Developing realistic scenes to enable virtual automated driving testing

Kunal Patil



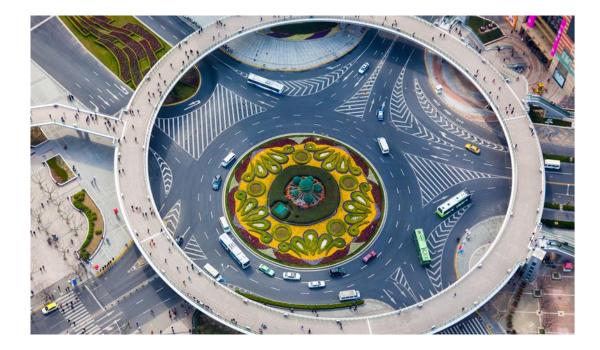
Peter Fryscak



Real world roads are complicated



Quickly create accurate road models



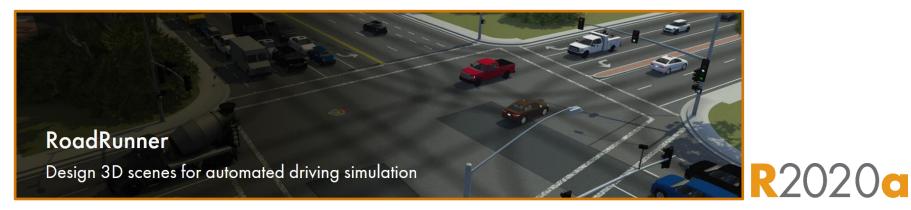


Photo

RoadRunner

RoadRunner Product Family in R2021a





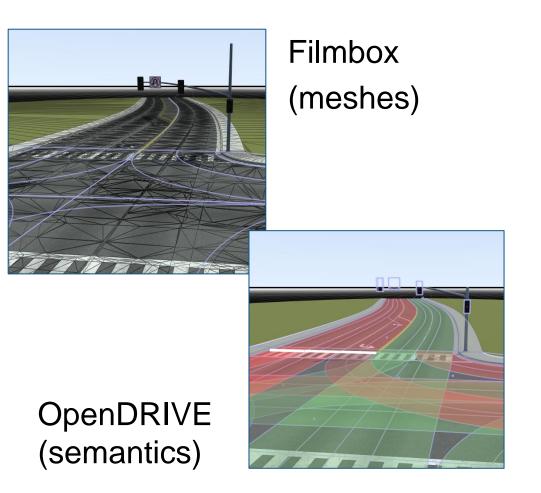
Export scenes to driving simulators and graphics engines

- Export to common file formats for use in third-party applications
 - Filmbox (.fbx), OpenDRIVE (.xodr)
 - Unreal Engine[®], CARLA
 - Unity[®], SVL
 - VIRES Virtual Test Drive, Monodrive
 - IPG Carmaker, Cognata, Baidu Apollo
 - rfPro, aiSim
 - Tesis Dynaware, TaSS PreScan
 - NVIDIA DRIVE Sim

Exporting

RoadRunner





Poll Question

• Which simulators are most important to you and your colleagues?

- a. CARLA
- b. IPG Carmaker
- c. MathWorks ADT
- d. Unreal
- e. VIRES VTD
- f. Other

Design 3D scenes for automated driving simulation

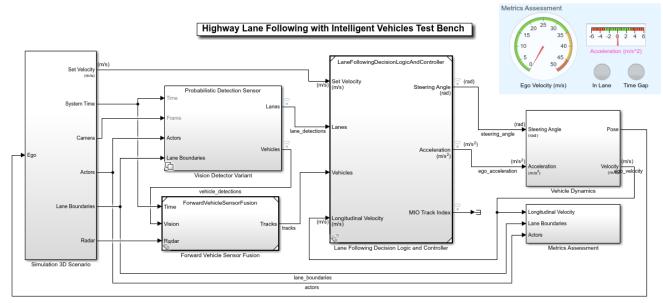


Integrate RoadRunner scene with lane following scenario

Explore highway lane following system

Integrate with driving scenario and Unreal Engine

Simulate



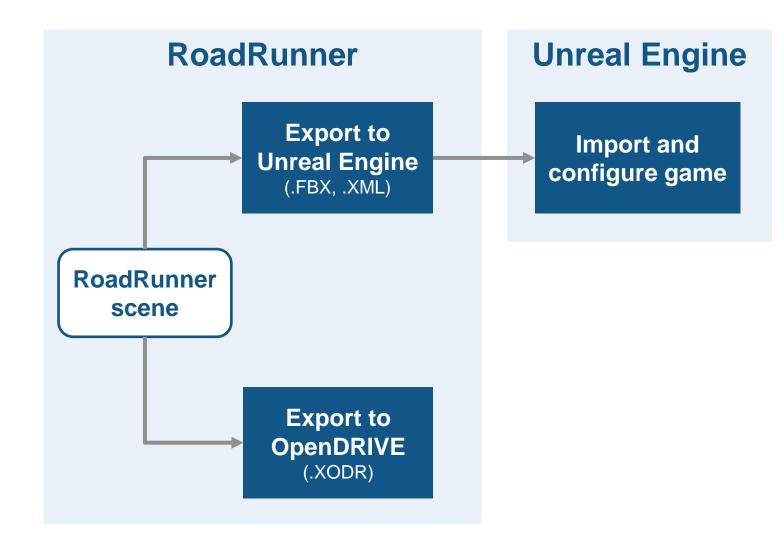
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Integrate algorithms

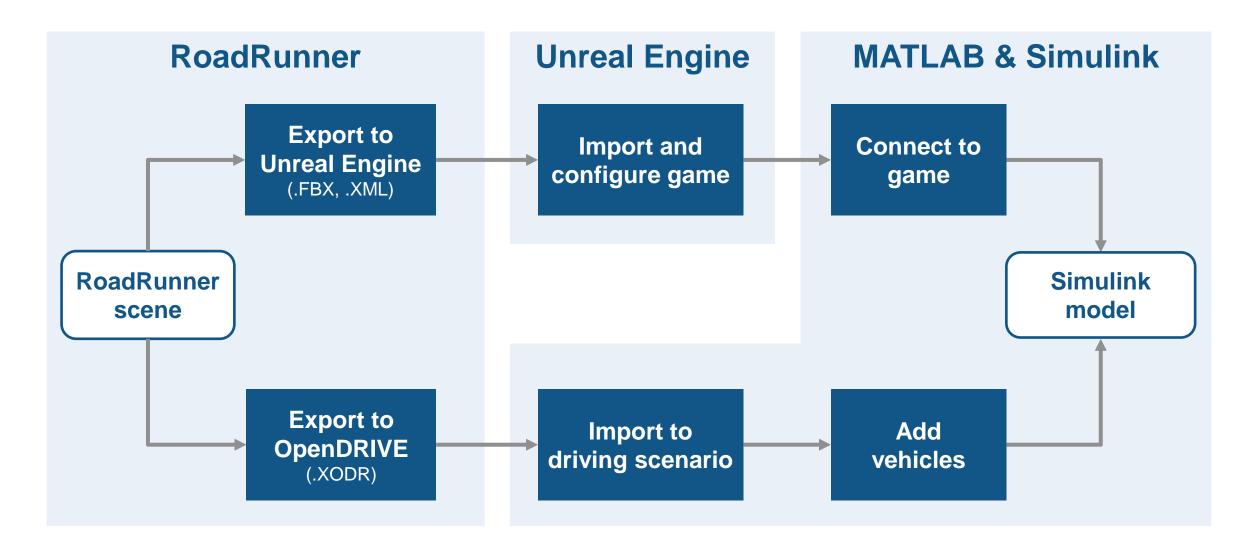
- Vision detection
- Sensor fusion
- Decision logic and controls

Highway Lane Following with RoadRunner Scene Automated Driving ToolboxTM

Integrate RoadRunner with MATLAB and Simulink workflows



Integrate RoadRunner with MATLAB and Simulink workflows



Design 3D scenes for automated driving simulation



Poll Questions

• What import formats are most important to you?

- a. HERE HD Live Map
- b. In-house or Proprietary format
- c. NDS files
- d. OpenDRIVE
- e. Tom Tom HD map
- f. Zenrin SD Map
- Are you interested in more information?
 - a. Yes, I have some questions and would like to talk
 - b. Yes, I would like to schedule follow up session on this topic with my team
 - c. Not at this time

Thank you



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