

MathWorks Automotive Conference EXPO 2021

Continental Group Structure

Effective January 1, 2020



Public



Automotive Technologies

Automotive Technologies

Automotive Central Functions

A Purchasing

A SCM

A Manufacturing

A Sales

A IT

A Quality

Finance Controlling

Human Relations

Communications







Autonomous Mobility and Safety

Holistic Engineering and Technologies

Vehicle Networking and Information

Vehicle Dynamics Hydraulic Brake Systems Passive Safety & Sensorics Adv. Driver Assistance Systems

Connected Car Networking

Human Machine Interface Commercial Vehicles & Services



About myself



- 2017 present
 - Team Lead, Base Software Development and Integration, Research & Advanced Engineering, Continental
- 1997 2017
 - Leading eCAL middleware core development for AD systems
 - > Senior Expert "Human Machine Interfaces"
 - Anti-lock braking system for EMB
 - Various other research projects ..
- 1997
 - Diploma Electrical Engineering Technical University Dresden / Germany



- 1 Motivation
- 2 eCAL
- 3 eCAL Toolbox
- 4 Conclusion



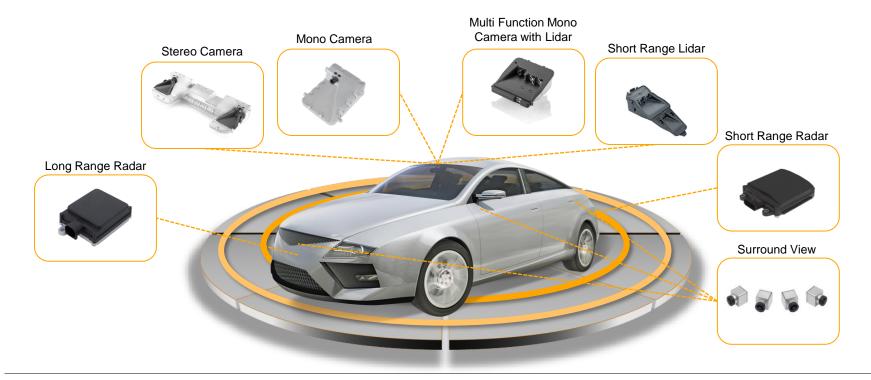
Autonomous Driving – The Challenge



- Radical changes to some aspects of driving
- From partially automated to fully automated driving
- Requires new sensor technologies and high-performance computer systems
- Cluster intelligence, formed from the vehicle fleet on the road
- Large quantities of data must be transmitted extremely reliably inside and outside the vehicles
- Cluster connectivity: The Internet will become the car's sixth sense.



Autonomous Driving – it's all about data processing





Middleware main requirements

- performance
 - > ethernet and shared memory instead classic vehicle bus systems
 - message transport with minimal latency and high data throughput
- new in-vehicle cloud / domain architecture
 - > heterogenous network of different hardware, operating systems, computing languages
 - publish / subscribe pattern
 - built-in support for different modern message serialization formats
- > development tools for monitoring, recording, replay, system start



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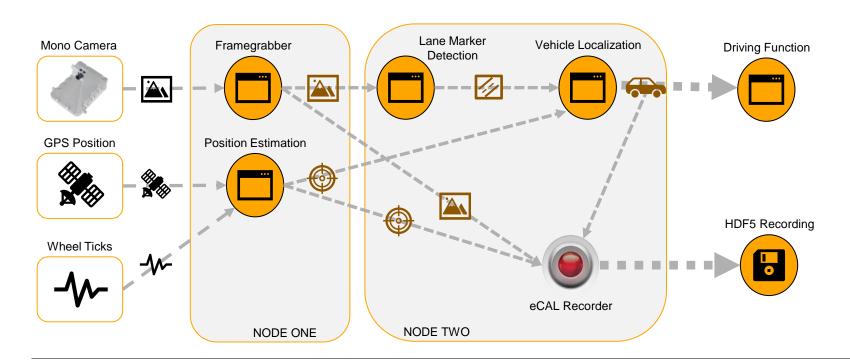


Architecture

User eCAL eCAL eCAL **Applications** Monitor Player Recorder Application Layer Interface Layer eCAL API (C / C++ / Python / Rust) TimeSync, Logging, Monitoring Service Layer Google Protobuf (Flatbuffers, Cap'nProto, MsgPack, JSON ..) Message Layer Transport Layer UDP Multicast / Shared Memory Windows / Linux / QNX / macOS OS Layer x86 / arm **HW Layer**

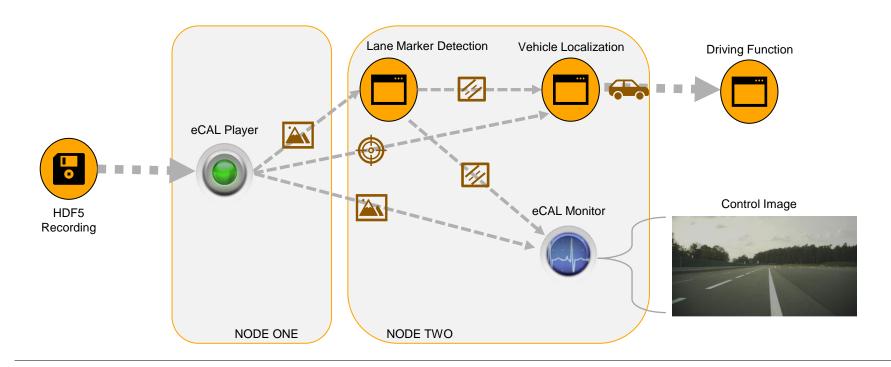


Data driven design – Run & Record





Data driven design – Replay & Test

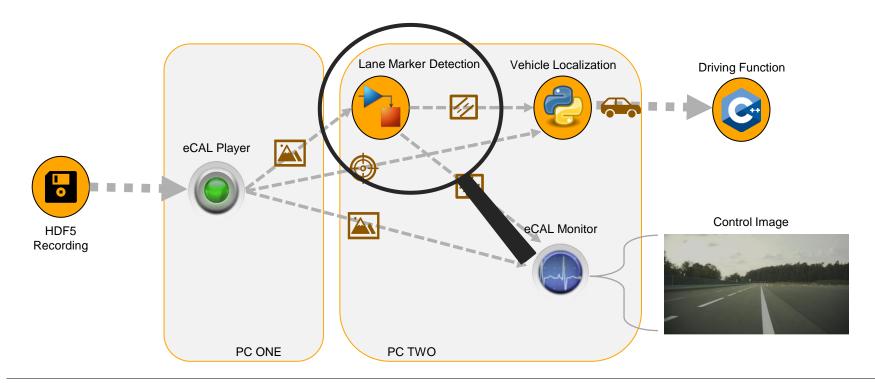




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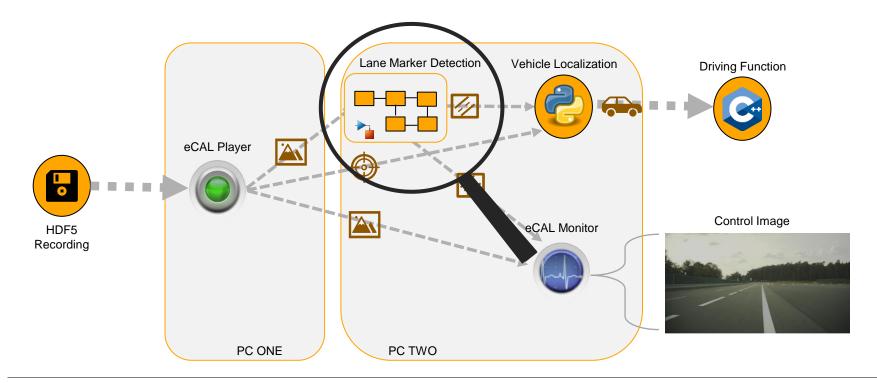


Development diversity



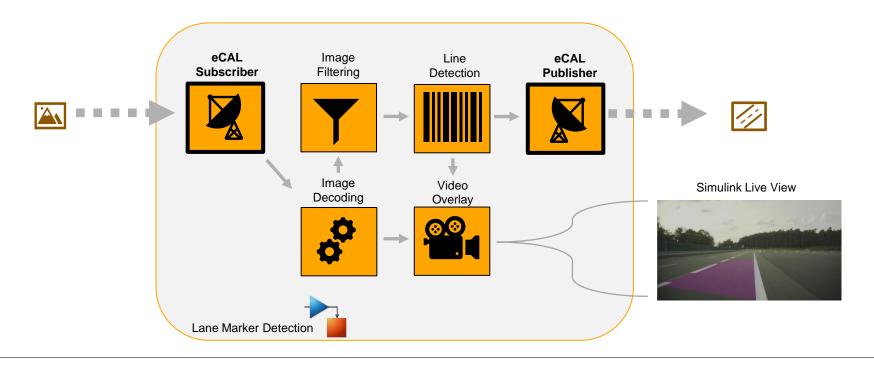


Model-based development with eCAL





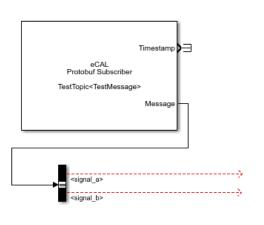
Model-based development with eCAL



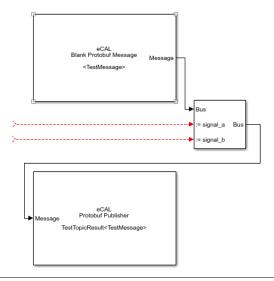


Simulink blockset for eCAL



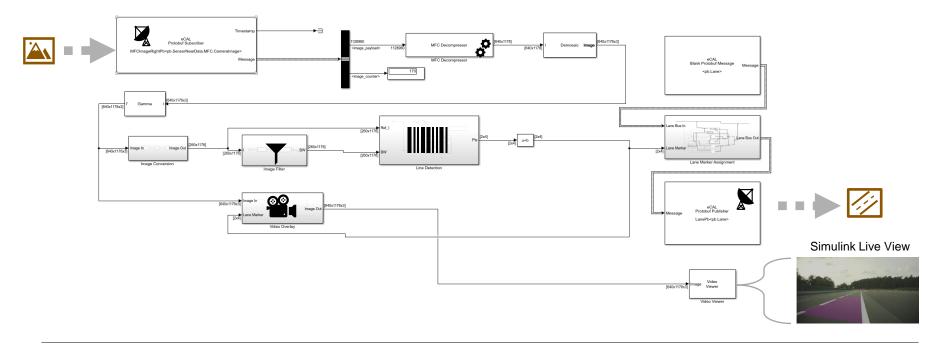








Lane Marker Detection Model





Lane Marker Detection Model – Live Demo

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MAC Expo 2021

Public

Conclusion

- CAL provides high performance interprocess communication for rapid prototyping
- > eCAL is open source software (https://github.com/continental/ecal)
- > eCAL Simulink toolbox opens a wide range of new applications
-) eCALize your Simulink based development!



Thank you for your attention



