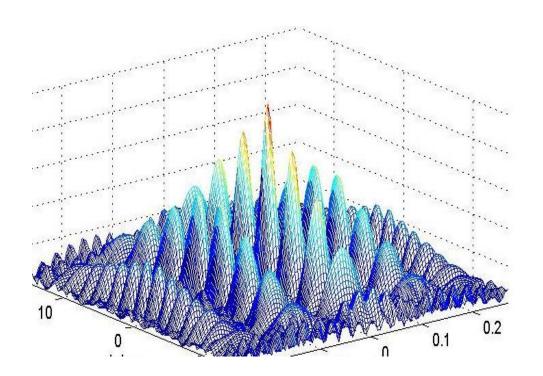




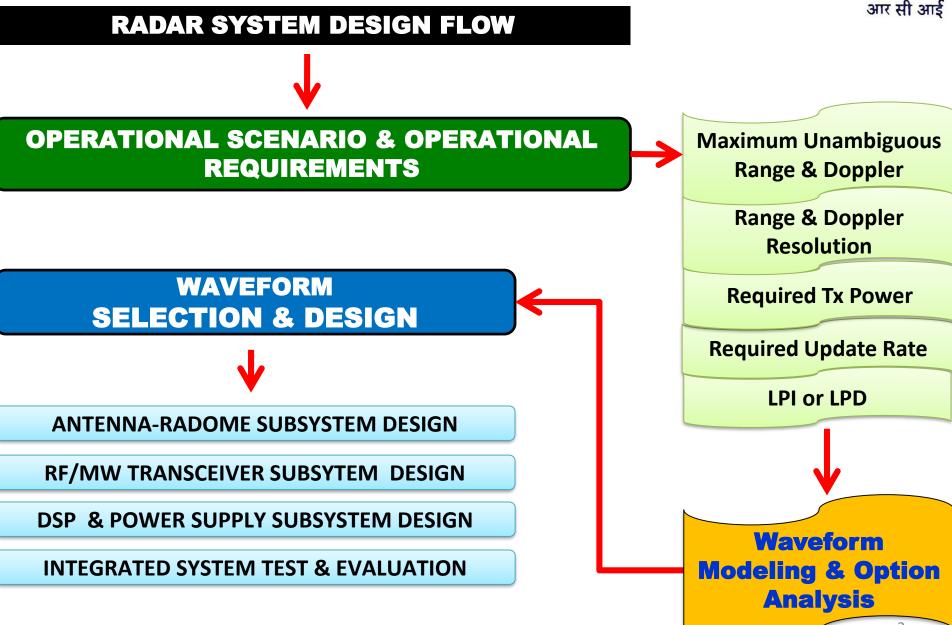
Waveform Modeling & Option Analysis For Radar Systems Using MATLAB



Nilang Trivedi Scientist-E, RCI, DRDO, Hyderabad



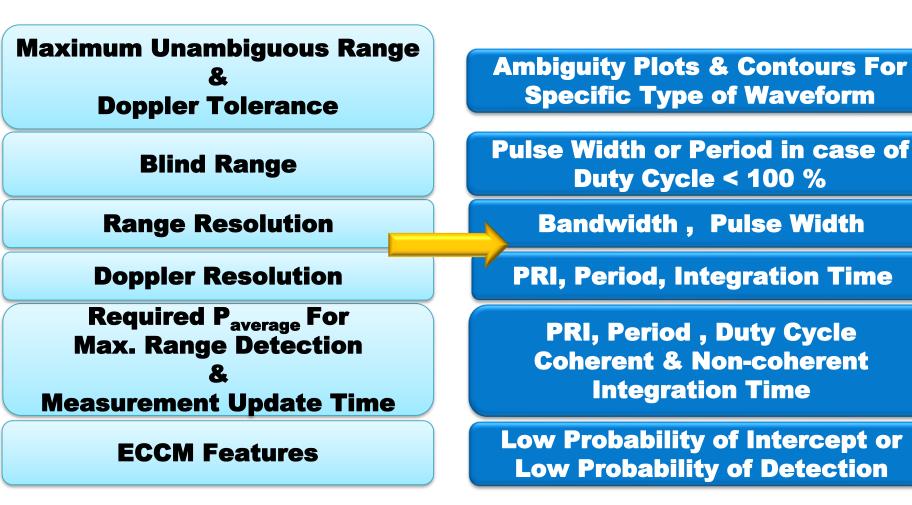




Waveform Modeling & Option Analysis



Dependency of System Parameter on Waveform Design



The choice of transmitter waveform depends on the following factors:

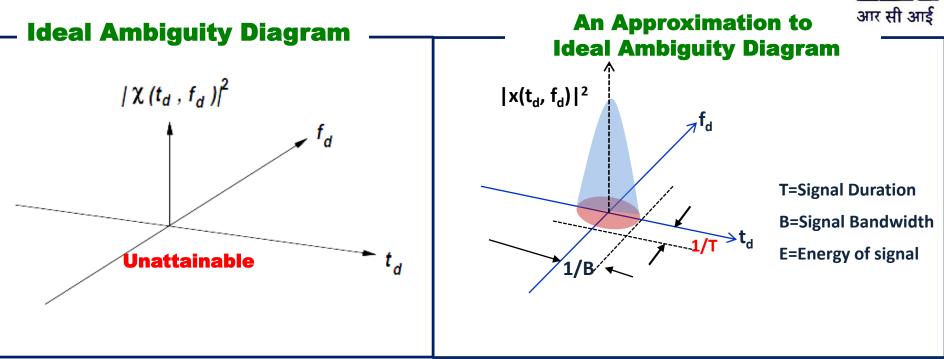
- Ease of generation of the waveform
- Peak power required by the waveform
- Extent of compression offered by the waveform and the resultant resolution
- Doppler tolerance and Range–Doppler ambiguity relation.
- The extent to which the waveform can be detected, intercepted, jammed.

The waveforms considered for analysis:

- Pulsed RF
- Linear Frequency Modulated Waveform.
- Pseudo Randomly Bi-phase Modulated Continuous Waveform

Importance of Ambiguity Plots & Contours For Waveform selection



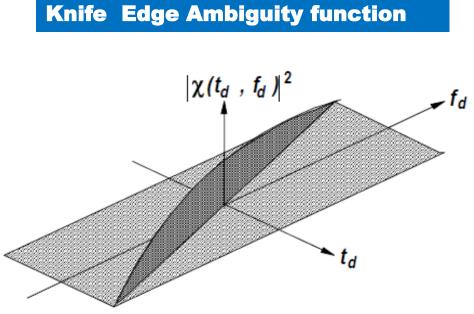


Properties :

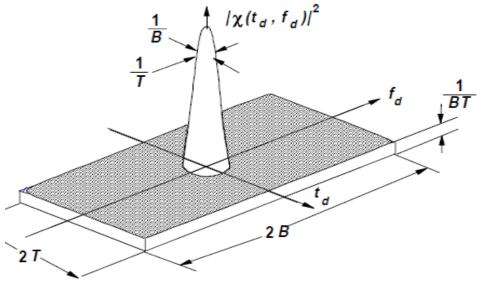
- \Rightarrow Max. value of $|x(t_d, f_d)| = |x(0,0)|^2 = 2E^2$
- \Rightarrow |x(-t_d, -f_d)|² = |x(t_d, f_d)|²
- Along td Axis $|x(t_d, f_d)|^2$ is a autocorrelation function of u(t)
- Along fd Axis |x(t_d, f_d)|² is a Spectrum of u(t)
 - Total volume the ambiguity plot is constant : v =2E²

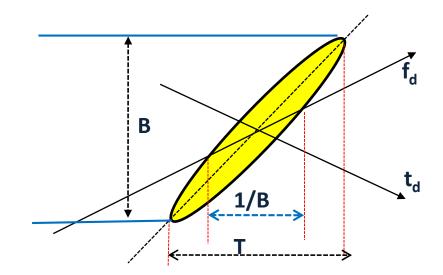
Ambiguity Plots & Contours For LFM & PN Coded Waveform

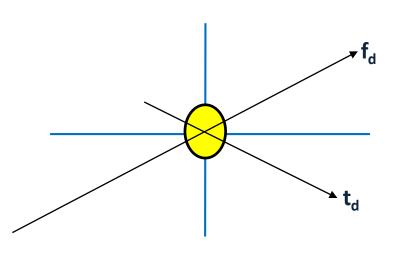




Thumb Tack Ambiguity function





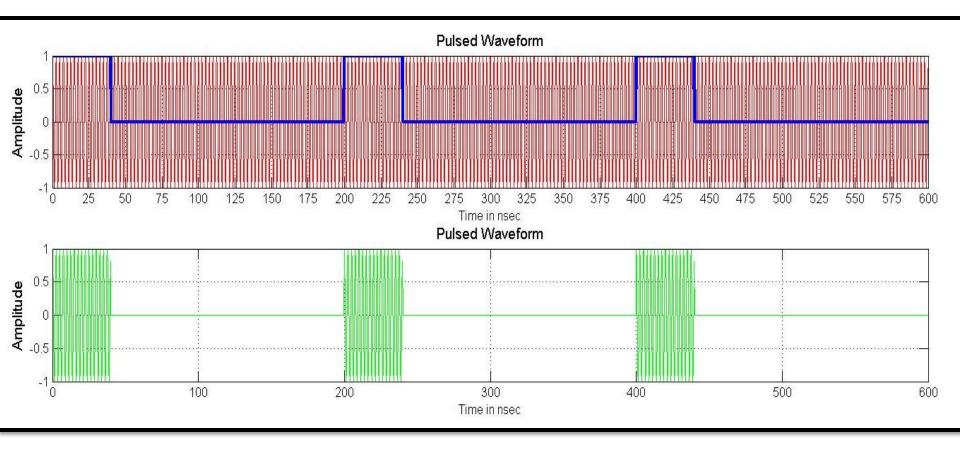


MATLAB Simulation Results For Pulsed RF Signal

Time Domain Plot: Coherent Pulse Train

आर सी आई

Ton= 40 nsec, PRI= 200nsec, DC=20 %

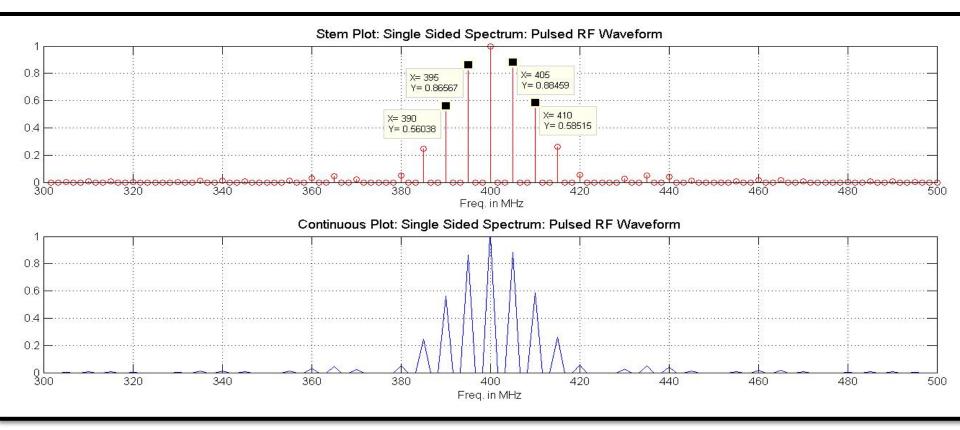


Signal Spectrum : Coherent Pulse Train



Ton= 40 nsec, PRI= 200nsec, DC=20 %

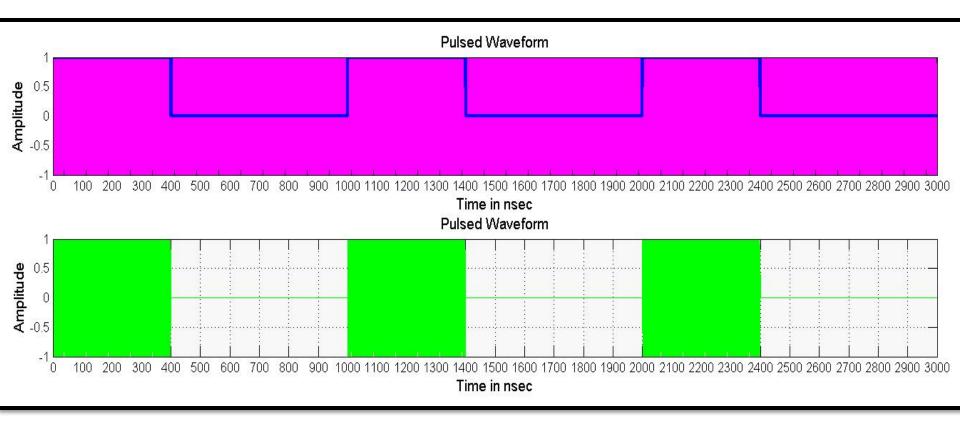
Spacing between Spectral Lines= PRF = 5 MHz



Time Domain Plot: Coherent Pulse Train



Ton= 400 nsec, PRI=1000 nsec, DC=40 %

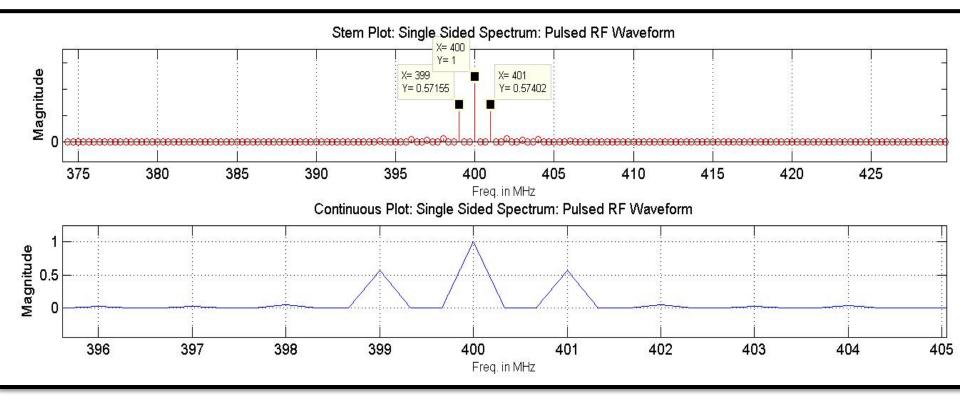


Signal Spectrum : Coherent Pulse Train



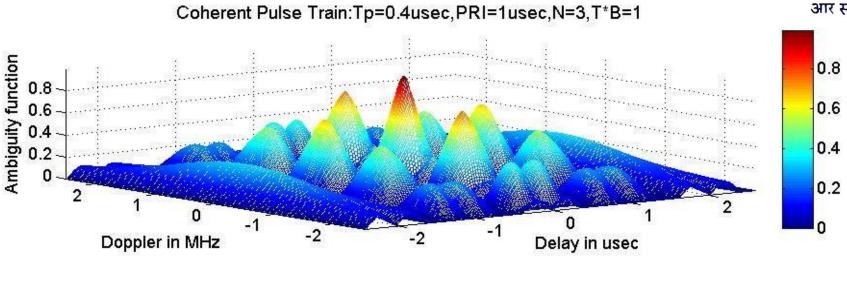
Ton= 400 nsec, PRI=1000 nsec, DC=40 %

Spacing between Spectral Lines= PRF =1 MHz

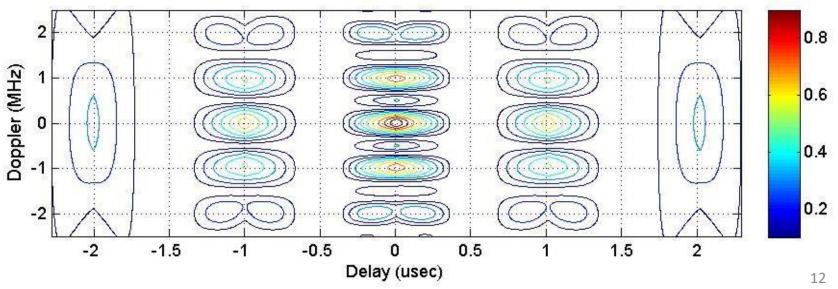


Ambiguity Plot: Coherent Pulse Train



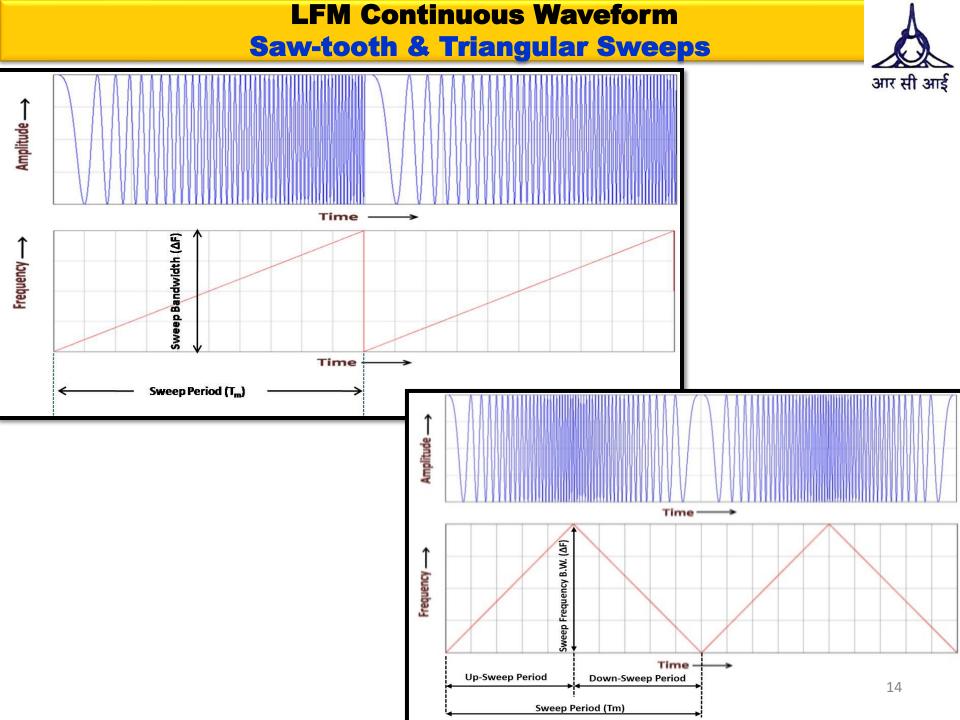


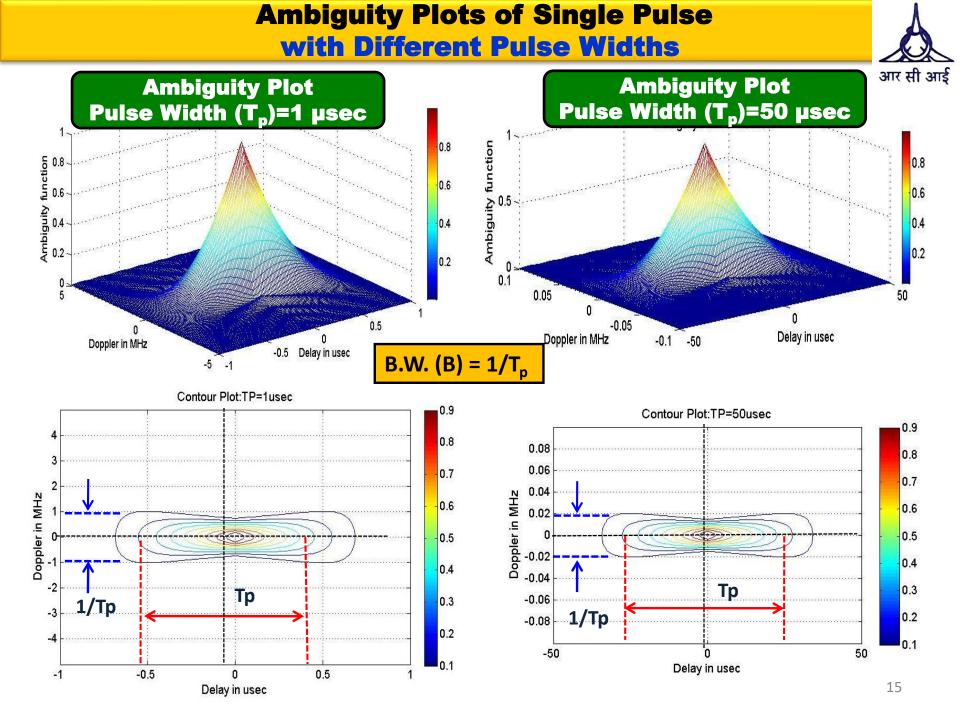
Contour Plot



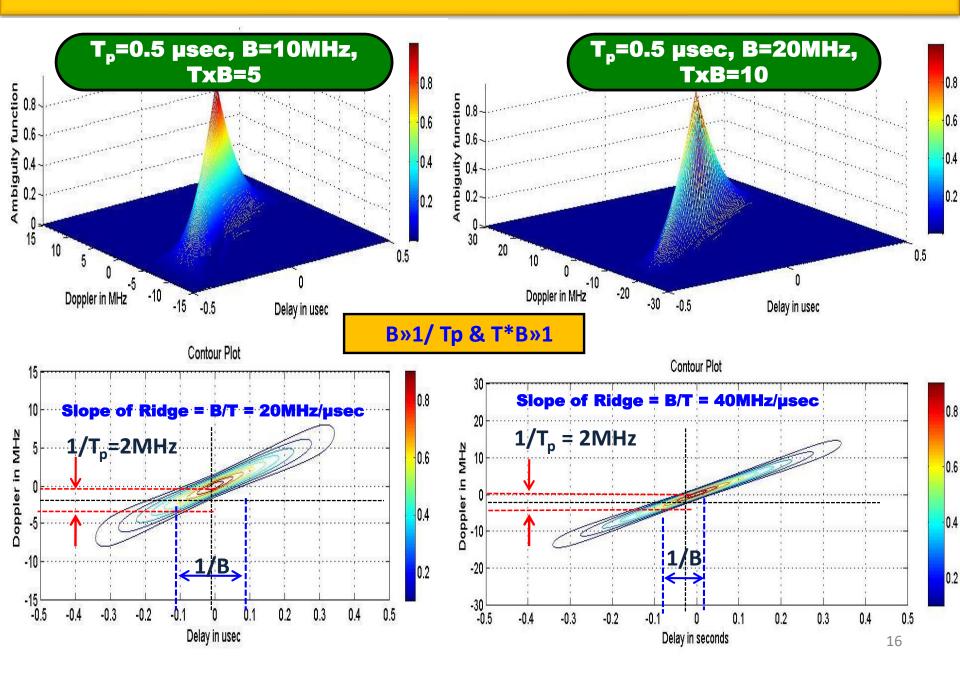


MATLAB Simulation Results For Linear Frequency Modulated Signal





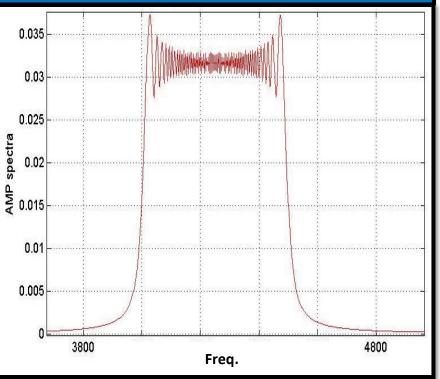
Ambiguity Plots of LFM Pulse with Different TxB Products



Amplitude Spectra: LFM Chirp Effect of Sweep Frequency Bandwidth(B)

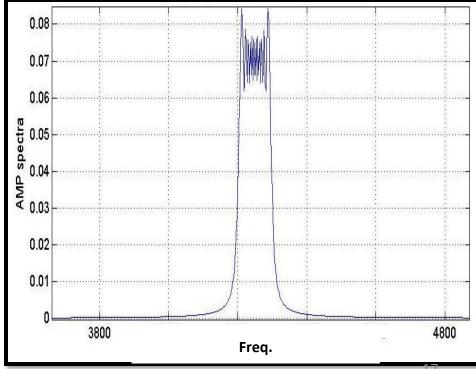


LFM Up Chirp: Amplitude Spectra: Bandwidth = 500 MHz



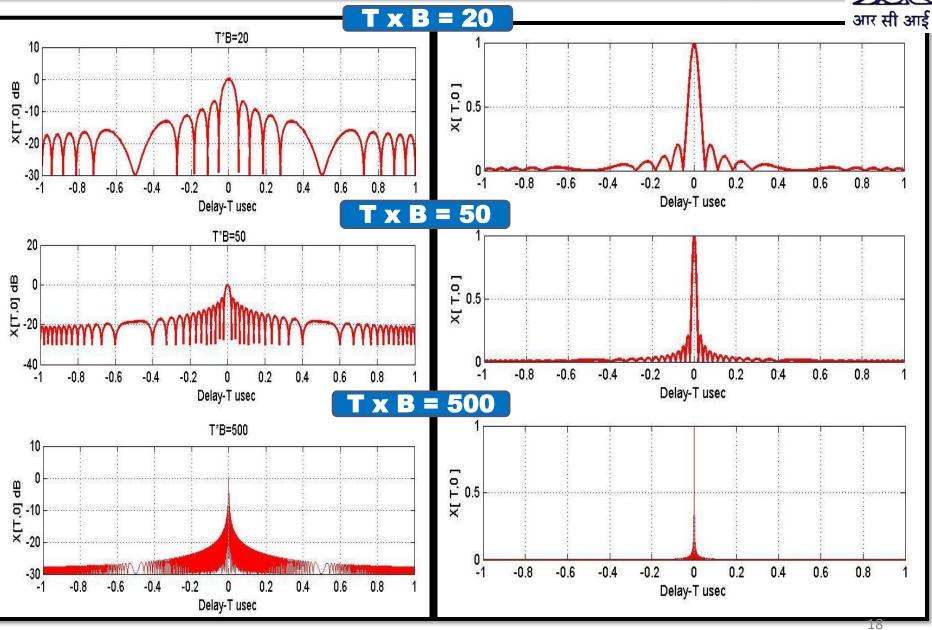
Y-Axis is in normalized scale

LFM Up Chirp: Amplitude Spectra: Bandwidth = 100 MHz



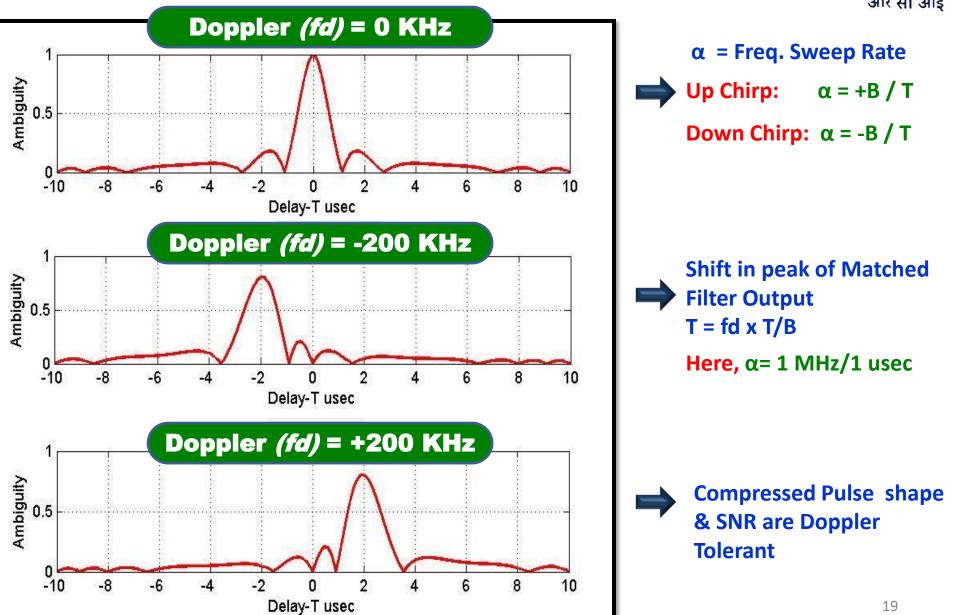
17

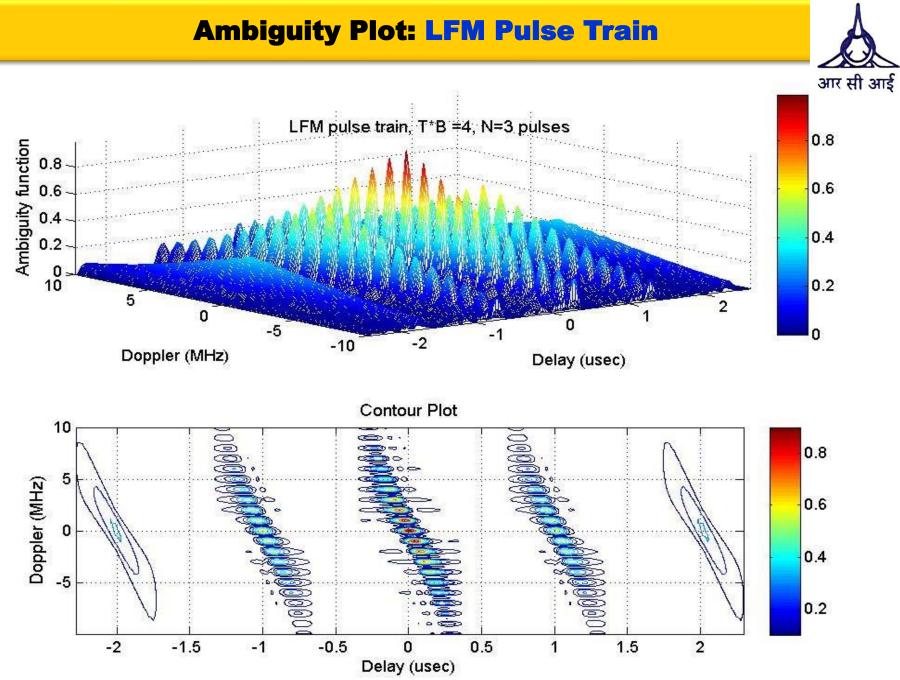
Effect of (Time x Bandwidth) Product on LFM Autocorrelation



Range–Doppler Coupling Effect in LFM Waveform





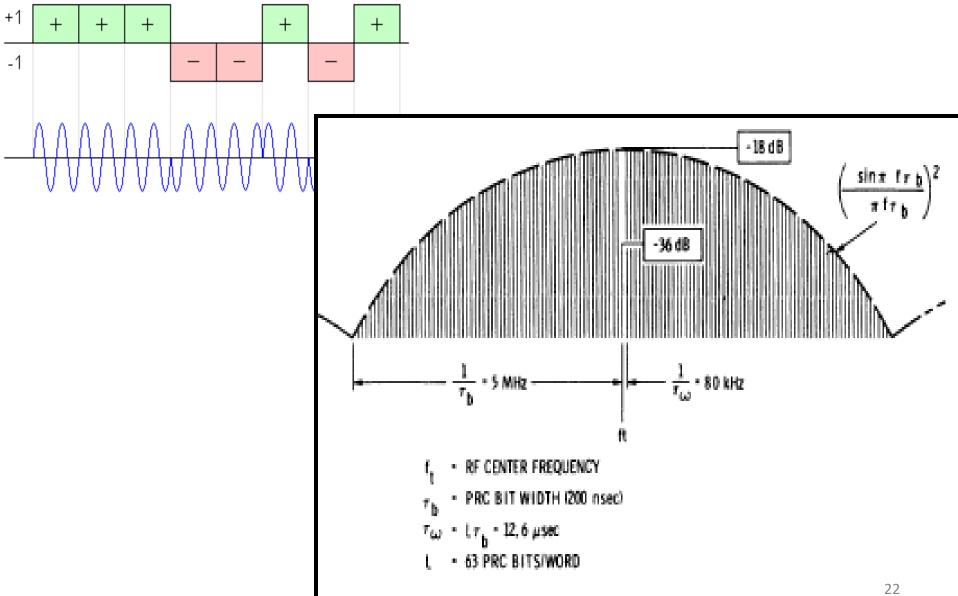




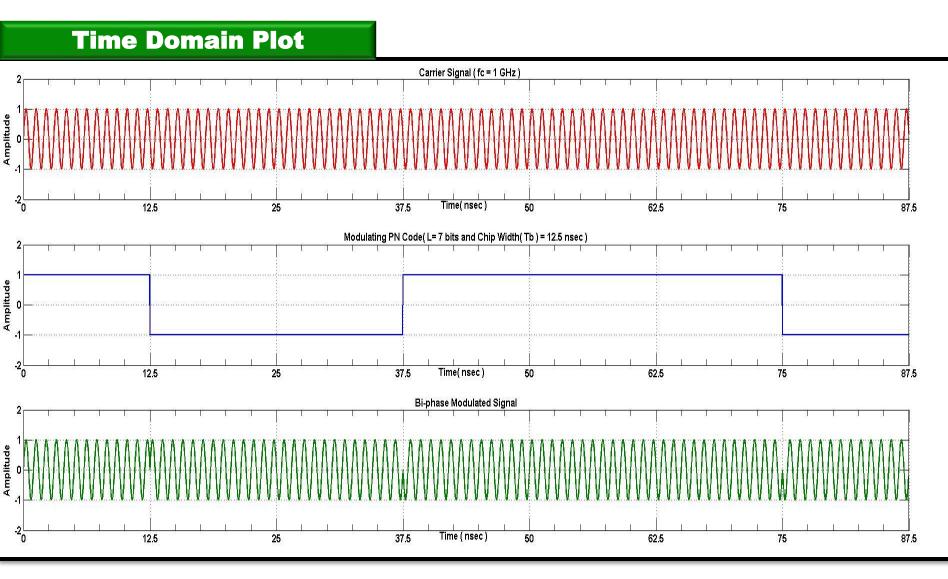
MATLAB Simulation Results For Pseudo-Randomly Bi-phase Coded Waveform

Pseudo-Randomly Bi-phase Coded Waveform



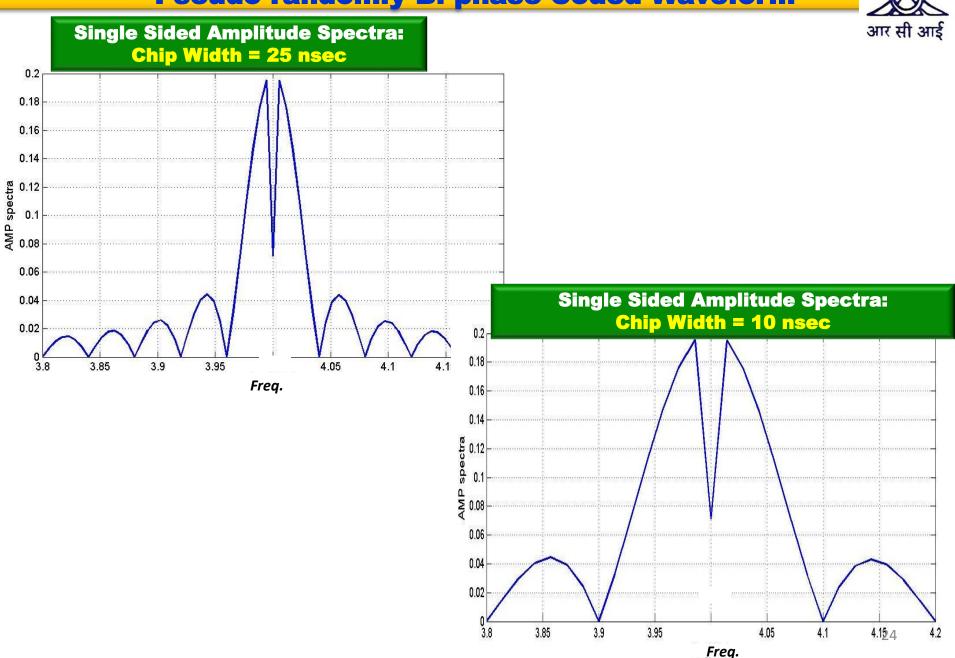






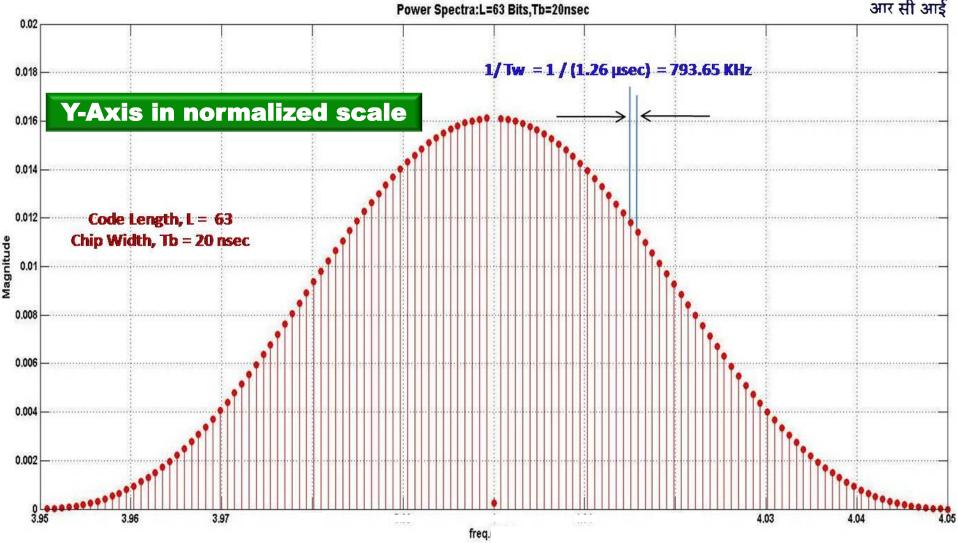
Amplitude Spectra

Pseudo-randomly Bi-phase Coded Waveform



Stem Plot Amplitude spectra of Biphase coded waveform

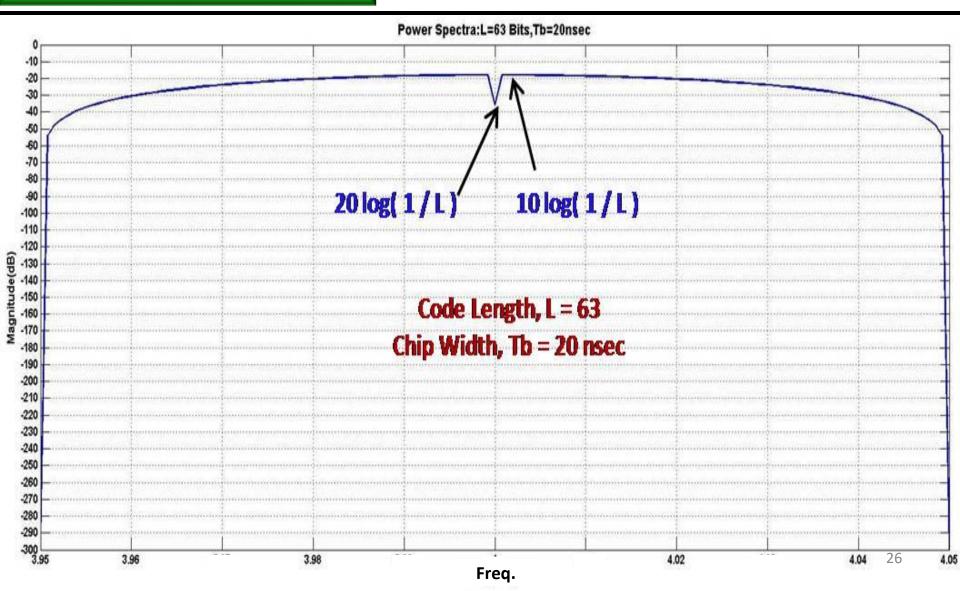




Continuous Plot Amplitude spectra of Biphase coded waveform

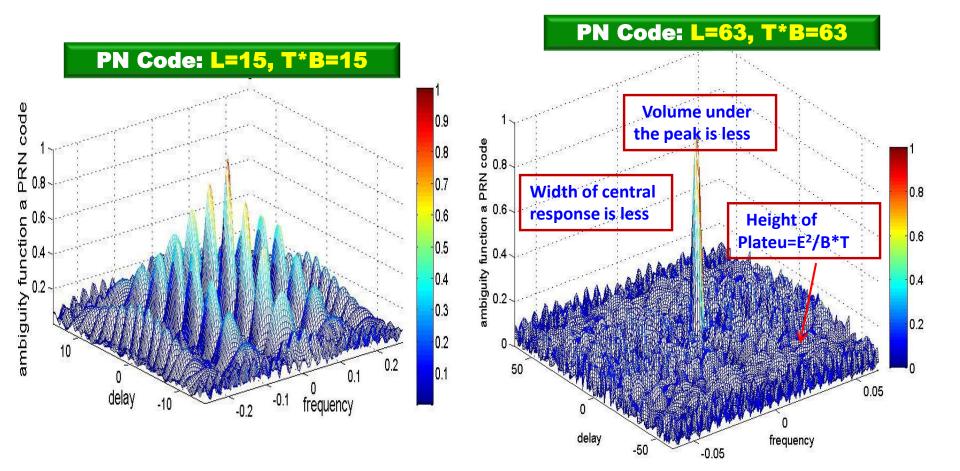


Y-Axis in dB



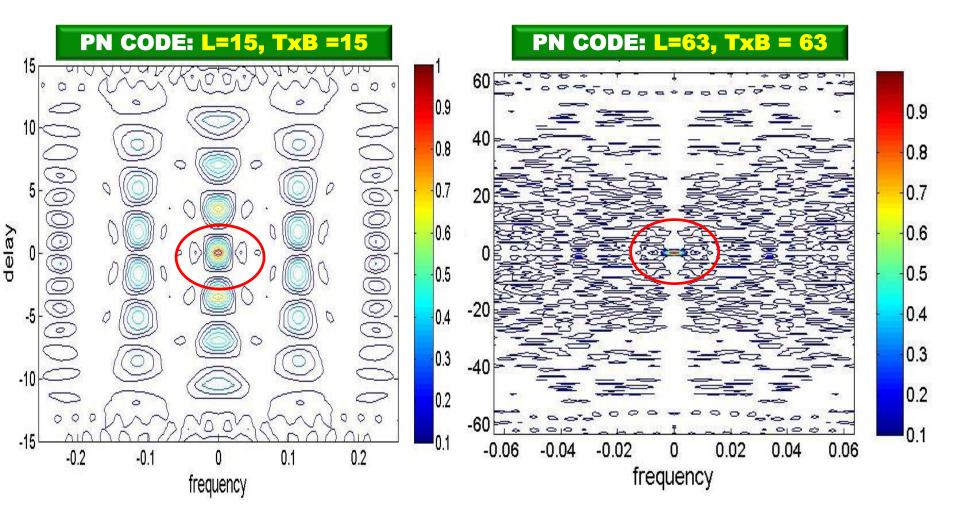
Comparison of Ambiguity Plots: PN Codes Effect Of Code Length





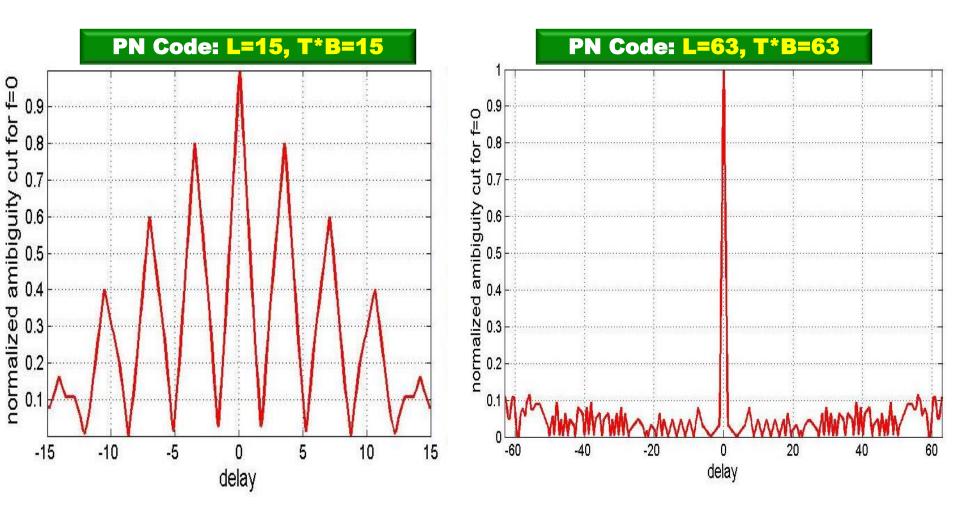
Contour Plots: PN Codes Effect Of Code Length





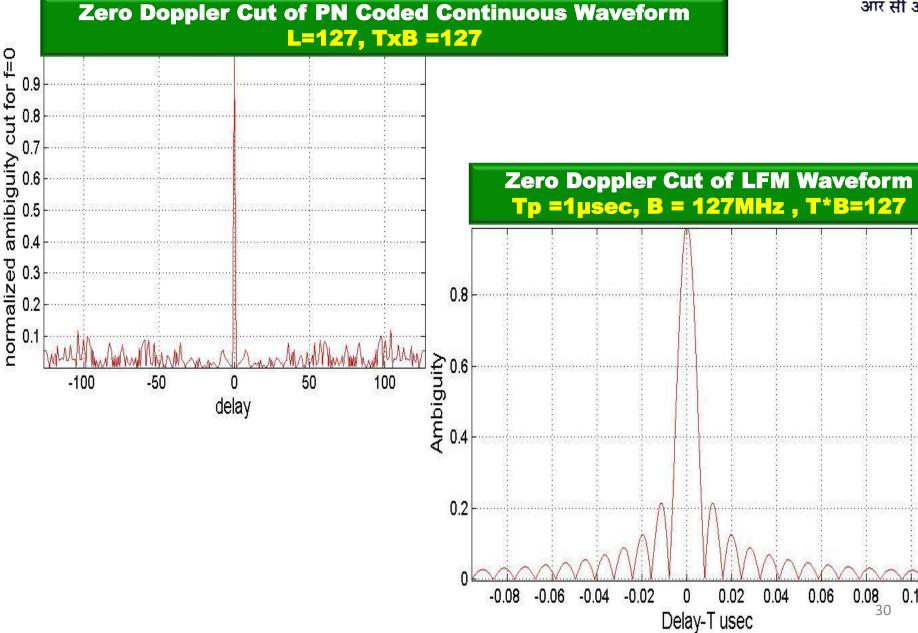
Zero Doppler cut of Ambiguity plots of PN Codes Effect Of Code Length



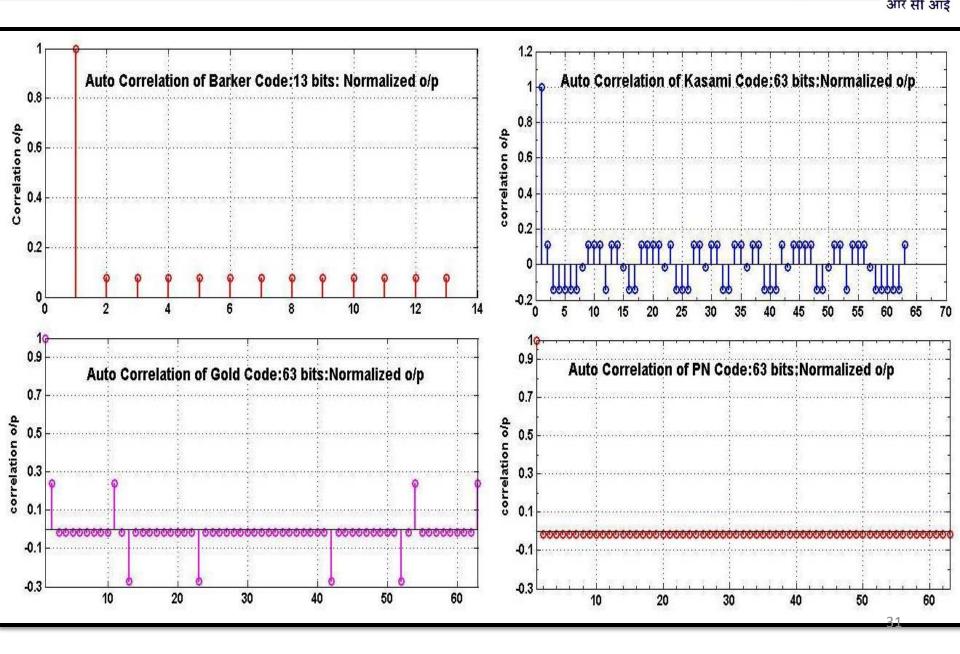


Comparison of Range Sidelobes of PN CODED & LFM Waveforms





Comparison of Autocorrelation Properties Effect of Different Type of Codes



Results: Comparative Evaluation of Radar Waveforms

Characteristic	Pulse Delay Ranging	FMCW	PN Coded CW
Tx Peak Power Requirement	High Due to absence of pulse compression.	Reduced Due to pulse compression	Reduced Due to Pulse compression. Lower than FMCW.
Range Resolution	ΔR=C x Tp/2 Tp=Pulse Width	$\Delta R=C/2 \times \Delta F$ $\Delta F=Frequency Sweep$ Higher range Resolution can be achieved easily. Higher T * B Product by increase in B = Δ F.	ΔR=C x Tb/2 Tb=Chip Width Limitation on low value of Tb due to ADC technology. Higher T * B Product by increase in Bandwidth = 1/Tb.
Long Range Measurement	Higher PRI.	Longer Waveform Period(T).	Longer Waveform Period(Tw).
	Low Duty Cycle.	100 % Duty Cycle. Lower sweep rate(Δ F/T)	100 % Duty Cycle.
	Req. Of High Peak Power	Higher T * B = T * Δ F Product by increase in T.	Higher T * B = Tw * B Product by Increase in Tw.

Results: Comparative Evaluation of Radar Waveforms

Characteristic	Pulse Delay Ranging	FMCW	PN Coded CW
T x B Product	T x B=Tp x 1/ Tp =1(Unity)	T x B =T x ΔF >>1 Δ F=Frequency Sweep	T x B=Tw x 1/Tb=L*Tb/Tb=L L=Code length(no. of bits)
	Tp=Pulse Width T=Period, B=Bandwidth	T=Period, ΔF =Bandwidth	Tb= Chip Width Lower than FMCW Radar.
Time Side lobes	Very High	Lower. Req. of Weighing filter following the Match filter. Use of Weighing filter results	Lowest. No Req. of Weighing filter following the Match filter. Higher SNR achieved.
Doppler		in reduced SNR.	Better Correlation achieved.
Tolerance	Good.	Supports doppler shift upto +/- B/10.	Fdmax=1/(4*Tw)
		Time side lobes performance remains intact with large doppler shifts.	Time side lobes performance & the peak of correlation deteriorates with large doppler shifts.

Results: Comparative Evaluation of Radar Waveforms

Characteristic	Pulse Delay Ranging	FMCW	PN Coded CW
Spill over & Tx Leakage	Less	Poor Performance.	Overall performance improvement by 15-20dB compared to FMCW.
	Due to discontinuous waveform pattern.	Operation limited to short range applications	Decrease in spill over by 1/L2 (i.e. 48 dB for L=127) compared to unmodulated radar signal.
Range Doppler Coupling	No.	Yes. Due to the Frequency Sweep Rate (ΔF/T).	No.
Low Probability of Intercept & ECCM	No LPI & ECCM features.	Better than Pulse delay ranging due to Pulse Compression.	Better LPI & ECCM capability compared to FMCW.

Thank You !