MATLAB EXPO 2019

Developing Battery Management System using Simulink

Romain LACHAUX



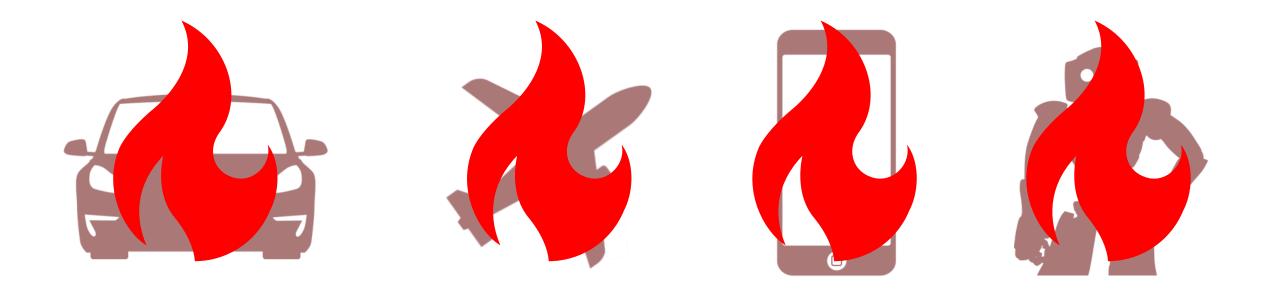


Battery: a good answer to energy storage across industries...





... with some risks to keep under control





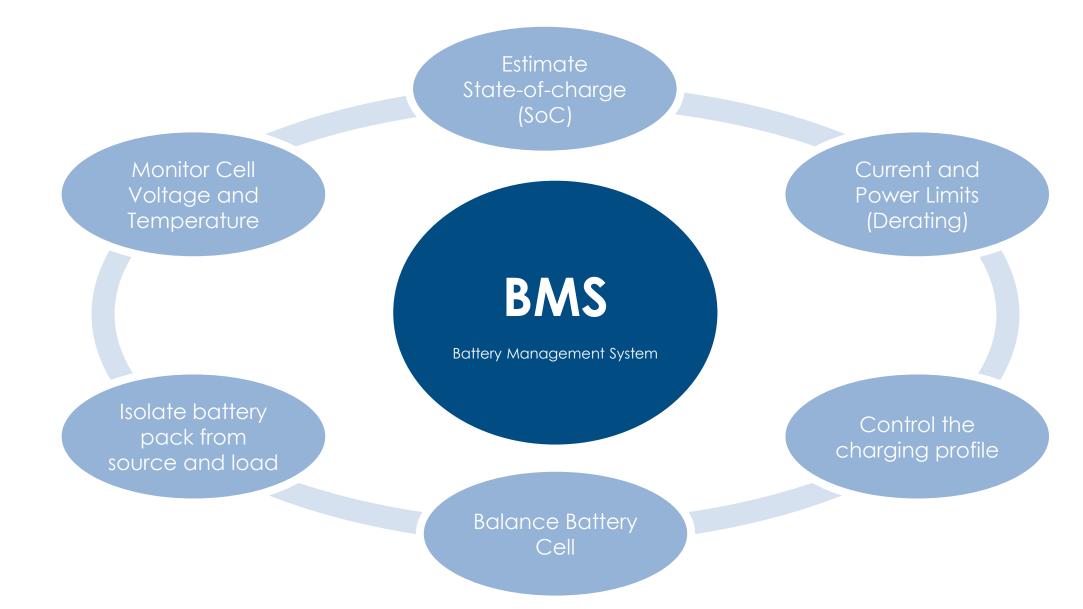


BY JENNI FINK ON 8/1/18 AT 11:00 AM EDT



CHALLENGE: Design and verify battery management functions



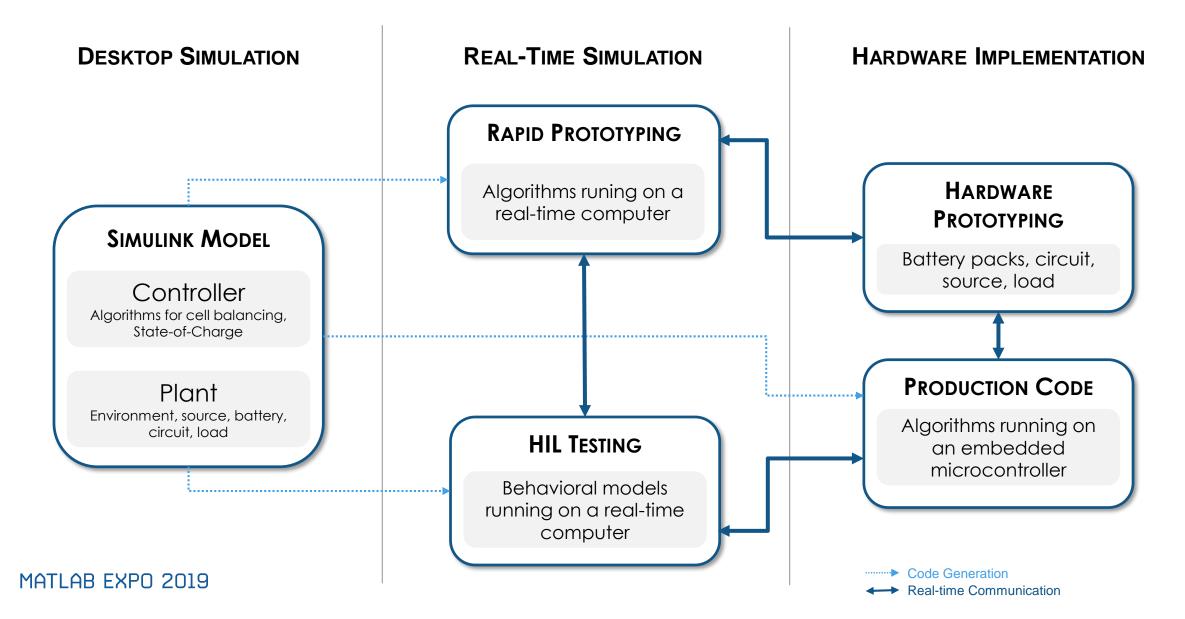




SOLUTION: Perform system-level simulations with Simulink



BMS Development Workflow with Simulink and MBD





Agenda

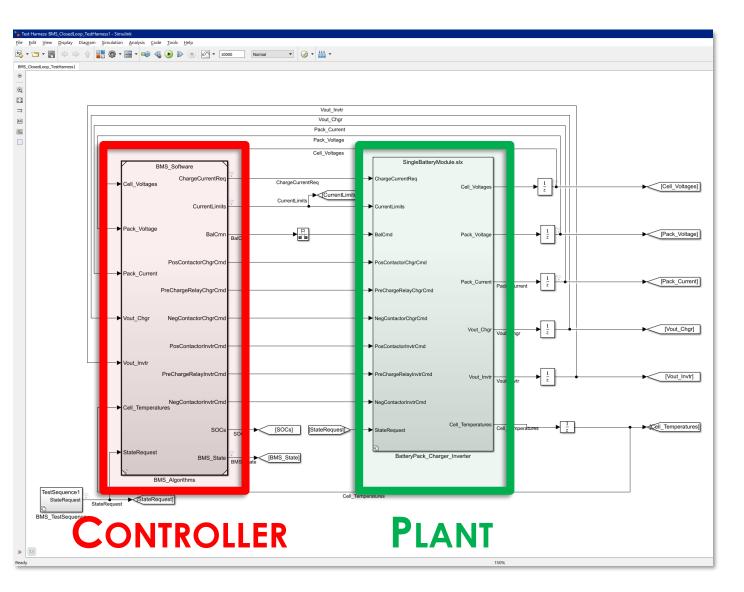
BMS Model Demo

- Physical Modeling
- BMS Algorithms
- Deployment on Hardware
 - Code Generation
 - Real-Time Testing



BMS Model Overview

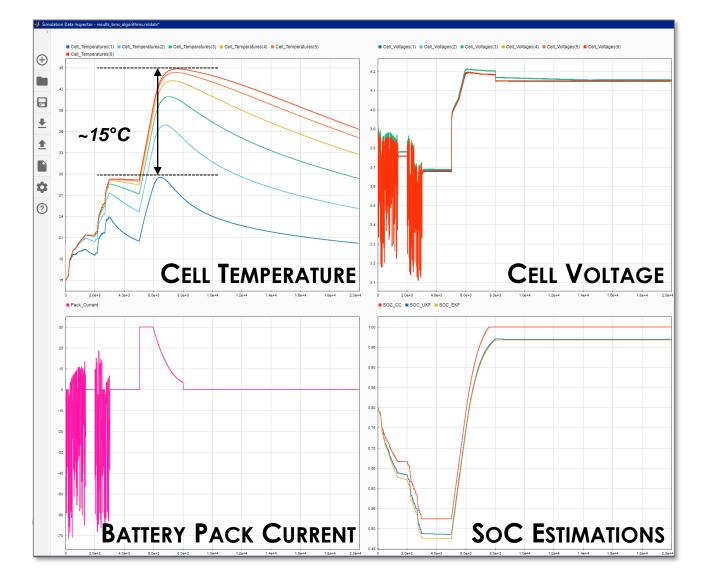
- System Model
 - Controller: BMS Algorithms
 - Plant : Physical Modeling
- Advantages of System-Level Simulation:
 - Quick design iterations
 - Early results in the development workflow
 - Possible to test each part alone or together in the same model (Closed-loop testing)





Simulation Results Overview

- Early results during design process
 - ➔ Possible to refine or add missing requirements
- Example:
 - Temperature differences
 - Potential impact on cells ageing
 - ➔ Need of a cooling system?





PLANT: Battery Physical Modeling with **Simulink** and **Simscape**

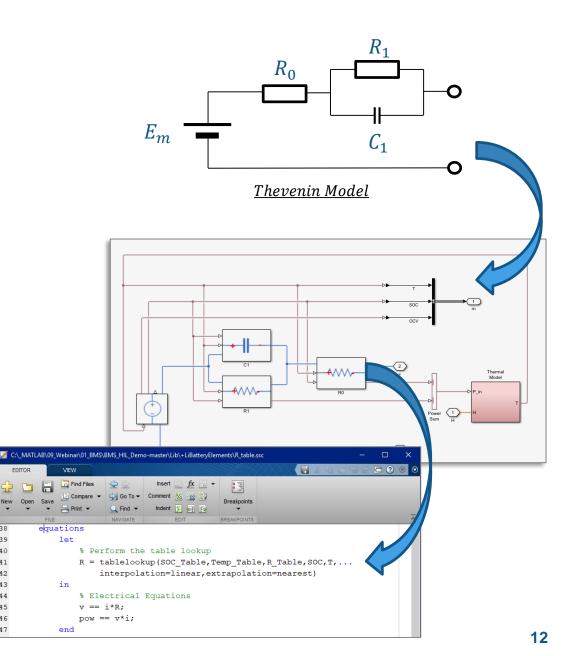


Battery Cell Modeling

- Thevenin Model (1st Order) to represent electrical behavior of battery cell
- Model based on Simscape Foundation Library components...
- ... with dependance upon SoC and temperature by modifying source code



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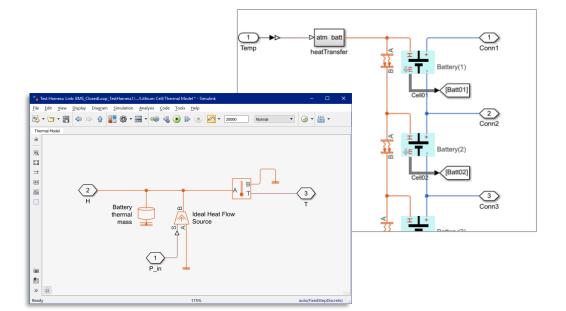
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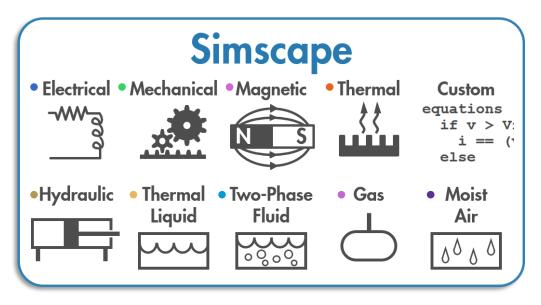


Battery Cell Modeling

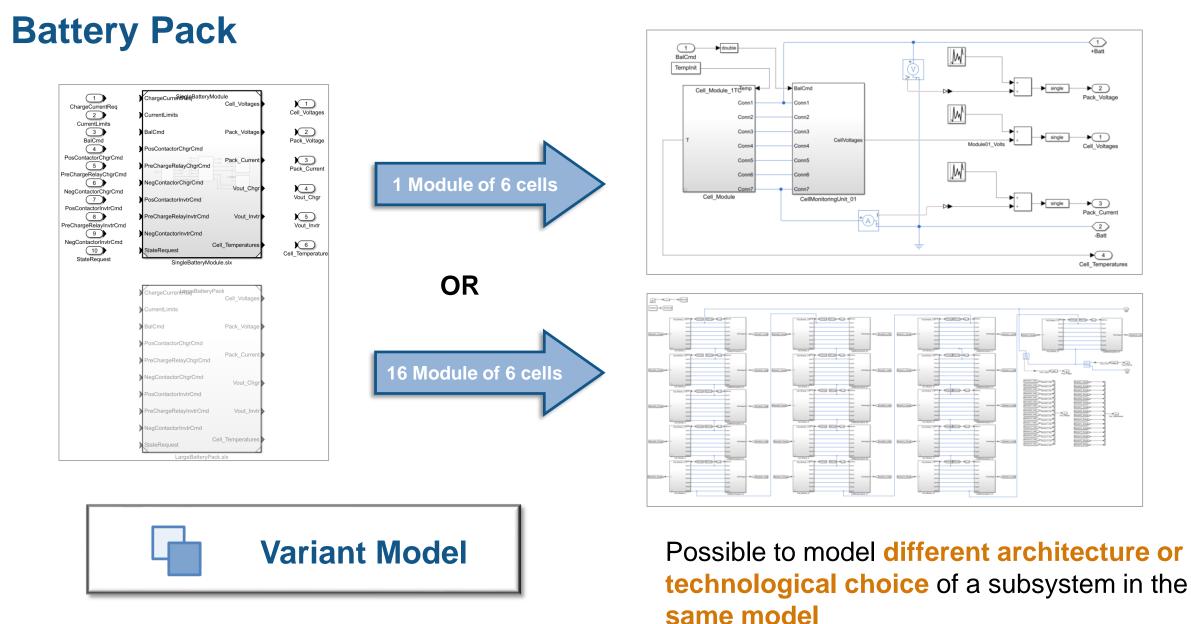
- What about thermal behavior?
 - Cell heat up under load
 - Convection heat flux between cells
 - Thermal exchange with environment
- → Thermal component from Foundation Library







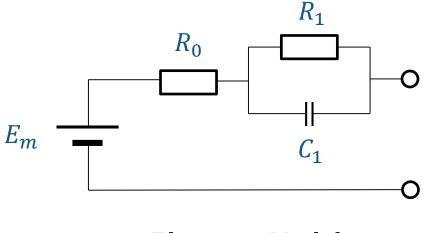






Tuning a Lithium Battery Model to Match Measured Data

Cell Physical Model:



Lithium Cell Characteristic <u>Measurement</u>:

Em	SOC 1	SOC 0.9	SOC 0.8	 SOC 0
5°C	4.20 V	4.12 V	4.05 V	 3.09 V
20°C	4.18 V	4.09 V	4.01 V	 3.05 V
40°C	4.15 V	4.02 V	3.97 V	 3.01 V

<u>Thevenin Model</u>

OBJECTIVE: Match model behavior to tests measurements



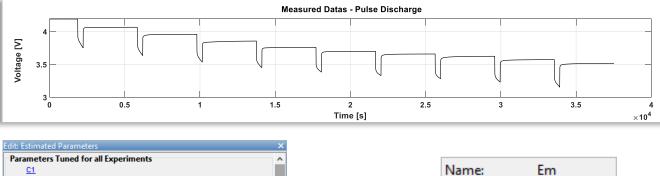
Estimating Parameters Using Measured Data

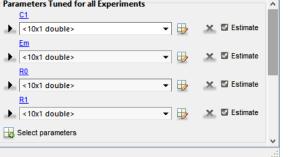
1. Import measurement datas

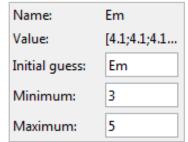
2. Identify parameters and set range

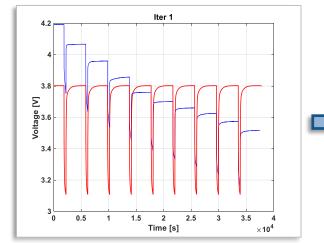
3. Perform estimation

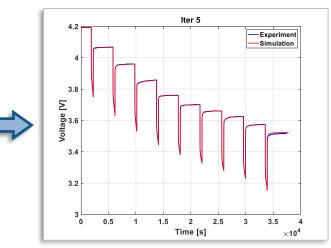
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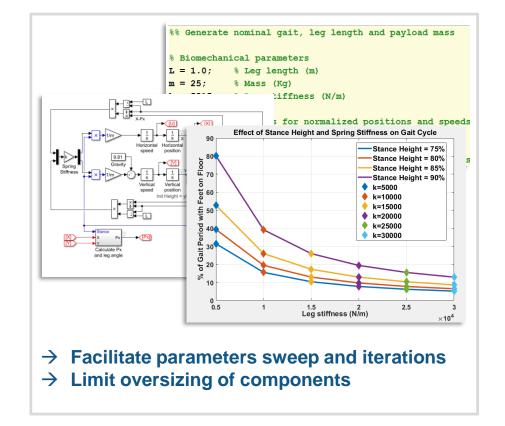


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Advantages of Physical Modeling

- With this physical model, you can
 - Evaluate your architecture
 - Optimize your design
 - Refine and Validate your requirements



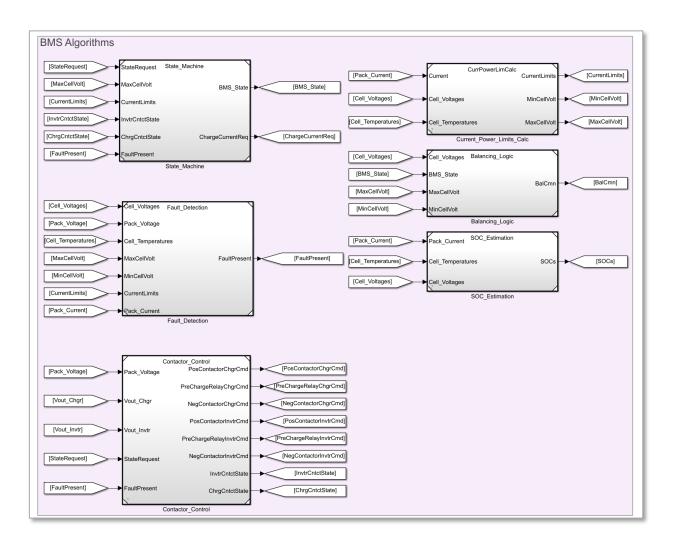
+ Enable Closed-loop testing of your control algorithms to verify and validate it



CONTROLLER: BMS Algorithms with Simulink and Stateflow



Battery Management System Functions

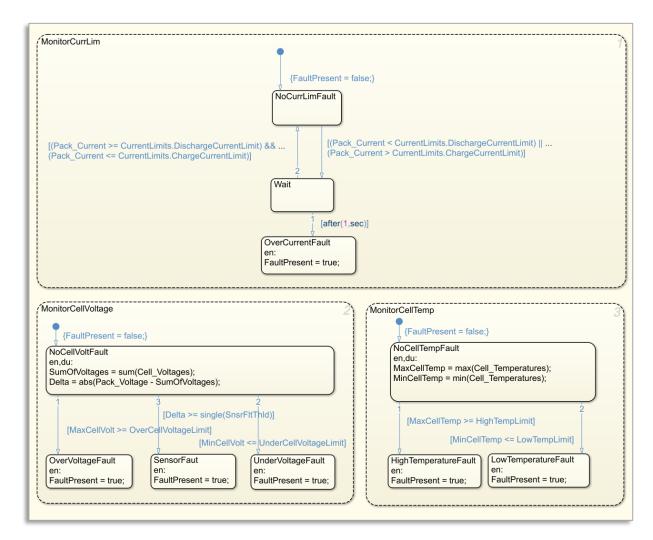


- Battery State
- Fault Management
- Battery isolation control
- Derating Calculations
- State-of-Charge Estimation



Fault Management

- Monitoring three physical channels:
 - Battery Pack Current
 - Cell Voltage
 - Cell Temperature
- Broadcasting Fault Presence to other BMS subsystems
 → Contactor Opening (SAFETY)
 - → BMS State == FAULT



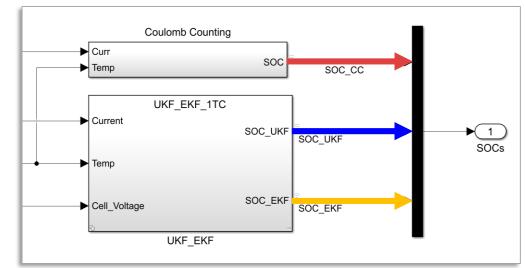


State-Of-Charge Estimation

Two methods:

– Coulomb Counting

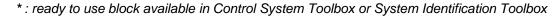
- Simple to implement / low computational needs
- \mathbf{X} : Accuracy and robustness

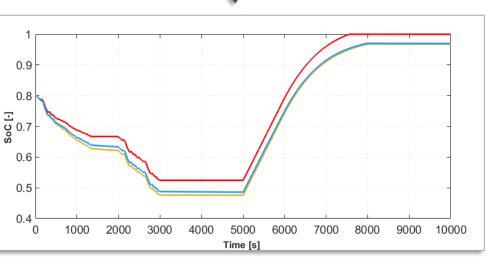




– Kalman Filtering*

- High accuracy by including a nonlinear battery model which uses current and voltage measurement
- ✗ : Slightly higher computational effort





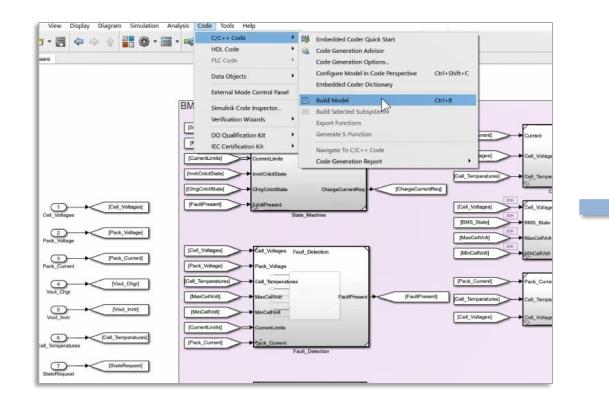


Agenda

- BMS Model Overview
 - Physical Modeling
 - BMS Algorithms
- **Deployment on Hardware**
 - Code Generation
 - Real-Time Testing

MathWorks[®]

Generate C/C++ Code From BMS Models



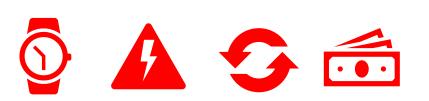
- Generate target optimized C/C++ code
- Fine-tune code optimizations, package and build generated code

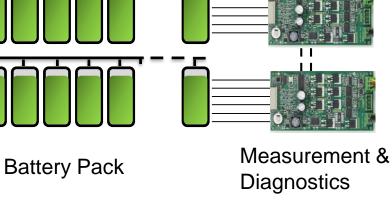
🔁 Code Generation Report — 🗆 🗙					
< 🄶 🌀 Find:	🔐 🕹 Match Case				
Contents	File: BMS_Software.c				
Summary Subsystem Report Code Interface Report Traceability Report Static Code Metrics Report List of inserted blocks Code Replacements Report Coder Assumptions Generated Code [-] Main file	<pre>/* /* /* File: BMS_Software.c /* /* Code generated for Simulink model 'BMS_Software'. /* /* /* /* /* /* /* /* /* /* /* /* /*</pre>				
ert_main.c	22 <u>DW_BMS_Software_T</u> BMS_Software_DW; 23 24 /* External inputs (root inport signals with default storage) */				
BMS_Software.c BMS_Software.h BMS_Software_private.h BMS_Software_types.h	<pre>25 ExtU_BMS_Software_T_BMS_Software_U; 26 27 /* External outputs (root outports fed by signals with default storage) * 28 ExtY_BMS_Software_T_BMS_Software_Y; 29 30 /* Real-time model */ 31 RT_MODEL_BMS_Software_T_BMS_Software_M_; 32 RT_MODEL_BMS_Software_T_*const_BMS_Software_M = &BMS_Software_M_;</pre>				
[-] Shared files rtwtypes.h	<pre>33 34 /* Model step function for TIDO */ 35 void BMS_Software_step0(void) /* Sample time: [0.1s, 0.0s] */ 36 { 37 /* Update the flag to indicate when data transfers from</pre>				
Referenced Models	38 * Sample time; [0.1s, 0.0s] to Sample time; [5.0s, 0.0s] */ 39 <u>BMS Software M</u> ->Timing.RateInteraction.b_TID0 1 = 40 (<u>BMS Software M</u> ->Timing.RateInteraction.tTD0 1 == 0);				
Balancing_Logic	<pre>41 (<u>BMS_Software_M</u>->Timing.RateInteraction.TID0_1)++; 42 if ((<u>BMS_Software_M</u>->Timing.RateInteraction.TID0_1) > 49) {</pre>				
Contactor_Control	<pre>43 <u>BMS_Software_M</u>->Timing.RateInteraction.TID0_1 = 0; 44 } 45</pre>				
CurrPowerLimCalc Fault_Detection	45 46 /* ModelReference: ' <u><root>/Current Power Limits Calc</root></u> ' incorporates: 47 * Inport: ' <u><root>/Cell Temperatures</root></u> ' 48 * Inport: ' <u><root>/Cell Voltages</root></u> '				
SOC_Estimation State_Machine	49 * Inport: ' <u><root>/Pack_Current</root></u> ' 50 * Outport: ' <u><root>/CurrentLimits</root></u> ' 51 * 52 * Block requirements for '< <u>Root>/Current Power Limits Calc</u> ':				



Real-Time Testing of Battery Management System

- Testing BMS with Battery Cells
 - Longer test cycles
 - Difficult to test fault conditions
 - Difficult to reproduce results
 - Limited test automation
 - → Costs (Hardware prototype, possible failure, several people to perfom tests, etc)





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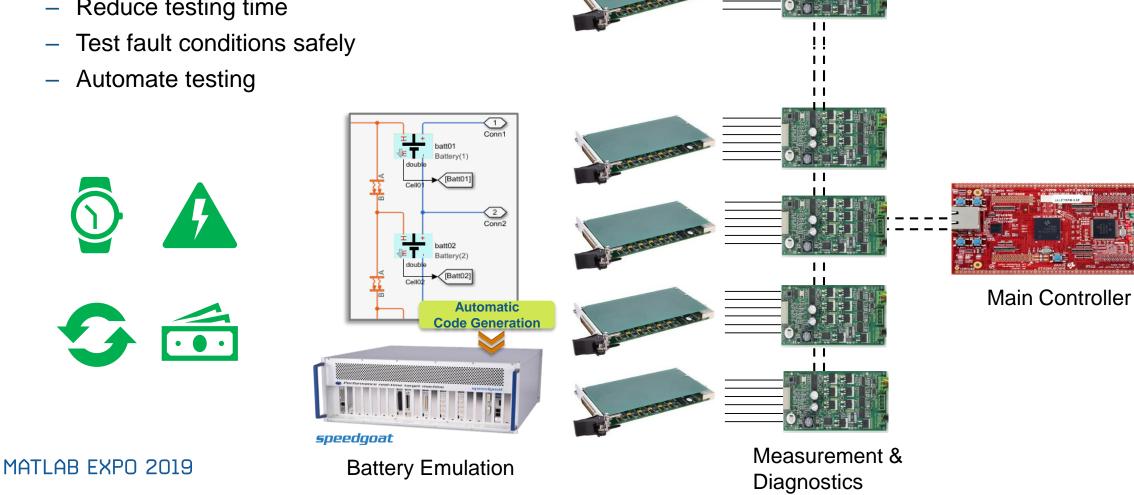
Main Controller

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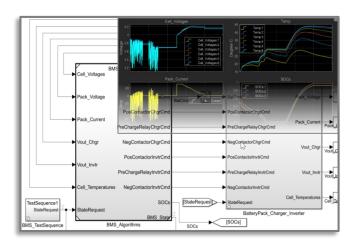
Hardware-In-Loop Testing of Battery Management System

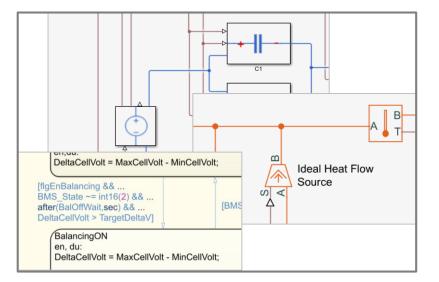
- Testing BMS with Emulated Battery Cells
 - Reduce testing time —
 - Test fault conditions safely —
 - Automate testing —

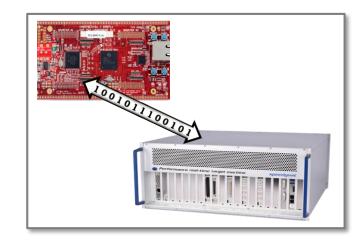




BMS Development with Simulink









Reduce Design Iteration Time



Collaborate Across Domains

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Gain Confidence in Design