pace for Semantic Segmentation

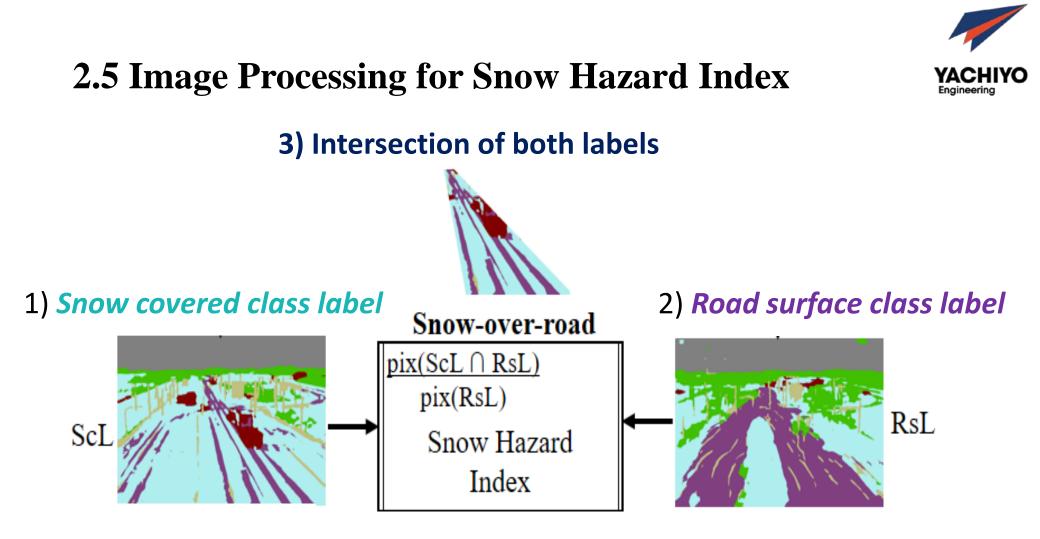
Standard Deep Learning Enablers

- 1) pixelLabelImageDatastore: handle image and label paired set
- 2) deeplabv3plusLayers : easy to build e.g. MobileNetv2, Xception
- 3) trainNetwork: training dataset, layers, and options
- 4) semanticseg: easy to predict test image by trained network
- 5) evaluateSemanticSegmentation: easy to evaluate accuracy

MATLAB® (primary tools)

- Deep Learning Toolbox[™], Computer Vision Toolbox[™]
- Parallel Computing Toolbox[™]





• Automatically compute **the snow hazard ratio index**, without the ground-truth of the road surface image.





3. Snow Hazard Indicator Results

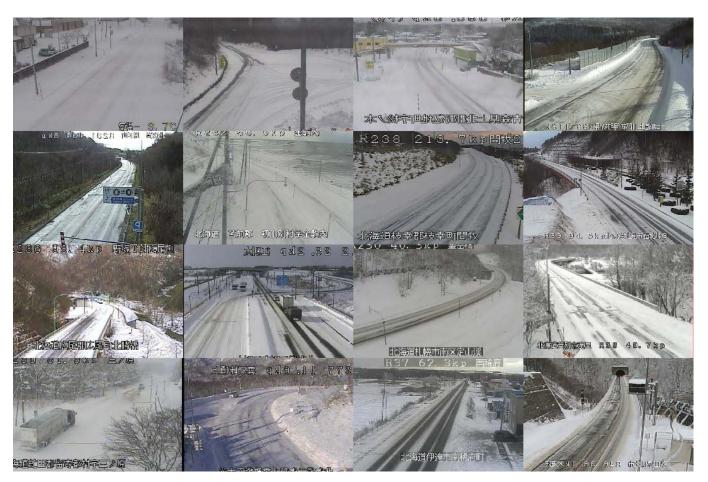


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3.1 Input Raw Image Examples



- Snowy road surface test image, hazardous condition
- Note: background snow is NOT dependent on traffic accident



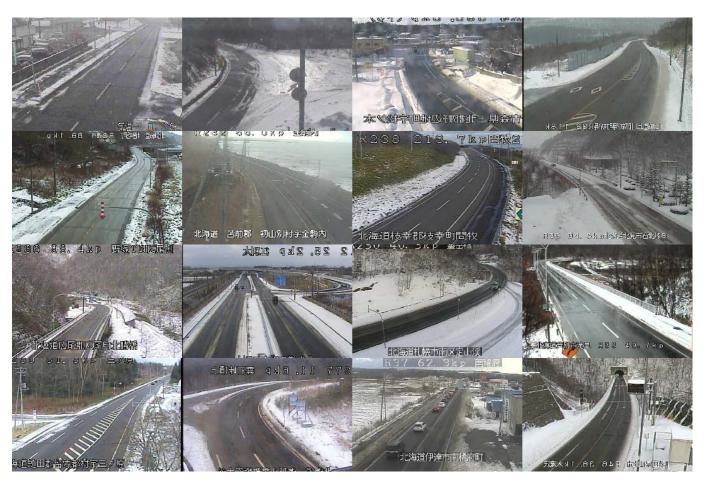


https://www.mlit.go.jp/road/road_e/index_e.html

3.2 Ground truth Road Surface Examples



- "before snow" real situation,
- Target ROI road surface have been shown clearly





https://www.mlit.go.jp/road/road_e/index_e.html

3.3 Fake output Road Surface Examples



 Test snowy raw input is translated to "before snow" fake situation using the trained pix2pix

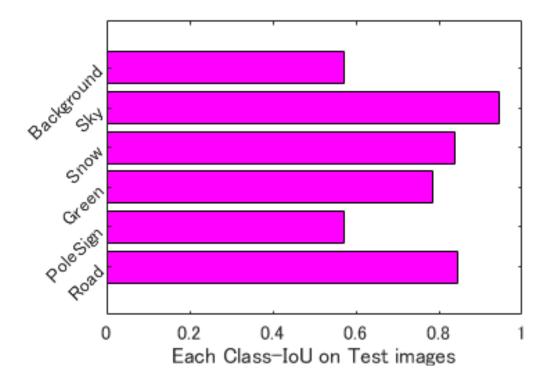




3.4 Trained Segmentation for Snow and Road Surface



- Train a DeepLabv3+ with a backbone MobileNetv2
- Each class Intersection of Union(IoU) is more than 0.6.
- The road and snow class IoU is 0.8, so useful

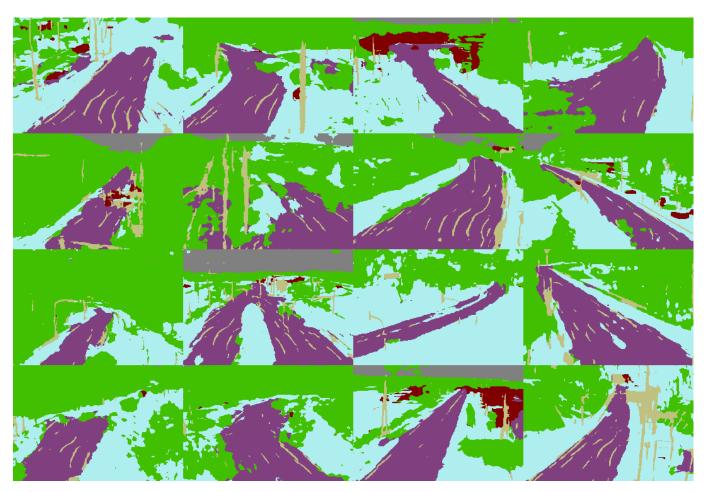




3.5 Road Surface Label Prediction from fake output



 Predict the fake output of "before snow" using the trained semantic segmentation network

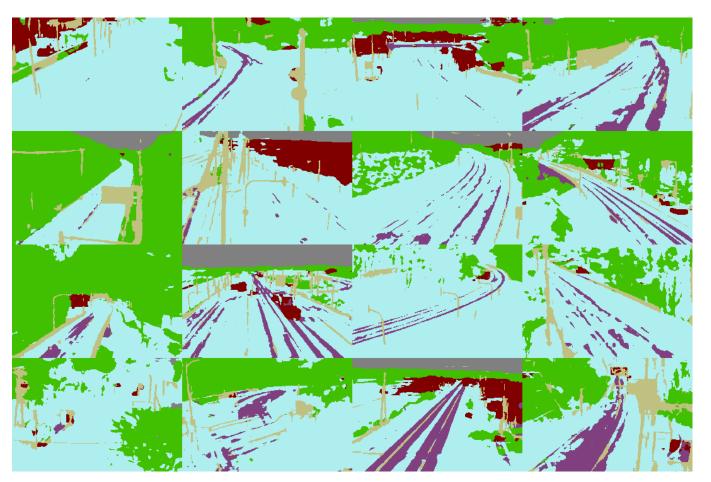




3.6 Snow Region Label Prediction from raw input



• Predict the real region of "snowy road" using the trained semantic segmentation network

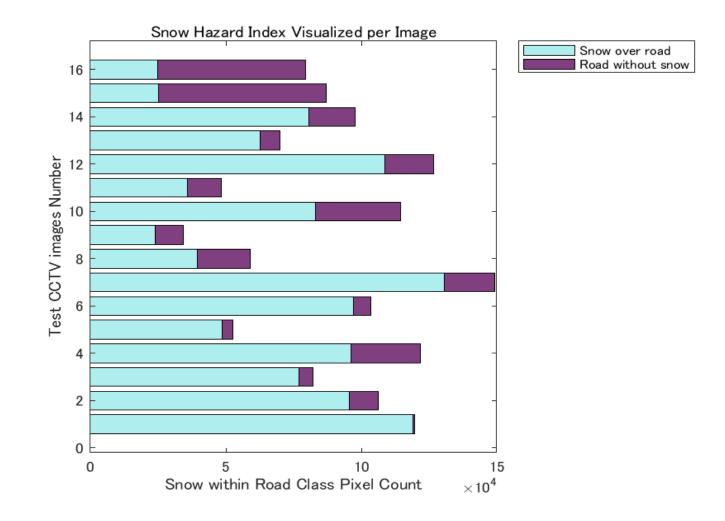




3.7 Snow-over-road and Road Surface without Snow



- Bar plots of the pixel count for the monitoring target ROI
- Snow-over-road, and Road surface without snow

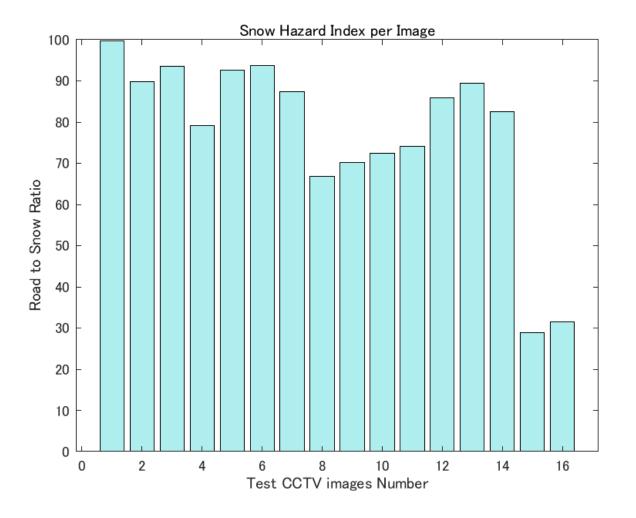




3.8 Snow Hazard Ratio Index



• Bar plots of the *snow hazard ratio* index; indicates the snow ratio within the road surface ROI of each image.







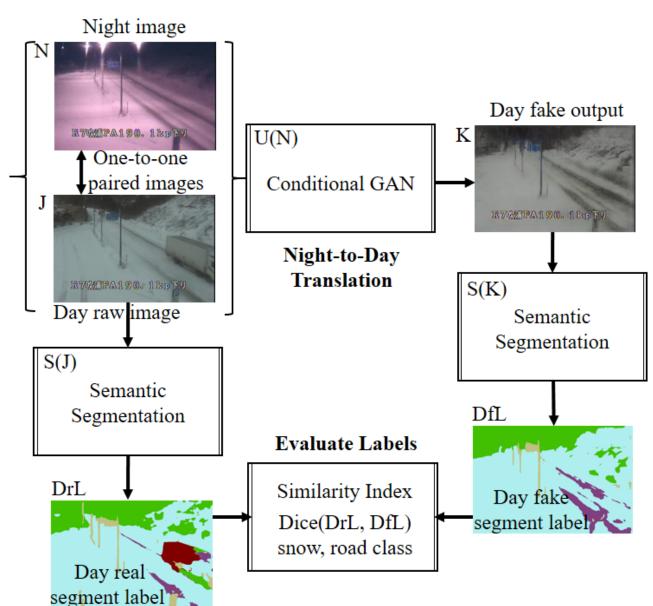
4. Snowy Night-to-Day Results



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Talk+ : Snowy Night-to-Day Translator Pipeline



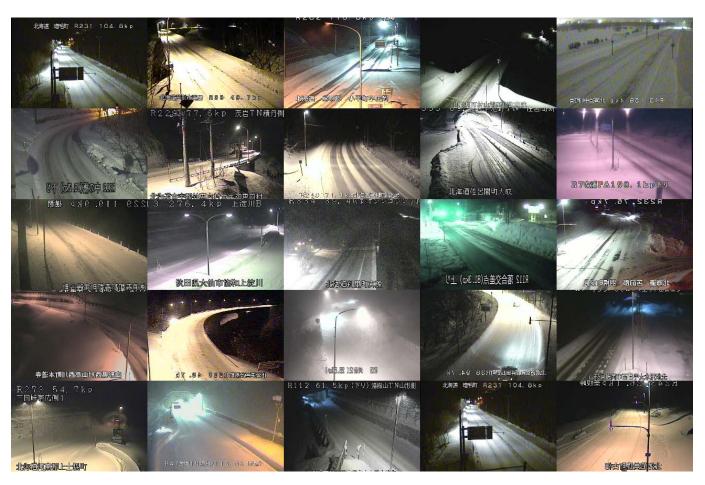




4.1 Input Night Image Examples



- Snowy night road surface : test images are selected
- Under lighting points, roads are moderately lighted up



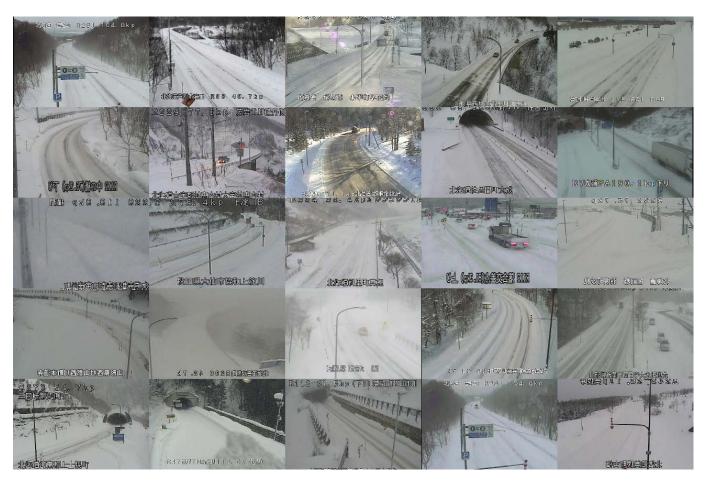


https://www.mlit.go.jp/road/road_e/index_e.html

4.2 Ground truth Day image Examples

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- "day time" real situation,
- Snowy road surface have been shown clearly





https://www.mlit.go.jp/road/road_e/index_e.html

4.3 Fake Day output Examples



 Test night raw input is translated to "day time" fake situation using the trained the "night-to-day" pix2pix

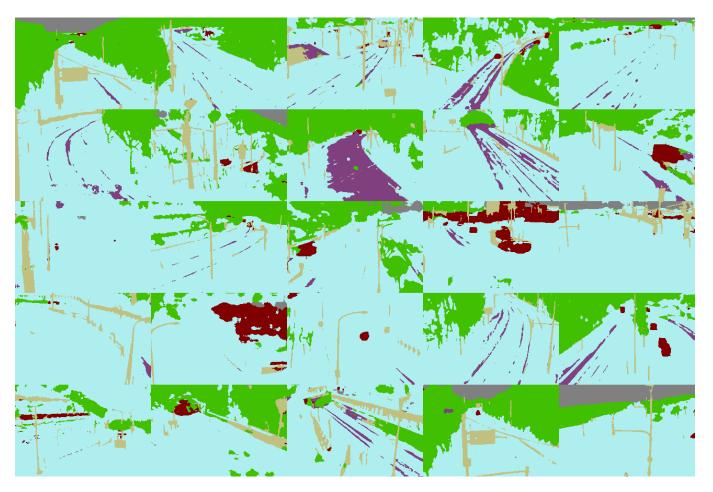




4.4 Day Label Prediction from Real input



 Predict the fake snow label of "day time" using the trained semantic segmentation network

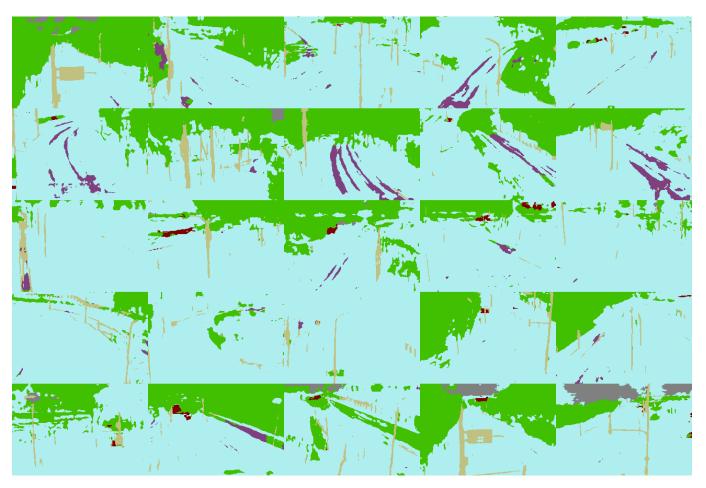




4.5 Fake Day Label Prediction from fake output



 Predict the real snow region of "day time" using the trained semantic segmentation network

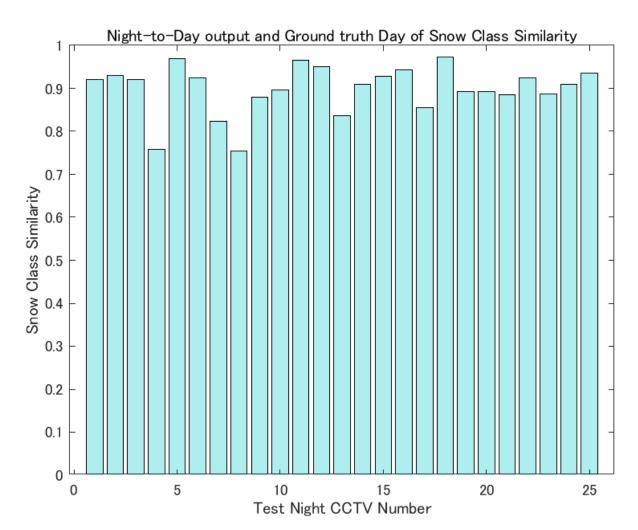




4.6 Similarity between Real Snowy day and Fake



- Intersection of fake day snow region, and real day snow region
- These similarity scores are high more than 0.75





5. Concluding Remarks



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5. Concluding Remarks

- Fake day label output from snowy night image have been well approximated to the Real snowy day label.
- Combine two pipelines for snowy night road status to make decisions of operations : "road closures" / "snow removal", even at night.
- Extend to **edge computing** for automatic real-time provision for drivers about hazardous road status.



Deep Learning for Pattern Recognition



- RIIPS (Research Institute for Infrastructure Paradigm shift).
- DLPR project: Natural Disaster, Traffic Detection.

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If you have any questions, I'd happy to respond it. Please feel free to contact me. <u>e-mail : tk-yasuno@yachiyo-eng.co.jp</u>