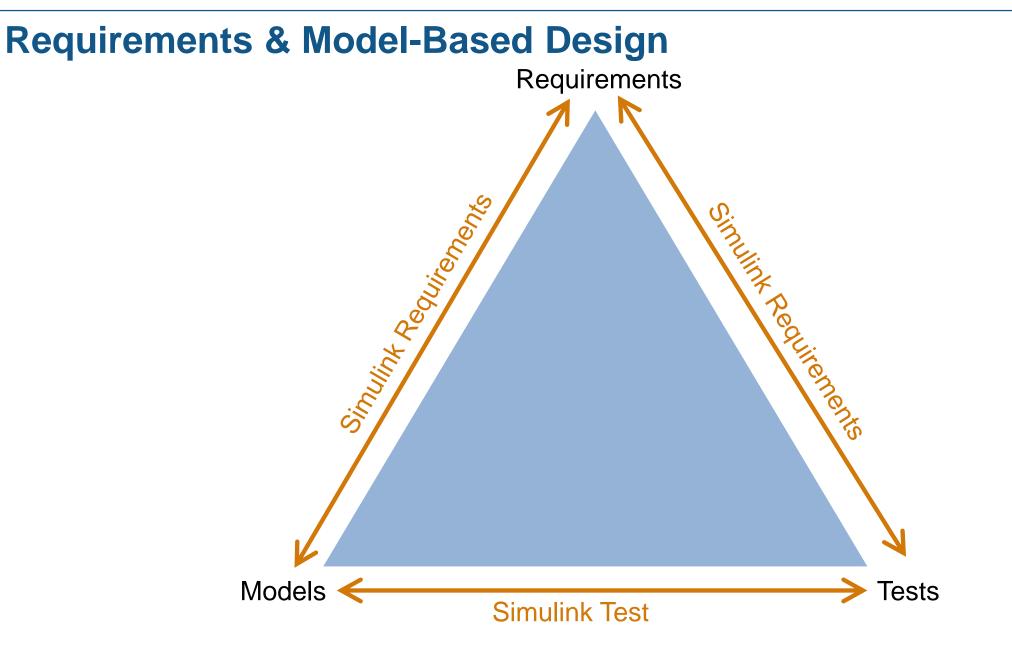
# MATLAB EXPO 2019

Simplifying Requirements Based Verification with Model-Based Design

**Fraser Macmillen** 









**Verification & Validation Products** 

# 86 slides of new features in 2019...

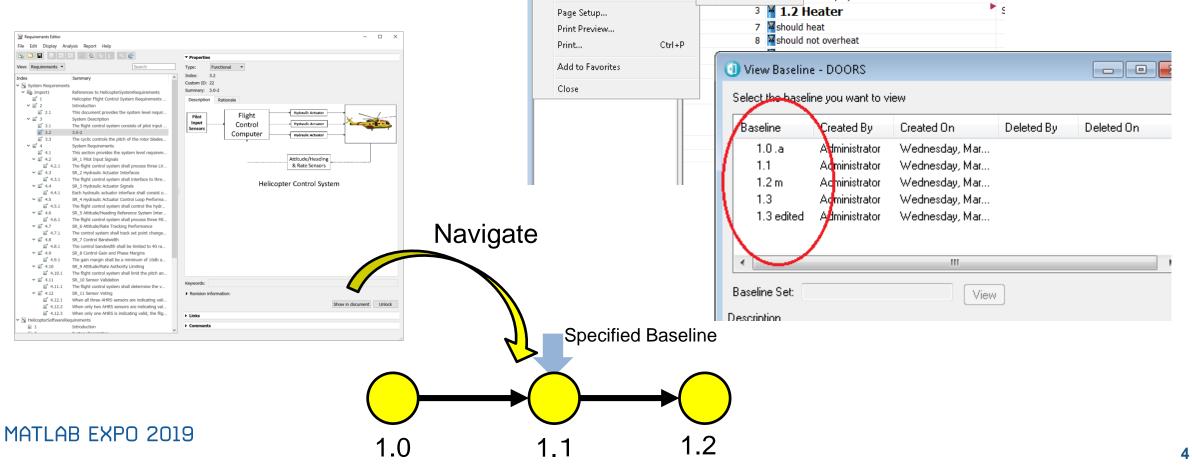
# R2019a R2019b

MathWorks<sup>®</sup>

**R**2019b

# **DOORS 9 Baseline Navigation**

### Simulink Requirements is aware of baseline in DOORS 9



Save

Baseline

Export

Import

Module Properties...

📰 'househeat\_example' current 1.3 (edited) in /Two Small Modules (Formal module) - DOORS

New...

View...

Copy...

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# **Unlock and Edit Referenced Requirements**

# Augment referenced requirements with additional details

- Add additional custom attributes without modifying imported content
  - Update restores data from external source and preserves additional content
- Export to ReqIF for roundtrip workflow of local edits with third party tool

See: <u>Roundtrip Workflows with ReqIF Files</u>

Image: Search   Type: Functional Index: 2.2		
iew: Requirement ▼ Search iew: Requirement ▼ Search idex Grs_req ▼ Import1 I 1 ▼ 2 > 2 2.1 2.2 2.3 > 3 > 4 Grs_req_func_spec Keywords: > Revision information: Show in document Unlock Viruse control mode indicator Two indicator lights are installed onto the instrument panel. CRUISE: Turned on when the cruise control system is activated. Keywords: > Revision information: Show in document Unlock	Requirements Editor	- 🗆 X
iew: Requirement ▼ Search iew: Requirement ▼ Search idex idex igers_req Y Import1 Index: 2.2 Custom ID: Cruise control mode indicator Summary: Cruise control mode indicator Description Rationale Cruise control mode indicator Description Rationale Cruise control mode indicator Two indicator lights are installed onto the instrument panel. CRUISE: Turned on when the cruise control system is activated. Keywords: Revision information: Show in document Unlock	ile Edit Display Analysis Report Help	
index       Index:       2.2         Custom ID:       Cruise control mode indicator         Summary:       Cruise control mode indicator         Summary:       Cruise control mode indicator         Description       Rationale         Cruise       Control mode indicator         Description       Rationale         Cruise control mode indicator       Index:         Description       Rationale         Cruise control mode indicator       Index:         Description       Rationale         CRUISE:       Turned on when the cruise control system is activated.         Keywords:       •         • Revision information:       Show in document         Unlock       •		▼ Properties ^
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Keywords: • Revision information: Show in document Unlock • Links No links	<pre>     crs_req</pre>	Custom ID: Cruise control mode indicator Summary: Cruise control mode indicator Description Rationale Cruise control mode indicator Two indicator lights are installed onto the instrument panel. CRUISE: Turned on when the cruise control
<ul> <li>Revision information:</li> <li>Show in document Unlock</li> <li>Links</li> <li>No links</li> </ul>		v
Show in document Unlock   Links No links		Keywords:
No links		
		▼ Links

### **Test Specification Report**



MathWorks<sup>®</sup>

- Generate report in PDF, ZIP or DOCX format consisting of test specifications (models, inputs, baseline, assessments etc)
- Customization through templates for report formatting
- Custom sections to add extra content that are user specific

#### **Table of Contents**

1.	ExampleTestFile
	1.1. Example TestSuite
	1.1.1. Example BaselineTest
	1.1.2. Example EquivalenceTest
	1.1.3. Example SimulationTest

#### **Baseline** Criteria

Signal Name	Abs Tol	Rel Tol	Leading Tol	Lagging Tol
baseCap.mat	12	0.25	0	3
Input Conversion Subsystem:2	12	0.25	0	3
vehiclespeed	12	0.25	0	3

Create a Test Specification Report ? ×									
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Title:	Test Specification Report								
Author:	Author name								
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Customization Ten	nplates								
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Test Case Reporter         Select TestCaseReporter Template (optional)									
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But what are my requirements for this talk?

1. I shall expand awareness and capability in the use of our tools that support verification of requirements

2. I shall not repeat content from previous EXPOs

3. I shall deliver content appropriate to a masterclass

4. I shall make it interesting!



# Simplifying Requirements Based Verification with Model-Based Design

Minimising

the less we have to deal with the simpler it is

Insight

insight leads to understanding and makes our work simpler

Automation

to speed up the process and avoid errors makes our work simpler



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Minimising – being at the right level

Requirements at the right level

Verification at the right level

Tracing to the right level



# Minimising – handling multiple levels

Example

Control system requirements specify the need for filtering of certain signals

The design uses a reusable custom filter to implement the requirement

There are lower level requirements for the filter behaviour itself

Let's start by creating some links to an instance of the custom filter in the design

#### A Project - WindTurbine

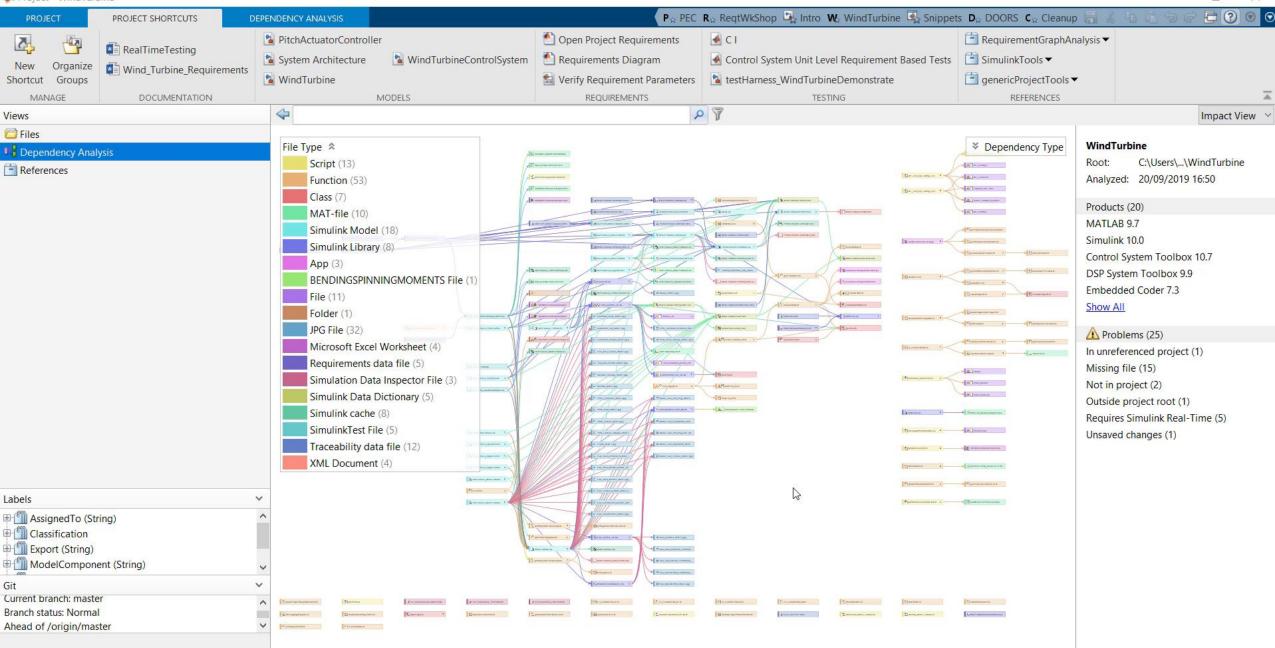
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# Minimising – handling multiple levels

When linking a requirement to a Simulink block...

- Can link from either end
- The Simulink block is always the source
- The requirement is always the destination
- The link is saved in the file associated with the source:
  - i.e. [modelFileName].slmx



### Minimising – handling multiple levels

Linking Between Requirements At Different Levels

The prime purpose of traceability is to infer what is the origin/parent/source of an object.

- i.e. a link is from child to parent, from source to destination
- i.e. the source is the lower level requirement the destination is the upper level requirement

The link is saved in the file associated with the source

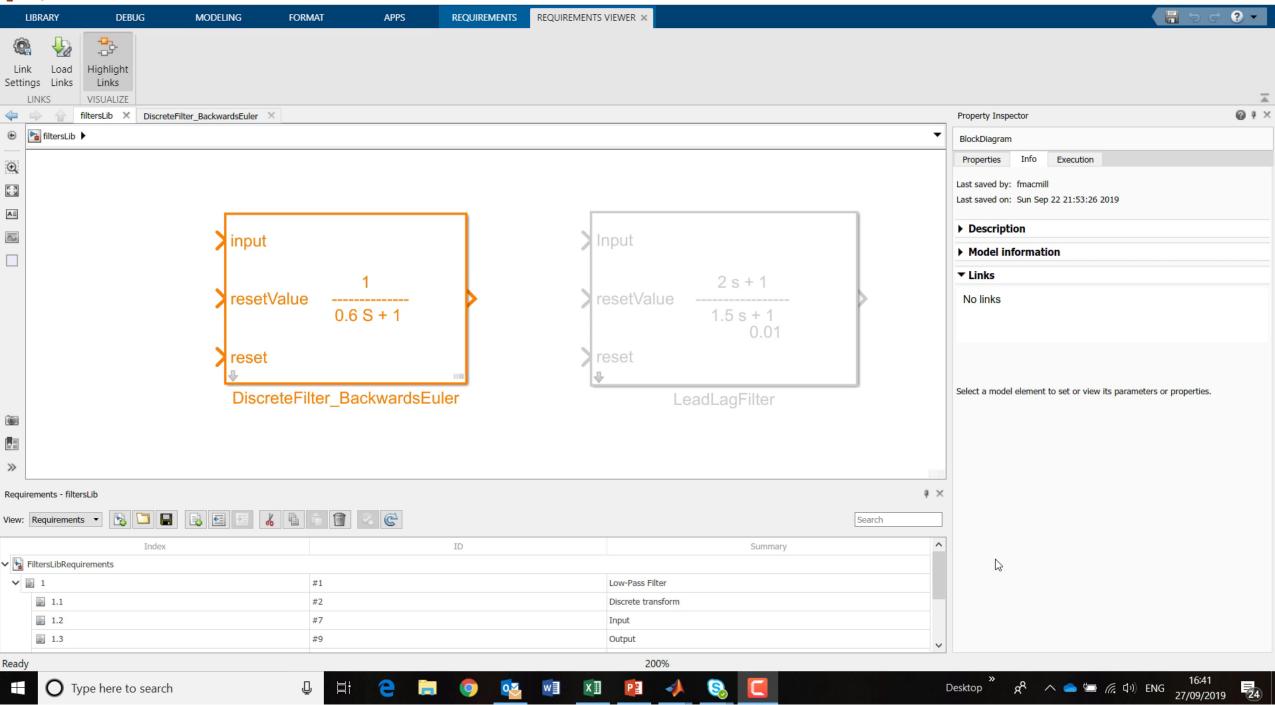
So: click on source (lower-level requirement) first and create link from the parent requirement...

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VindTurbineControllerRequirements						Summary: Low-Pass Filter
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	User Interface		Heading			
	Justifications					
2.1						
> 📓 WindTurbineControllerDerivedReq					:	
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# **Minimising - Links**

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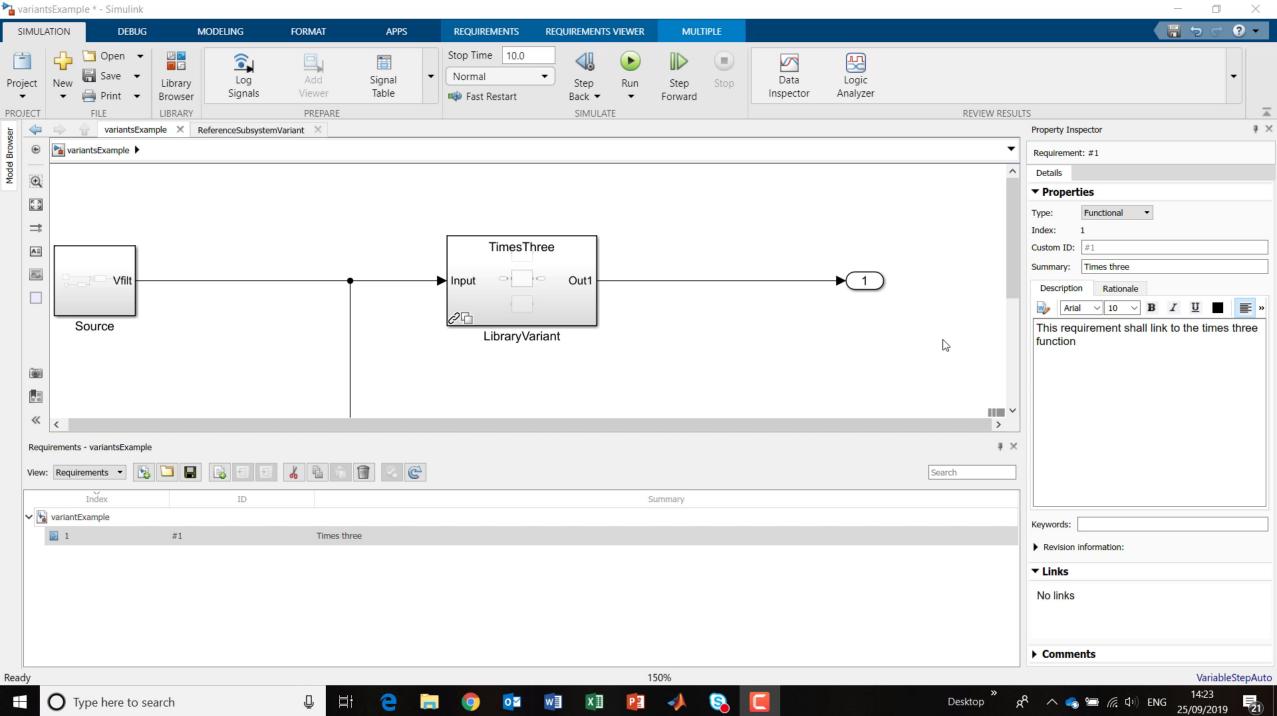
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# **Minimising**

Using re-usable components can help

- minimise requirements
- minimise requirement links





# Simplifying Requirements Based Verification with Model-Based Design

Minimising

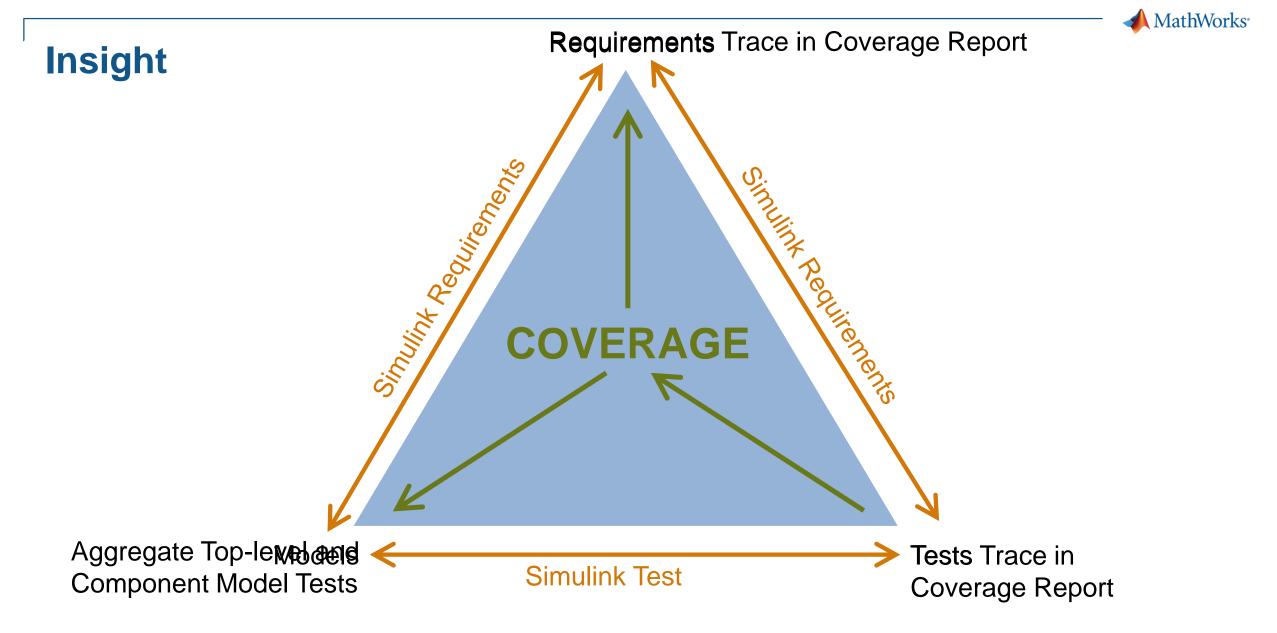
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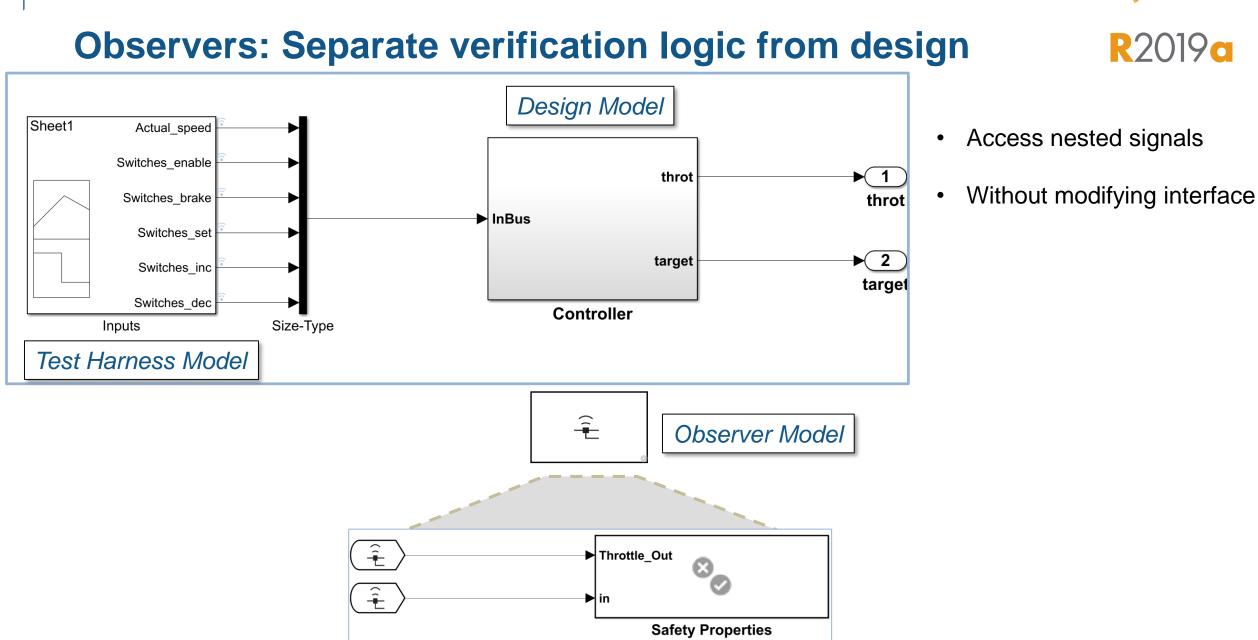


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Rotor speed dependency	> REQUIREMENTS	2
Component Tests	> CALLBACKS	?
FreqResponse	▼ COVERAGE SETTINGS*	?
TimeResponse	← COVERAGE TO COLLECT	
	Record coverage for system under test	
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	Coverage filter filename: [Model Settings]	
	COVERAGE METRICS	
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# **Insight - Observers**



#### MATLAB EXPO 2019

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### **Insight – Logical & Temporal Assessments**

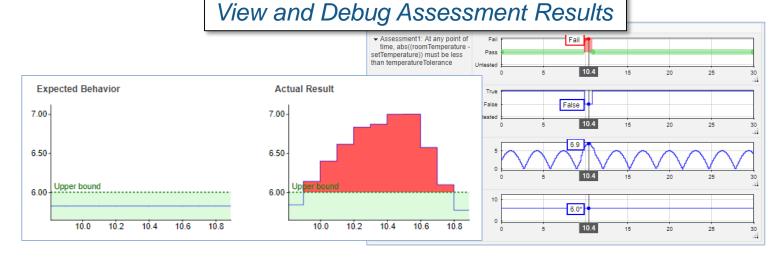
### Translate textual requirements into unambiguous Assessments

- Compose assessments using form based editor
- View assessments as English-like sentence
- Review and debug temporal assessment results
- Link to requirements

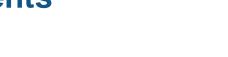
MATLAB EXPO 2019

#### Temporal Assessment Editor

ASSESSMENT	REQUIREMENTS	+	VISUAL REPRESENTATION
✓ At any point of time	Speed Tolerance	*	Ĩ
bounds-check-pattern: always inside bounds			Upper bound
signal: signal lower-bound: lowerBound lower-bound-type: greater than upper-bound: upperBound upper-bound-type: less than			Lower bound
At any point of time, if driverInput > driverInputAmplitude * stepRatio becomes true then, with no delay, abs(signal - signalRef) < overshootTolerance must stay true for at least tau seconds	Prevent Overshoot		SYMBOLS  The driverInput  driverInputAmplitude  Statio



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📓 Requirements Editor

File Edit Display Analysis Report Help

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~ 🖣	WindTurbineController									
~	Import1	References to WindTurbineControllerReq			Container					1
	✓ ≝ <sup>1</sup> 1	Front Matter		$\square$	Heading			No		2
	E 1.1	WindTurbine Controller Functional Requi		$\square$	Functional			No		3
,	✓ ≝ <sup>*</sup> 2	Controllers			Heading			No		4
	✓ ≝ <sup>2</sup> 2.1	Signal Conditioning		$\square$	Heading			No		5
	2.1.1	Wind speed filtering attenuation shall be		$\square$	Functional			No		6
	2.1.2	Wind speed filtering attenuation shall be	$\square$	$\square$	Functional			No		7
	2.1.3	Wind direction filtering attenuation shall		$\square$	Functional			No		8
	2.1.4	Wind direction filtering attenuation shall	$\square$	$\square$	Functional			No		9
	✓ ≝ 2.2	Supervisory Control			Heading			No		10
	2.2.1	Normal Operation		$\square$	Functional			No		11
	2.2.2	In normal "auto" operation the turbine s		$\square$	Functional			No		242
	2.2.3	The turbine shall enter the Standby mod		$\square$	Functional			No		243
	2.2.4	The turbine shall enter Brake mode if A		$\square$	Functional			No		12
	2.2.5	The turbine shall enter the Generating			Functional			No		13
	2.2.6	Abnormal Conditions		$\square$	Functional			No		14
	2.2.7	The turbine shall stop if wind speed exc	$\square$	$\square$	Functional			SafetyRelated		15
	✓ ≝ 2.3	Pitch Control System			Container			No		16
	2.3.1	when in power generation mode the rot		$\square$	Functional			No	by system level simulation	17
	2.3.2	Under inertial load only (zero aerodyna			Functional			No	by sub-system simulation	18
	2.3.3	Under inertial load only (zero aerodyna			Functional			No	by sub-system simulation	19
	2.3.4	Open-loop gain margin shall be greater t		$\square$	Functional			No	by sub-system simulation	166
	2.3.5	Open-loop phase margin shall be greate		$\square$	Functional			No	by sub-system simulation	167
	✓ ≝ <sup>*</sup> 2.4	Yaw Control System			Heading			No		20
	2.4.1	The yaw rate magnitude shall be less th			Functional			No	by system simulation	21
	E 2.4.2	The commanded yaw torque per actuat			Functional			No	by system simulation	55
	✓ 🖺 3	User Interface		$\square$	Heading			No		22
	<b>3.1</b>	Operator inputs to system		$\square$	Functional			No		23
	3.2	The operator panel shall provide a switc		$\square$	Functional			No		24
	E 3.3	Information displayed to operator		$\bigcirc$	Functional			No		25
>	2	Justifications								26
> 😼	WindTurbineController			$\square$						
> 😼	FiltersLibRequirements			$\square$						

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#### Properties Type: Functional -2.2.5 Index: Custom ID: SRD-CONTROL-84 Summary: The turbine shall enter the Generating mode [GeneratorTrip FALSE] ... Description Rationale The turbine shall enter the Generating mode [GeneratorTrip FALSE] if the generator speed is greater than 1200 rpm and less than 2200 rpm Keywords: No Revision information: Show in document Unlock Custom Attributes Links Implemented by: ℅ [GeneratorSpeed>... GeneratorSpeedCutin] WindSpeed<... WindSpeedCutInLower... ||WindSpeed>... WindSpeedCutOut... ||GeneratorSpeed>... Verified by: GeneratingMode ? < > Comments 2 Add Comment

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# **Insight - What if verification is by analysis, not simulation?**

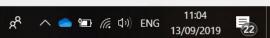
📣 Project - WindTurbine

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# **Simplification – Automation**

Examples:

- Checking parameter values against requirements

- Continuous Integration

# **API**

#### - <del>\\</del> 😓 🔶 ቀ Simulink Requirements — Functions 💥 🕂 Documentation All Examples Functions Blocks ■ CONTENTS Close Simulink Requirements — Functions « Documentation Home « Functions Category Simulink Report Generator . **Requirements Definition** Simulink Requirements

slreq.ReqSet	Work with Requirements sets
slreq.Reference	Work with external requirement proxy objects
slreq.Requirement	Work with Requirement objects
slreq.clear	Clear requirements and links from memory
<pre>slreq.convertAnnotation</pre>	Convert annotations to requirement objects
slreq.editor	Open Requirements Editor
slreq.find	Find requirement, reference, and link set artifacts
slreq.import	Import requirements from external documents
slreq.load	Load requirements/link set
slreq.new	Create requirements set
slreq.open	Open requirements set
<pre>slreq.resetViewSettings</pre>	Reset saved view settings
<pre>slreq.importViewSettings</pre>	Import view settings
<pre>slreq.exportViewSettings</pre>	Export view settings

#### **Requirements Traceability**

<pre>slreq.LinkSet</pre>	Work with link sets
slreq.Link	Work with link objects
slreq.clear	Clear requirements and links from memory
<pre>slreq.createLink</pre>	Create traceable links
slreq.find	Find requirement, reference, and link set artifacts
slreq.load	Load requirements/link set
<pre>slreq.cmConfigureVersion</pre>	Set version of linked requirements documents
<pre>slreq.cmGetVersion</pre>	Get configured version of linked requirements documents

Requirements Definition 14

Requirements Traceability

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Requirements-based Testing

Requirements Comparison and 3 Change Tracking

Requirements Management 16 Interface

Simulink Test

Stateflow

Statistics and Machine Learning Toolbox

System Composer

System Identification Toolbox

Text Analytics Toolbox



# **Simplification – Automation**

# Programmatic Interface:

- Find and interrogate requirements and links
- Use to create custom artefacts or utilities



#### 📓 Requirements Editor

File Edit Display Analysis Report Help

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View: Requirements -								Search		
Index	Summary	Implemented	Verified	Туре	ParameterValue	ParameterUnits	Keywords	Verification	SID	^
WindTurbineSystemRequirements										
1	General Information			Container					1	
✓ ■ 2	Operating Conditions		$\square$	Container					7	
2.1	Cut-in wind speed			Functional	3.0	m/s	Parameter		23	
2.2	Rated wind speed		$\square$	Functiona	12.5	m/s	Parameter		24	
2.3	Cut-out wind speed		$\square$	Functional	25	m/s	Parameter		25	
2.4	Maximum design speed		$\square$	Functional	59.5	m/s	Parameter		26	
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E 2.1.2	Wind speed filtering attenuation shall be		$\square$	Functional			No		7	
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E 2.1.4	Wind direction filtering attenuation shall		$\square$	Functional			No		9	
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∎ 2.2.5	The turbine shall enter the Generating		$\square$	Functional			No		13	
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✓ 🖺 2.3	Pitch Control System			Heading			No		16	
2.3.1	when in power generation mode the rot		$\square$	Functional			No	by system level simulation	17	
2.3.2	Under inertial load only (zero aerodyna			Functional			No	by sub-system simulation	18	
2.3.3	Under inertial load only (zero aerodyna			Functional			No	by sub-system simulation	19	
2.3.4	Open-loop gain margin shall be greater t		$\square$	Functional			No	by sub-system simulation	166	
2.3.5	Open-loop phase margin shall be greate		$\square$	Functional			No	by sub-system simulation	167	
✓ 🛒 2.4	Yaw Control System			Heading			No		20	
2.4.1	The yaw rate magnitude shall be less th			Functional			No	by system simulation	21	
2.4.2	The commanded yaw torque per actuat			Functional			No	by system simulation	55	
✓ ≝ <sup>*</sup> 3	User Interface		$\square$	Heading			No		22	
3.1	Operator inputs to system		$\square$	Functional			No		23	
3.2	The operator panel shall provide a switc		$\square$	Functional			No		24	
E 3.3	Information displayed to operator		$\square$	Functional			No		25	~
	a								26	

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#### $\sim$ Properties Type: Functional -2.1 Index: Custom ID: #23 Summary: Cut-in wind speed Description Rationale ✓ 10 ✓ B I U ■ Ξ Ξ Ξ ■ - • ▲ Marial The rotor cut-in wind speed shall be [windSpeedCutIn] Keywords: Parameter Revision information: SID: 23 Revision: 31 Created by: fmacmill Created on: 14-Aug-2019 10:53:06 Modified by: fmacmill Modified on: 11-Sep-2019 10:42:51 Custom Attributes ParameterUnits: m/s ParameterValue: 3.0 Links Implemented by: X [WindSpeed>... WindSpeedCutInLower... &&WindSpeed<... WindSpeedCutOut] Design.WindSpeedCutInLower □ ⇒ Related to: SRD-CONTROL-32 The turbine shall enter Brake mode if ANY of the following conditi... C Ш $\sim$

Desktop

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21

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# **Simplification – Automation - Continuous Integration (CI)**

**Continuous Integration** (CI) originated as a software development process in which developers integrate their code into a shared repository on a regular basis.

Each commit into a repository is verified by an automated build and test.

These tests may be a pre-curser to pushing the changes to a main branch

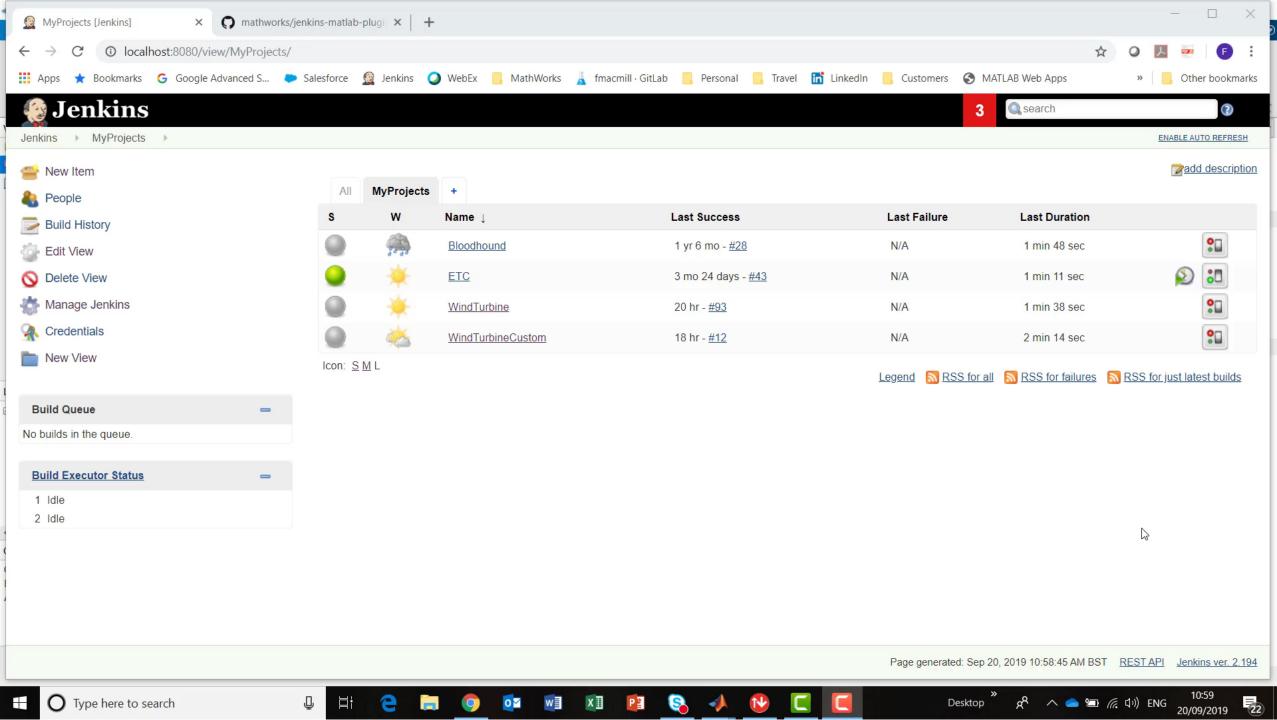
Continuous Integration can be applied to Mode-Based Design workflows



# Simplification – Automation – Continuous Integration (CI)

How quickly can one set up a continuous integration project to run Simulink Tests against requirements?

How many lines of MATLAB code are required?





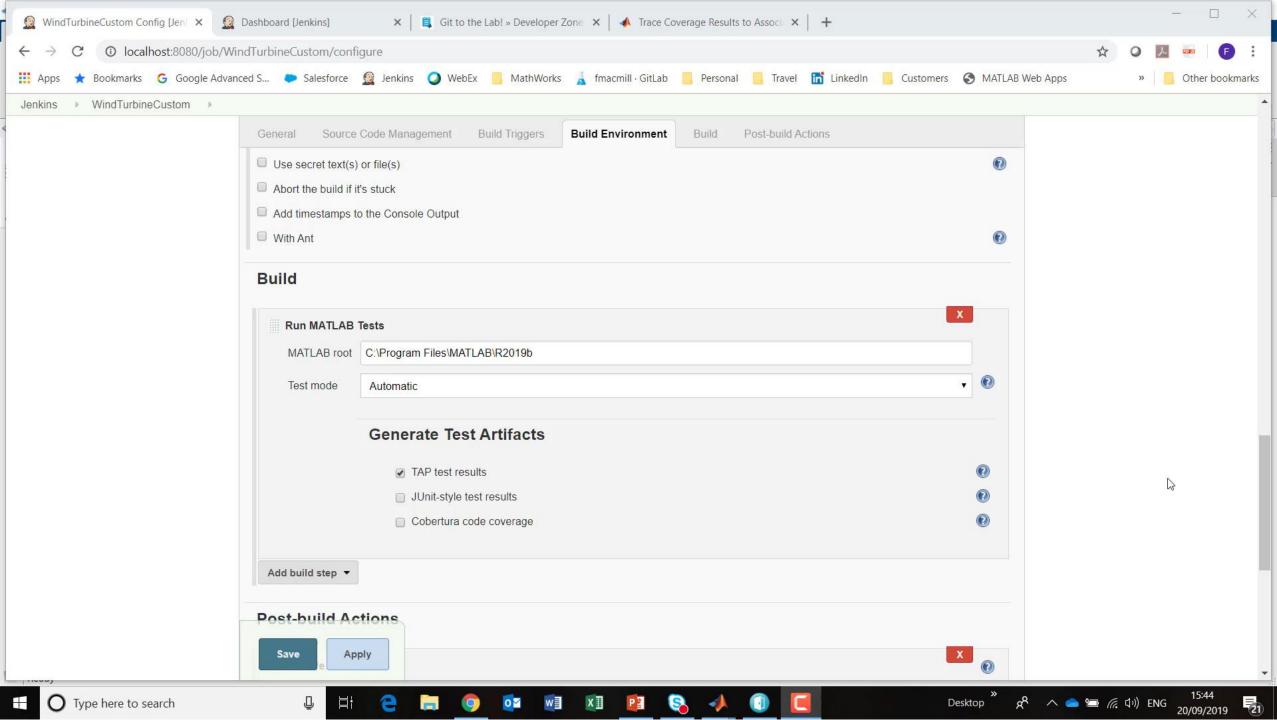
# **Simplification – Automation - Continuous Integration (CI)**

How quickly can one set up a continuous integration project to run Simulink Tests against requirements?

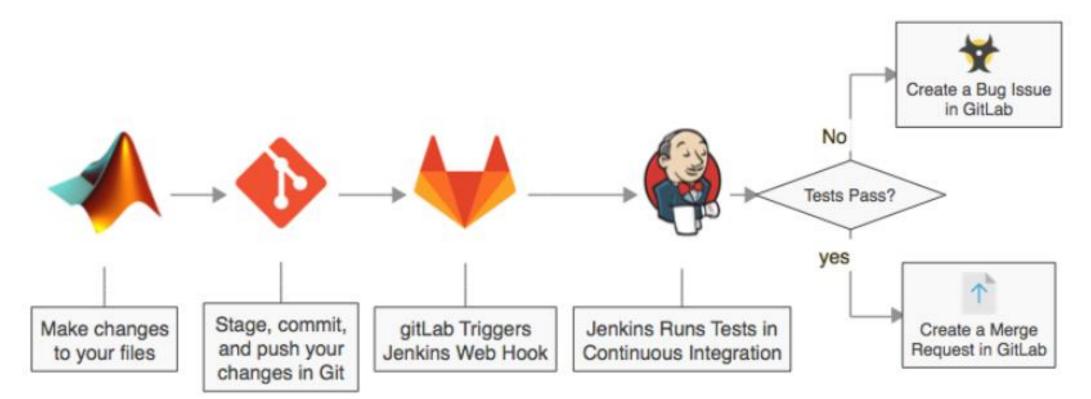
< 5 minutes!

How many lines of MATLAB code are required?

- None!



# Simplification – Automation - Continuous Integration (CI)



https://blogs.mathworks.com/developer/2018/08/23/gitlab-jenkins-workflow/

#### MATLAB EXPO 2019

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# Simplifying Requirements Based Verification with Model-Based Design

Best practices can minimise the work required

Model-Based verification tools continue to develop to provide insight

- more tool integration
- more ways of accessing information you need intuitively & unobtrusively
- more control over granularity

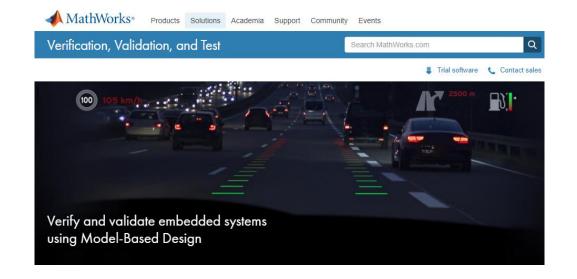
Automation can be quick to set up, and offers significant benefits



### **Learn More**

Key products covered in this presentation:

- Simulink Requirements
- Simulink Test
- Simulink Coverage
- System Composer



Learn more at Verification, Validation and Test Solution Page: <u>mathworks.com/solutions/verification-validation.html</u>