Sviluppo di un sistema di gestione delle batterie con Simulink

Maurizio Dalbard Aldo Caraceto











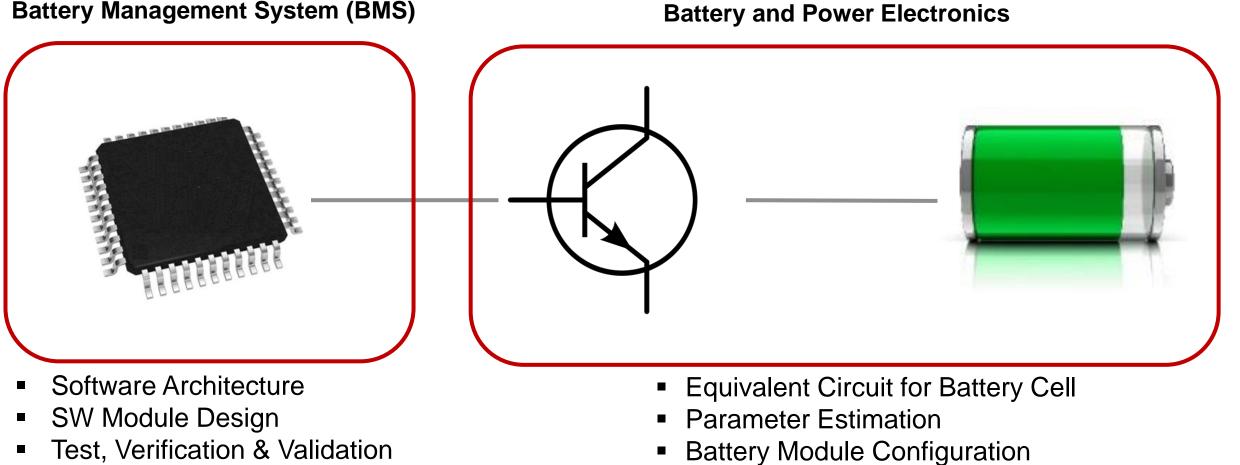








Battery System

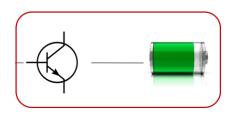


Charging & Balancing

- Test, Verification & Validation
- **BMS Integration Testing**



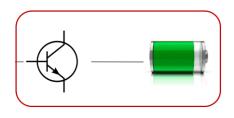
Battery and Power Electronics



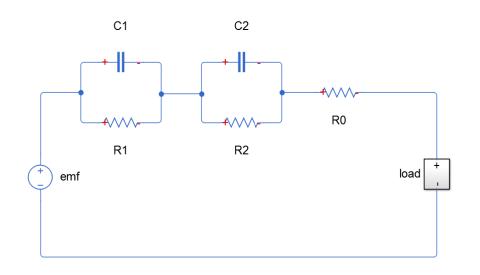
- Equivalent Circuit for Battery Cell
- Parameter Estimation
- Battery Module Configuration
- Charging & Balancing



Battery and Power Electronics

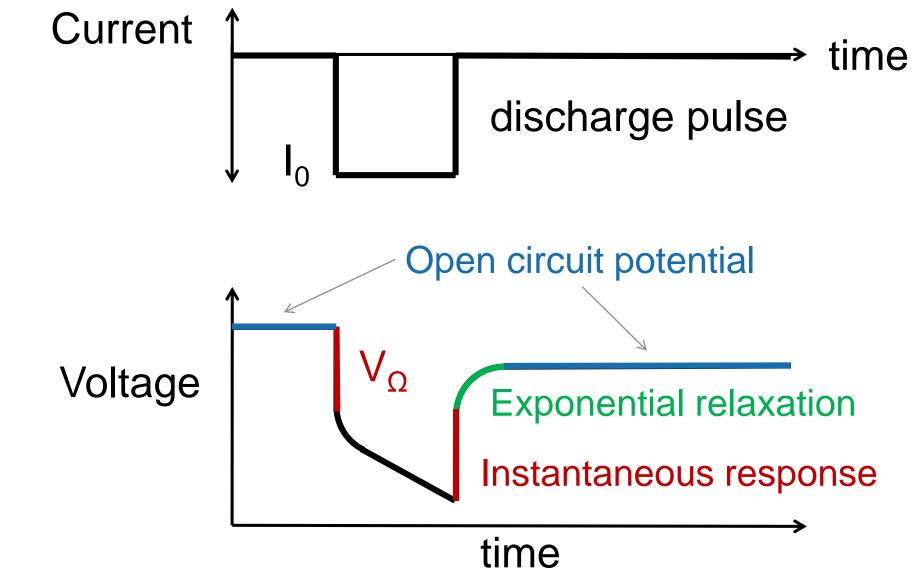


- Equivalent Circuit for Battery Cell
- Parameter Estimation
- Battery Module Configuration
- Charging & Balancing



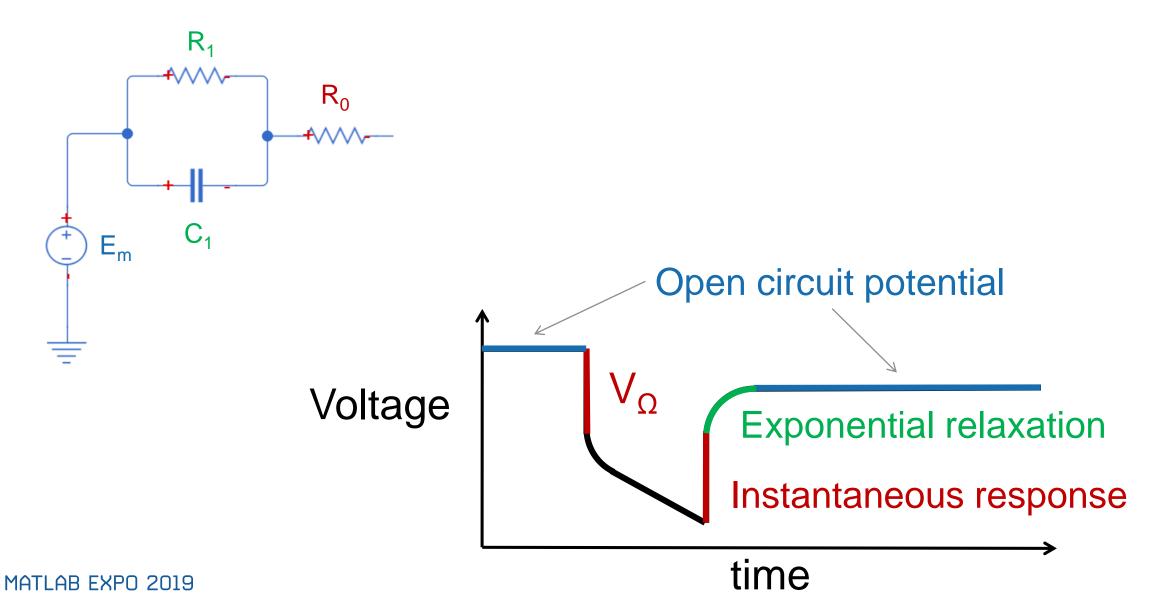


Pulse Discharge



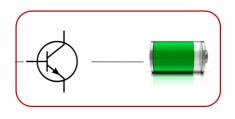


Equivalent Circuit

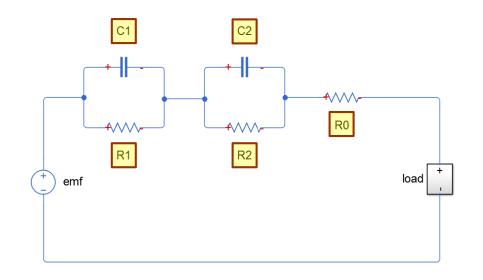




Battery and Power Electronics

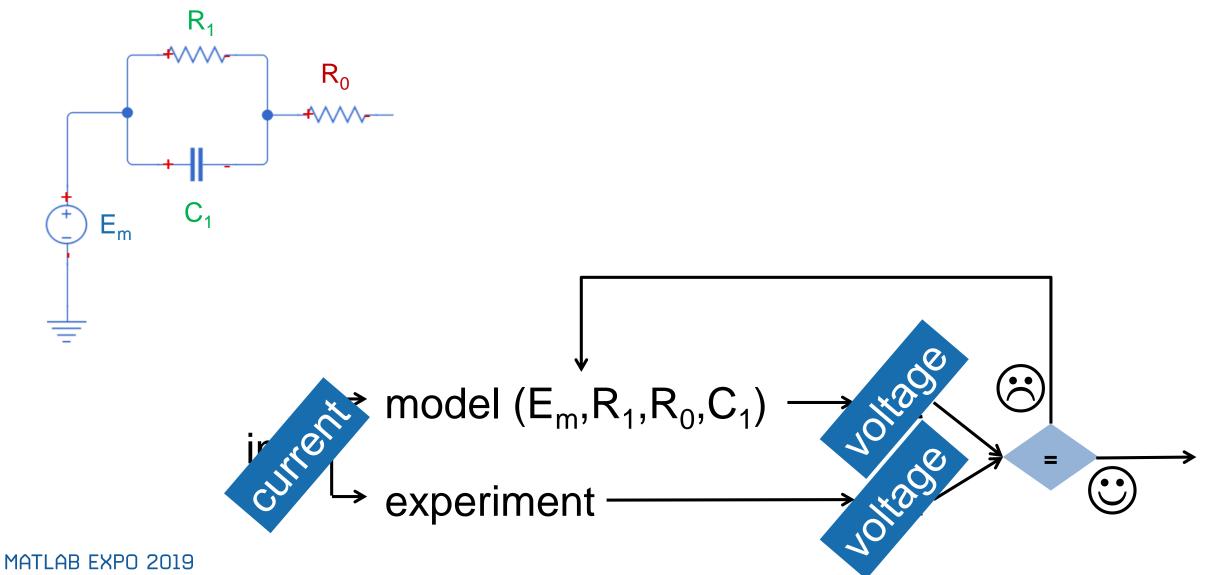


- Equivalent Circuit for Battery Cell
- Parameter Estimation
- Battery Module Configuration
- Charging & Balancing



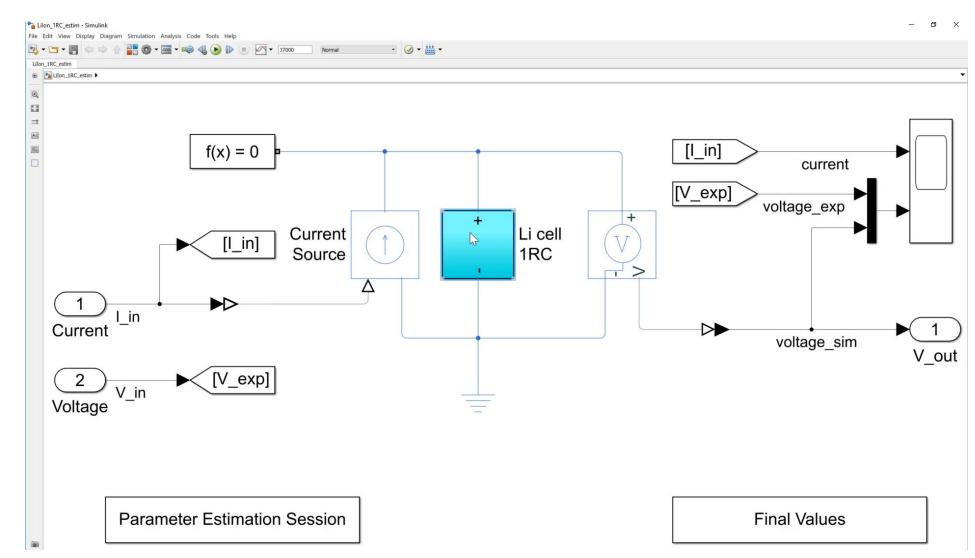


Parameter Estimation



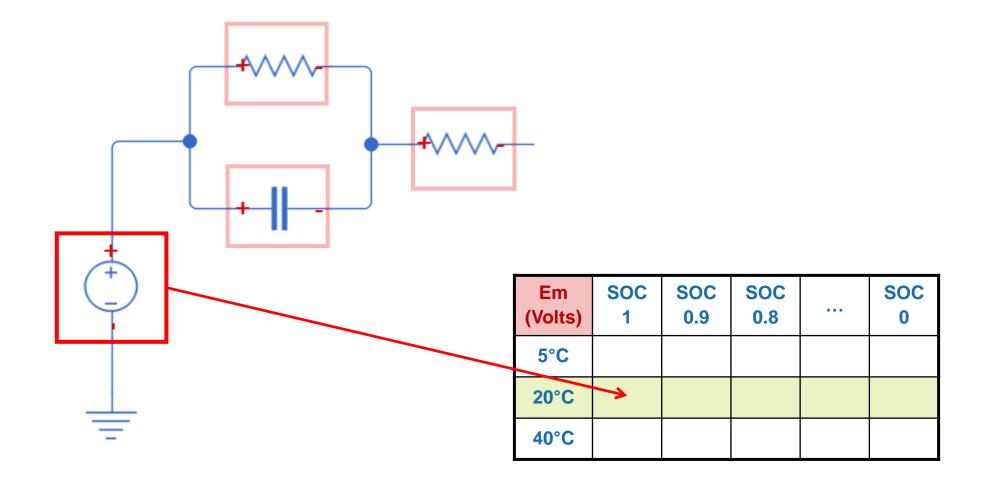


Estimate Parameters



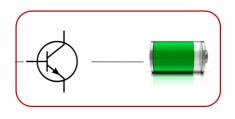


Look-up Tables





Battery and Power Electronics

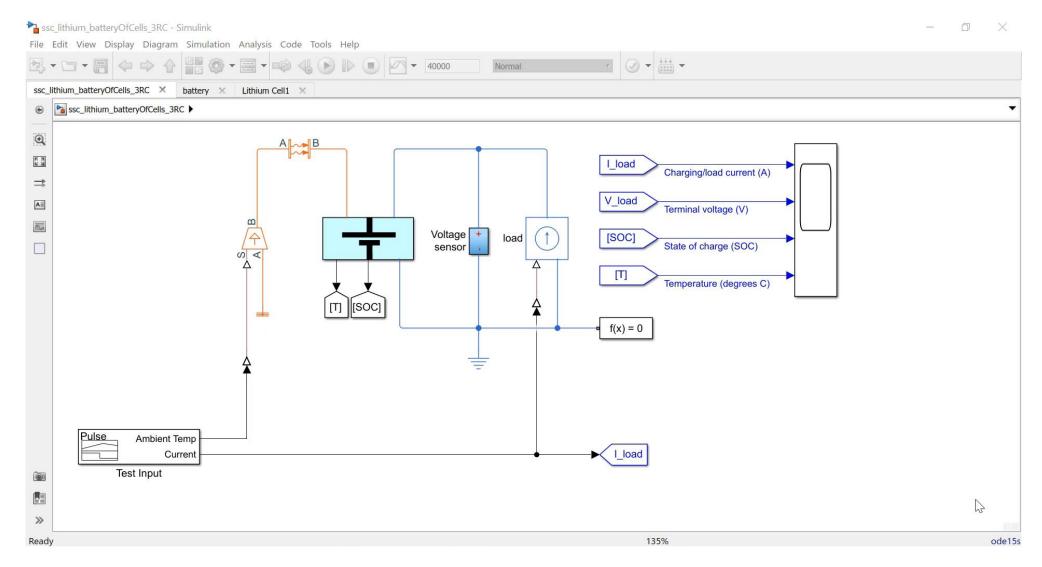


- Equivalent Circuit for Battery Cell
- Parameter Estimation
- Battery Module Configuration
- Charging & Balancing





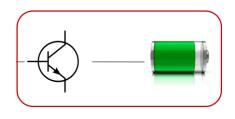
Battery Pack



MATLAL

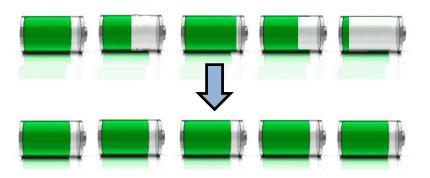


Battery and Power Electronics



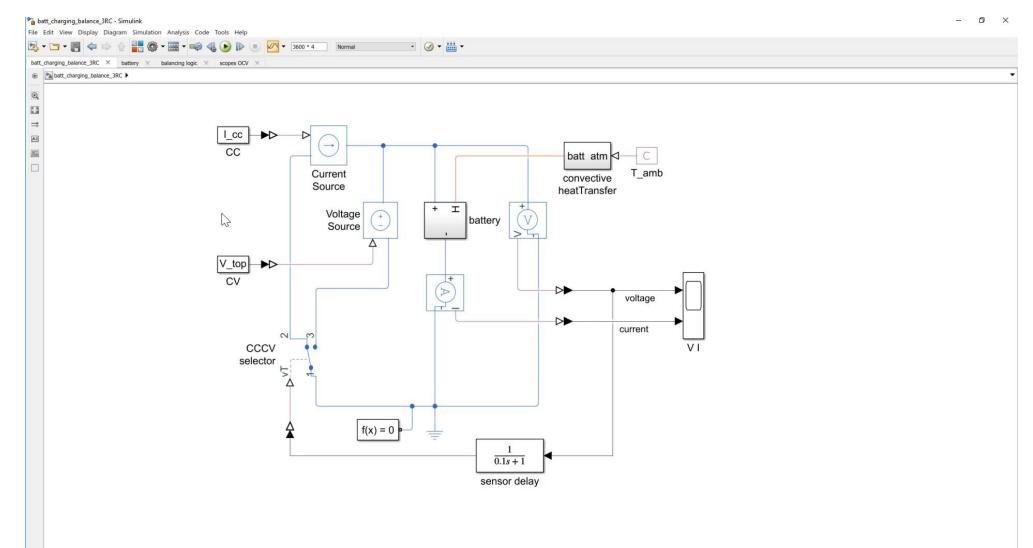
- Equivalent Circuit for Battery Cell
- Parameter Estimation
- Battery Pack Configurations
- Charging & Balancing





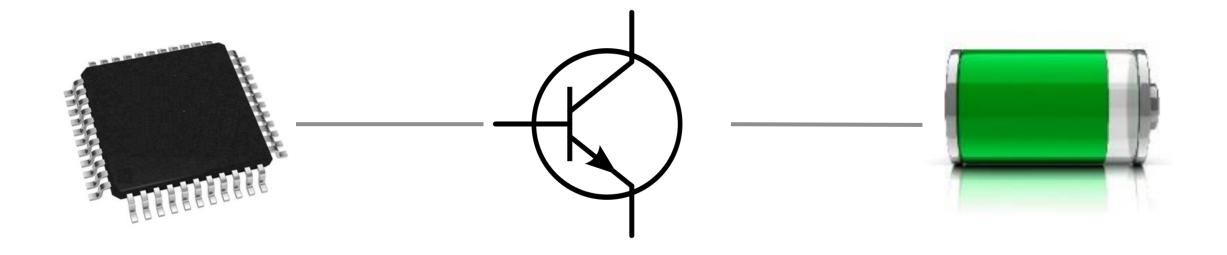


Charging & Balancing



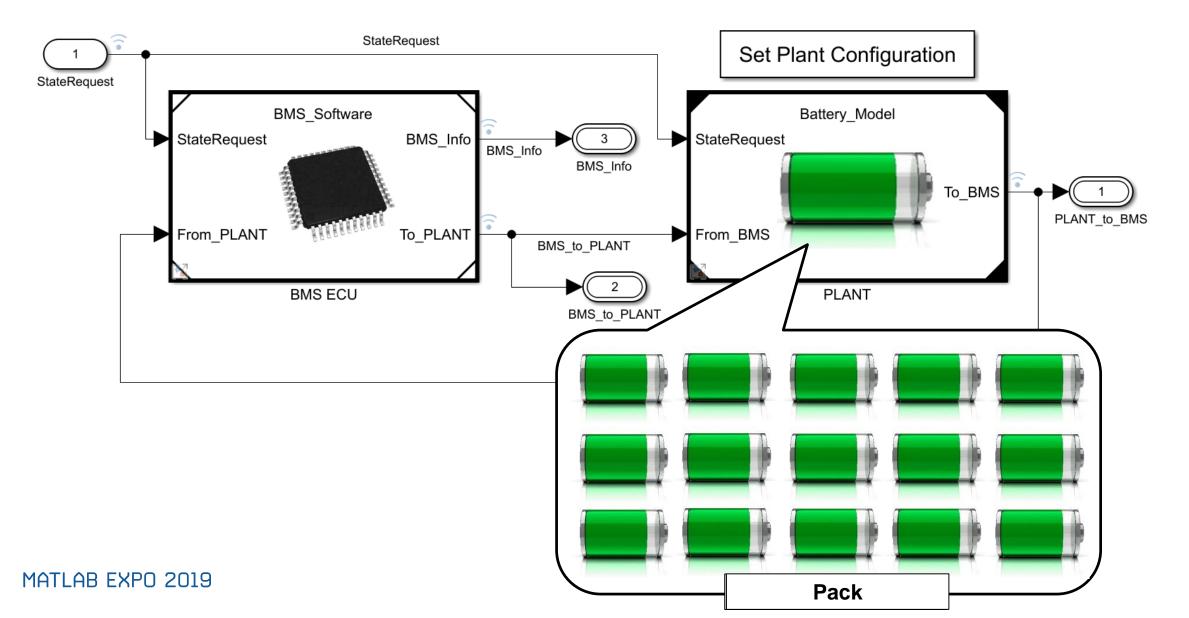


Battery Management System



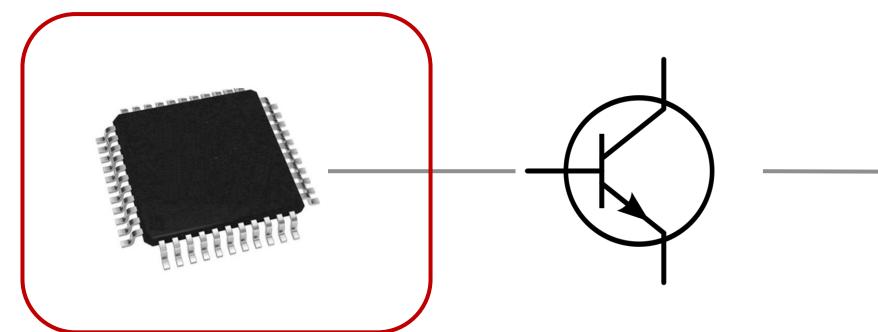


Battery Management System – Professional Simulink Model





Battery Management System



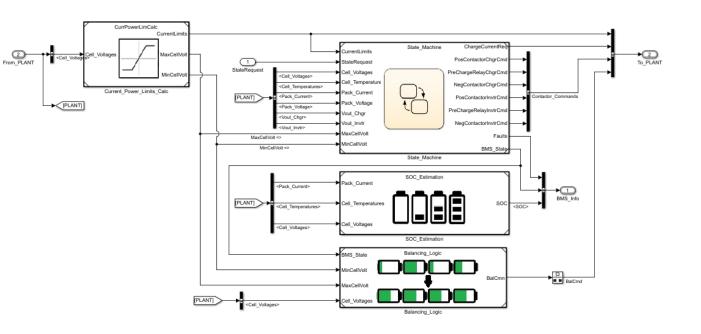


- Software Architecture
- SW Module Design
- Test, Verification & Validation
- BMS Integration Testing



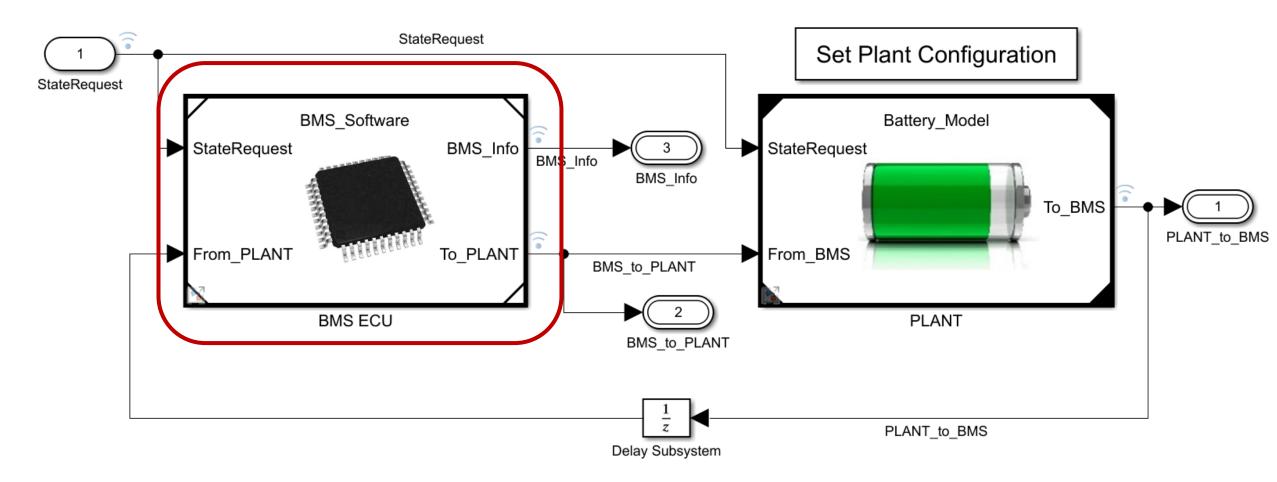


- Software Architecture
- SW Module Design
- Test, Verification & Validation
- BMS Integration Testing

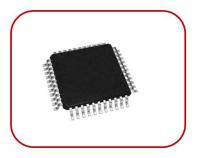




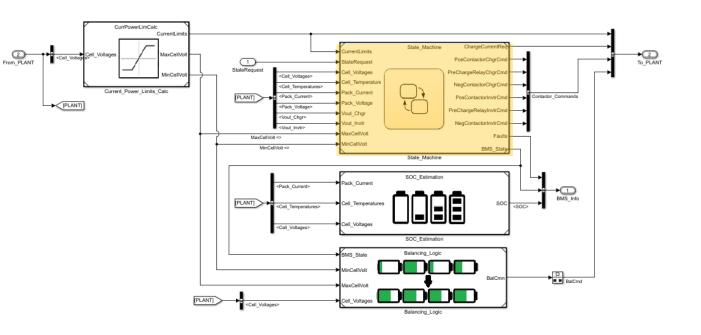
Battery Management System – Professional Simulink Model





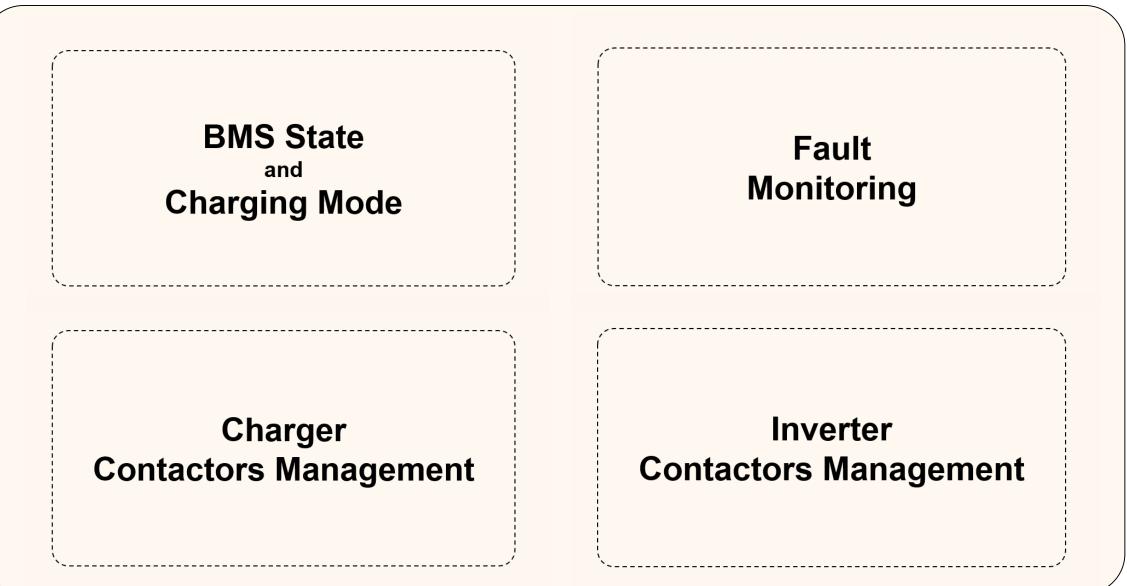


- Software Architecture
- SW Module Design
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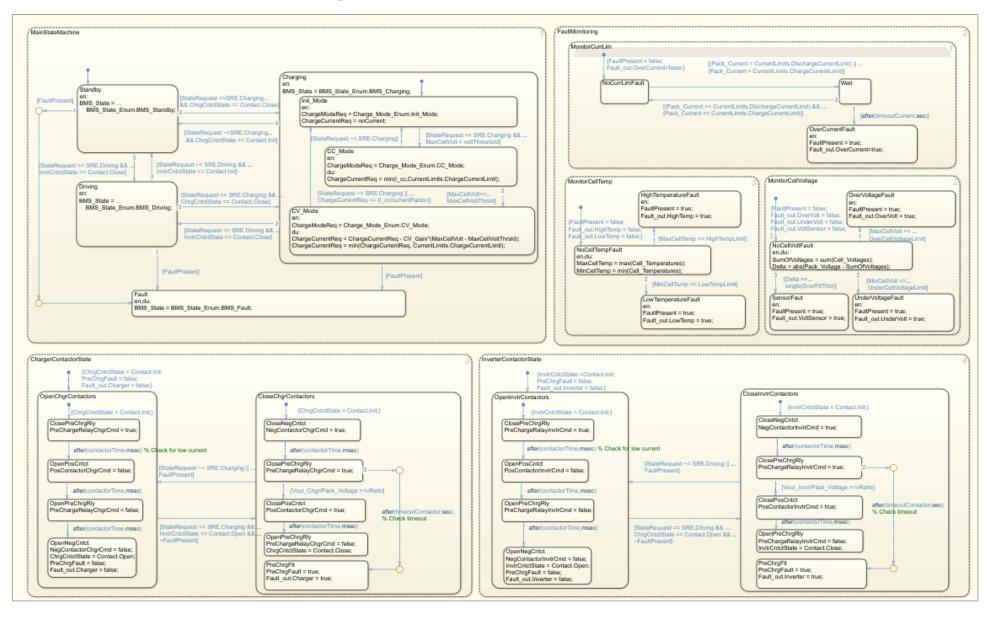


State Machine Logic

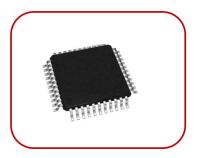




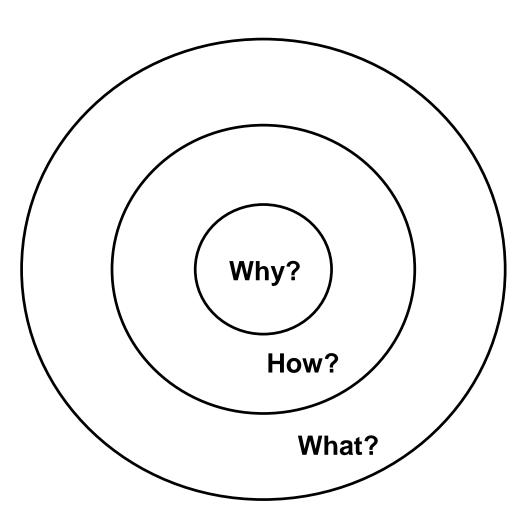
State Machine Logic in Stateflow



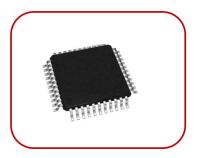




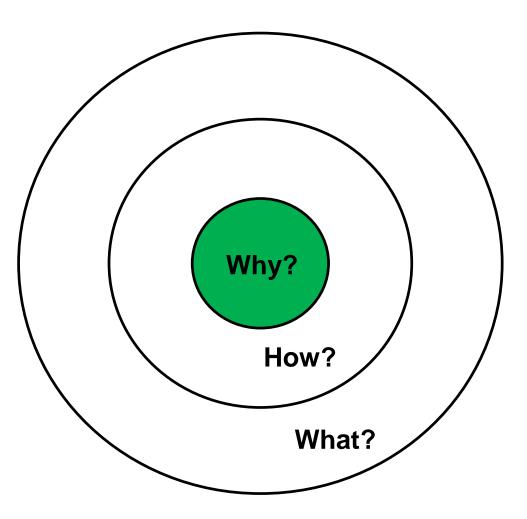
- Software Architecture
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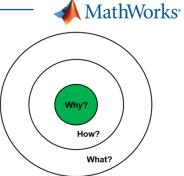


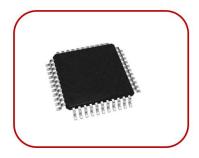




- Software Architecture
- SW Module Design
- Test, Verification & Validation
- BMS Testing







- Software Architecture
- SW Module Design
- Test, Verification & Validation
- BMS Integration Testing





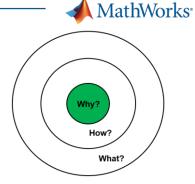


Software Architecture

- SW Module Design
- Test, Verification & Validation
- BMS Integration Testing

Battery Management System (BMS)

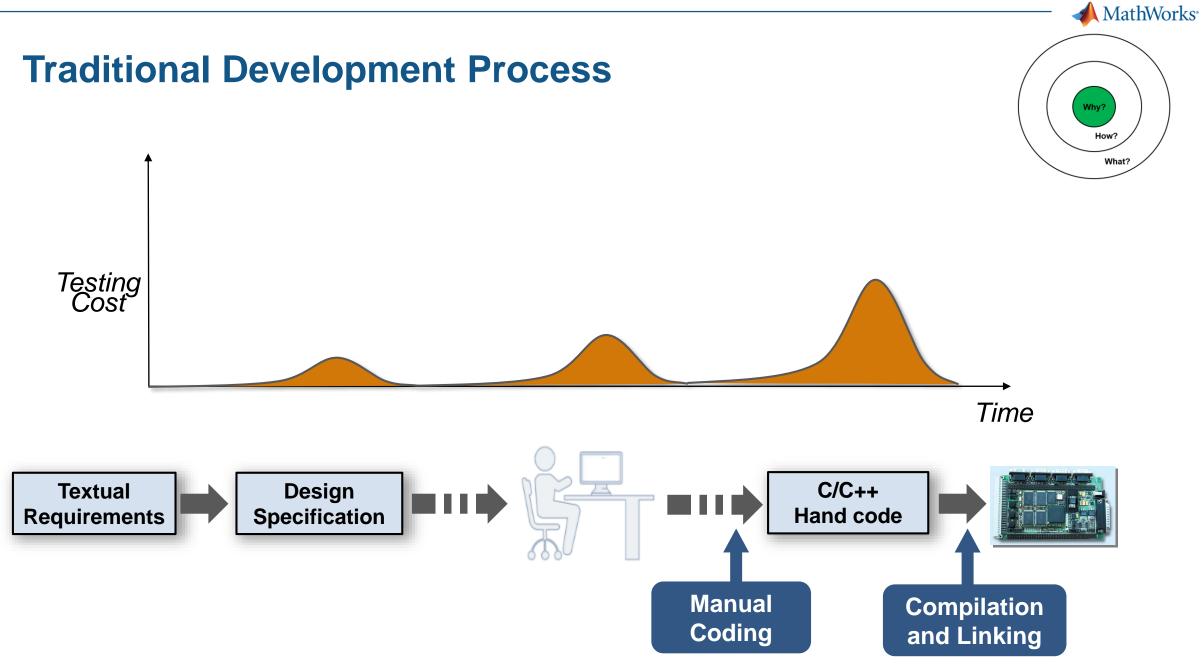




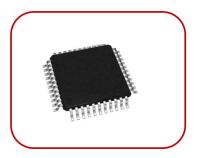
Safety Critical System

Functional Safety Certification

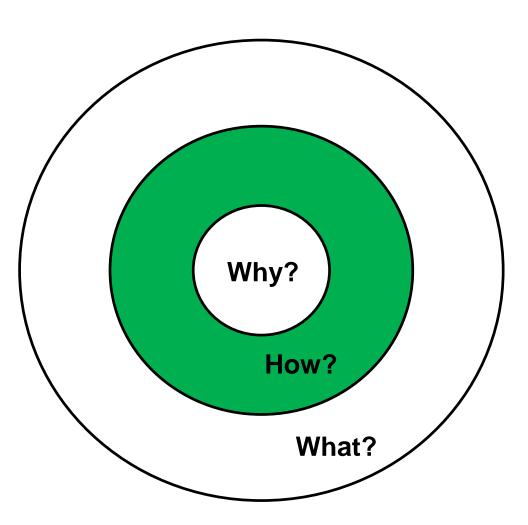


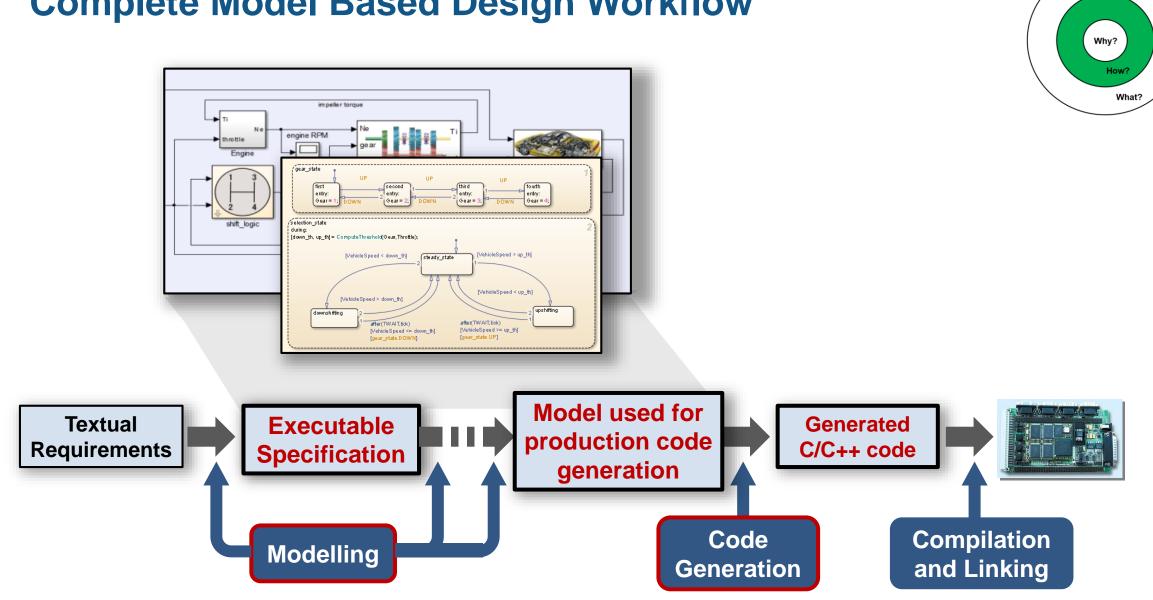






- Software Architecture
- SW Module Design
- Test, Verification & Validation
- BMS Integration Testing

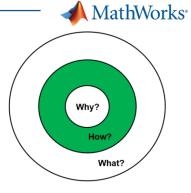


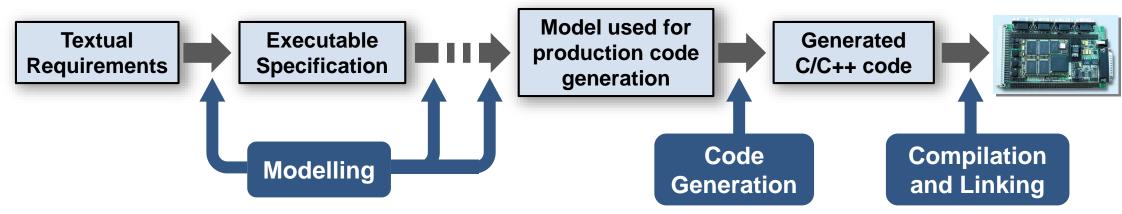


Complete Model Based Design Workflow

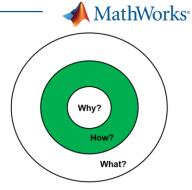
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Complete Model Based Design Workflow

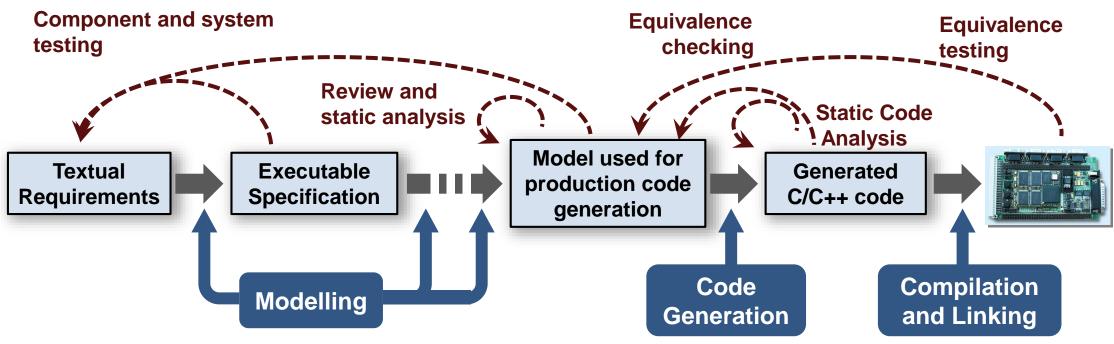


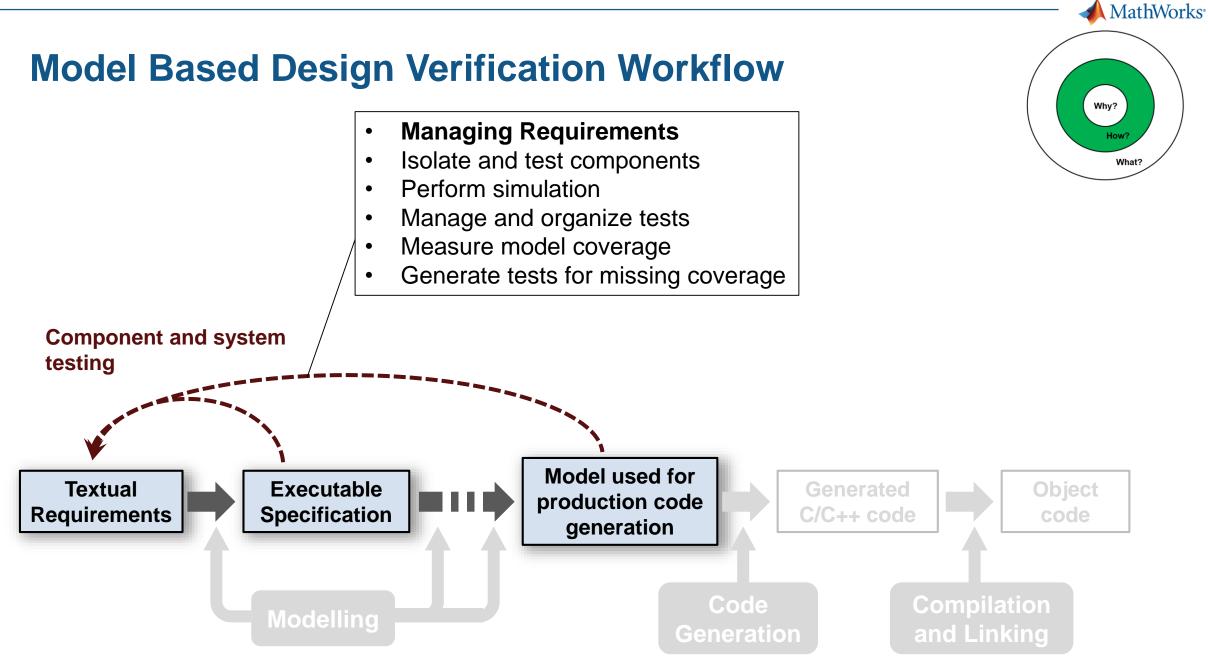


Complete Model Based Design Workflow



get the complete confidence in your design







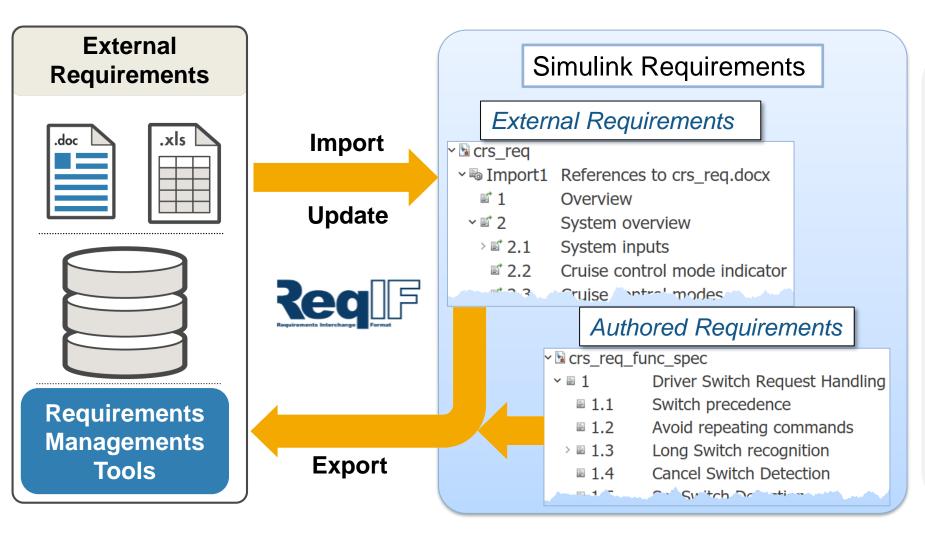
Why do 71% of Embedded Projects Fail?

Poor Requirements Management

Sources: Christopher Lindquist, Fixing the Requirements Mess, CIO Magazine, Nov 2005 MATLAB EXPO 2019

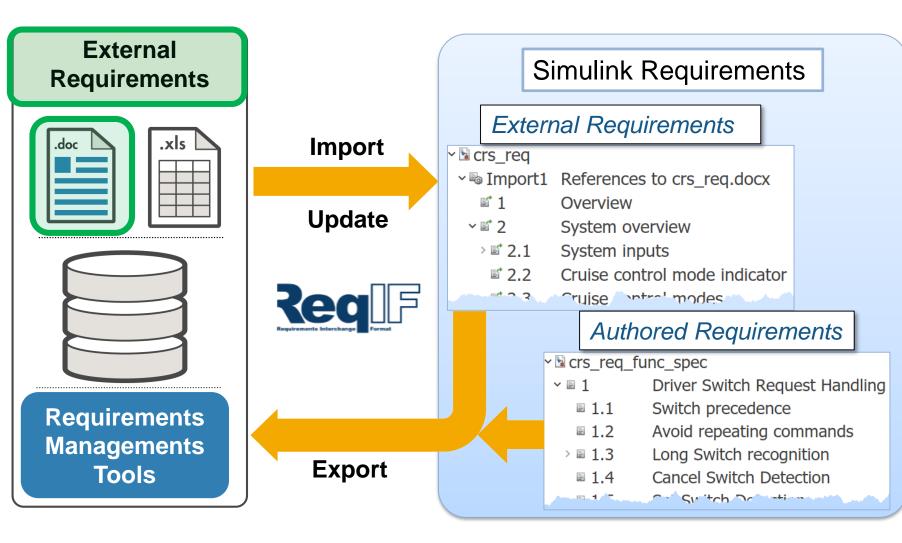


Integrate with requirements tools and author requirements



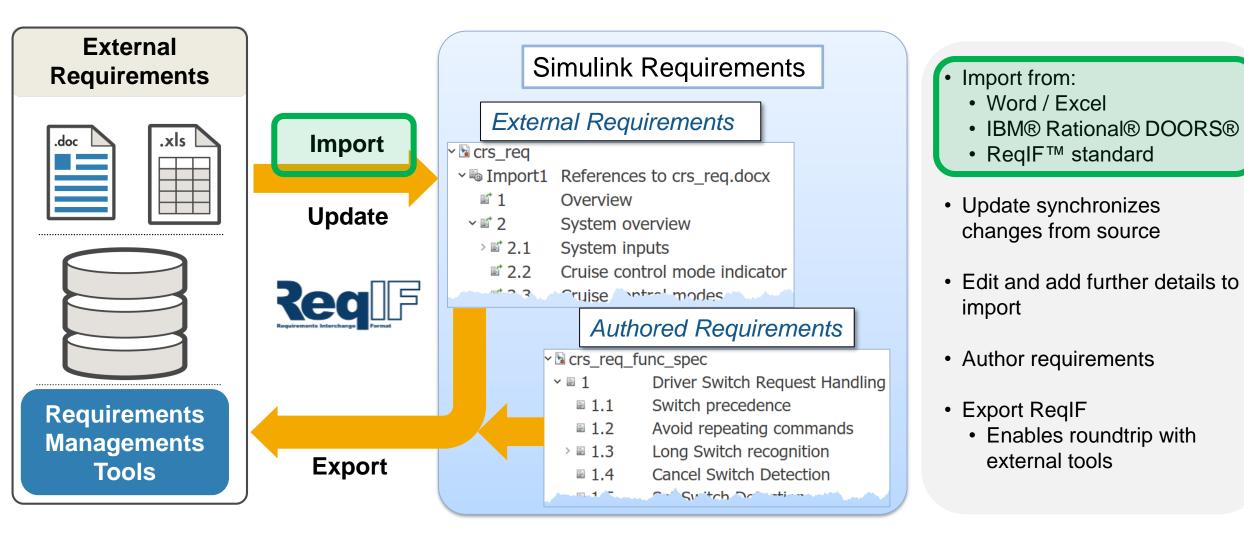
- Import from:
 - Word / Excel
 - IBM® Rational® DOORS®
 - ReqIF[™] standard
- Update synchronizes changes from source
- Edit and add further details to import
- Author requirements
- Export ReqIF
 - Enables roundtrip with external tools



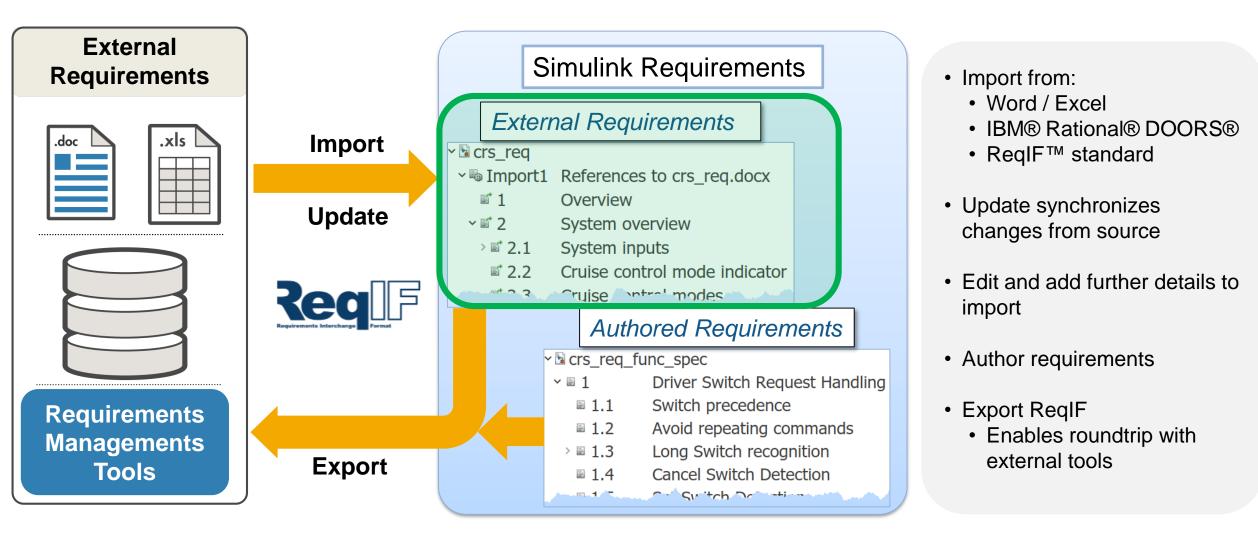


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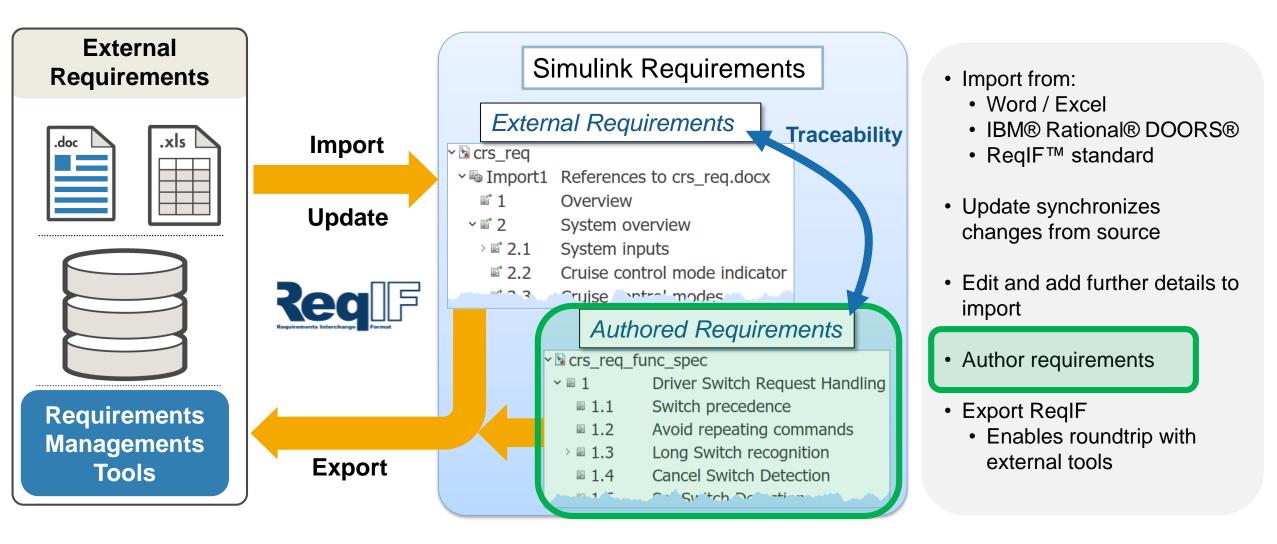




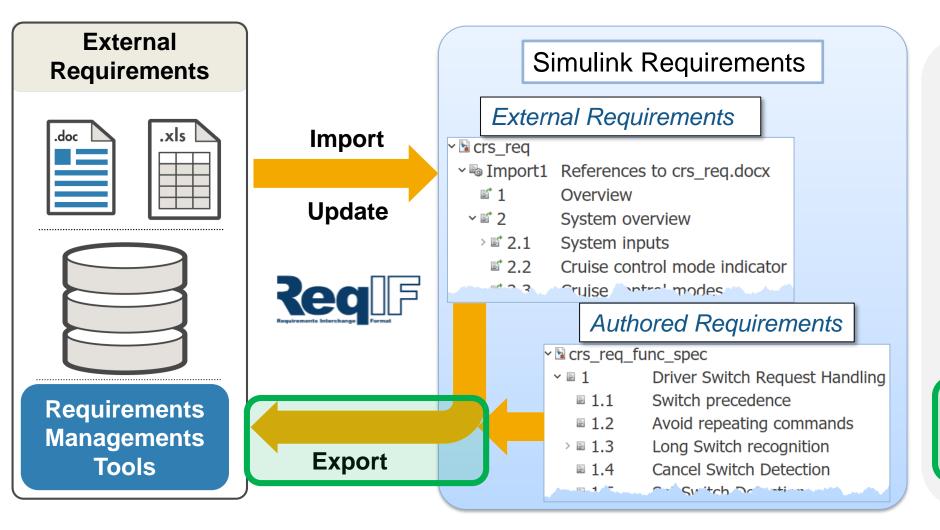








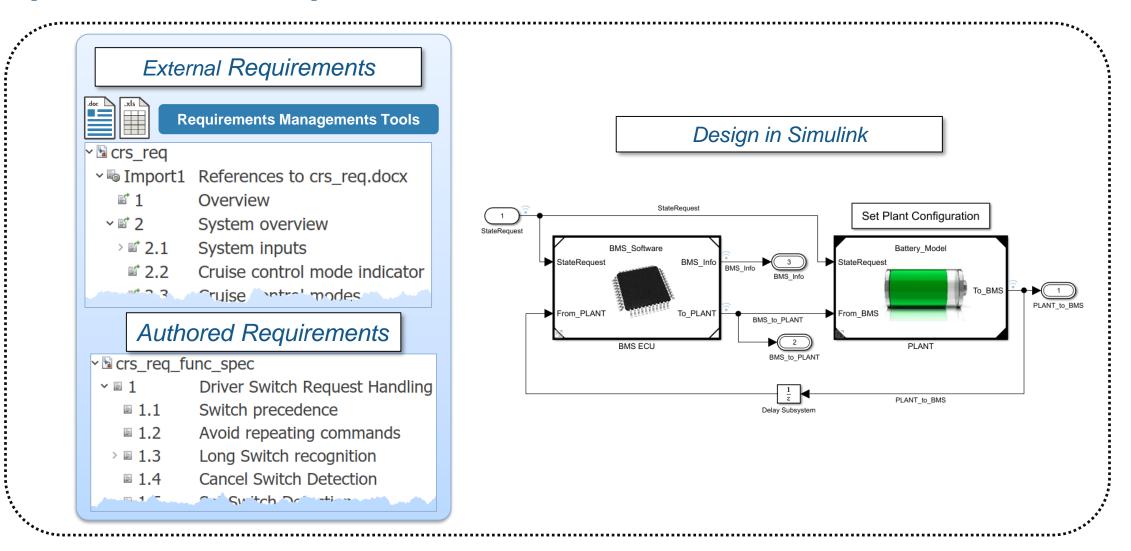




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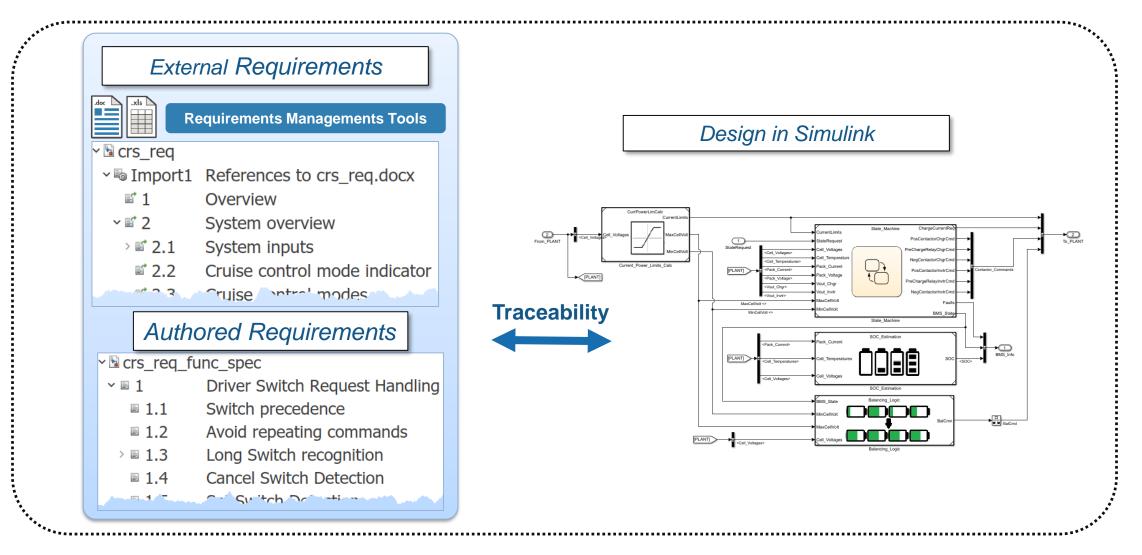


Requirements Perspective





Traceability: Requirements - Design

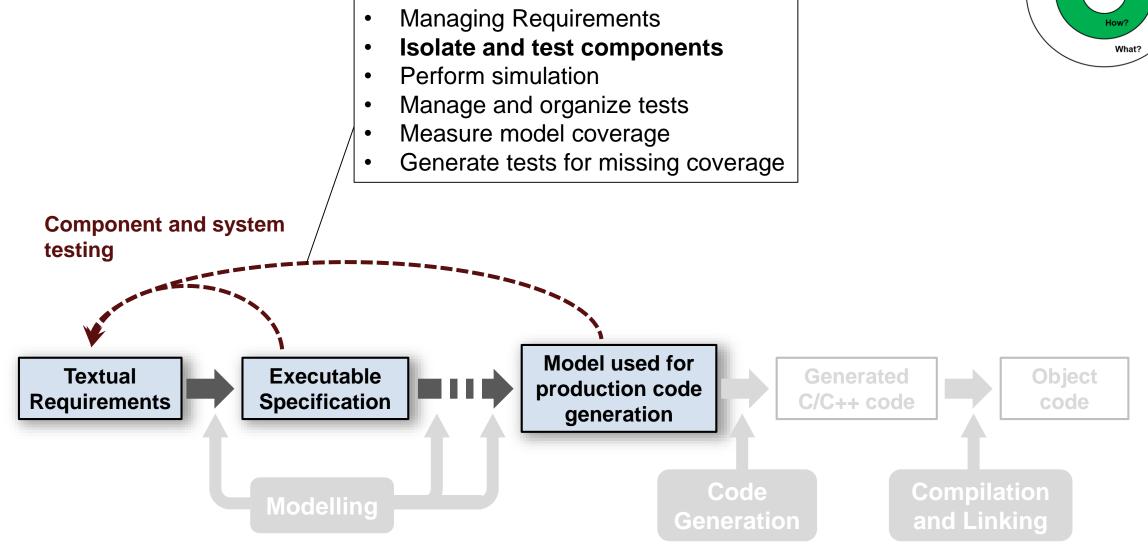




Requirements Implementation Status

Requirements - crs_controller			
ew: Requirements 🔻		1 e e 🔏 🔒 💼 🔍 (Ĉ
dex	ID	Summary	Implemented
crs_req_func_spec*	—	-	
> 1	#1	Driver Switch Request Handling	
✓	#19	Cruise Control Mode	
> 🖹 2.1	#20	Disable Cruise Control system	
> 🖹 2.2	#24	Operation mode determination	
ady			> stic
luy	_		Suc
			Implementation Status
			Implemented
			Justified
			Missing

Model Based Design Verification Workflow

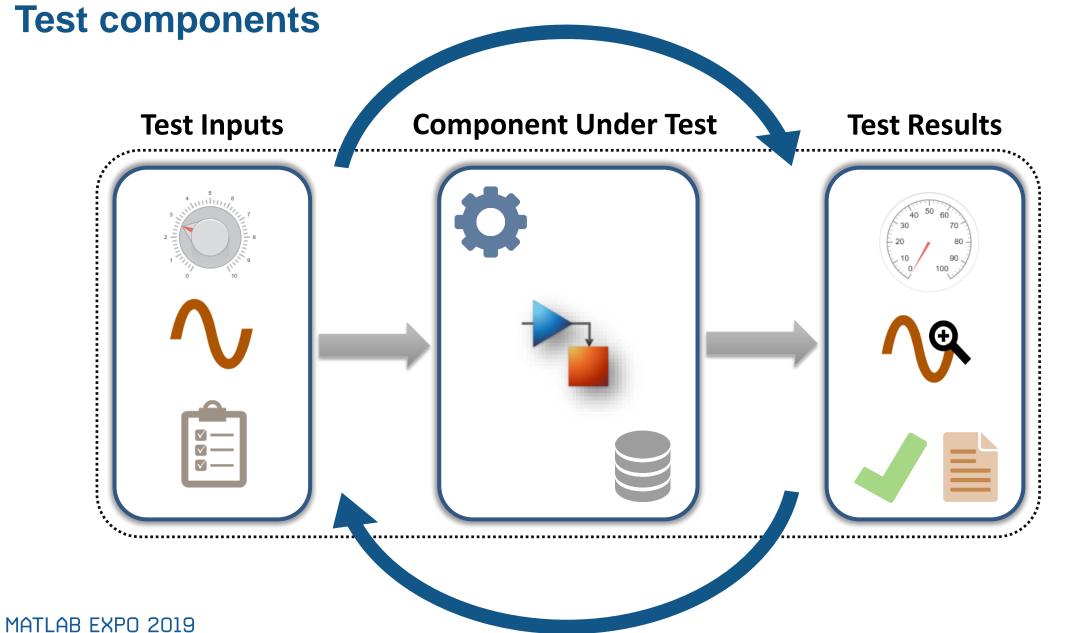


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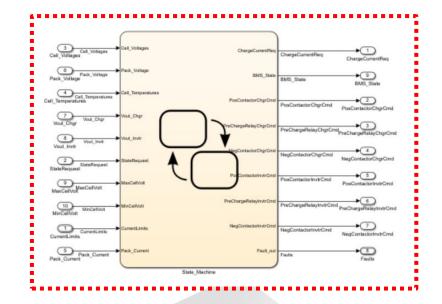
Why?

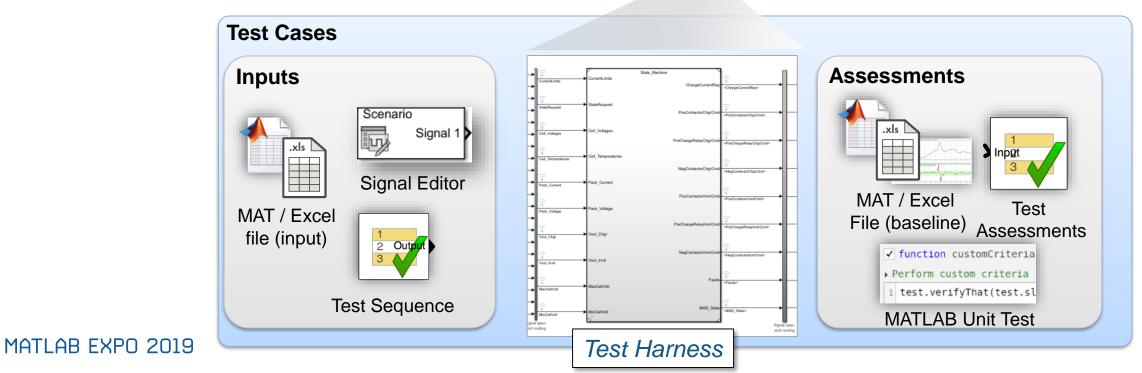
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Create Test Harnesses

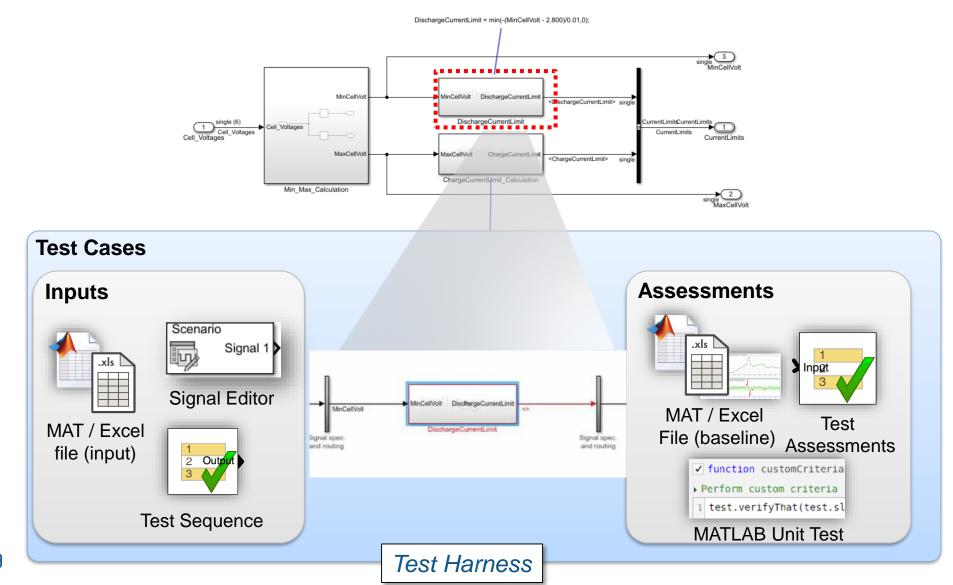


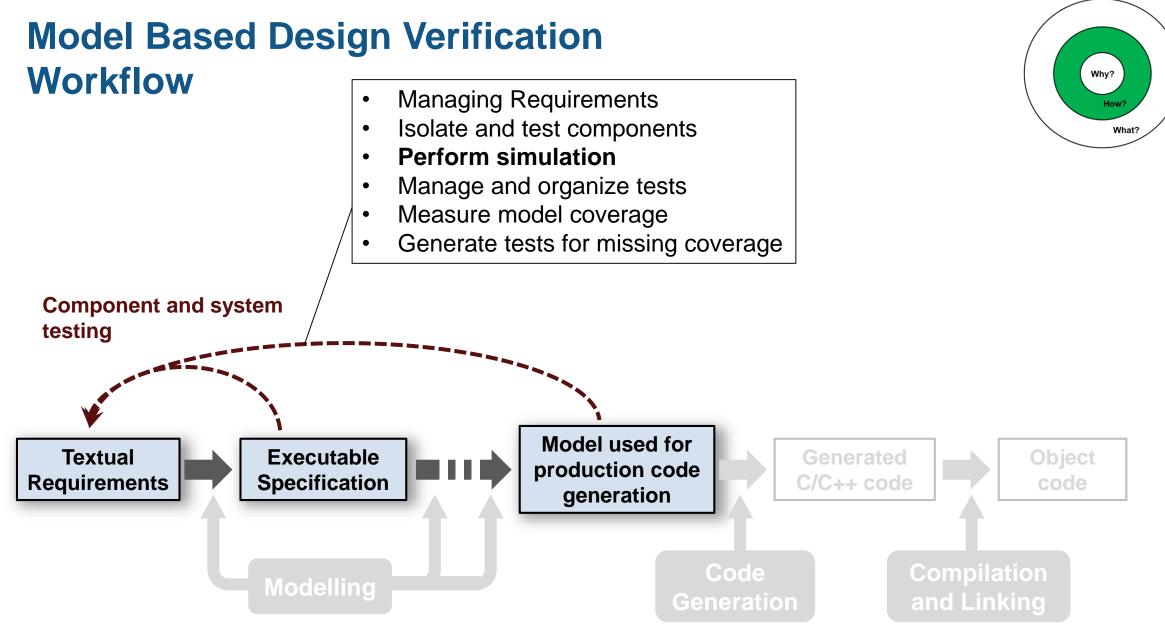


47



Create Test Harnesses on Subsystems



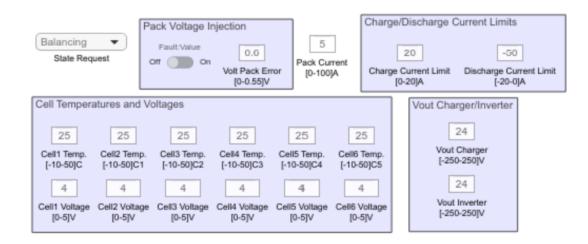


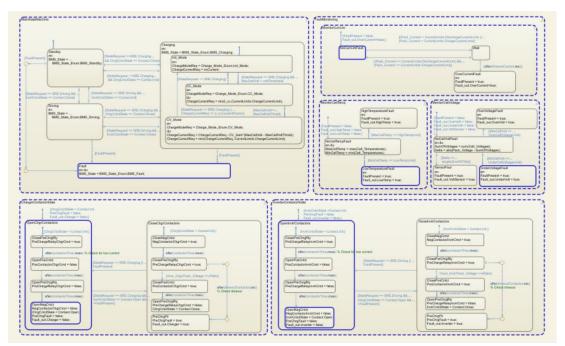
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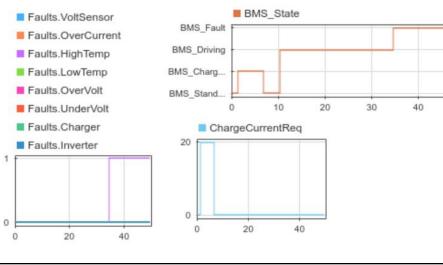
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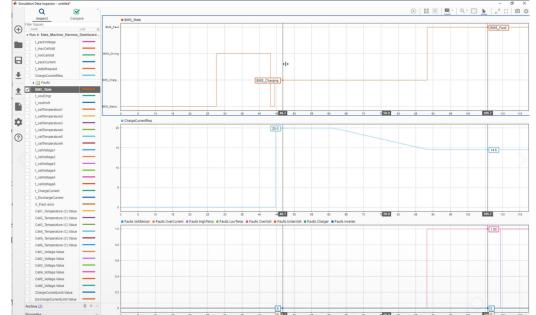


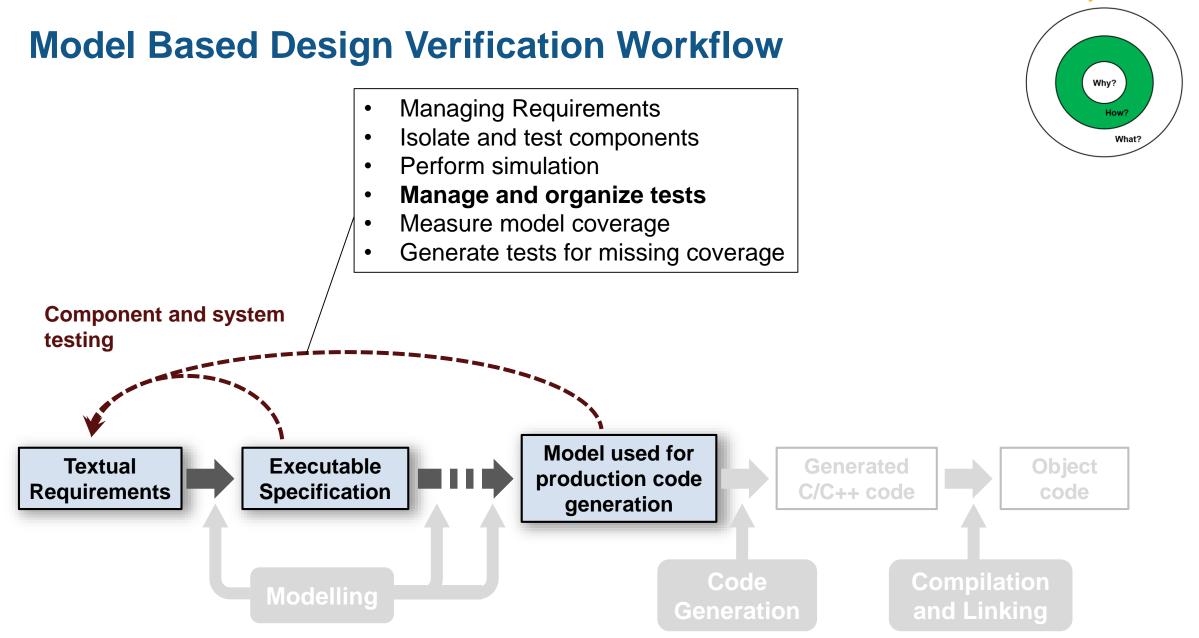
Test Ad-hoc with Dashboards









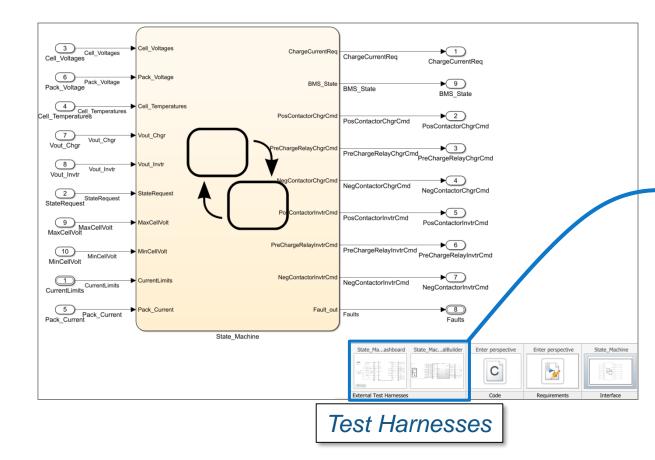


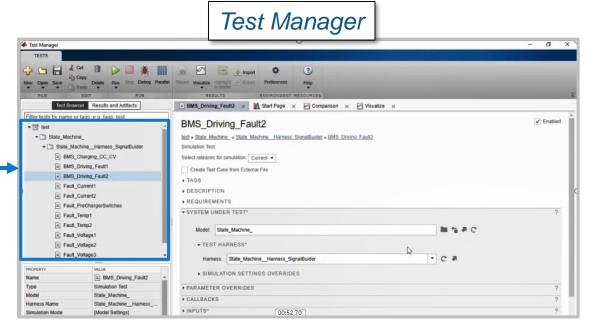
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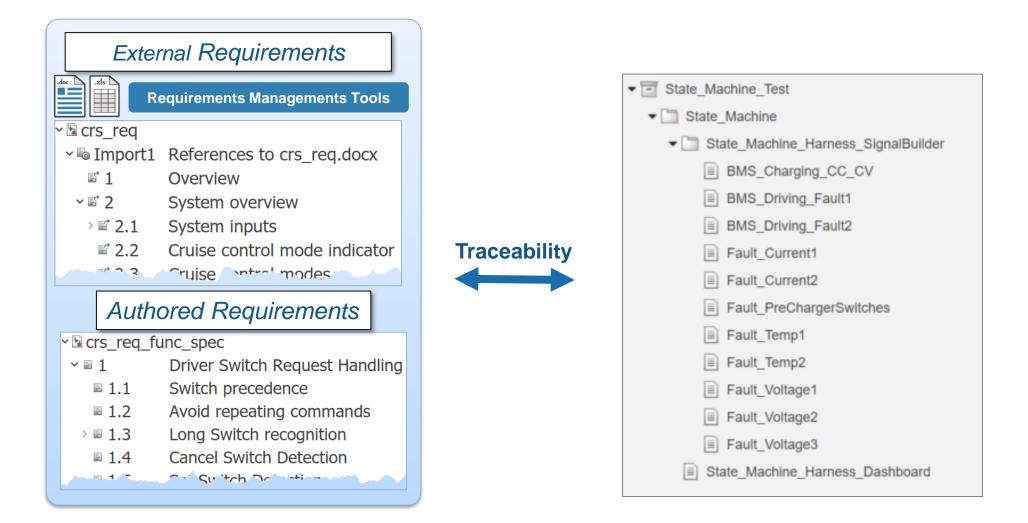
Test Harness Import in a Centralized Environment





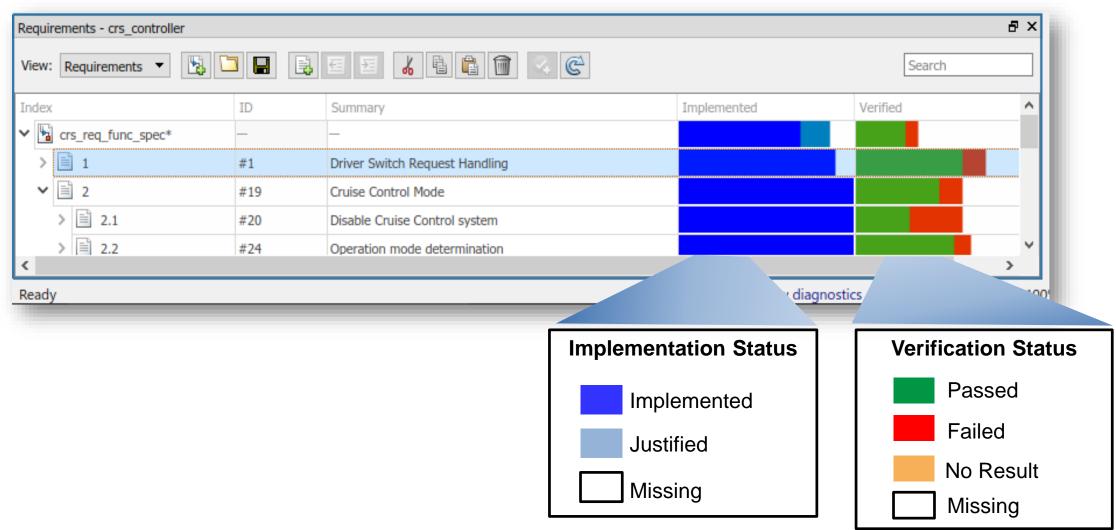


Traceability: Requirements - Tests



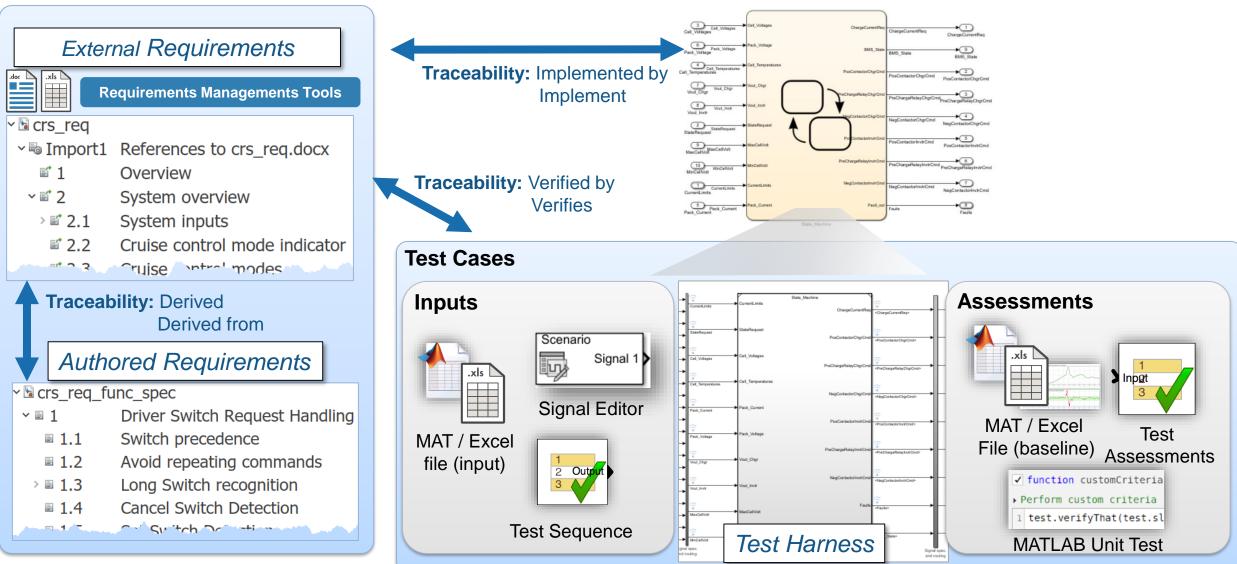


Requirements Verification Status

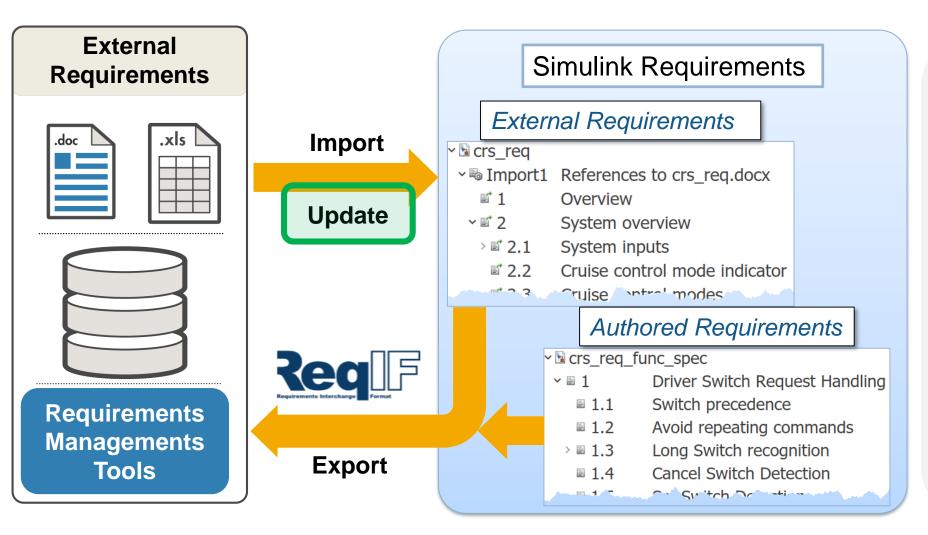




Requirements Verification with Simulink







- Import from:
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Respond to Change – Impact Analysis

Original Requirement

3.2.4 BMS Current Limit Calculation: Charge Current Limit

Calculate the charge current limit following: ChargeCurrentLimit = min((4.500 - MaxCellVolt)/0.01,0);

Updated Requirement

3.2.4 BMS Current Limit Calculation: Charge Current Limit

Calculate the charge current limit following: ChargeCurrentLimit = max((4.500 - MaxCellVolt)/0.01,0);



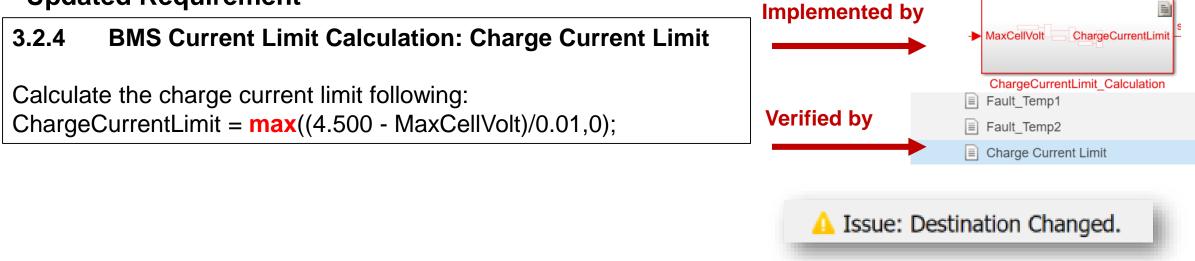
Respond to Change – Impact Analysis

Original Requirement

3.2.4 BMS Current Limit Calculation: Charge Current Limit

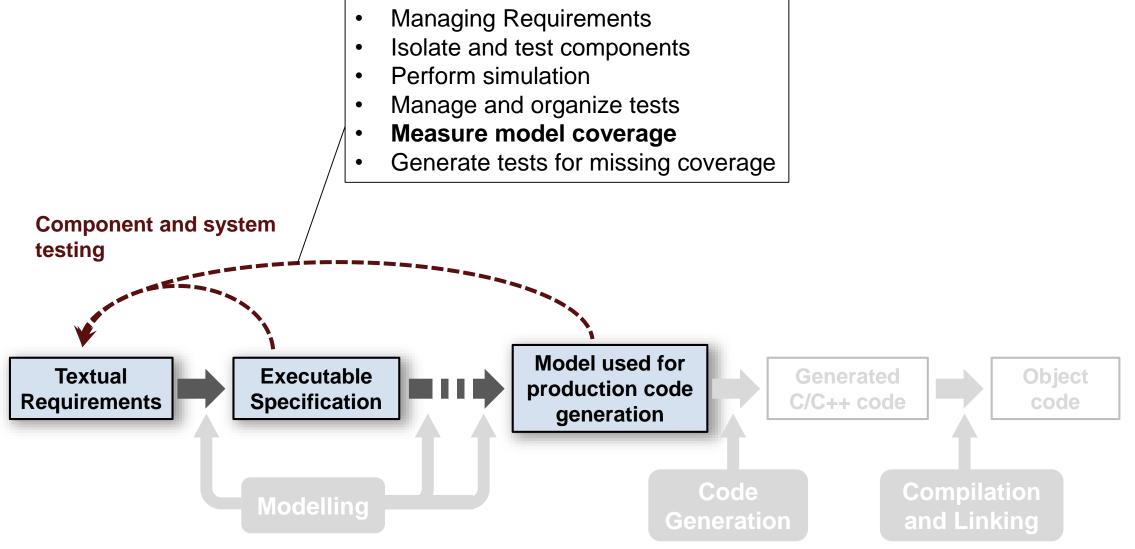
Calculate the charge current limit following: ChargeCurrentLimit = min((4.500 - MaxCellVolt)/0.01,0);

Updated Requirement





Model Based Design Verification Workflow





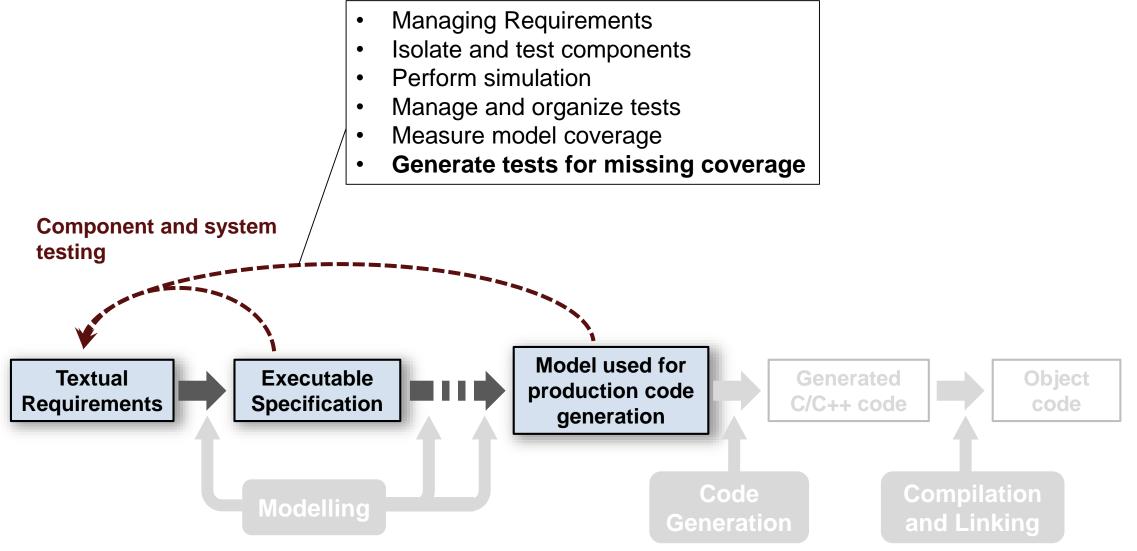
Why we didn't achieve full model coverage?

A. Missing tests

- B. Missing requirements
- c. Design errors

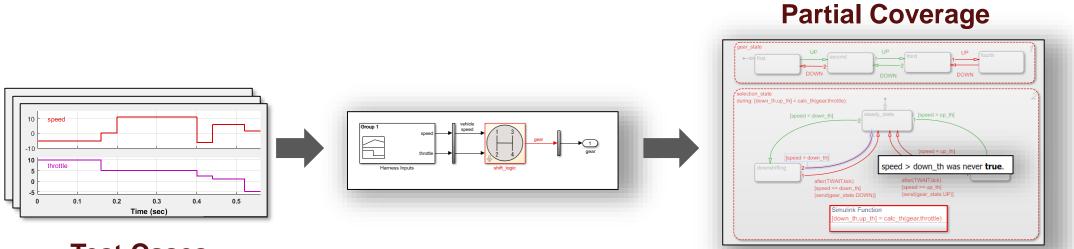


Model Based Design Verification Workflow





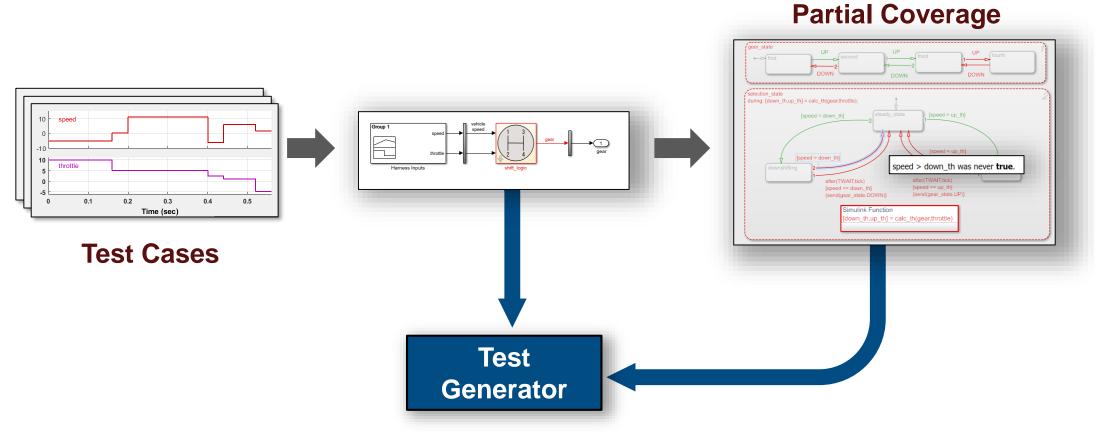
Addressing Missing Coverage



Test Cases



Addressing Missing Coverage



Simulink Design Verifier



Partial Coverage

speed > down_th was never **true**.

[speed >= up_th

lection_state

uring: [down_th,up_th] = calc_th(gear,throttle

speed > down_th

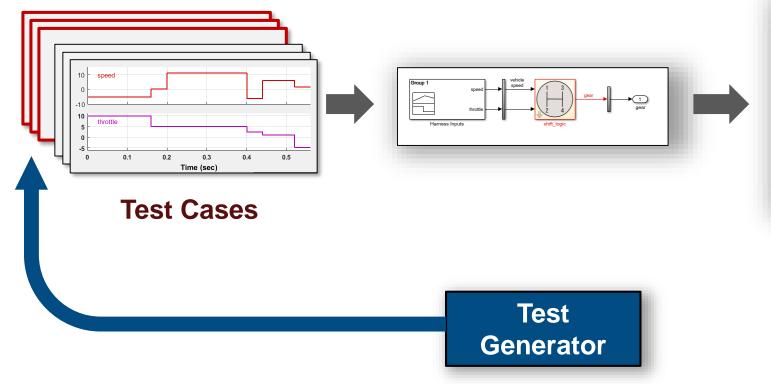
[speed <= down_th] [send(gear_state.DOWN)

mulink Function

n_th,up_th] = calc_th(gear,throttle

Addressing Missing Coverage

New Test Cases

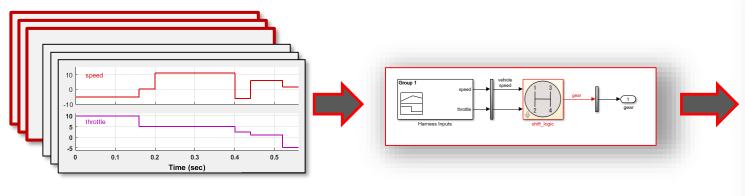


Simulink Design Verifier



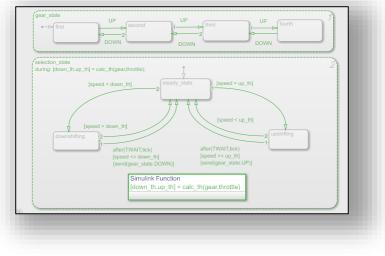
Addressing Missing Coverage

New Test Cases



Test Cases

Full Coverage



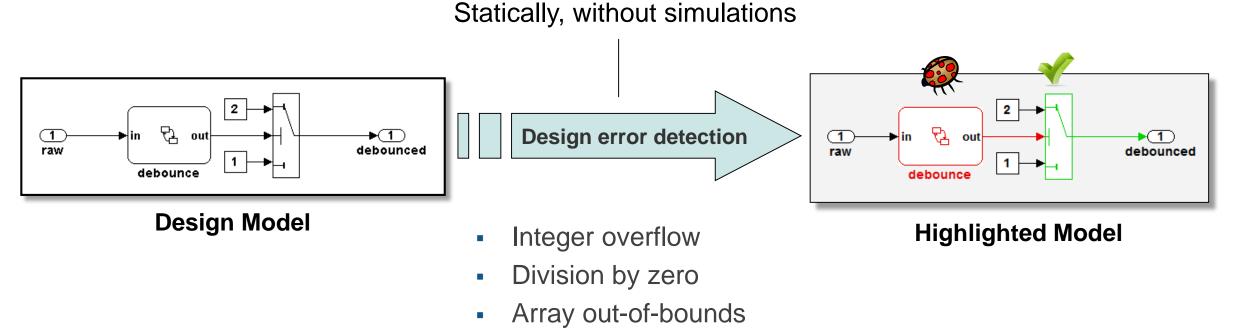


Why we didn't achieve full model coverage?

- A. Missing tests
- B. Missing requirements
- c. Design errors



Detecting Hidden Run-Time Design Errors



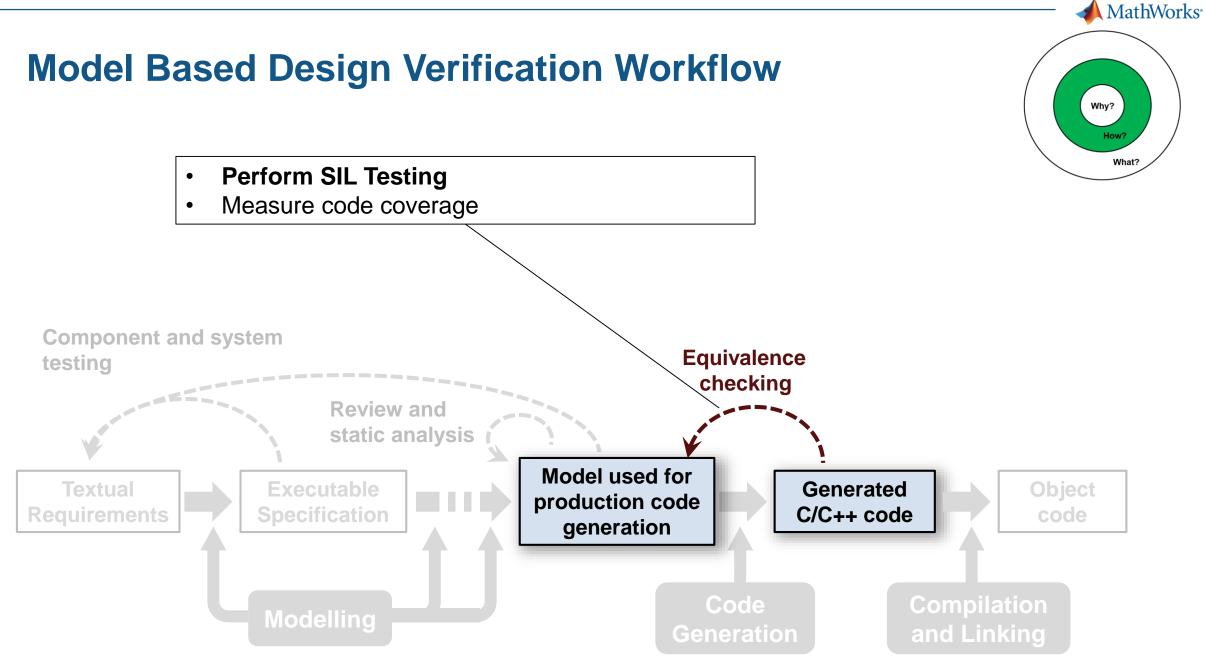
- Range violations
- Dead Logic

Why? How? What? **Component and system** testing **Review and** static analysis Model used for **Textual Executable** Generated **Object** production code Requirements **Specification** C/C++ code code generation Code Modelling Generation

Model Based Design Verification Workflow

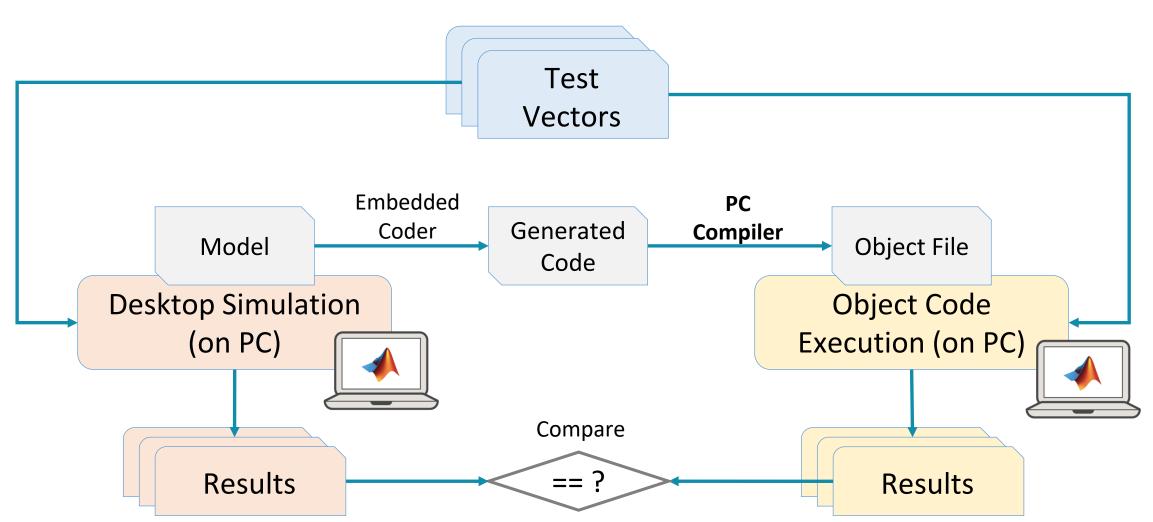
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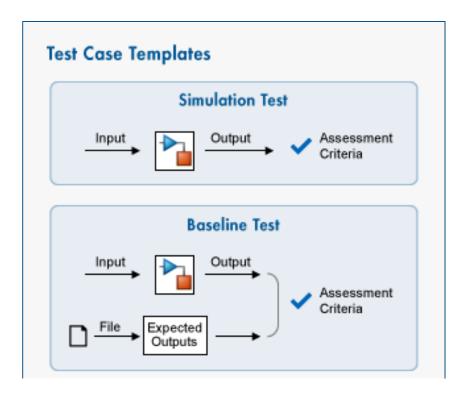
Software In the Loop (SIL) Testing





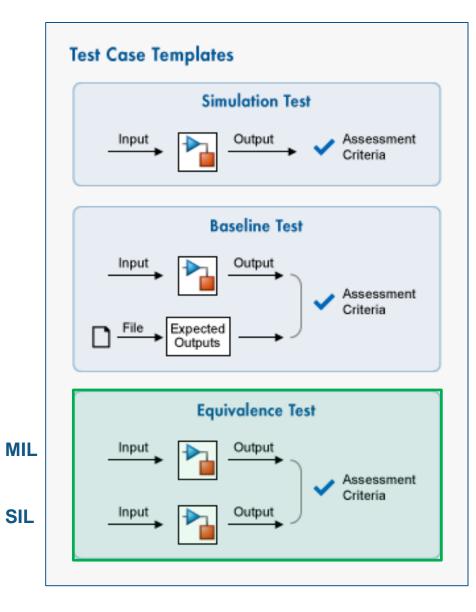
Test Case Templates	
Simulation Test	
Input Output Assessment Criteria	

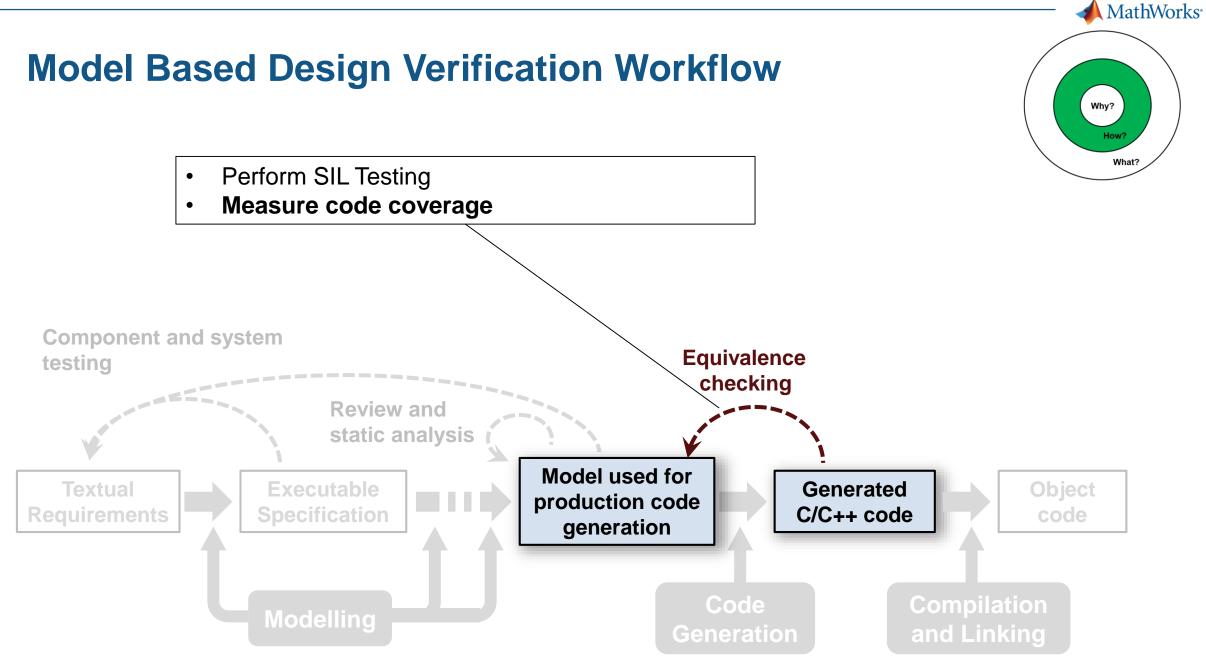




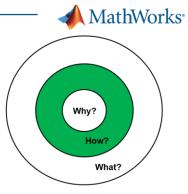


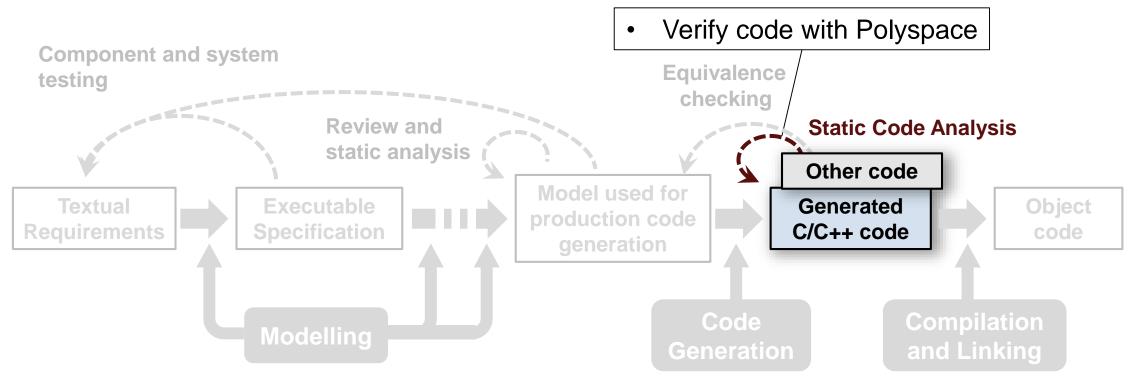
MIL vs SIL





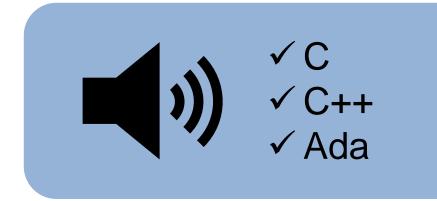
Static Code Analysis





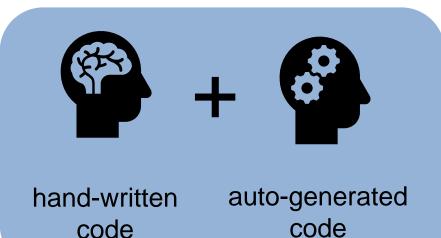


Polyspace Tools





Method: <u>Formal Method based</u> semantic analysis →Abstract Syntax Interpretation

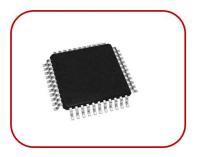


Goal:

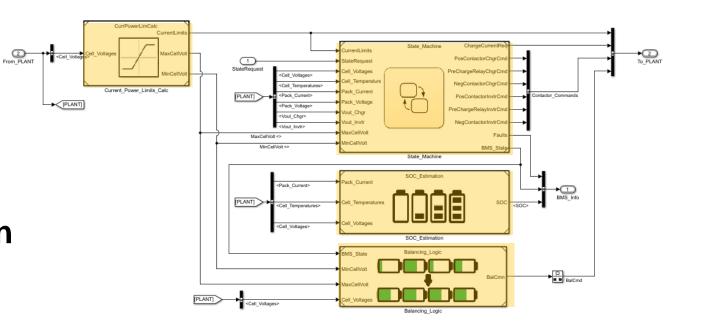
- ✓ Find Runtime Errors (division by zero, overflows, etc.)
 - Find MISRA violations
 - ✓ Provide code metrics
 - ✓ Prove absence of Runtime Errors



Battery Management System (BMS)

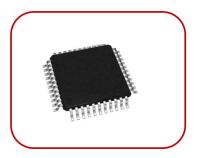


- Software Architecture
- SW Module Design
- Test, Verification & Validation
- BMS Integration Testing

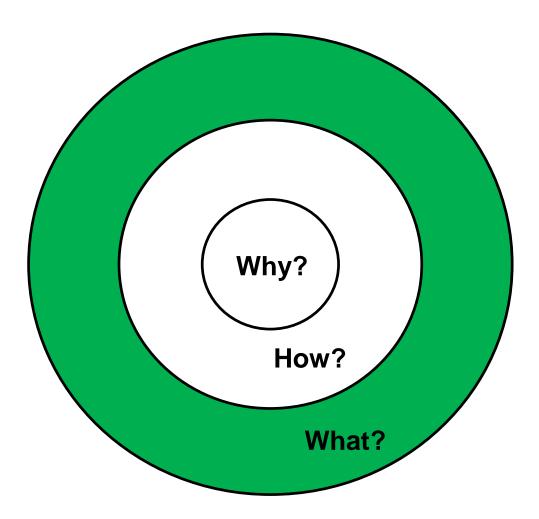




Battery Management System (BMS)

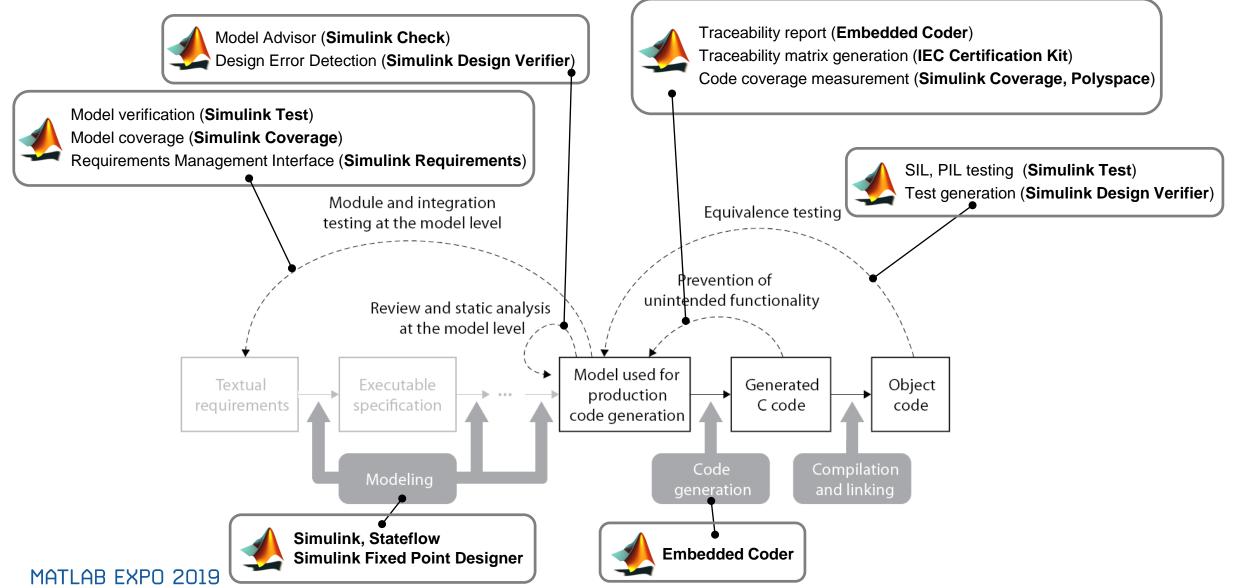


- Software Architecture
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Model Based Design Verification Workflow

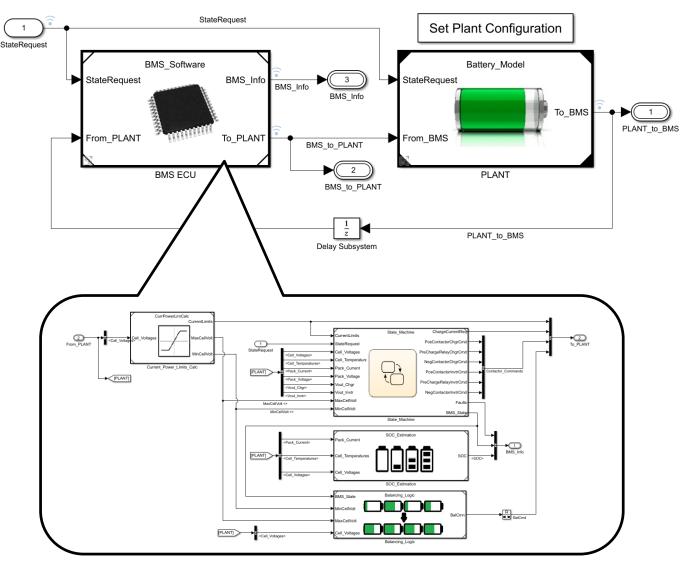




Battery Management System (BMS)

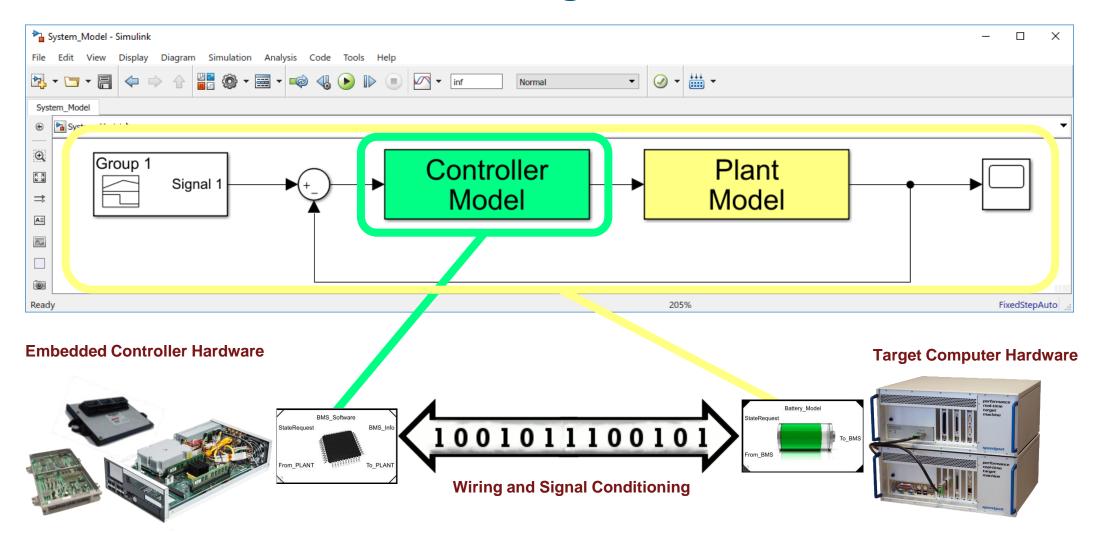


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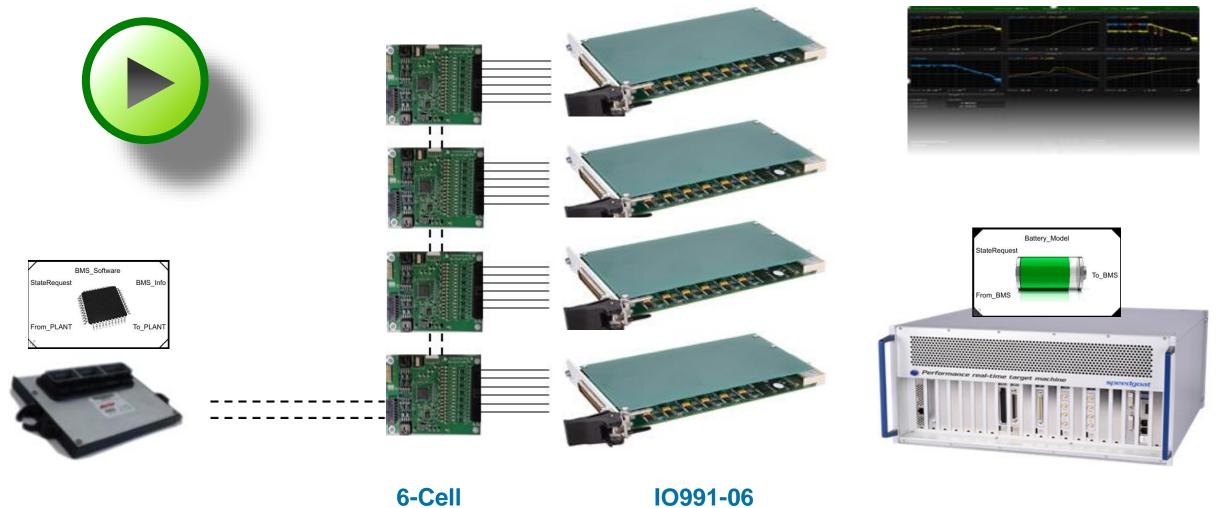


Real-time Simulation and Testing





HIL Testing – Speedgoat Solution



6-Cell Modules



