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Systems Engineering

Requirements to Architecture to Simulation

Laurent Royer





What does the typical process involve?

Early in the Process Concepts/Descriptions



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Later in the Process Models





What is the Gap?

Early in the Process Concepts/Descriptions



Later in the Process Models



Traceability

Synchronization

Analysis & Simulation

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Key Takeaways

Digital thread providing traceability between requirements, architecture, and design



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Key Takeaways

- Digital thread providing traceability between requirements, architecture, and design
- Connected environment for designing and analyzing architectures and designs





Key Takeaways

- Digital thread providing traceability between requirements, architecture, and design
- Connected environment for designing and analyzing architectures and designs
- Integrated platform for analyzing all parts of your architecture in one multidomain environment



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State Machines



Discrete-Event



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What goes into the bridge?







Now let's see it in action



De Havilland DHC-2 "Beaver"



Update the De Havilland "Beaver" airplane to have full electrification of the propulsion system and make it an optionally piloted aircraft



Requirements



Requirements imported from Word and captured in Simulink Requirements

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Components



Create components for a ground station and beyond-visual-line-of-sight navigation in addition to the vehicle



Interfaces



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Add details by defining interfaces



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Every requirement except Propulsion Power has been implemented

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Drilling down in our component hierarchy we can find the Propulsion Power Subsystem Component



We associate this component to the requirement on Propulsion Power to specify how this requirement is implemented





We now have implemented every requirement

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Simulink badge



The Simulink badge tells us that this component is linked to the Engine Power Simulink model



User-defined properties and their values can be accessed by MATLAB to run various types of analysis

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Electrification upgrade



Simulation is OK, move on to the electrification upgrade



We now change the Propulsion Power requirement to specify that the power must come from an electric motor



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Spotlight view



The spotlight view shows what other components may be directly impacted by the change

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The effect this may have on other components can be followed further downstream by creating a spotlight of the Propeller and Propulsion component







We replace the current Propulsion Power component with a new one with an electric motor Simulink model linked to it



To see how this change impacts the total mass and power of the plane, we first add the value of mass and power to the new component by applying a stereotype to the component, and set the values of mass and power properties.

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|--|----------|-----------|---------------------|-----|
| Analysis Viewer (Technical Preview) | | | | O X |
| HOME | | | | |
| Image: Save Delete Image: Continuous Image: Continuous Image: Continuous New Open Save Delete Analyze Arguments * Update Overwrite | | | | |
| INSTANCE MODEL ANALYSIS UPDATE | | | | Ā |
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| UAS_reference_architecture_electric_budgetRollup | 392.33 | 175614300 | | |
| BVLOS Navigation | 0 | 0 | | |
| Ground Station | 0 | 0 | | |
| Communication Box | 0 | 0 | | |
| Ground Station GPS interface | 0 | 0 | | |
| USB Serial Converter | 0 | 0 | | |
| Wireless Communication Subsystem | 0 | 0 | | |
| GPS receiver | 0 | 0 | | |
| Guidance and Navigation Computer | 0 | 0 | | |
| Flight Commands | 0 | 0 | | |
| Payload Computer | 0 | 0 | | C |
| Vehicle | 392.33 | 175614300 | | |
| Communications Subsystem | 2.63 | 58050 | | |
| Automatic Dependent Surveillance-Broadcast | 0.05 | 5000 | | |
| C-Band Radio Modern | 0.05 | 2000 | | |
| KU-Band Radio TX/RX | 2.5 | 50000 | | |
| On-Board GPS | 0.01 | 50 | | |
| Radio RX PPM/PWM | 0.02 | 1000 | | |
| Electrical Subsystem | 143.15 | 175355090 | | |
| Actuator Power Subsystem | 8 | 300000 | | |
| Power Distribution | 10 | 1000 | | |
| Power Monitor | 0 | 0 | | |
| Power Source | 20 | 1000 | | |
| Propulsion Power Subsystem (Electric) | 100 | 175000000 | | |
| Vehicle Power Subsystem | 5 | 50000 | | |
| apRegulator | 0.05 | 20 | | |
| commRegulator | 0.05 | 1070 | | |
| plRegulator | 0.05 | 2000 | | |
| Environment | 0 | 0 🗸 | | ▶1 |

Using the Analysis model, we can create an analysis matrix that can be used to perform trade studies. These trade studies will be used to guide us in optimizing the architecture.

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| Analysis Viewer (Technical Preview) | 0 | | | | - 13 | × |
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| INSTANCE MODEL ANALYSIS UPDATE | | | _ | | | - T |
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| UAS_reference_architecture_electric_budgetKollup DVI OS Neulastica | 392.33 | 200614300 | Nodelectance: Pronulsion 6 | Power Subsystem | (Electric) | |
| Orego Astronom | 0 | 0 | requester and a repulsion r | ower oubsystem | (Electric) | _ |
| Ground Station | 0 | 0 | Property | Units Value | Ec | lit |
| Communication Dox Ground Station CDS interface | 0 | 0 | SubsystemBudget | | | |
| USB Sarial Convertor | 0 | 0 | Mass | kg | 100 | 3 |
| Wiraless Communication Subsystem | 0 | 0 | Power | mW | 200.000.000 | 2 |
| GPS receiver | 0 | 0 | | | | |
| Guidance and Navigation Computer | 0 | 0 | | | | |
| Flight Commands | 0 | 0 | | | | |
| | 0 | 0 | | | | |
| | 392 33 | 200614300 | | | | |
| Communications Subsystem | 263 | 58050 | | | | |
| Automatic Dependent Surveillance-Broadcast | 0.05 | 5000 | | | | |
| C-Band Radio Modem | 0.05 | 2000 | | | | |
| KU-Band Radio TX/RX | 2.5 | 50000 | | | | |
| On-Board GPS | 0.01 | 50 | | | | |
| Radio RX PPM/PWM | 0.02 | 1000 | | | | |
| Electrical Subsystem | 143.15 | 200355090 | | | | |
| Actuator Power Subsystem | 8 | 300000 | | | | |
| Power Distribution | 10 | 1000 | | | | |
| Power Monitor | 0 | 0 | | | | |
| Power Source | 20 | 1000 | | | | |
| Propulsion Power Subsystem (Electric) | 100 | 20000000 | | | | |
| Vehicle Power Subsystem | 5 | 50000 | | | | |
| apRegulator | 0.05 | 20 | | | | |
| commRegulator | 0.05 | 1070 | | | | |
| pIRegulator | 0.05 | 2000 | | | | |
| Environment | 0 | 0 🕳 | | | | ÞI |

We can change the values of properties to run what-if calculations to do trade-offs of the system



As a next step, running a simulation would allow us to size the battery that will act as the power source for the new electric motor

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Simulink Requirements

Digital Thread from Requirements to Architecture and Design

Author requirements or view from external source



Link requirements, architectures, design, code and test



Identify gaps in architecture or design Implemented Verified

Implemented: 16, Justified: 0, None: 2, Total: 18

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Identify impact of requirement changes

- Implemented by:
 - counter



System Composer



Intuitively design system and software architectures



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Perform trade studies based on data driven analysis to optimize architectures

Add custom data



| Architecture | Info | |
|--------------|-------|------------|
| NAME | | VALUE |
| ✓ Main | | |
| Name | | Power Unit |
| Stereotype | | Add |
| ✓ OnboardEle | ement | Select |
| Mass | | 0.217 kg |
| Power | | 0 mW |
| RFHarnessl | ength | 0 cm |

Create analysis model

| SmallUAV | |
|------------------------------------|----------|
| Instances | Mass(kg) |
| SmallUAV | 0 |
| Airframe | 0 |
| Fuselage | 1.7 |
| LandingGear | 1.65 |
| Tail and Boom | 2.7 |
| Wings | 3.2 |
| Flight Support Components | 0 |
| ADSB Module | 0 |
| ABDSB Antenna | 0.058 |
| ADSB Board | 0.098 |
| GPS Module | 0 |
| GPS | 0.128 |
| GP. | 0.27 |
| Pitot Tube Mo | 0.075 |
| FlightComputer | 0 |
| Main Board | 0.145 |
| Protective Case | 0 195 |

Calculate mass roll-up data

| SmallUAV | |
|------------------------------------|----------|
| nstances | Mass(kg) |
| SmallUAV | 15.932 |
| Airframe | 9.25 |
| Fuselage | 1.7 |
| LandingGear | 1.65 |
| Tail and Boom | 2.7 |
| Wings | 3.2 |
| Flight Support Components | 0.629 |
| ADSB Module | 0.156 |
| ABDSB Antenna | 0.058 |
| ADSB Board | 0.098 |
| GPS Module | 0.398 |
| GPS Antenna | 0.128 |
| GPS Board | 0.27 |
| Pitot Tube Module | 0.075 |
| FlightComputer | 0.388 |
| Main Board | 0.145 |
| Protective Case | 0.195 |

System Composer

Tackle Architecture complexity with spotlight views

Composition





Spotlight

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System and software architectures connected to implementations in Simulink

Generate Simulink models from architecture components

Link Simulink models to architecture components



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