

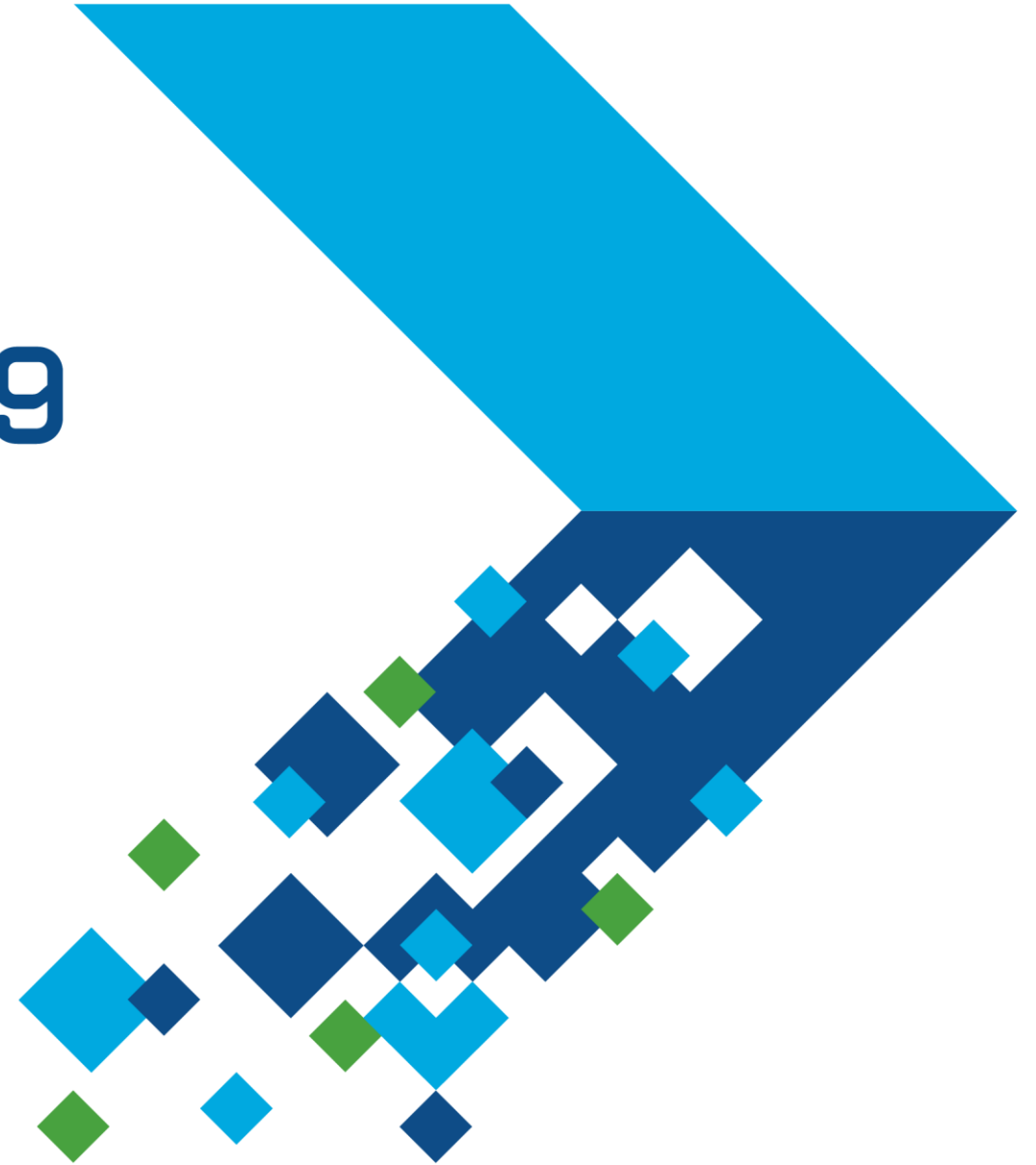
MATLAB EXPO 2019

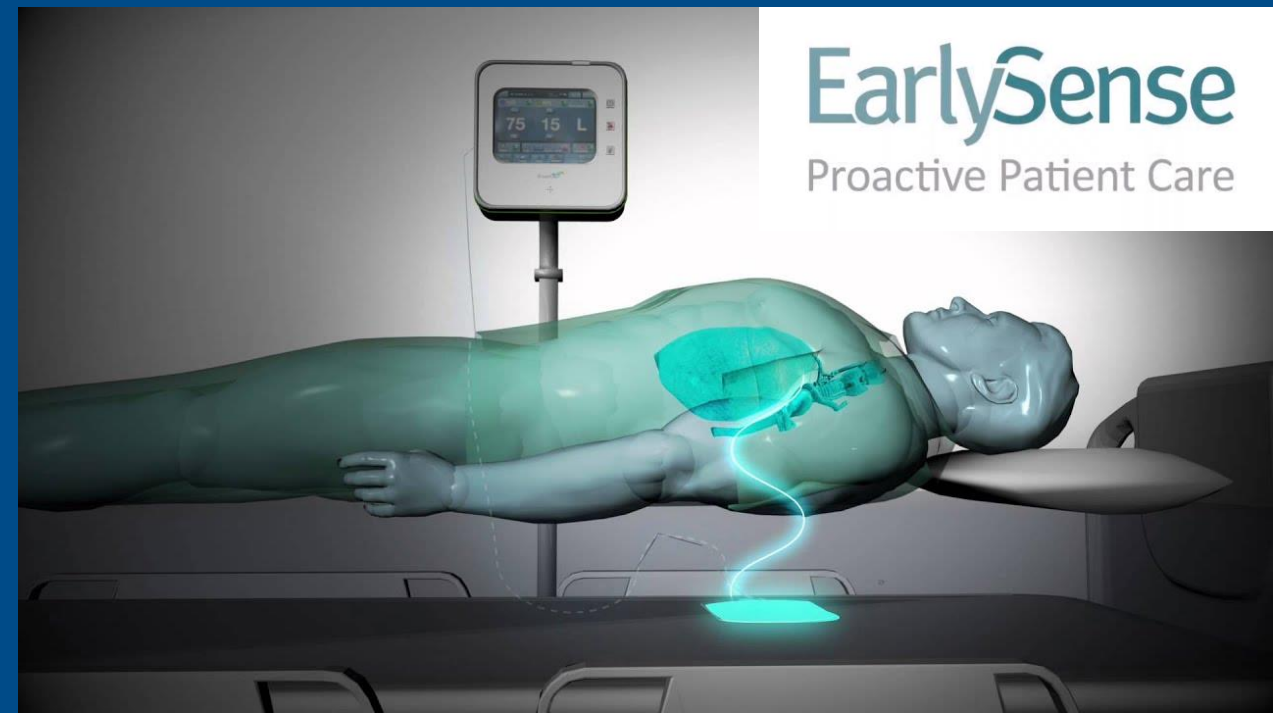
What's New in MATLAB and Simulink

 Prashant.Rao@mathworks.in

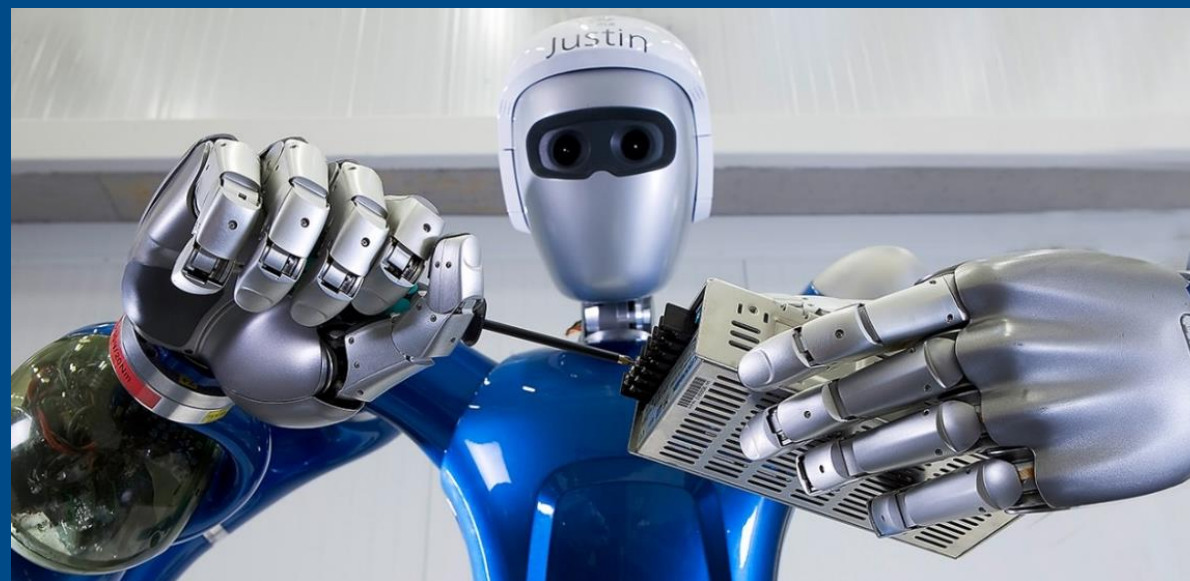
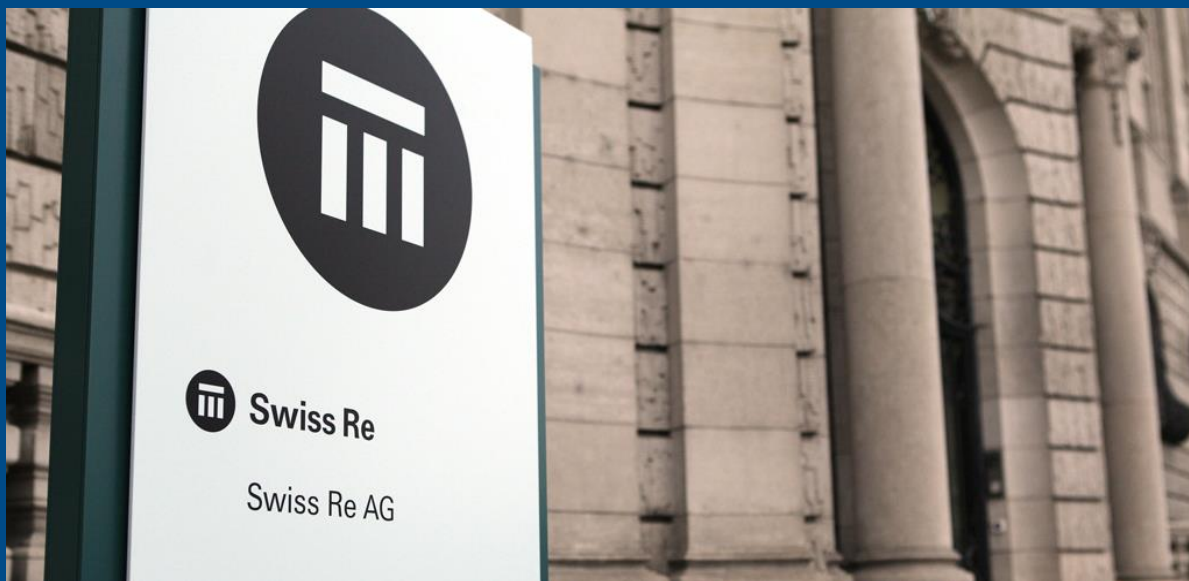
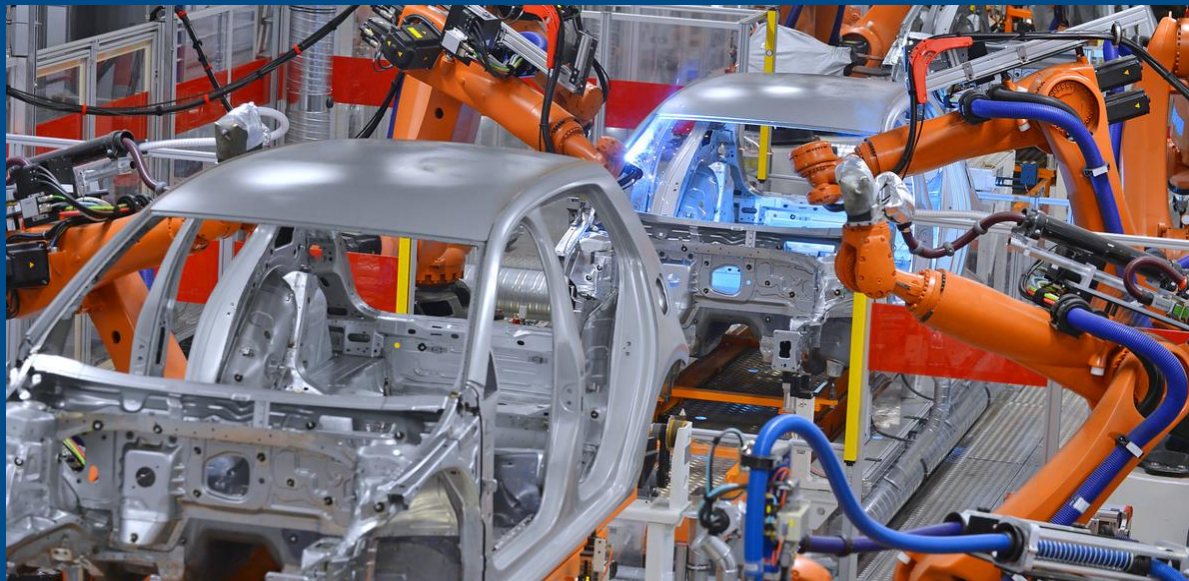
 @_prashantrao_

 prashantrao





Algorithms in Everything



Using MATLAB & Simulink to Build Algorithms in Everything

Simplifying your work...

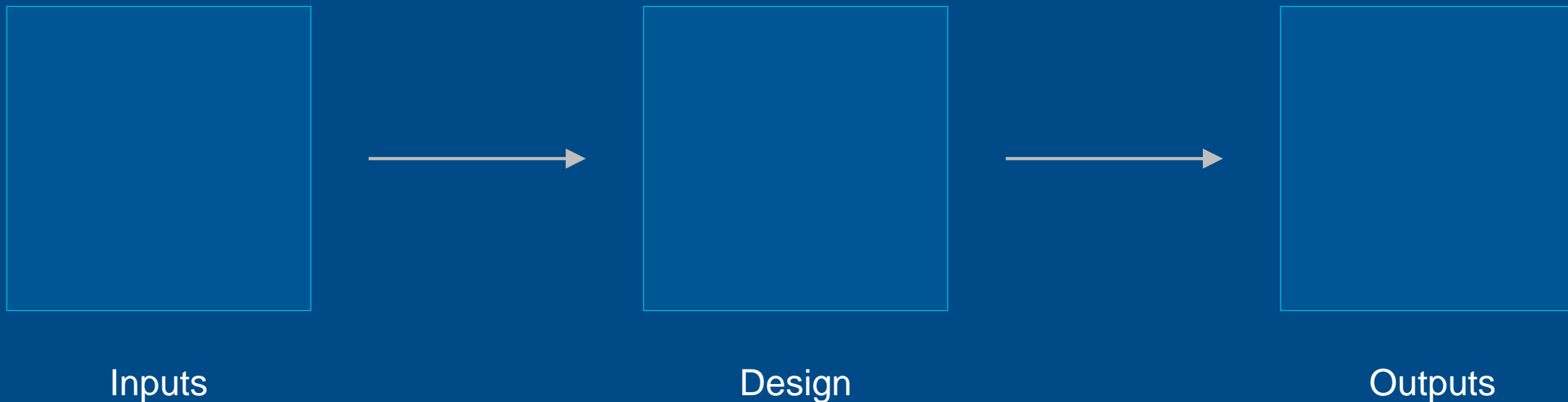
...often at higher levels of abstraction.



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Using MATLAB & Simulink to Build Algorithms in Everything



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Artificial Intelligence

*The capability of a machine to
match or exceed intelligent human behavior by
training a machine
to learn the desired behavior*

There are two ways to get a computer to do what you want

Traditional Programming

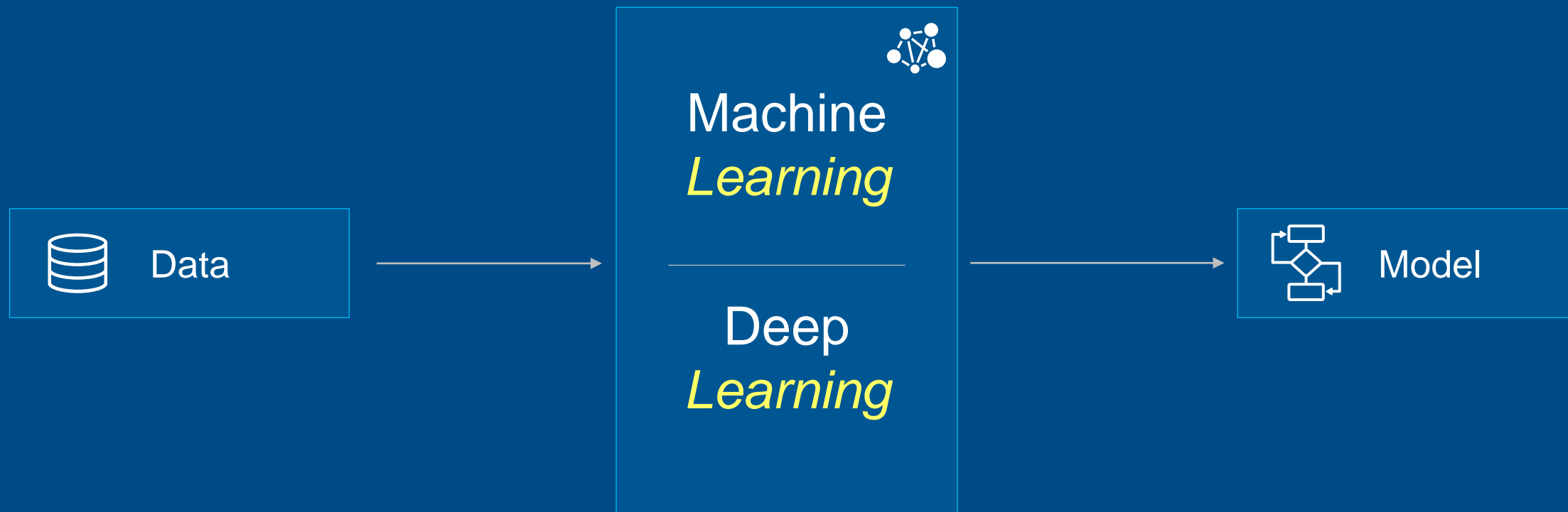


There are two ways to get a computer to do what you want

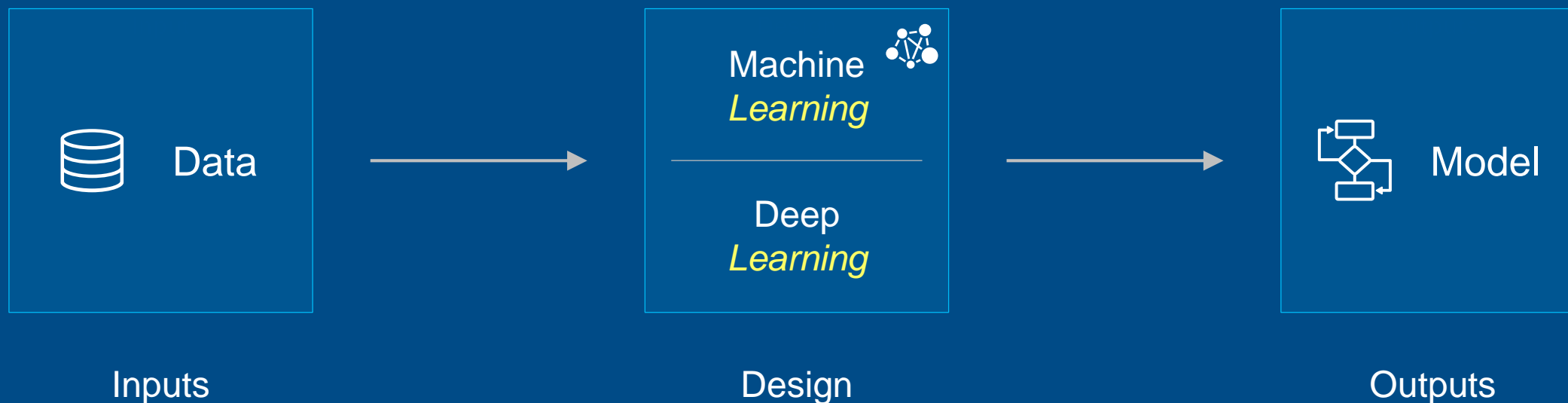
Machine Learning



Artificial Intelligence



Using MATLAB and Simulink to Build **Deep Learning Models**



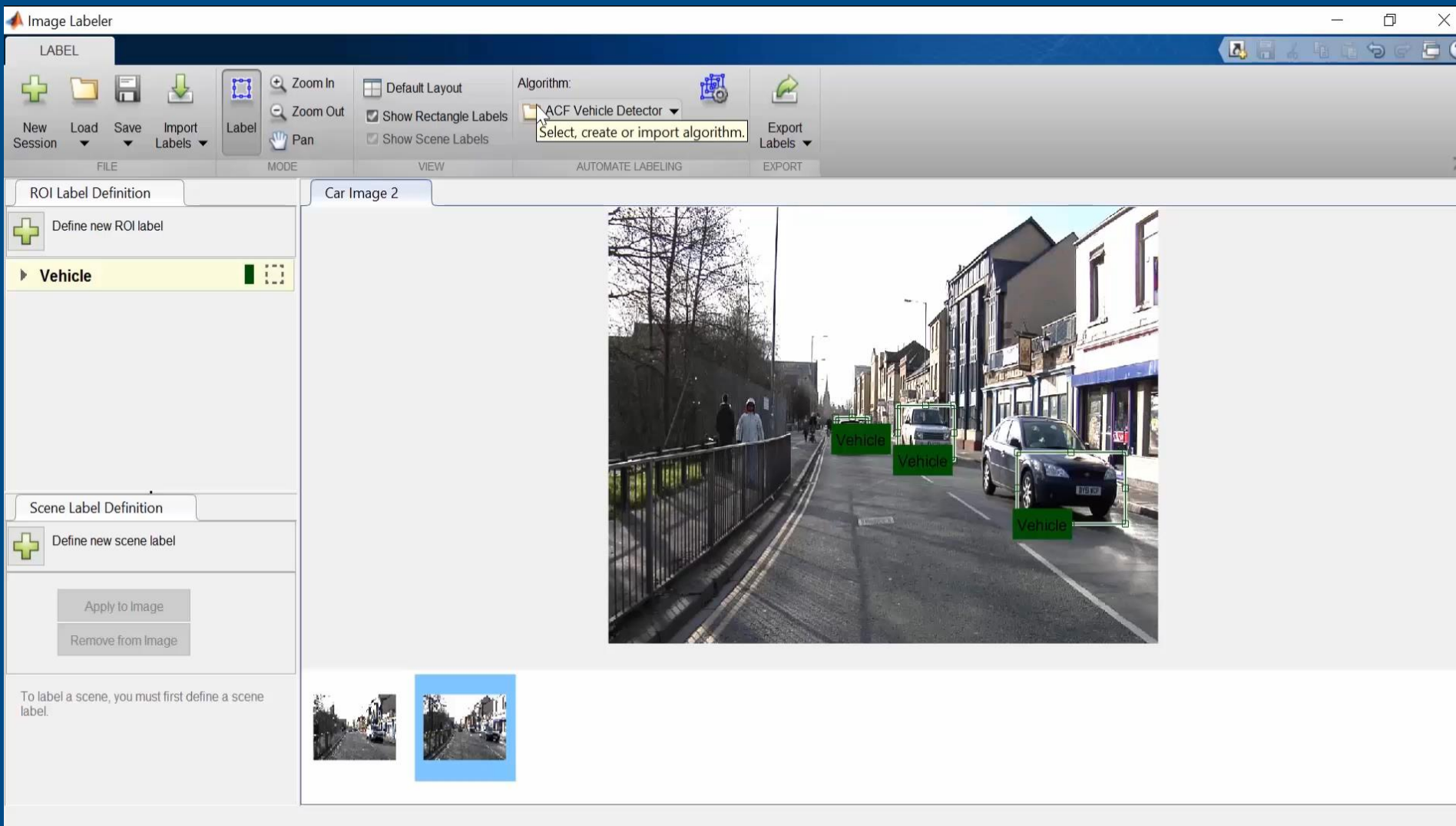
MATLAB® & SIMULINK®



Using Apps for Ground Truth Labeling

Image and Video Data

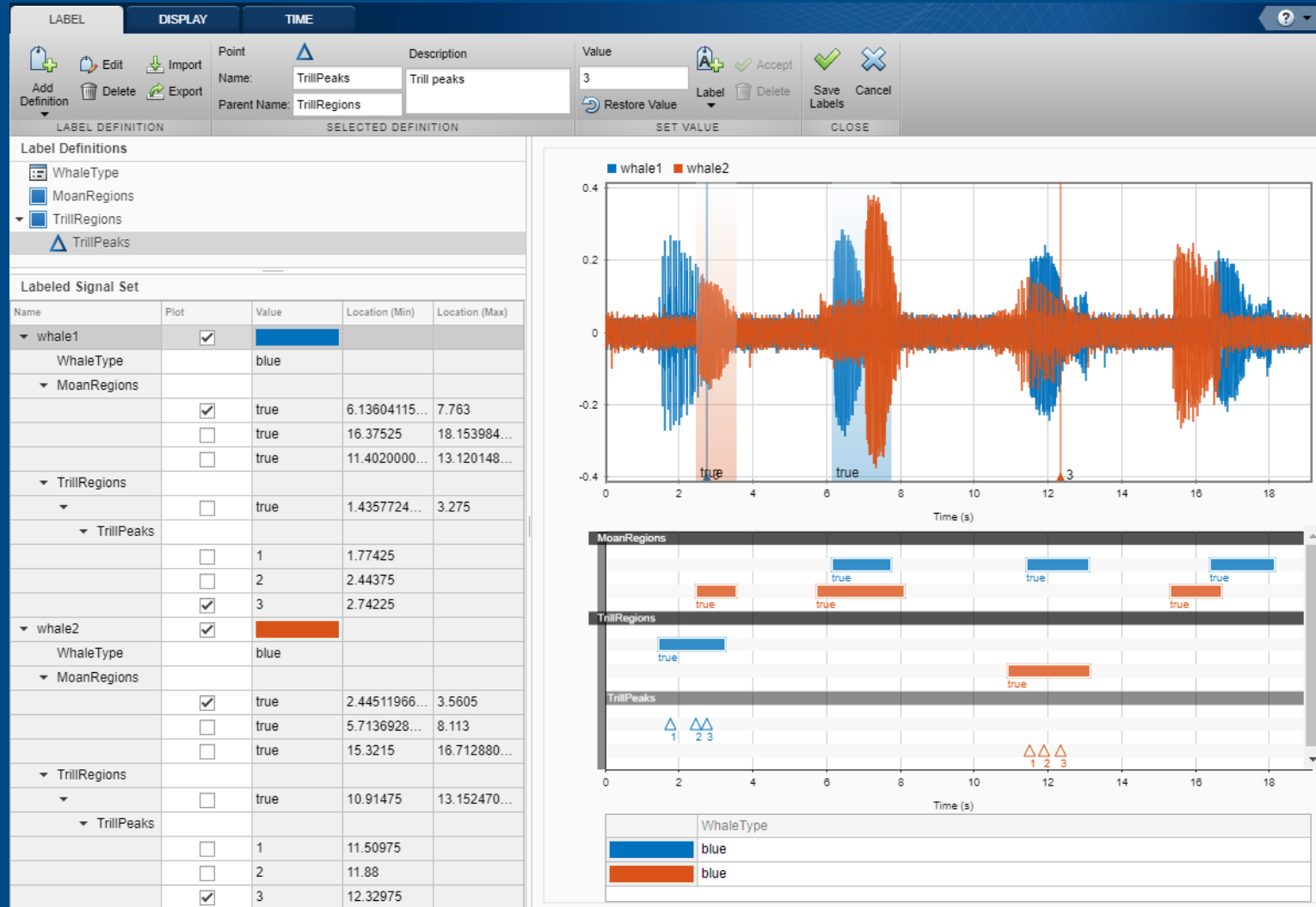
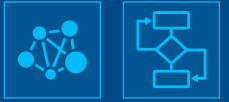
Input



Using Apps for Ground Truth Labeling

Signal Data

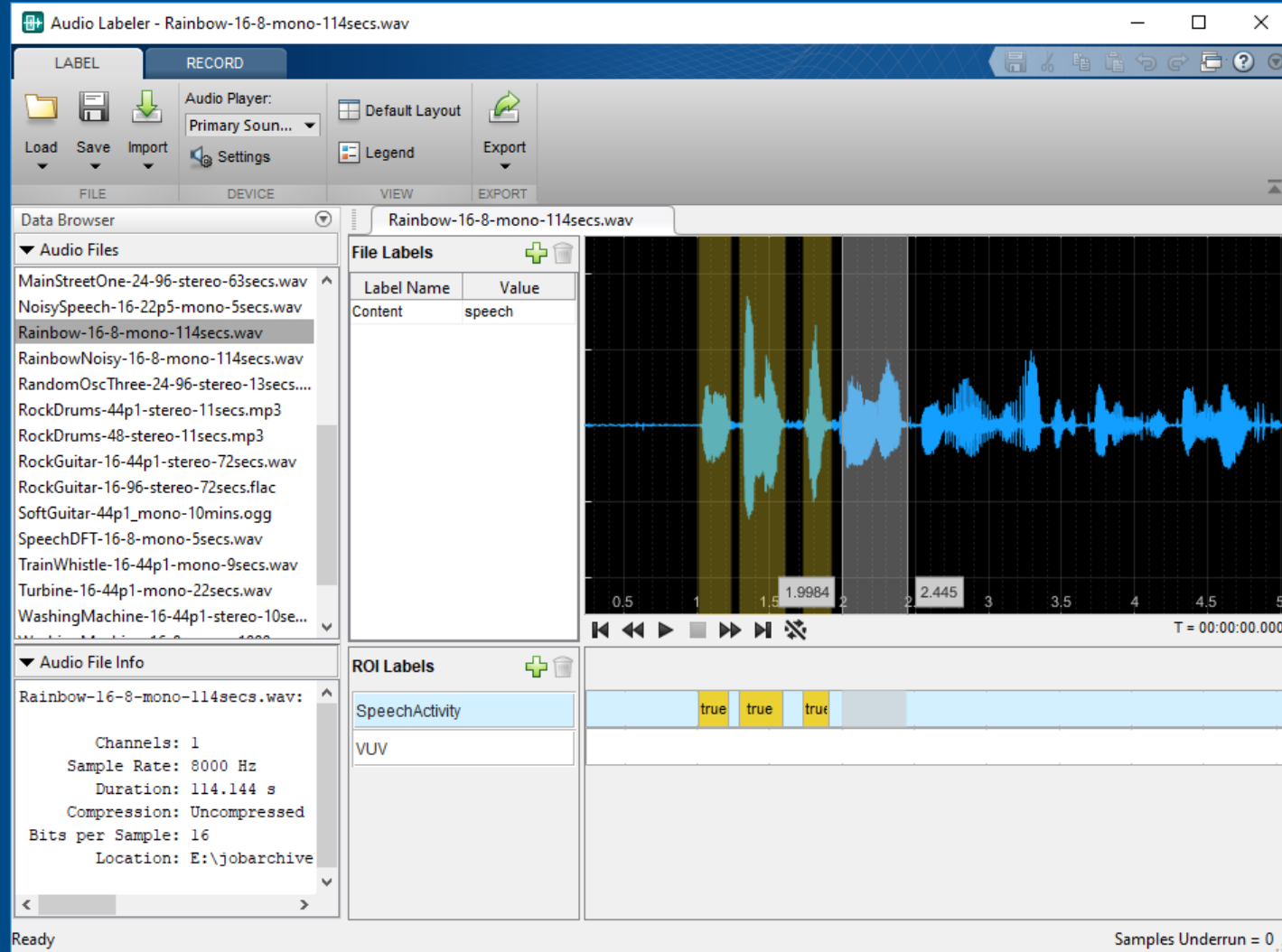
Input



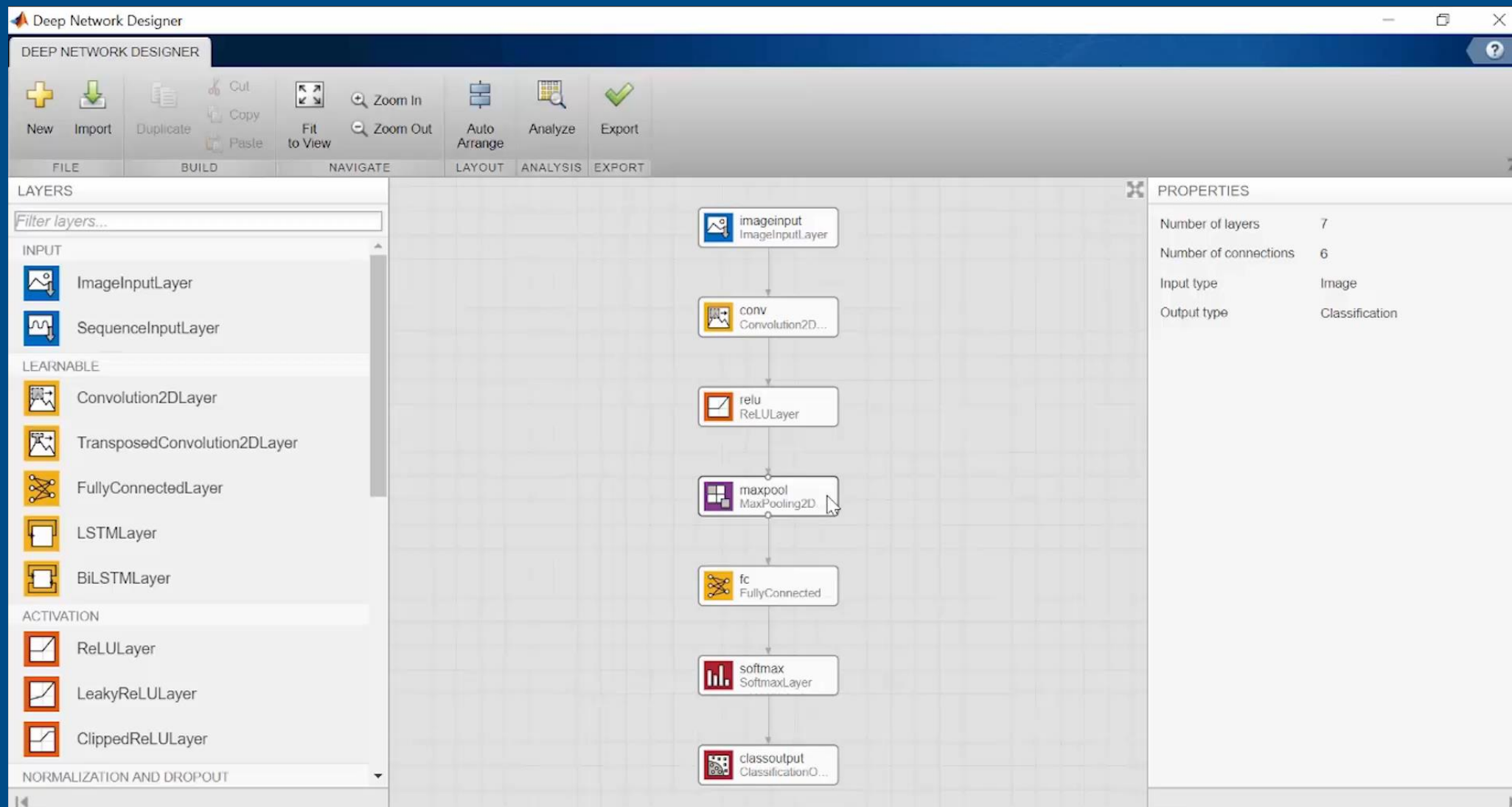
Using Apps for Ground Truth Labeling

Audio Data

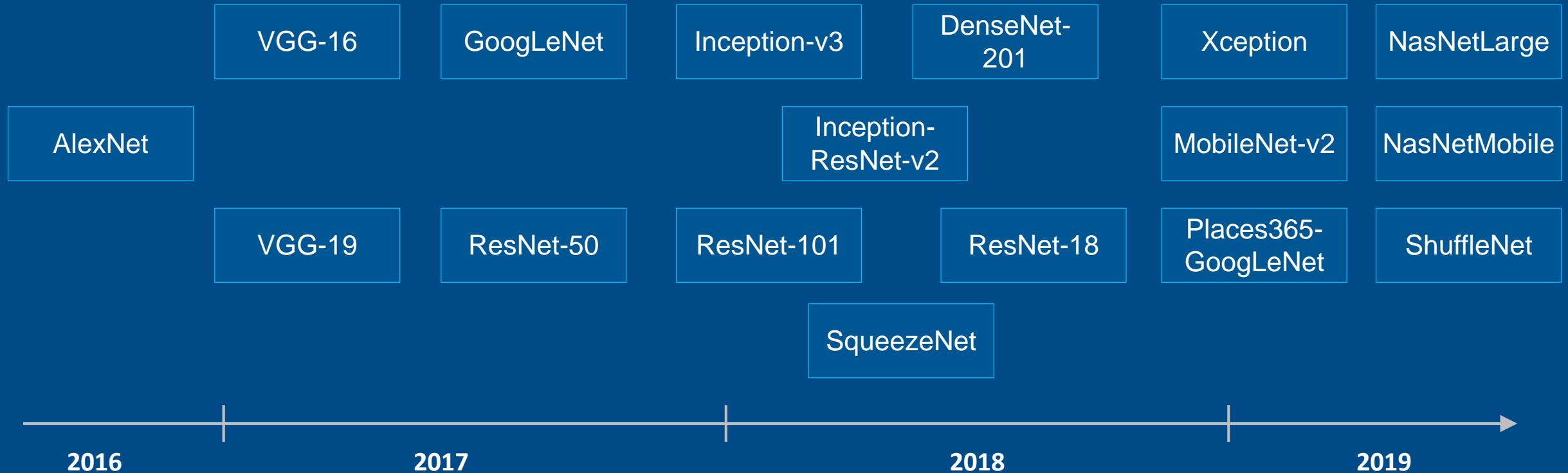
Input



Using Apps for Designing Deep Learning Networks

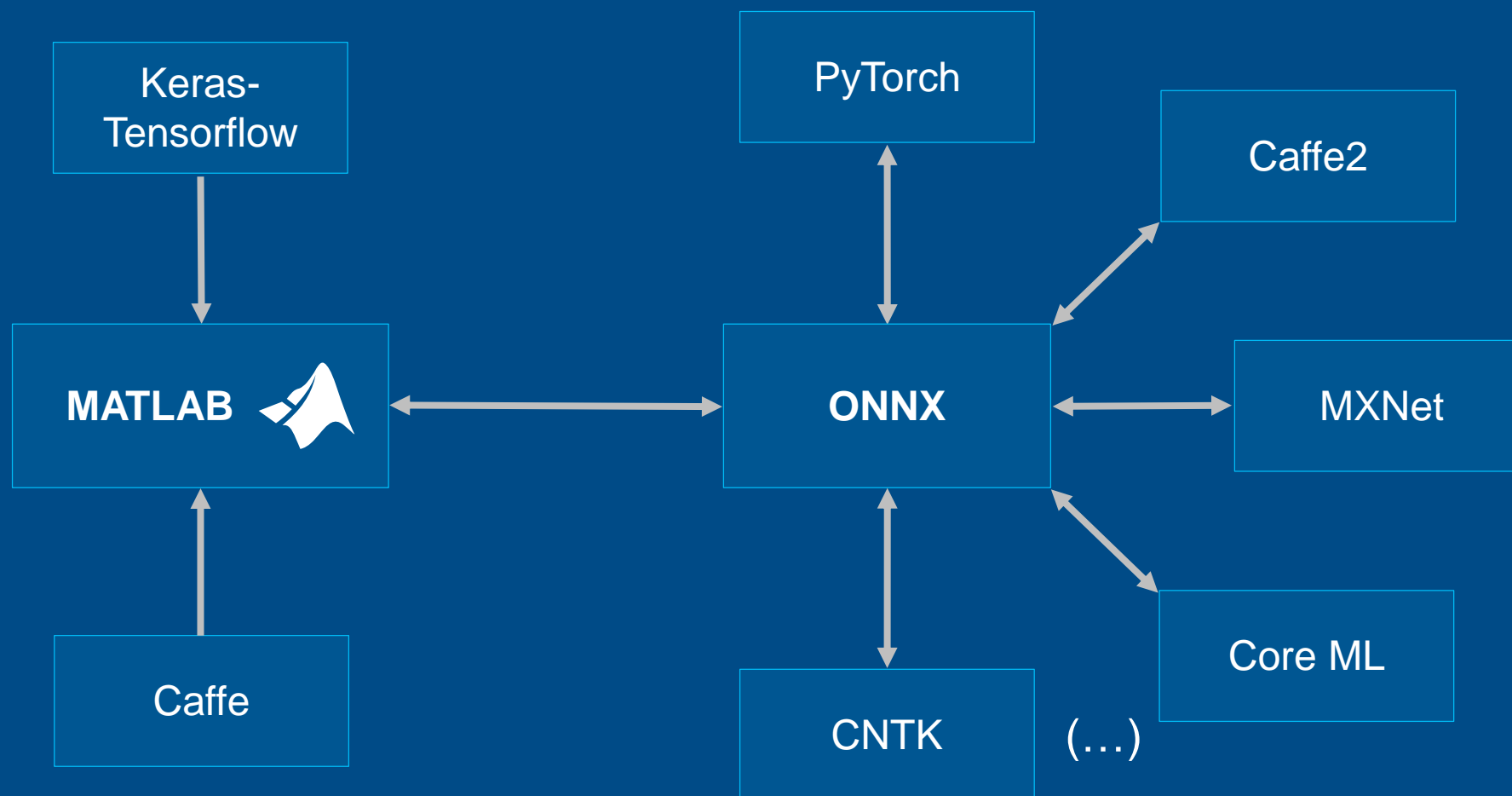


Using Transfer Learning with Pre-trained Models

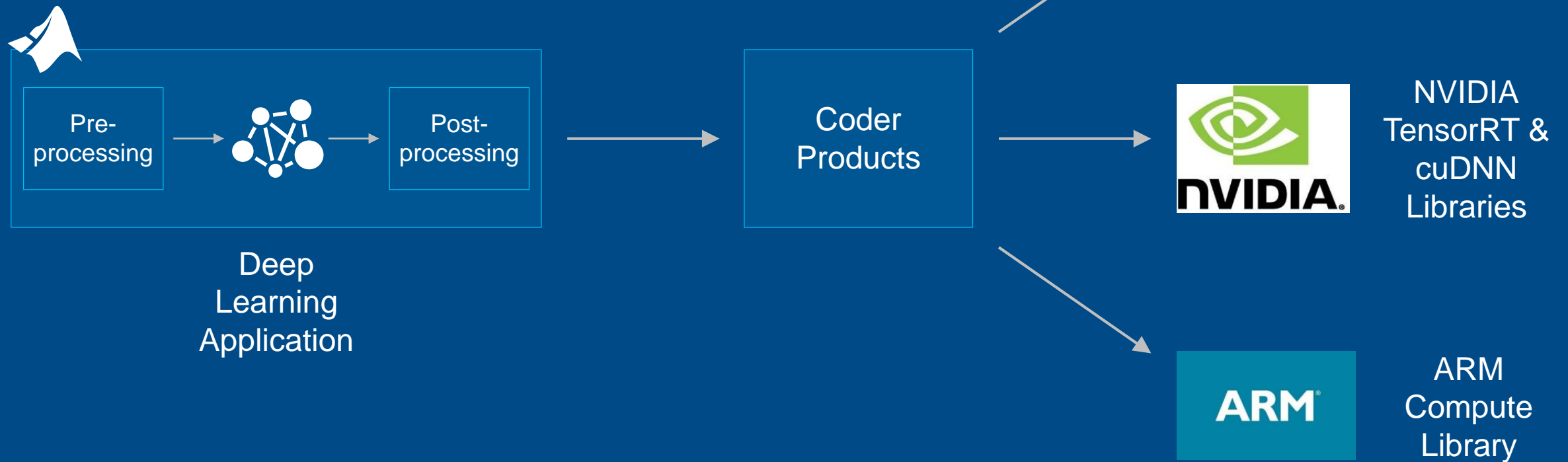




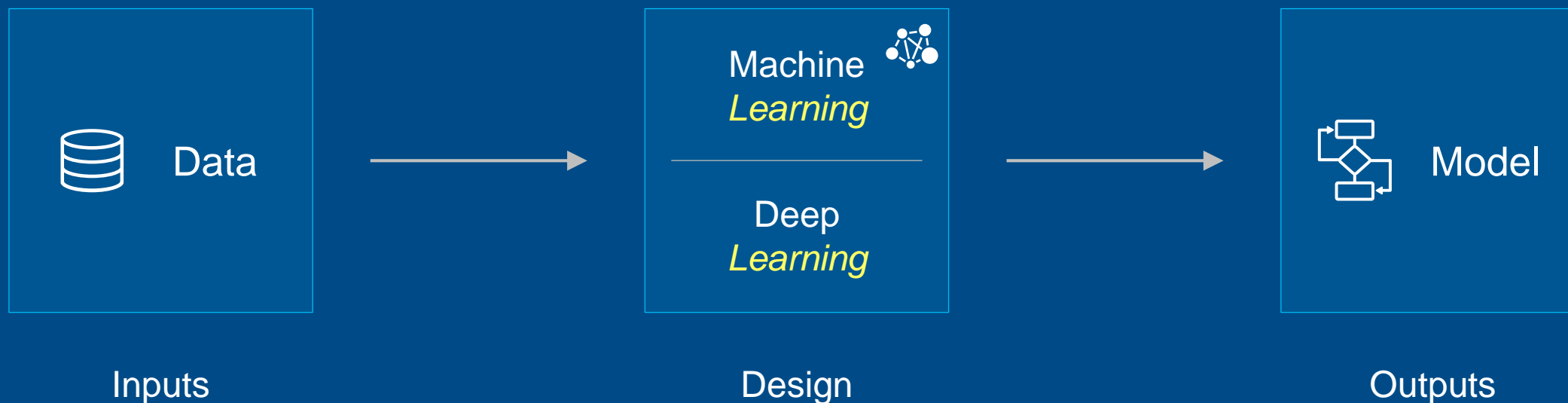
Using Models from Other Frameworks



Deploying Deep Learning Applications



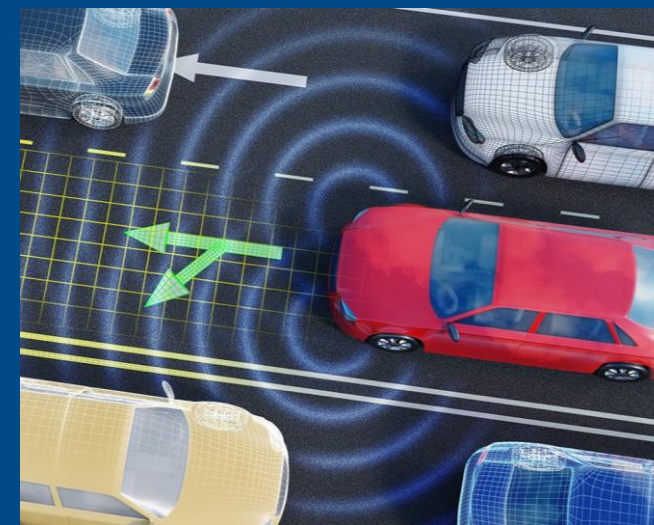
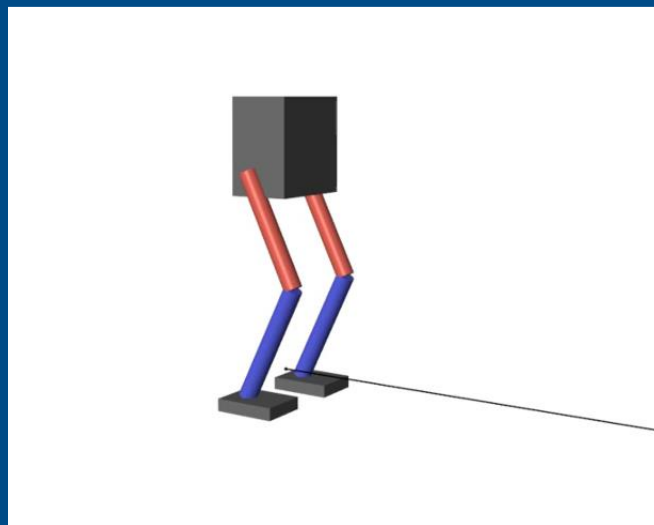
Using MATLAB and Simulink for Reinforcement Learning



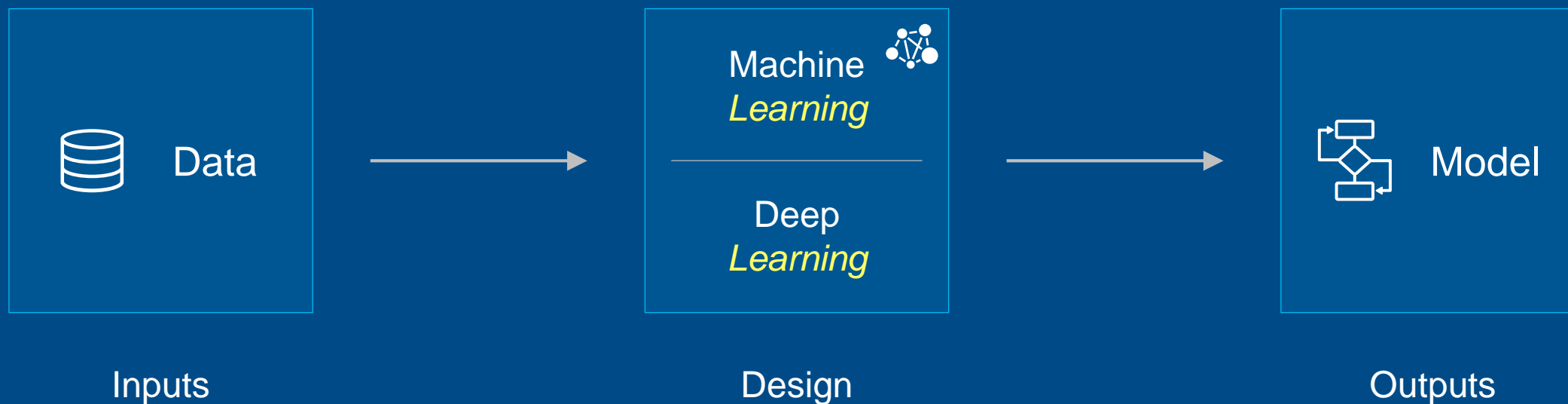
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Using MATLAB and Simulink for Reinforcement Learning



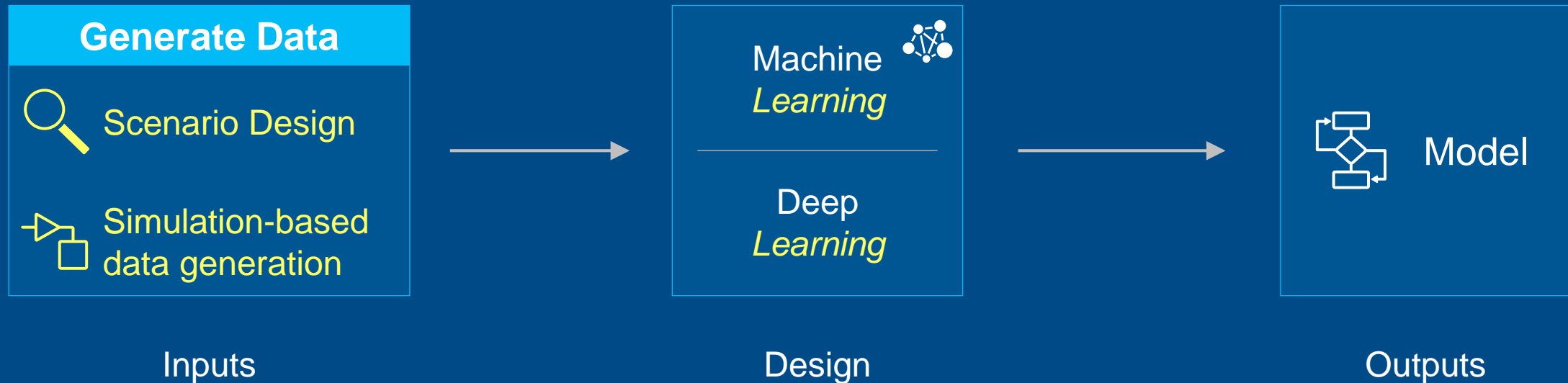
Using MATLAB and Simulink for Reinforcement Learning



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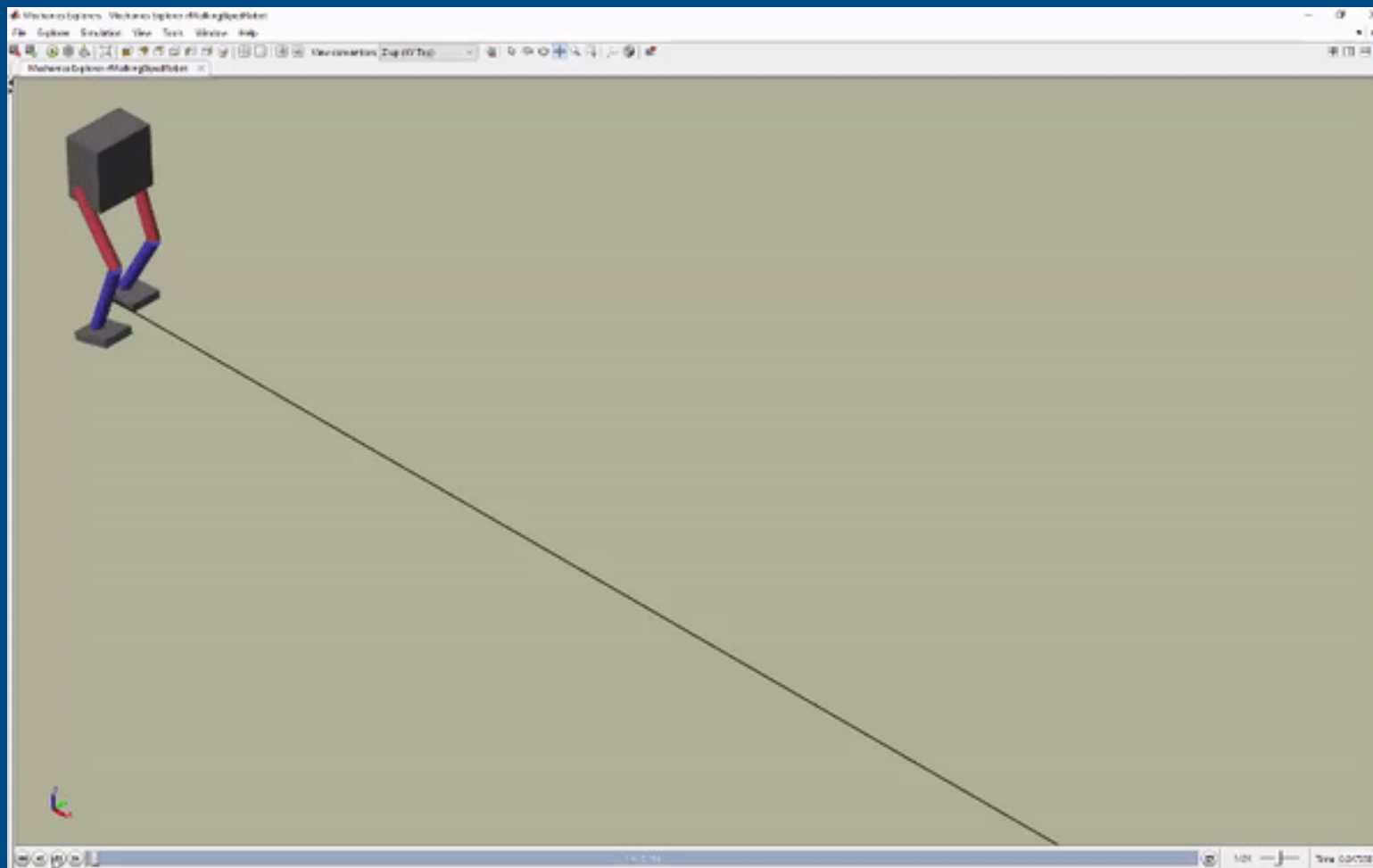
Using MATLAB and Simulink for Reinforcement Learning



MATLAB® & SIMULINK®



Using MATLAB and Simulink for Reinforcement Learning



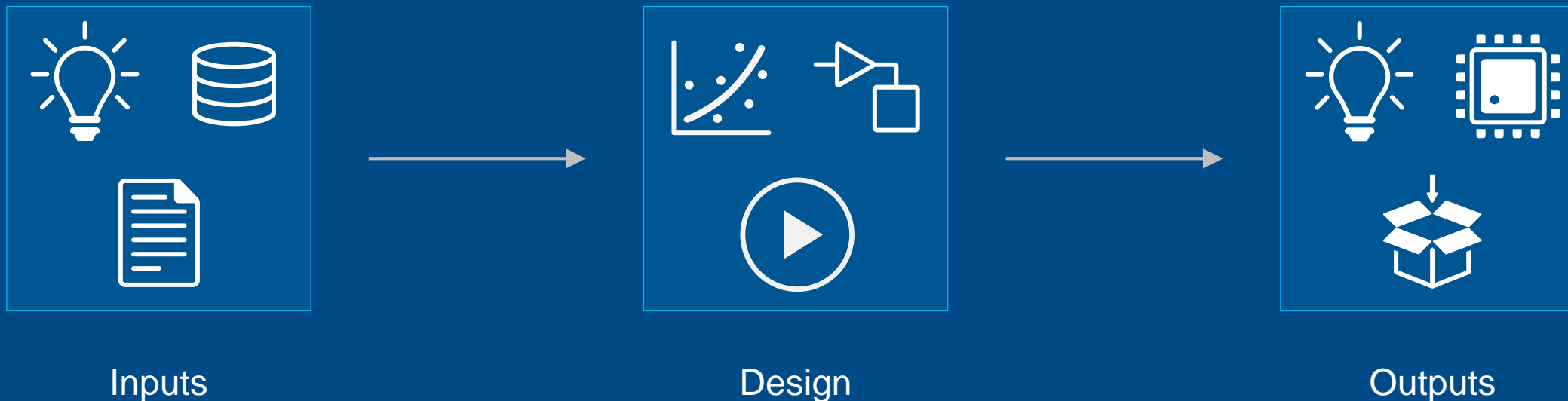
Using MATLAB and Simulink for Reinforcement Learning



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Using MATLAB & Simulink to Build Algorithms in Everything



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Working with Text Data



```

Vehicle_Repairs.csv
Dept,JobDate,jobno,VehicleId,UnitNo,Reason,Notes,CostParts,CostLabor,CostTotal
1020,01/06/2015 12:00:00 AM,14073,118743,14,04 DRIVER'S REPORT,"PM SERVICE, CHECK TURN SIGNAL, CLUNKING NOISE WHEN DRIVING",493.85,0,493.85
1020,01/14/2015 12:00:00 AM,14232,230973,13,08 PM SERVICE ***,"SERVICEROB,EXT,5604",38.869999999999997,0,38.869999999999997
2111,01/02/2015 12:00:00 AM,14006,1243,116,04 DRIVER'S REPORT,NEED 4 PLOW PINS,45,0,45
2111,01/02/2015 12:00:00 AM,14140,B39109 ,178,04 DRIVER'S REPORT,INSTALL SPINNER ASSY,0,0,0
2111,01/03/2015 12:00:00 AM,14163,574950,215,13 SNOW BREAKDOWN,DONT START,0,0,0
2111,01/05/2015 12:00:00 AM,14169,A00413 ,283,04 DRIVER'S REPORT,DOG BONE PIN BROKEN,20,0,20
2111,01/06/2015 12:00:00 AM,14000,766153,248,08 PM SERVICE ***,"NEED SERVICE, CHECK BRAKES",387.17,0,387.17
2111,01/06/2015 12:00:00 AM,14155,525670,232,04 DRIVER'S REPORT,HYD CAP CHECK ENGINE LIGHT ON,12.95,0,12.95
2111,01/06/2015 12:00:00 AM,14157,621909,213,40 NEGLIGENCE,TARP VALVE STICKINGRIGHT SIDE MIRROR BRACKET BROKEN,50.02,0,50.02
2111,01/06/2015 12:00:00 AM,14164,1226,117,13 SNOW BREAKDOWN,HANDLES IN CAB LOOSE,0,0,0
2111,01/06/2015 12:00:00 AM,14165,525999,114,04 DRIVER'S REPORT,NO PLOW LIGHTS,0,0,0
2111,01/06/2015 12:00:00 AM,14172,B34632 ,276,10 ROADCALL,WILL NOT START,0,0,0
2111,01/06/2015 12:00:00 AM,14174,1469,122,10 ROADCALL,WILL NOT START,0,0,0
2111,01/06/2015 12:00:00 AM,14175,68932,147,10 ROADCALL,WILL NOT START,0,0,0
2111,01/06/2015 12:00:00 AM,14176,68933,148,10 ROADCALL,WILL NOT START,0,0,0
2111,01/06/2015 12:00:00 AM,14177,621907,208,10 ROADCALL,WILL NOT START,0,0,0
2111,01/06/2015 12:00:00 AM,14181,337657,218,04 DRIVER'S REPORT,CONVEORY NOT WORKING,0,0,0
2111,01/06/2015 12:00:00 AM,14182,D-1920 ,164,10 ROADCALL,DONT START,0,0,0
2111,01/06/2015 12:00:00 AM,14183,525998,217,10 ROADCALL,DONT START,0,0,0
2111,01/06/2015 12:00:00 AM,14184,526000,225,10 ROADCALL,DONT START,0,0,0
2111,01/06/2015 12:00:00 AM,14185,621921,214,04 DRIVER'S REPORT,CONVORY NOT WORKING,0,0,0
2111,01/07/2015 12:00:00 AM,14188,001469 ,201,04 DRIVER'S REPORT,needs def/jim f,0,0,0
2111,01/07/2015 12:00:00 AM,14190,337656,219,04 DRIVER'S REPORT,NEEDS FLOOR MATTS,65.069999999999993,0,65.069999999999993
2111,01/07/2015 12:00:00 AM,14191,B34632 ,276,10 ROADCALL,DONT START,0,0,0
2111,01/07/2015 12:00:00 AM,14196,1222,118,04 DRIVER'S REPORT,HARDWARE FOR REAR SPRINGS,14.32,0,14.32
2111,01/07/2015 12:00:00 AM,14199,52565,626,04 DRIVER'S REPORT,WASHER FLUIDDEF,28.88,0,28.88
2111,01/09/2015 12:00:00 AM,14107,1467,121,08 PM SERVICE ***,"REMOVE & REPLACE REAR SPRINGS, CHECK COOLANT TUBESPM SERVICE",4697.55,0,

```

Working with Text Data

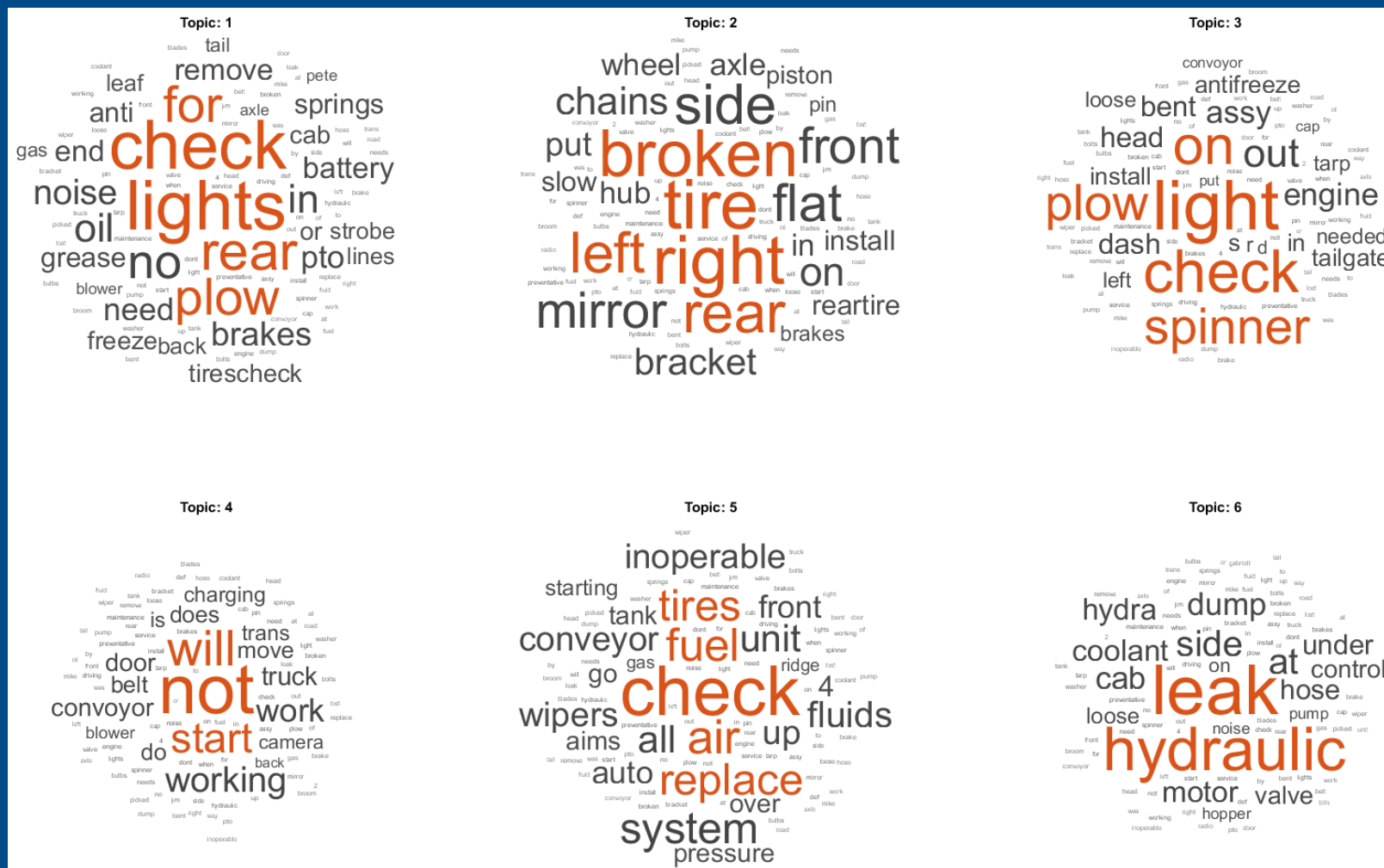
Input



```
t = readtable(filename, 'TextType', 'string');
disp(t(1:20,6:7))
```

Reason			Notes
"04	DRIVER'S REPORT"		"PM SERVICE, CHECK TURN SIGNAL, CLUNKING NOISE WHEN DRIVING"
"08	PM SERVICE	***"	"SERVICEROB,EXT,5604"
"04	DRIVER'S REPORT"		"NEED 4 PLOW PINS"
"04	DRIVER'S REPORT"		"INSTALL SPINNER ASSY"
"13	SNOW BREAKDOWN"		"DONT START"
"04	DRIVER'S REPORT"		"DOG BONE PIN BROKEN"
"08	PM SERVICE	***"	"NEED SERVICE, CHECK BRAKES"
"04	DRIVER'S REPORT"		"HYD CAP CHECK ENGINE LIGHT ON"
"40	NEGLIGENCE"		"TARP VALVE STICKINGRIGHT SIDE MIRROR BRACKET BROKEN"
"13	SNOW BREAKDOWN"		"HANDLES IN CAB LOOSE"
"04	DRIVER'S REPORT"		"NO PLOW LIGHTS"
"10	ROADCALL"		"WILL NOT START"
"10	ROADCALL"		"WILL NOT START"
"10	ROADCALL"		"WILL NOT START"
"10	ROADCALL"		"WILL NOT START"
"10	ROADCALL"		"WILL NOT START"
"04	DRIVER'S REPORT"		"CONVEORY NOT WORKING"
"10	ROADCALL"		"DONT START"
"10	ROADCALL"		"DONT START"
"10	ROADCALL"		"DONT START"

A diagram showing a simple neural network with three layers. The first layer is labeled 'Input' and contains a single blue square node. The second layer is labeled 'Hidden' and contains a single blue square node. The third layer is labeled 'Output' and contains a single blue square node. Arrows indicate the flow of information from the Input layer to the Hidden layer, and from the Hidden layer to the Output layer.



Nouns

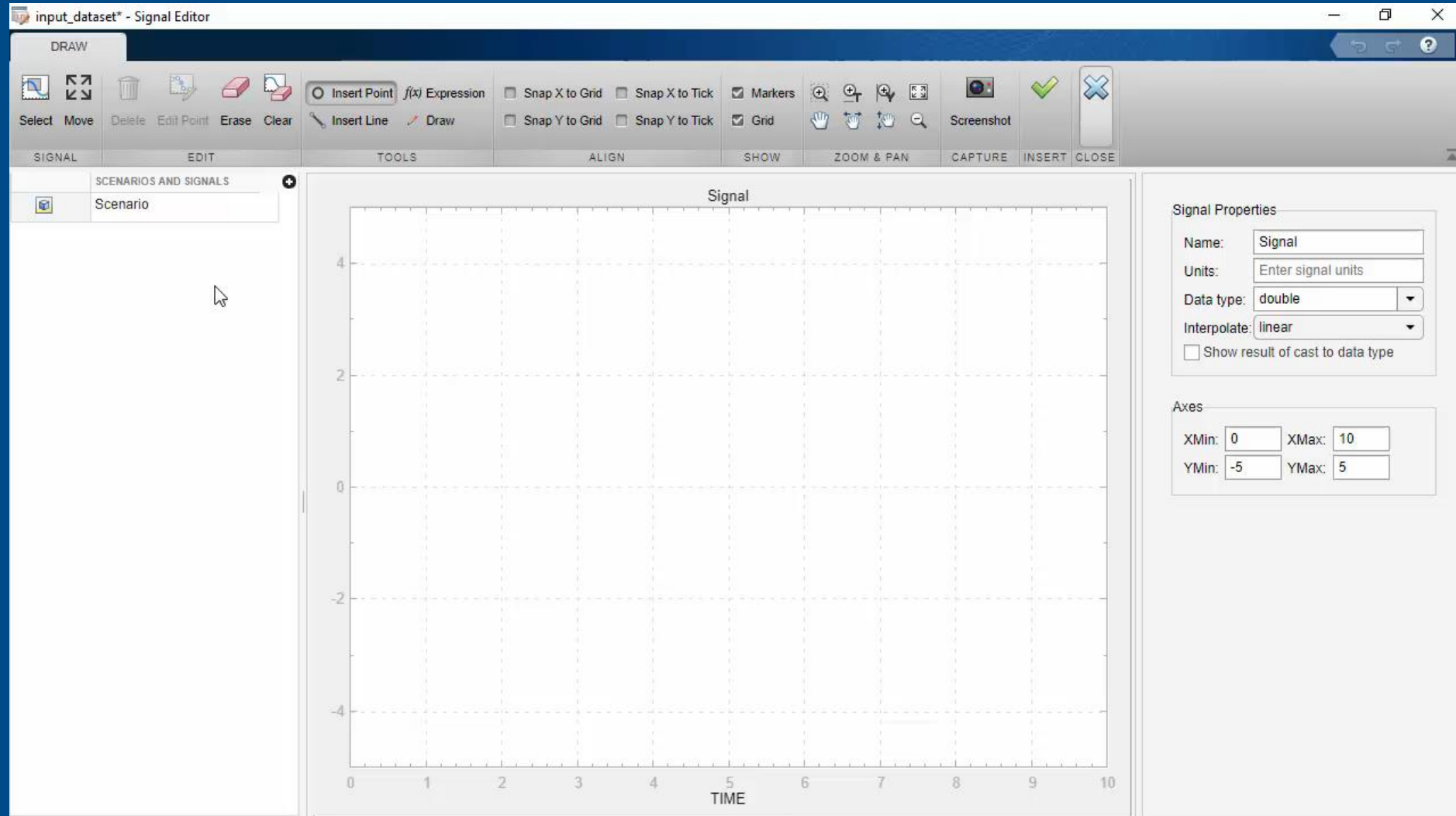


Nouns

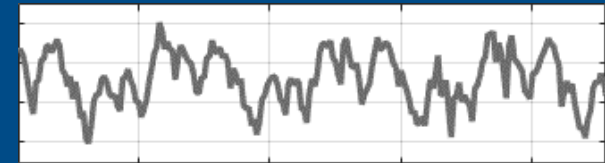
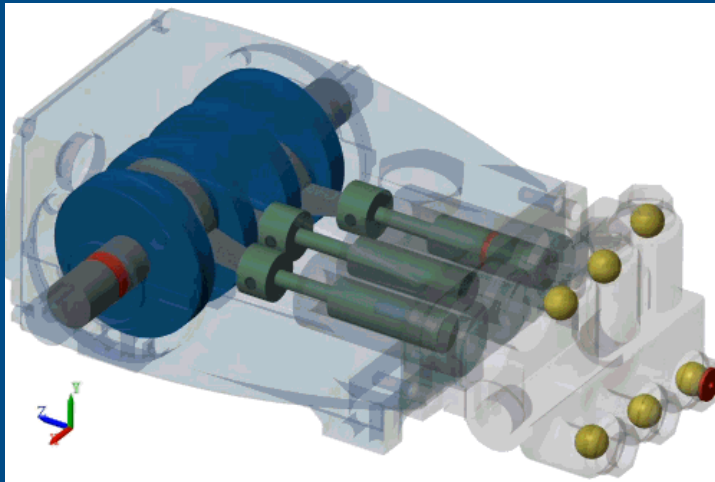
[illegible]

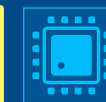
Creating Your Own Data

Input

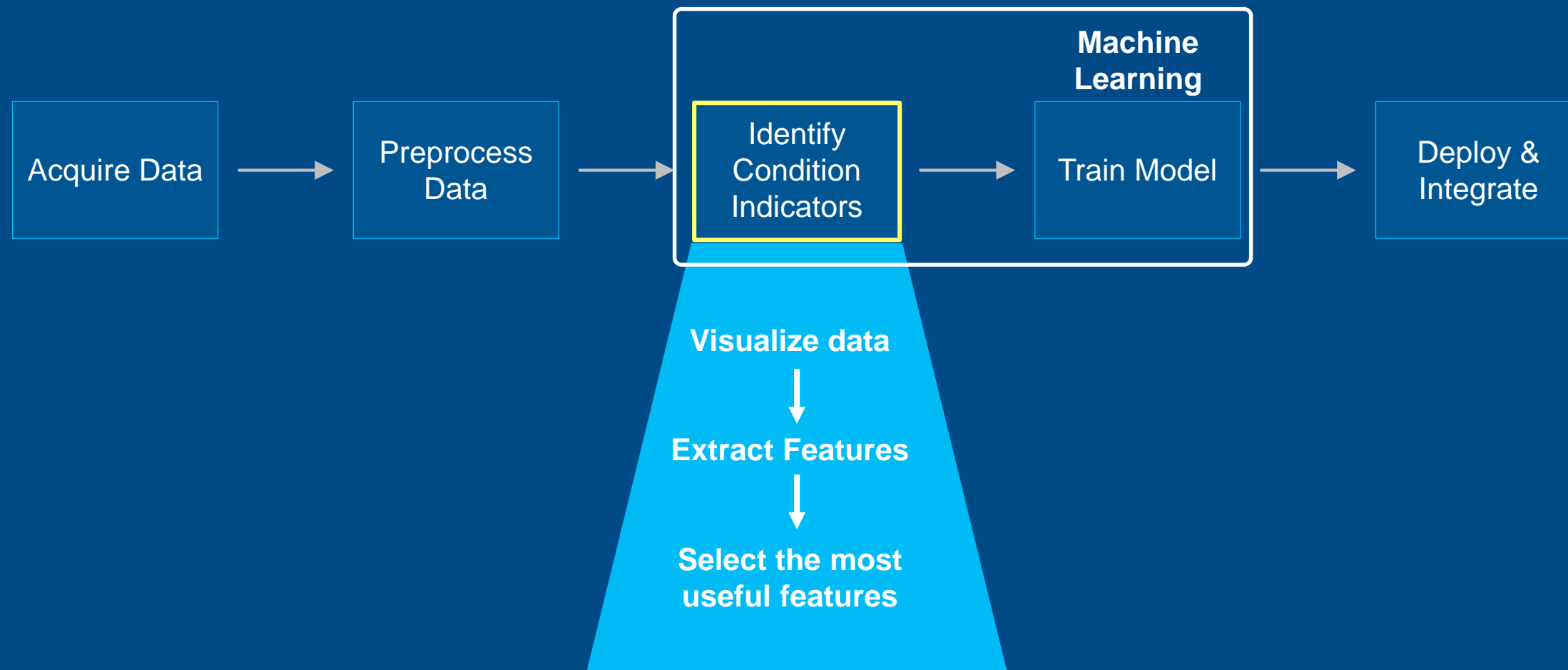


Input

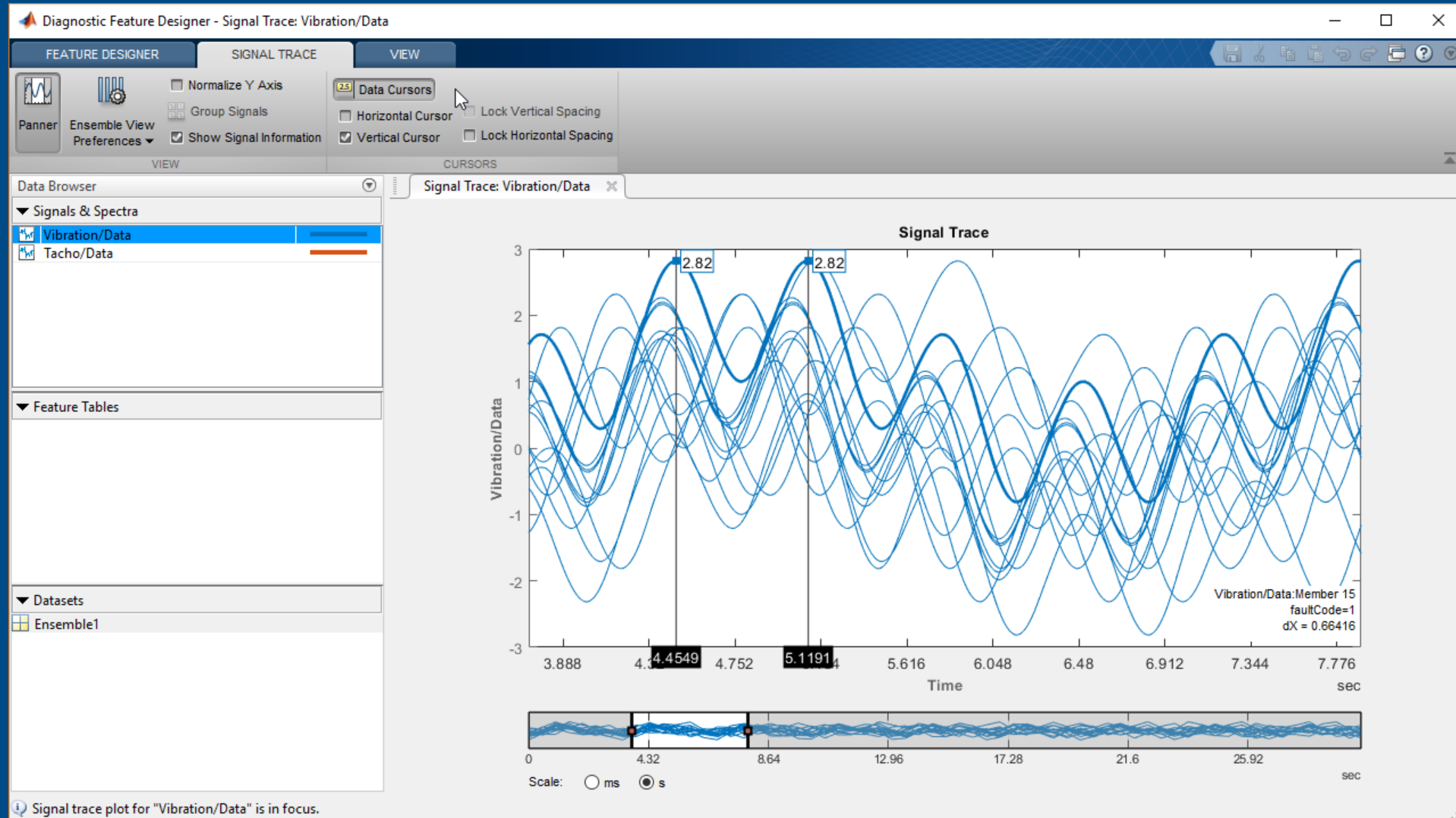




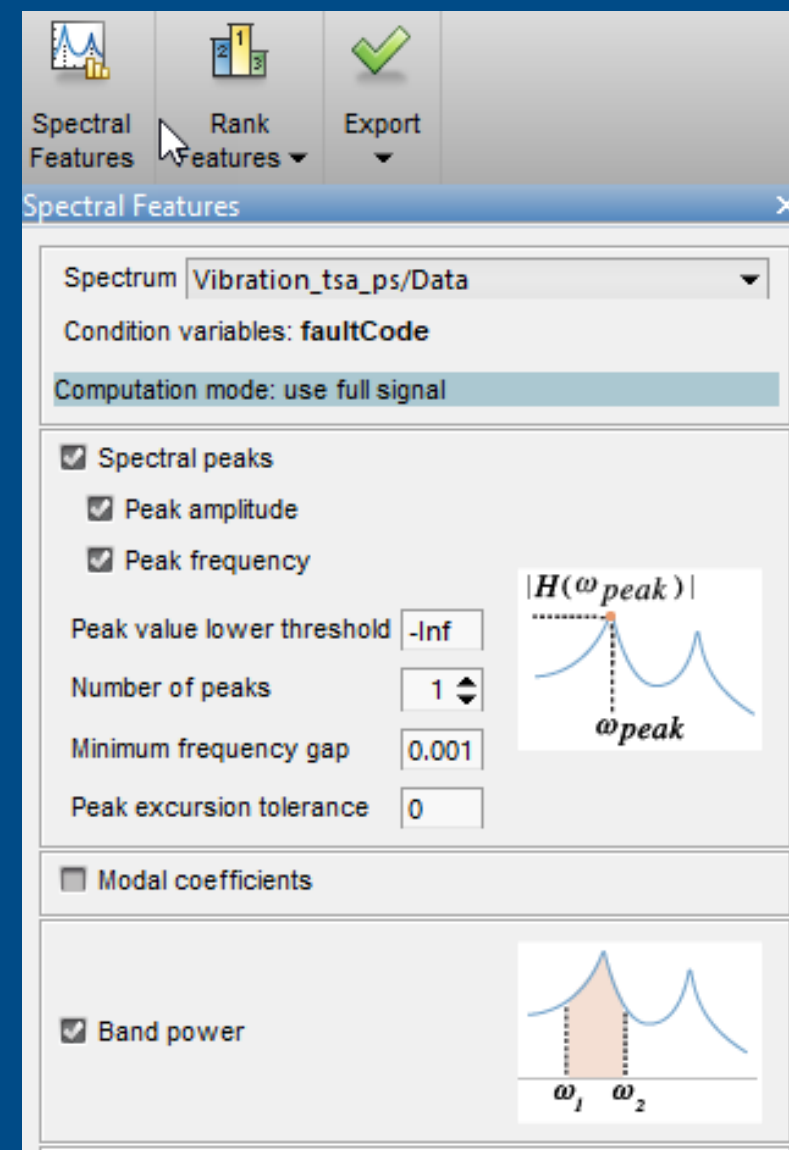
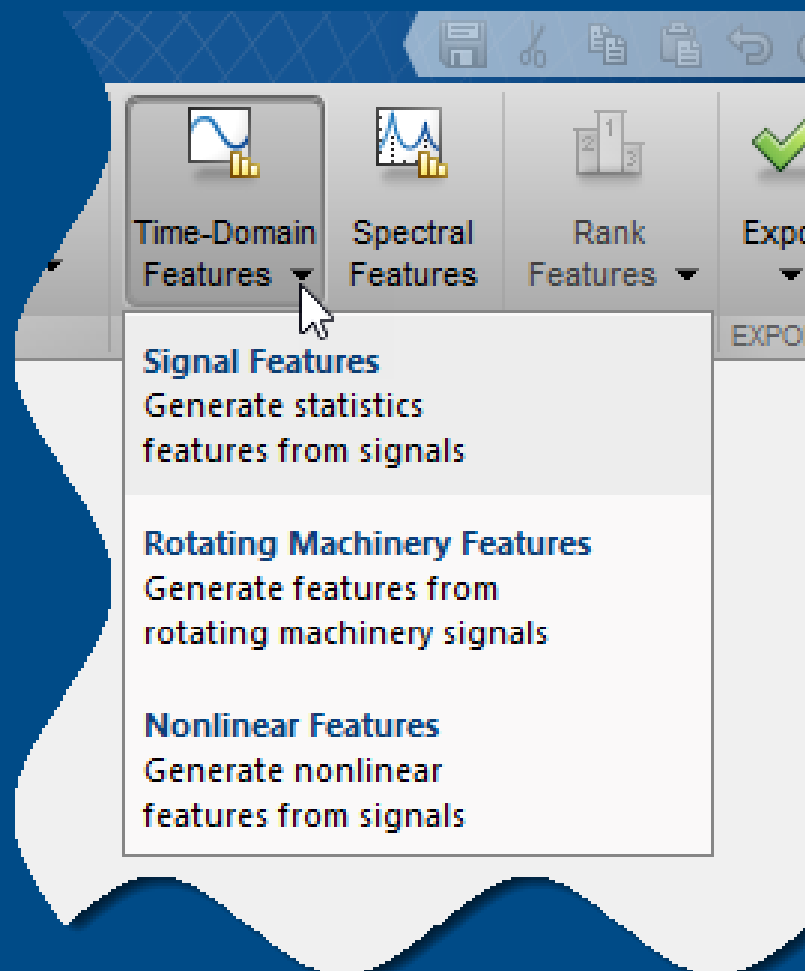
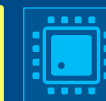
Identifying the Useful Data



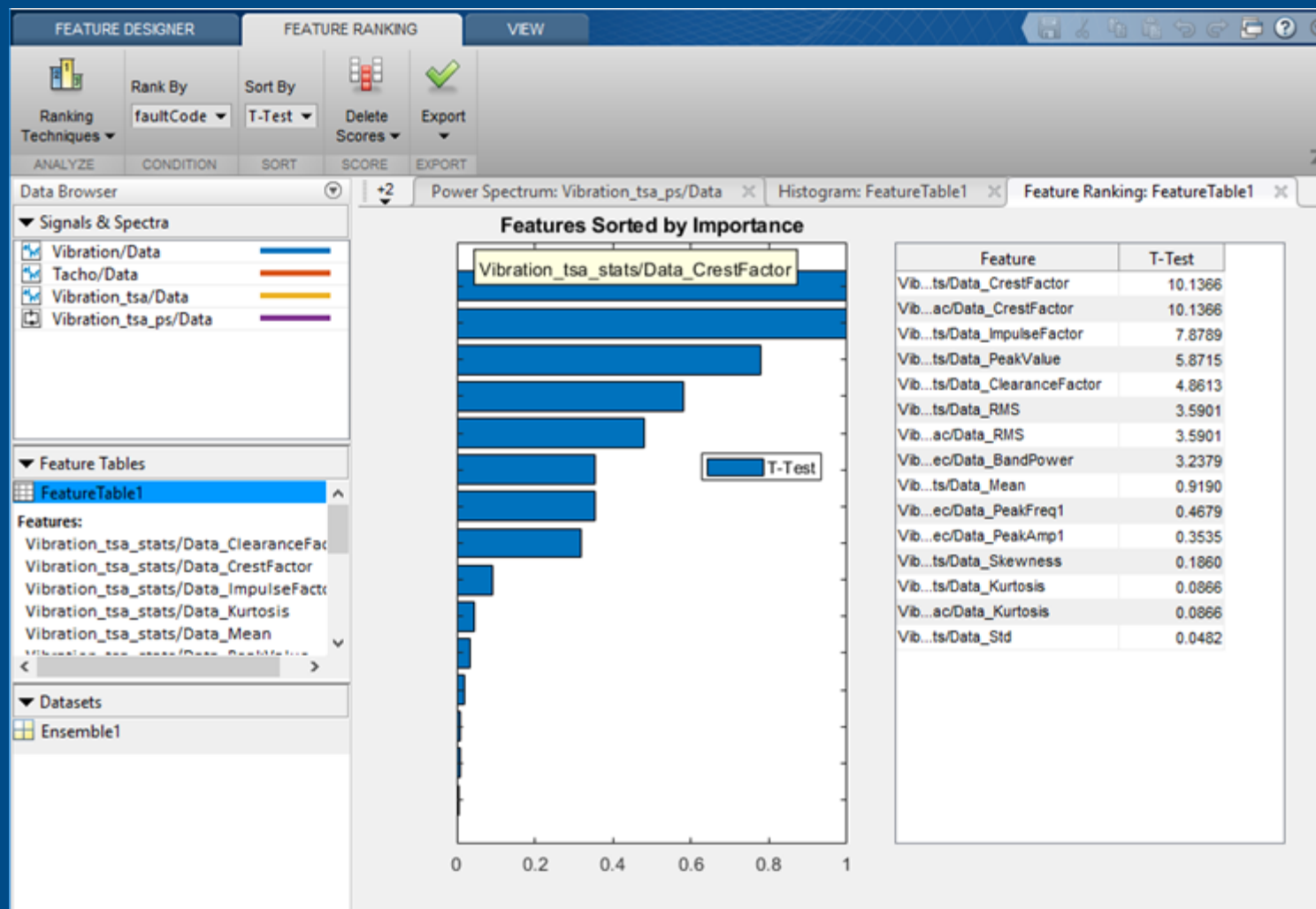
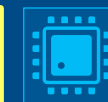
Identifying the Useful Data

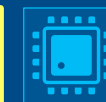


Identifying the Useful Data



Identifying the Useful Data



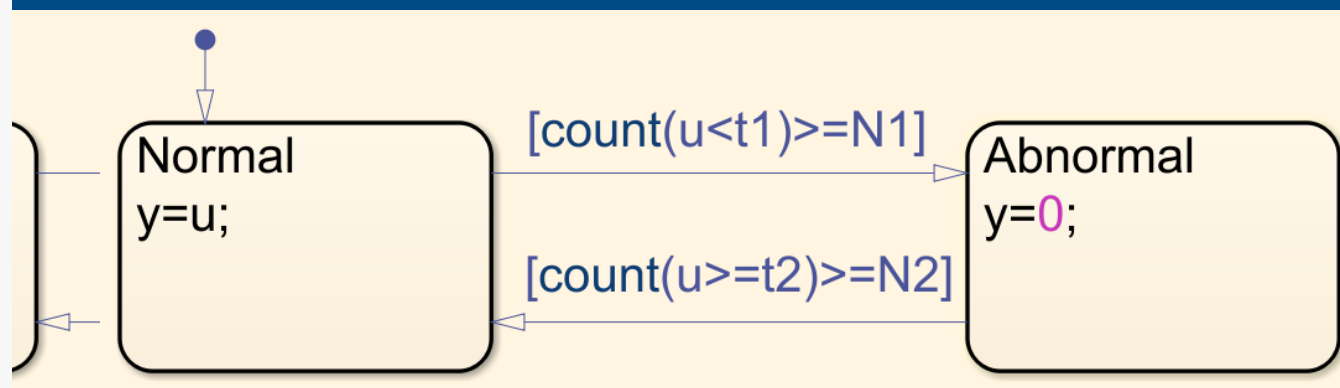


Designing Decision Logic with Stateflow

```

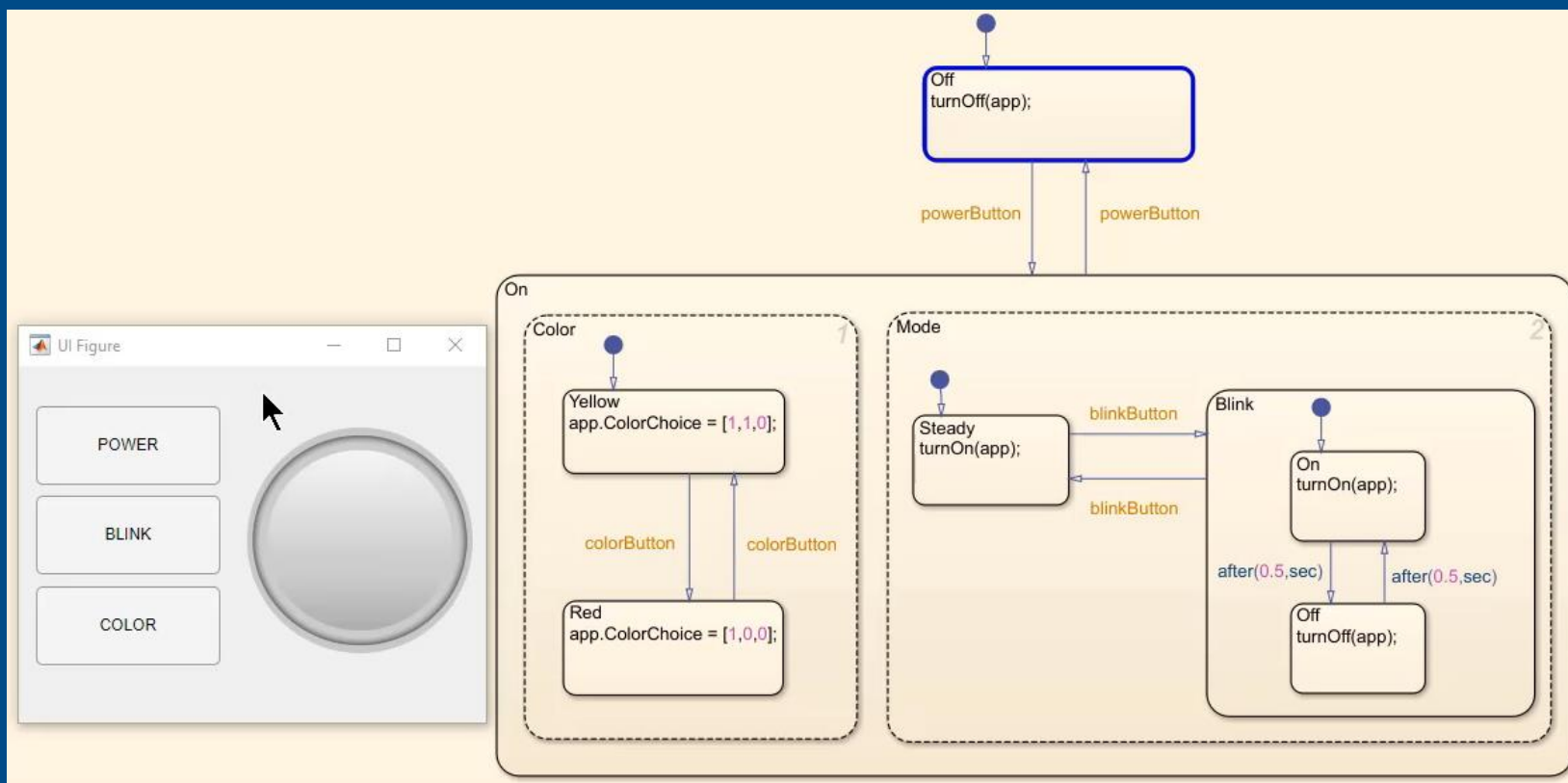
inNormalRegion = true;
counter = 0;
for i=1:length(inData)
    if(inNormalRegion)
        if(inData(i)<t1)
            counter = counter+1;
            if(counter>=N1)
                inNormalRegion = false;
            end
        else
            counter = 0;
        end
    else
        if(inData(i)>=t2)
            counter = counter+1;
            if(counter>=N2)
                inNormalRegion = true;
            end
        else
            counter = 0;
        end
    end
    if(inNormalRegion)
        outData(i) = inData(i);
    else
        outData(i) = 0;
    end
end

```





Using Stateflow in MATLAB



```
% Callbacks that handle component events
methods (Access = private)

% Code that executes after component creation
function startupFcn(app)
    app.LanternLogic = BlinkLanternLogic('app',app);
end

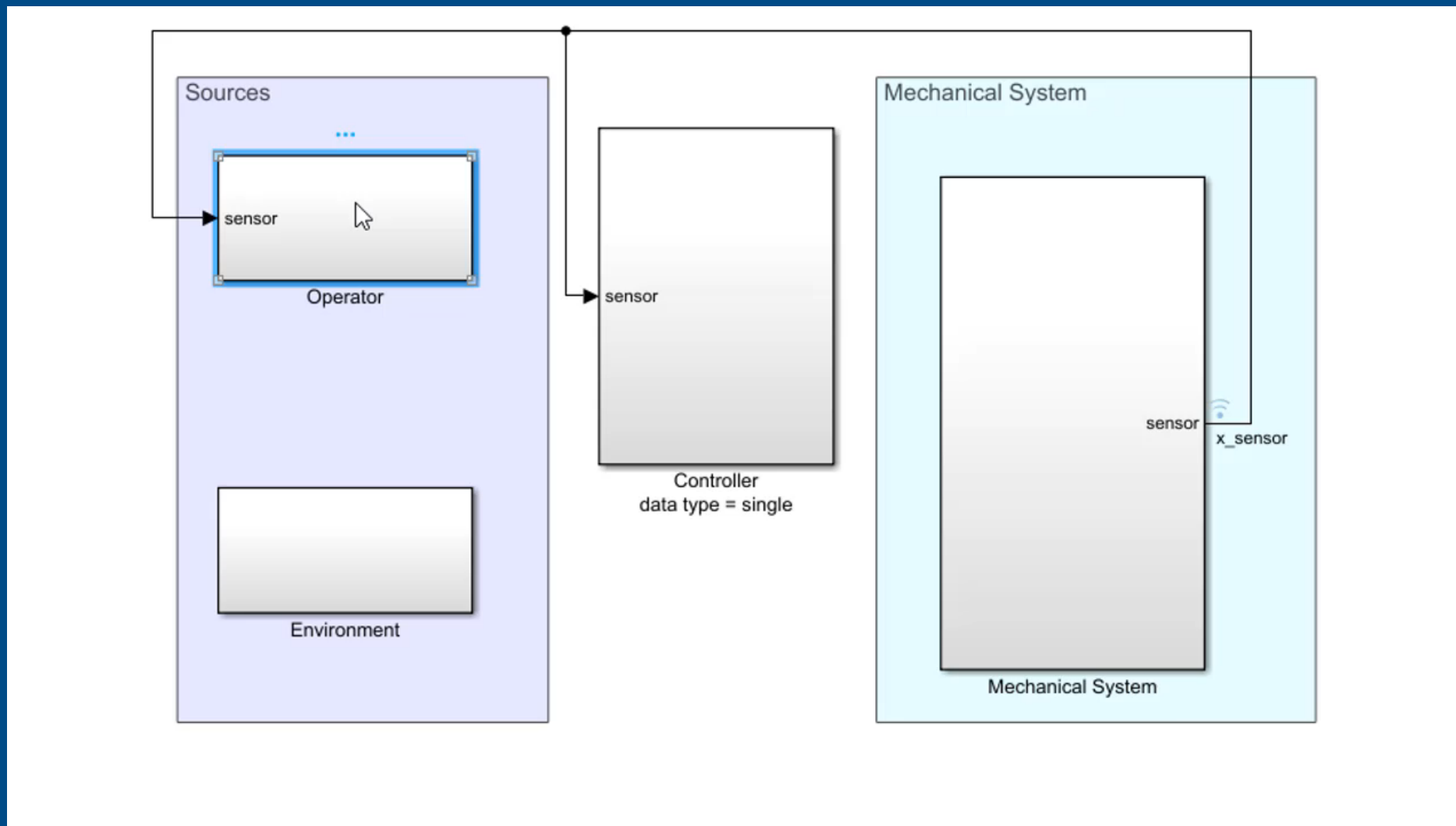
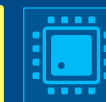
% Button pushed function: POWERButton
function POWERButtonPushed(app, event)
    app.LanternLogic.powerButton();
end

% Button pushed function: COLORButton
function COLORButtonPushed(app, event)
    app.LanternLogic.colorButton();
end

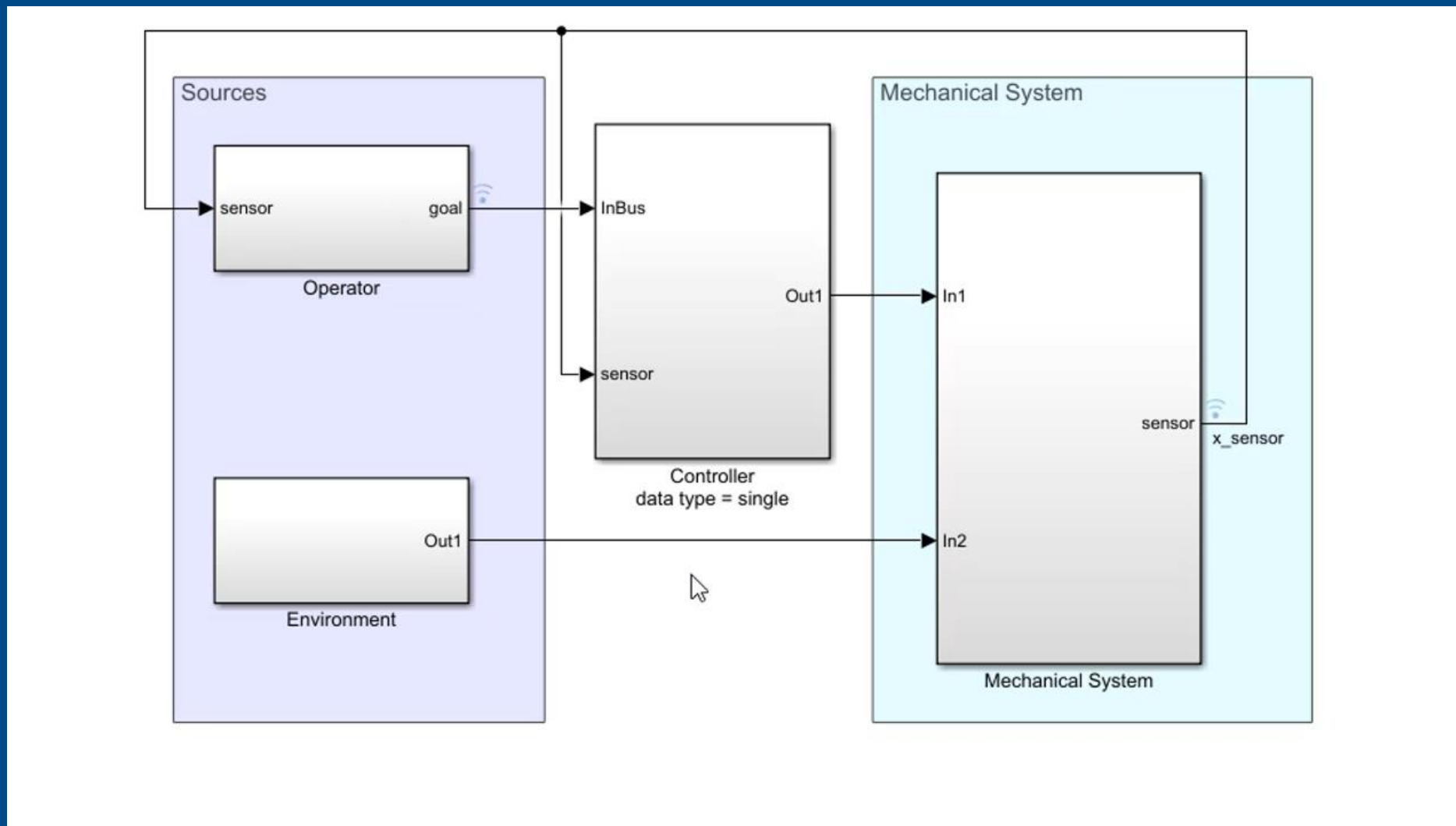
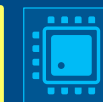
% Close request function: UIFigure
function UIFigureCloseRequest(app, event)
    delete(app.LanternLogic);
    delete(app);
end

% Button pushed function: BLINKButton
function BLINKButtonPushed(app, event)
    app.LanternLogic.blinkButton();
end
end
```

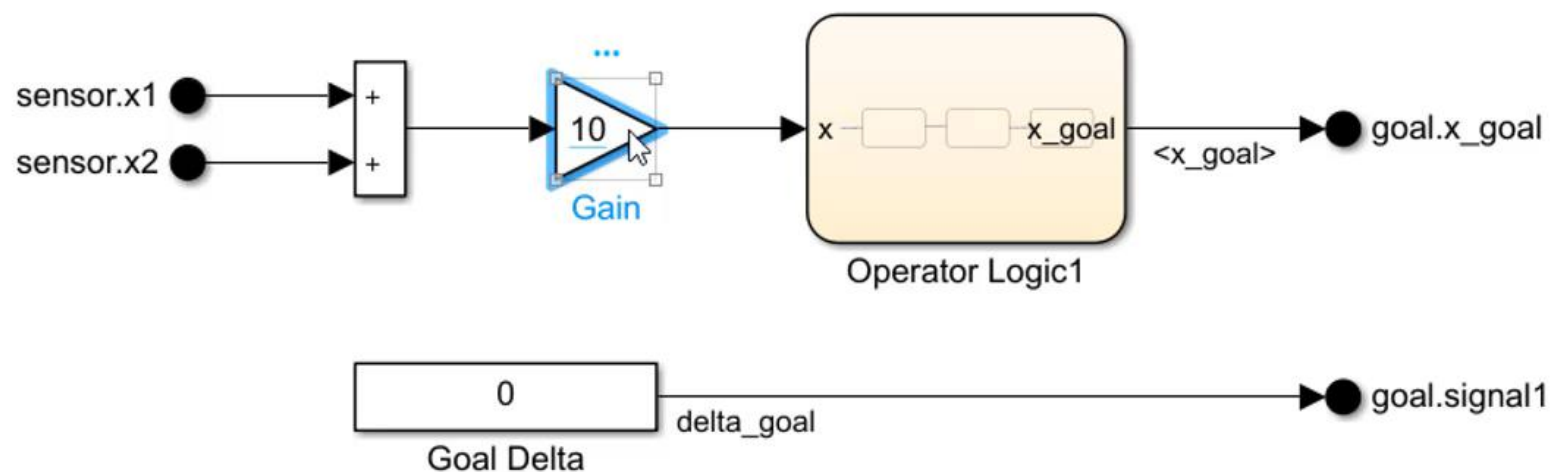
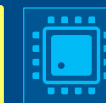
Editing at the Speed of Thought



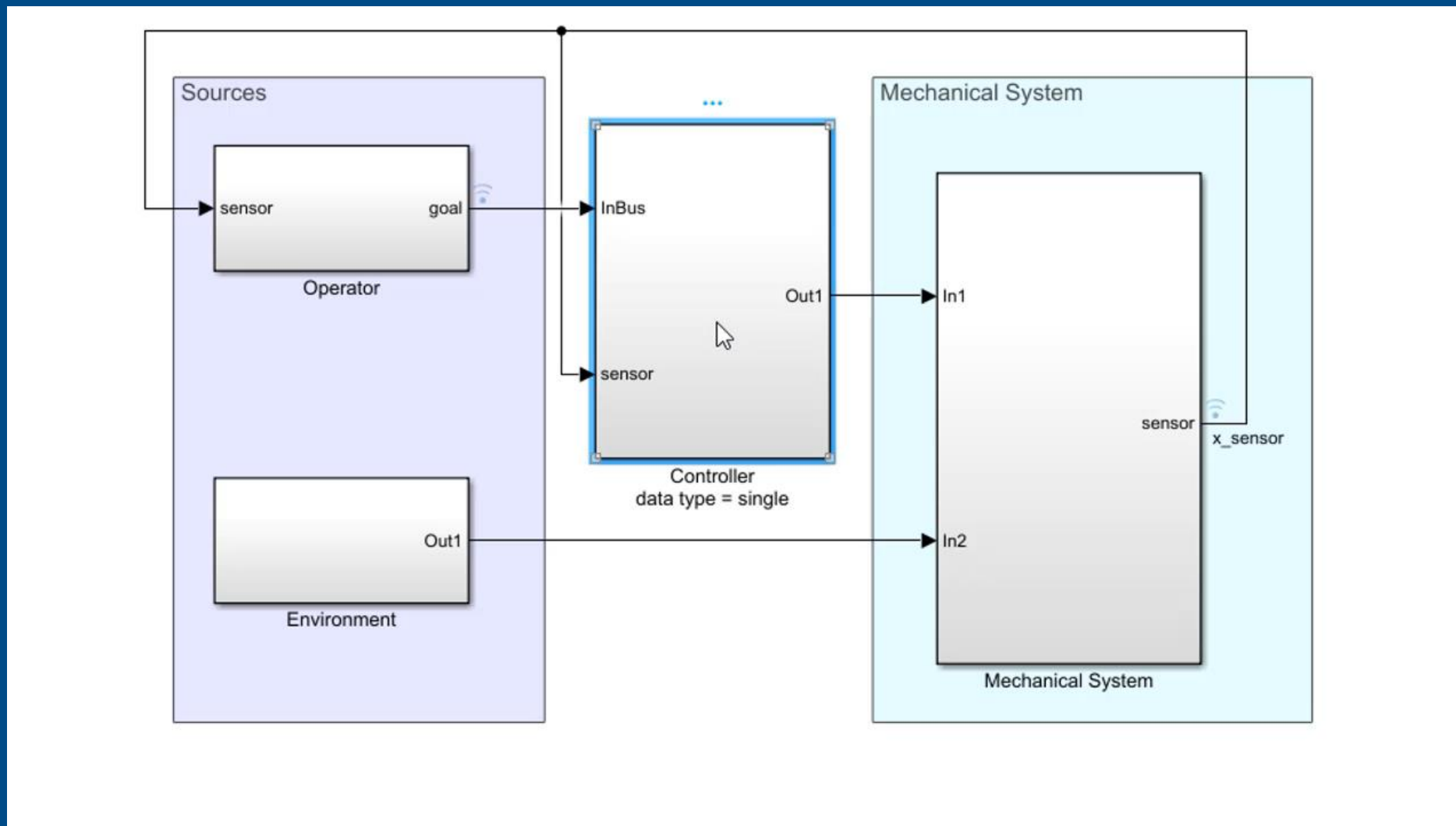
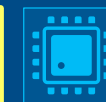
Editing at the Speed of Thought



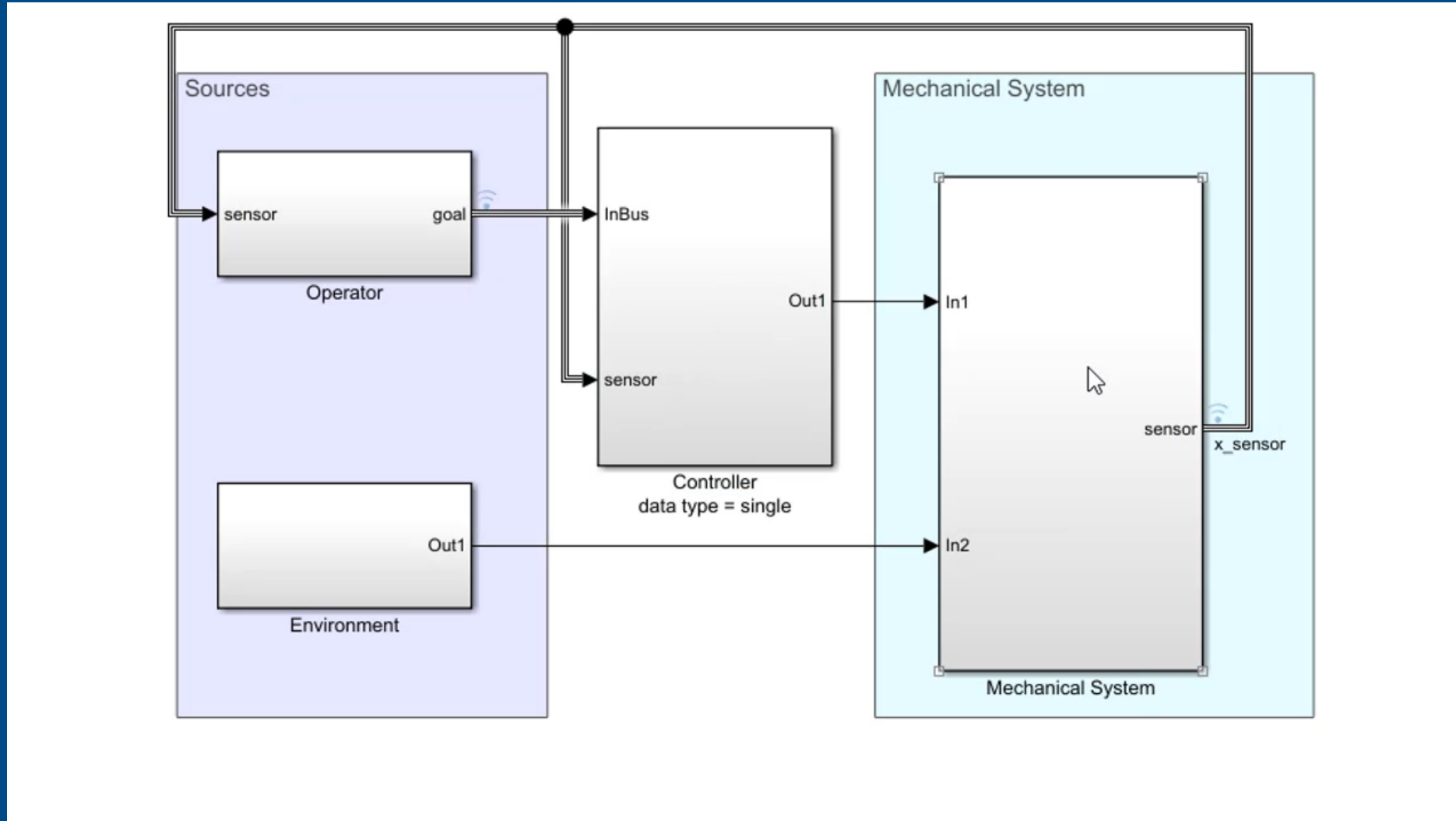
Editing at the Speed of Thought



Editing at the Speed of Thought



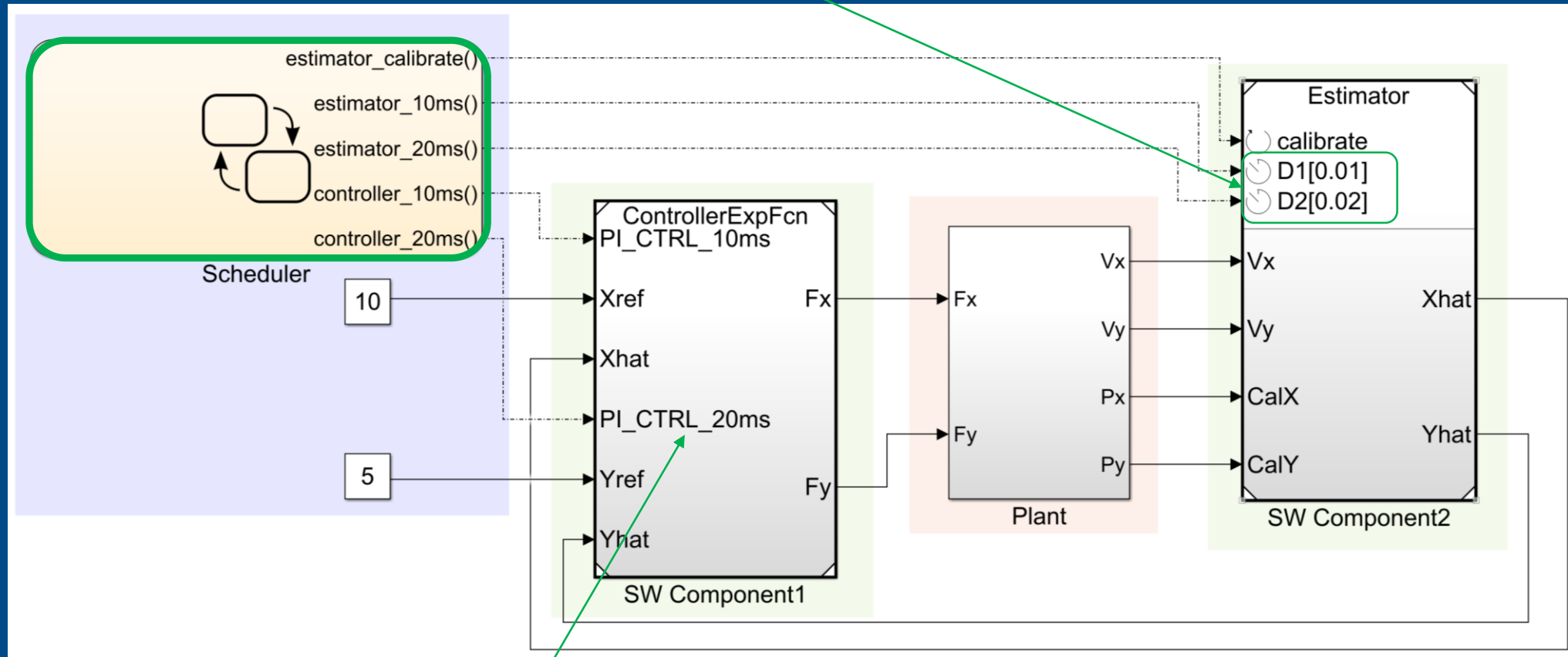
Editing at the Speed of Thought





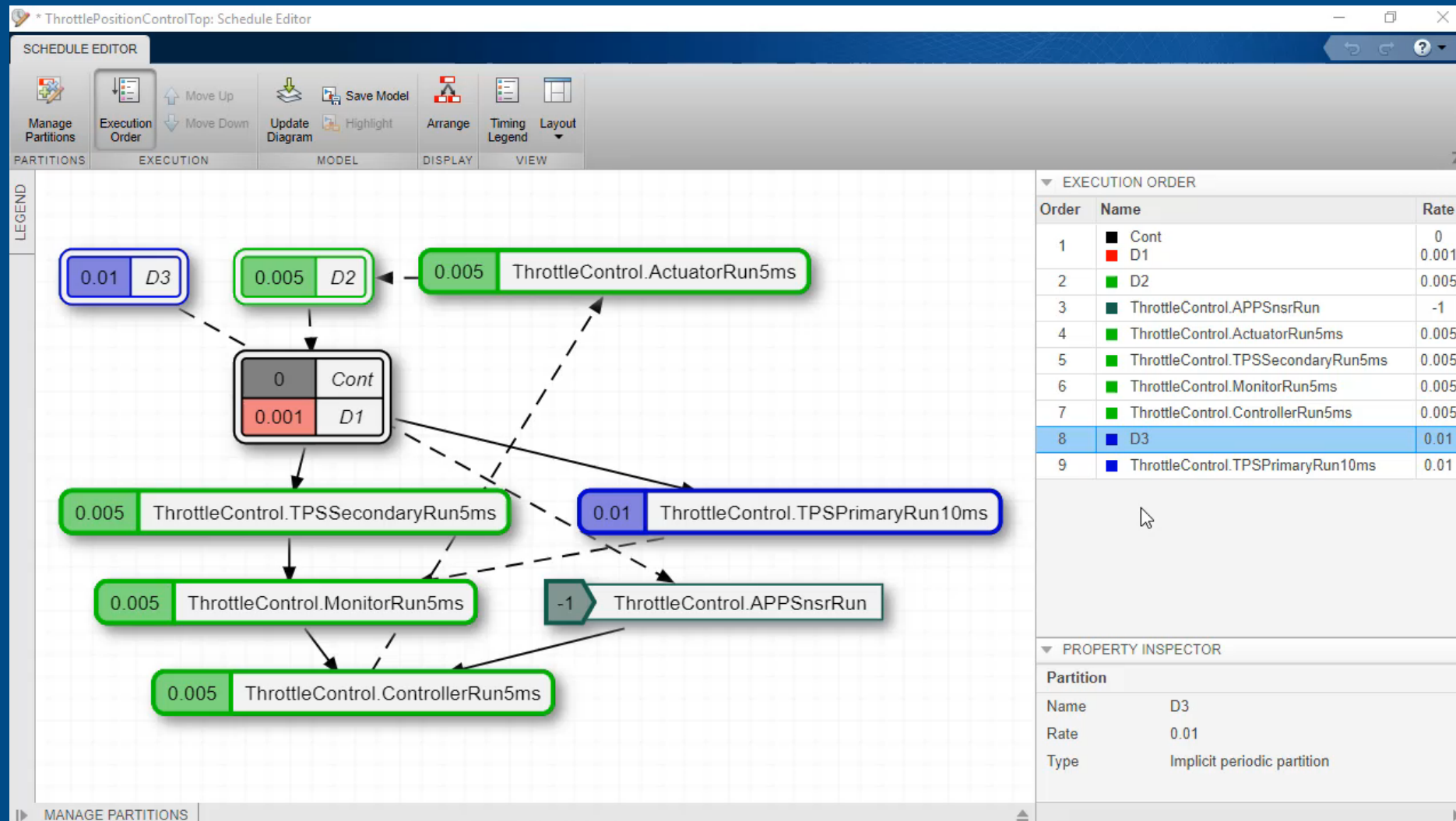
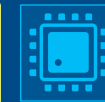
Controlling the Execution of Model Components

Schedulable Rate-Based Model

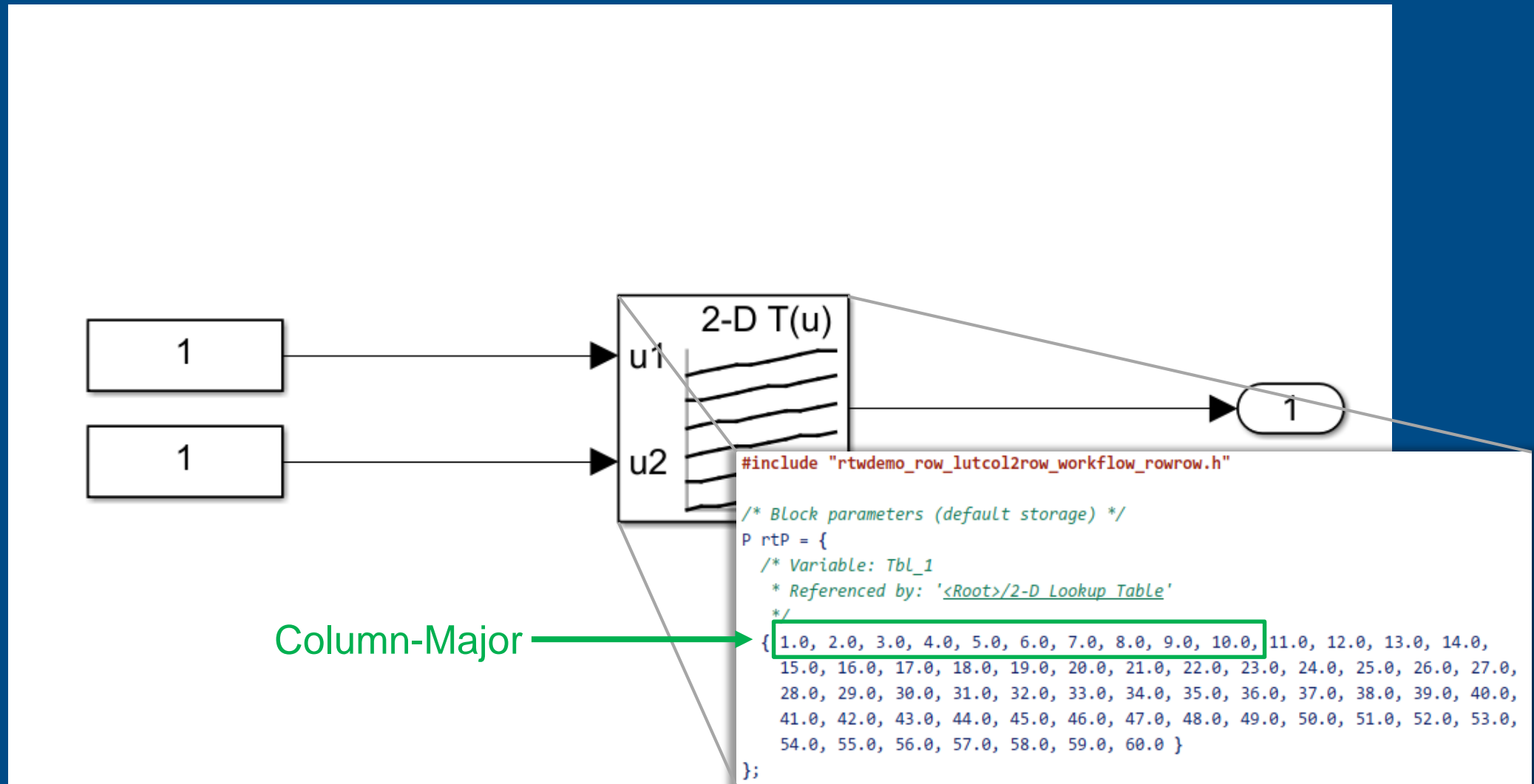


Export Function Model

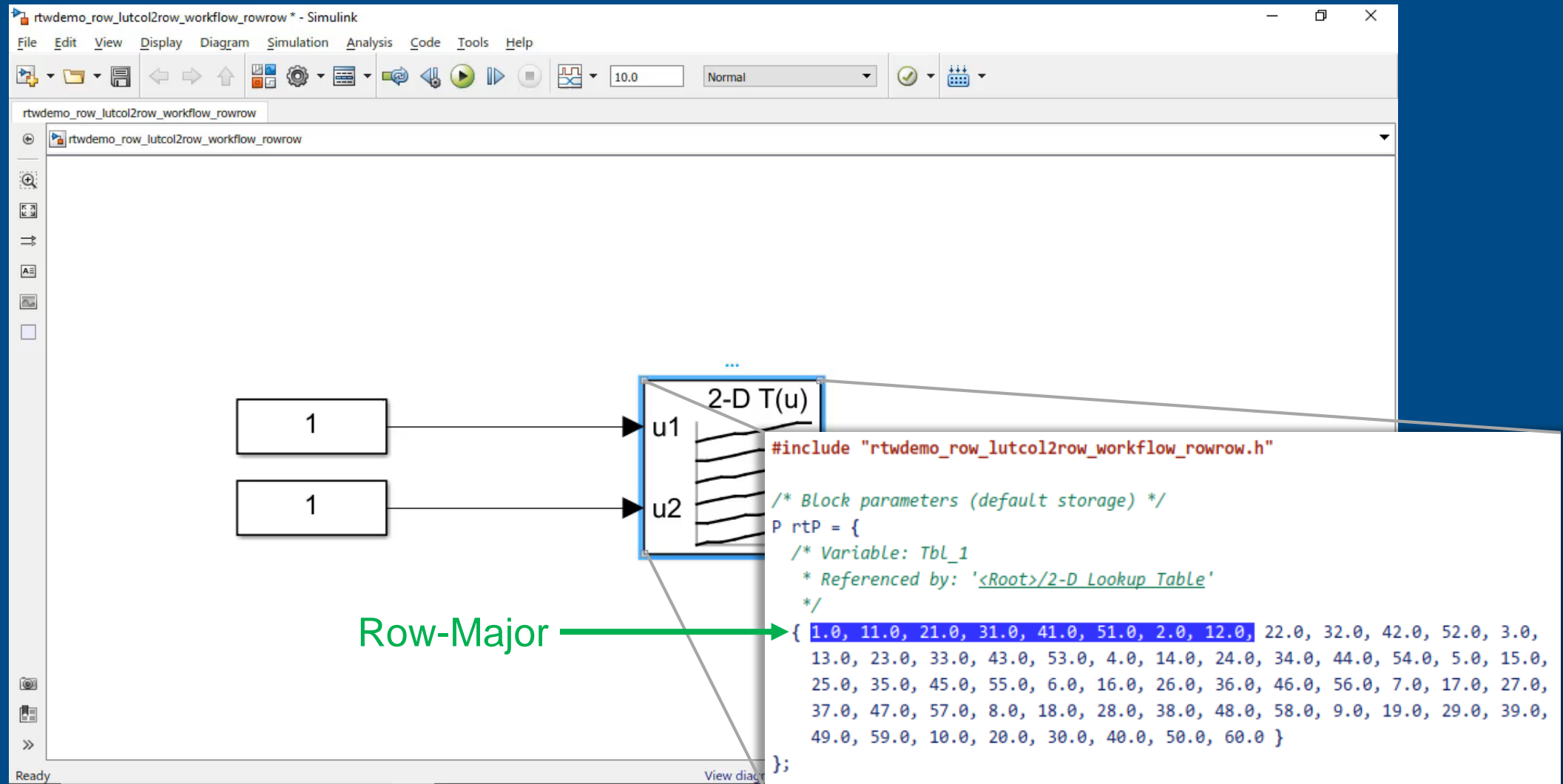
Controlling the Execution of Model Components



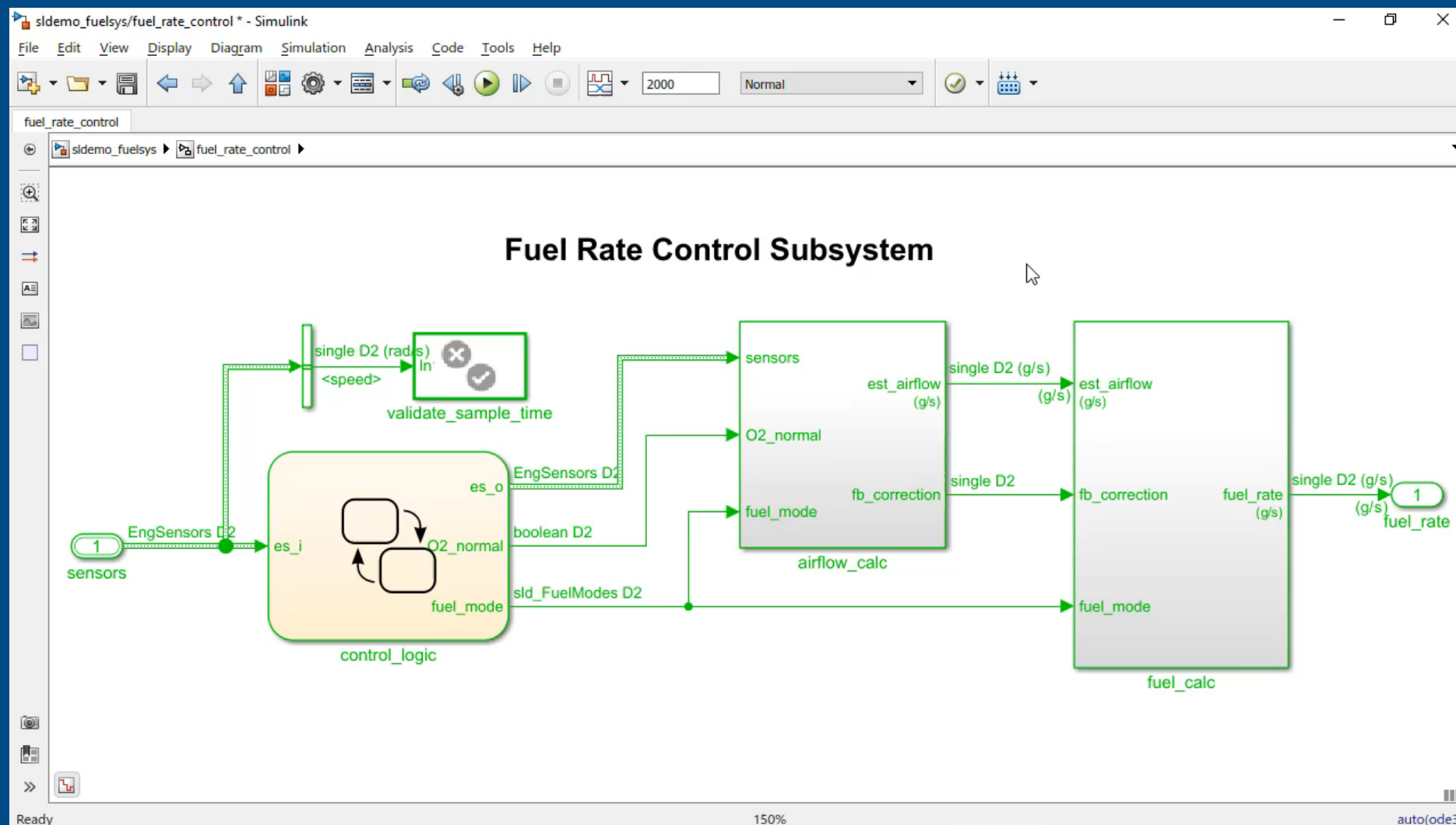
Simplifying Integration with External C/C++ Code



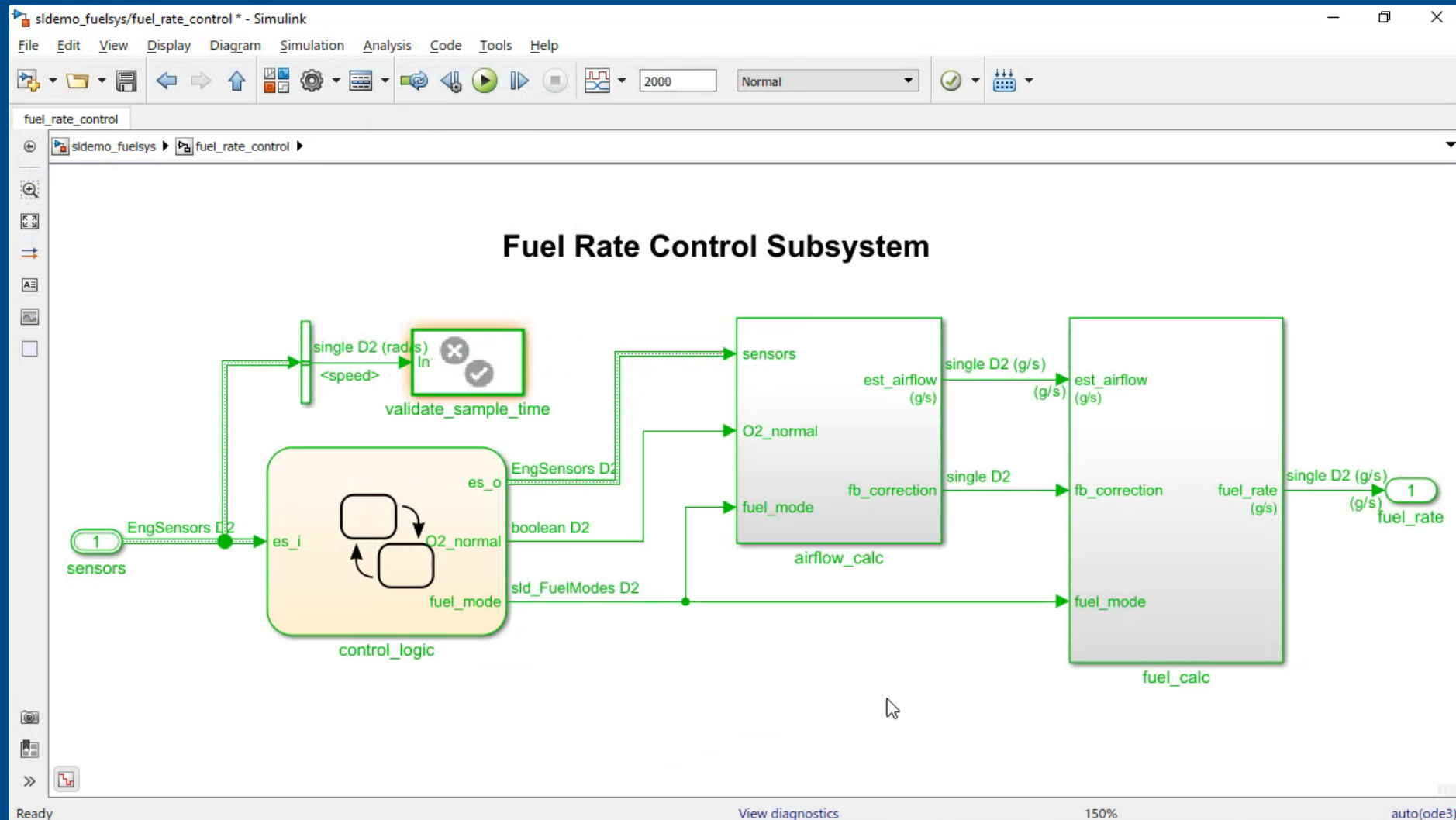
Simplifying Integration with External C/C++ Code



Viewing Generated Code Alongside the Model



Viewing Generated Code Alongside the Model



Sharing Live Scripts



Live Editor - C:\MATLAB\SunriseSunset_final.mlx *

FILE NAVIGATE TEXT CODE SECTION RUN

Find Files Find Compare Go To Find

New Open Save Print

Text Aa Normal B I U M



Code Control Refactor

Run Section Run and Advance Run to End

Run Step Stop

SunriseSunset_final.mlx *

Estimating Sunrise and Sunset



Using the latitude (ϕ), the sun's declination (δ) and the solar time correction (SC) we can calculate sunrise and sunset times.

$$\text{sunrise} = 12 - \frac{\cos^{-1}(-\tan \phi \tan \delta)}{15^\circ} - \frac{SC}{60}$$
$$\text{sunset} = 12 + \frac{\cos^{-1}(-\tan \phi \tan \delta)}{15^\circ}$$

Refer to [this page](#) for background and details on the equations used.

script



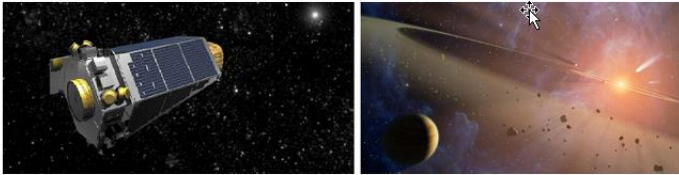
Sharing Live Scripts

AutoSave ExploringExoplanets.docx - Compatibility Mode David Garrison

File Home Insert Design Layout References Mailings Review View Help Tell me what you want to do Share

Clipboard Font Paragraph Styles Editing

Exploring Exoplanets



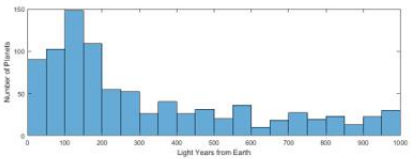
In this example we will explore some data on exoplanets - planets outside our own solar system. The data used here is a subset of data from the [NASA Exoplanet Archive](#). We will start by using the data to answer some questions about the set of exoplanets in the archive. Then we will do some calculations to try to identify planets in the archive that might be capable of supporting life.

```
exoplanets = readtable("exoplanets.xlsx");
exoplanets(1:10,:);
```

How Far Away Are these Planets?

There are 90 exoplanets within 50 light-years of earth and 450 exoplanets within 200 light-years.

```
histogram(3.26*exoplanets.st_distance, 'BinWidth', 50)
xlim([0 1000])
ylabel 'Number of Planets'
xlabel 'Light Years from Earth'
```

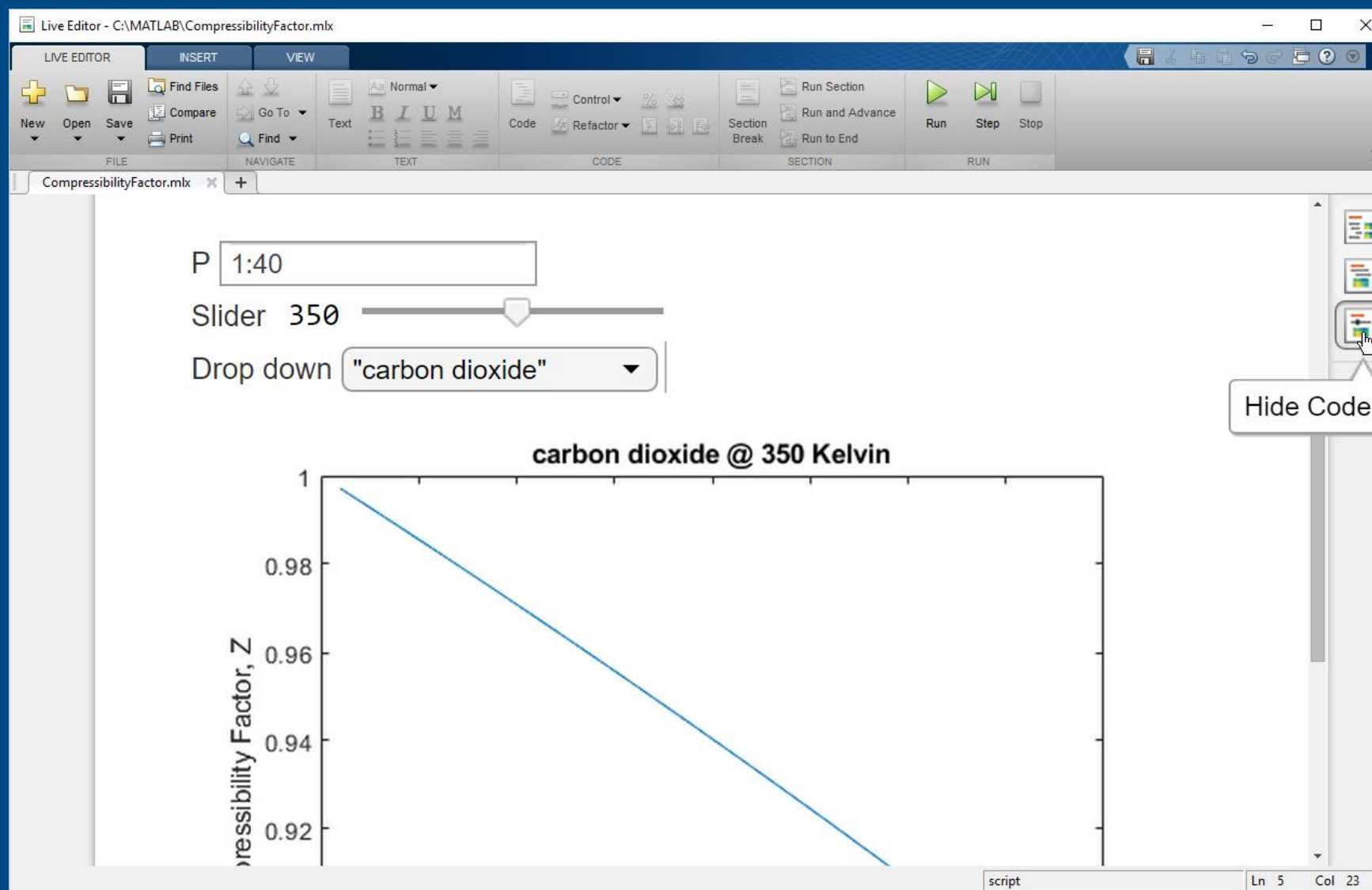


Where is the nearest exoplanet?

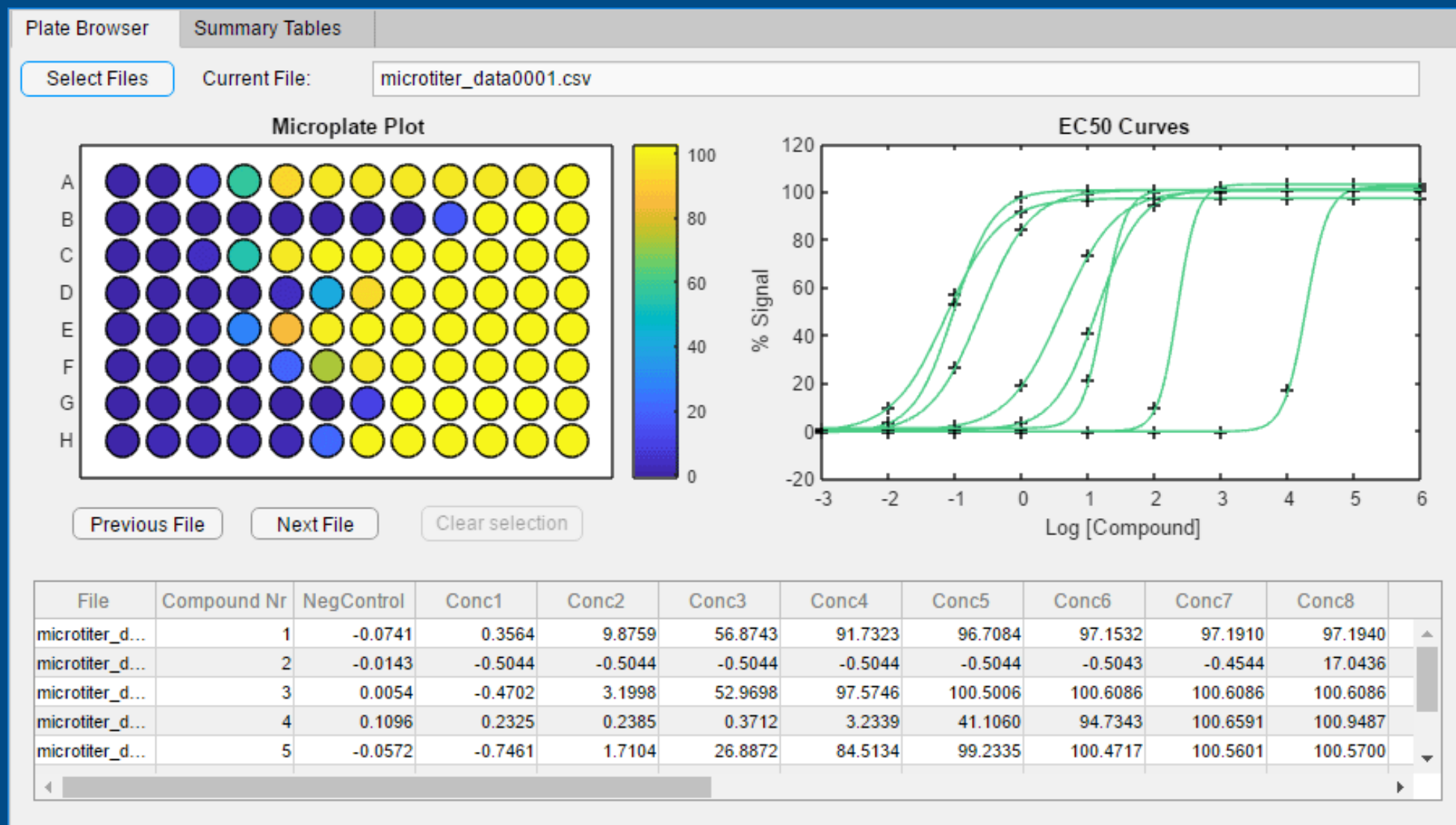
```
idx = find(exoplanets.st_distance == min(exoplanets.st_distance));
name = char(exoplanets{idx, 'st_name'});
```

Page 1 of 7 1468 words

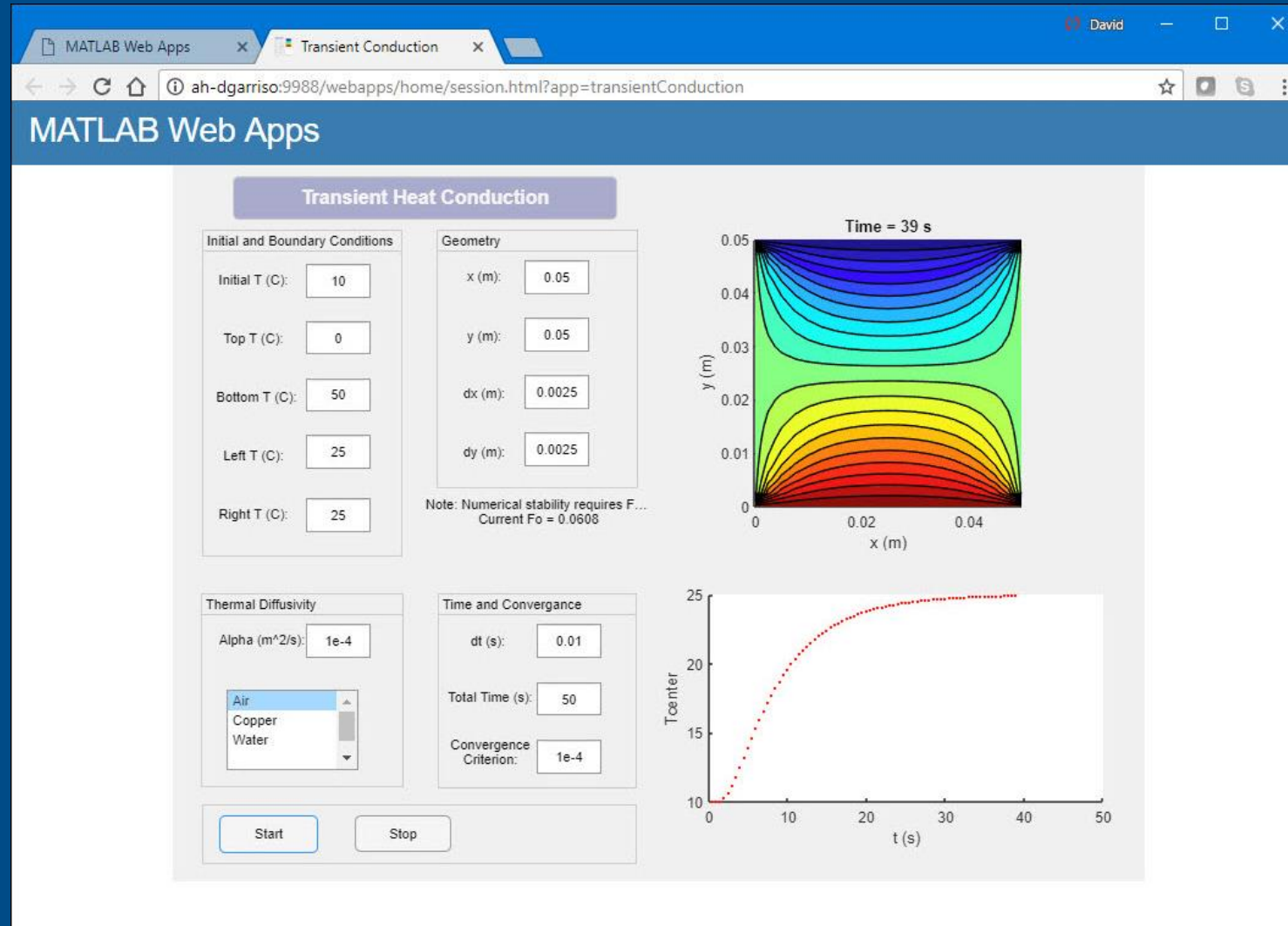
Sharing Live Scripts



Creating Apps



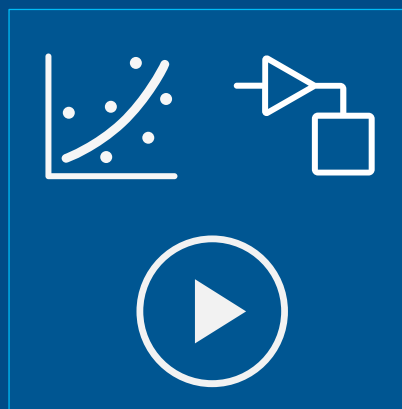
Deploying Web Apps



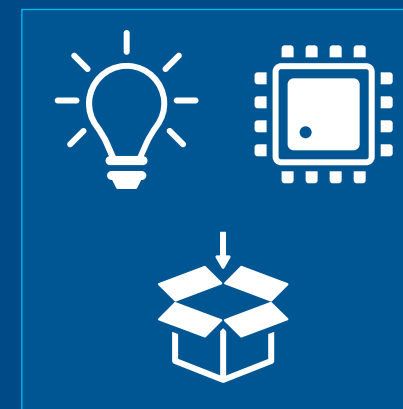
Using MATLAB & Simulink to Build Algorithms in Everything



Inputs



Design



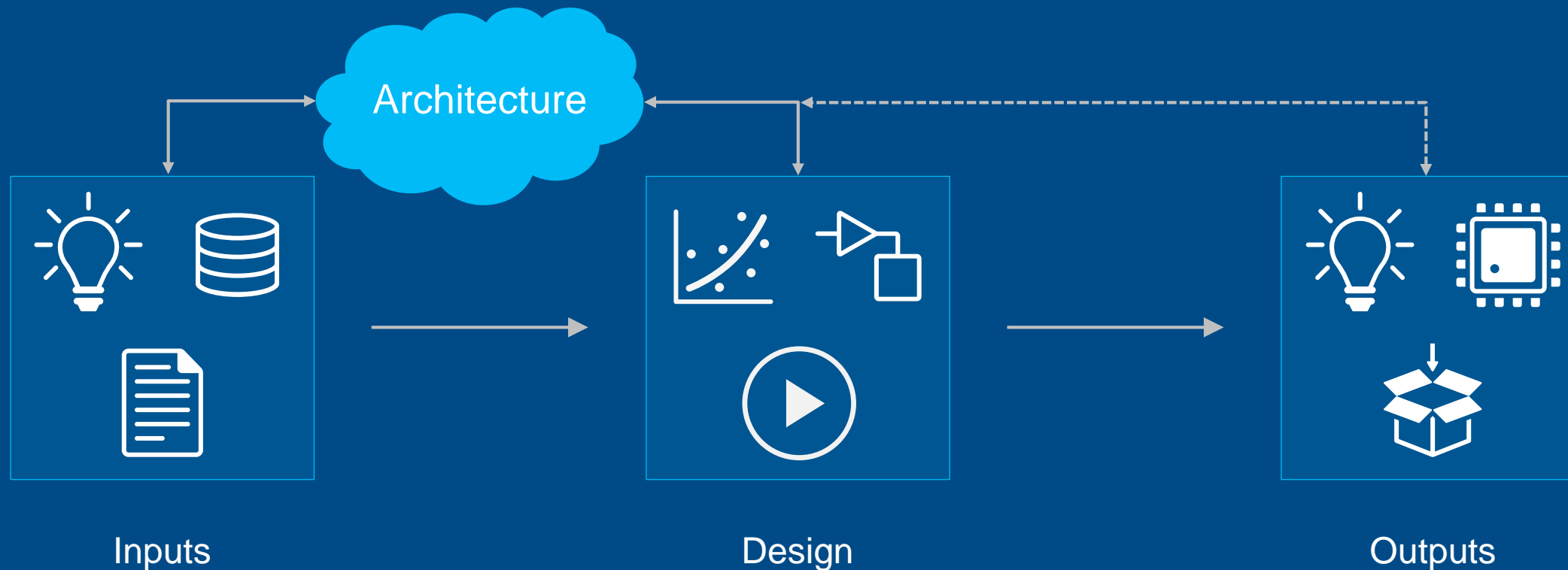
Outputs



MATLAB® & SIMULINK®



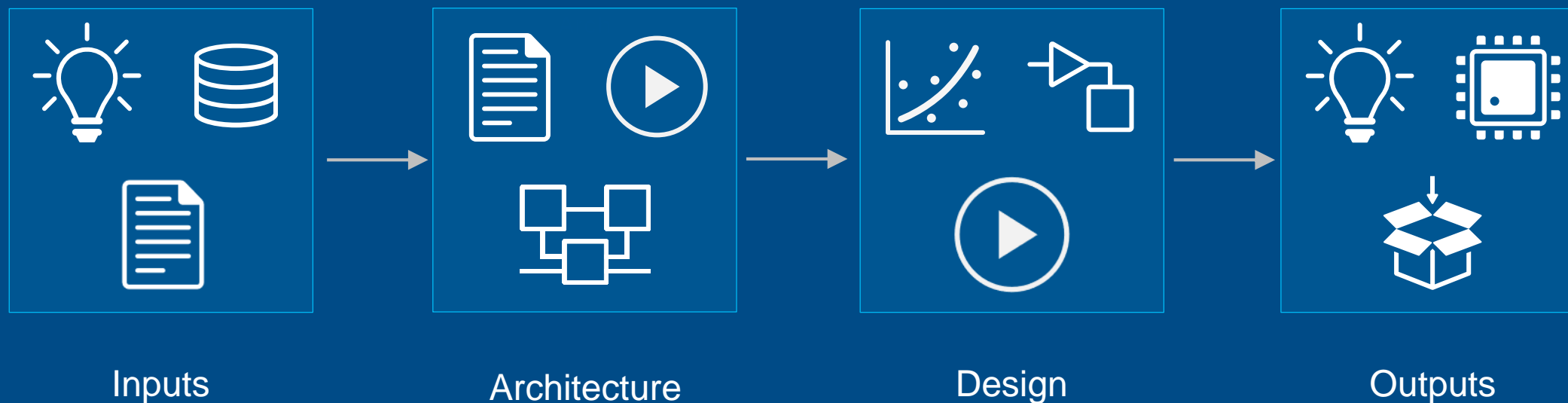
Evaluating Architectures



MATLAB® & SIMULINK®



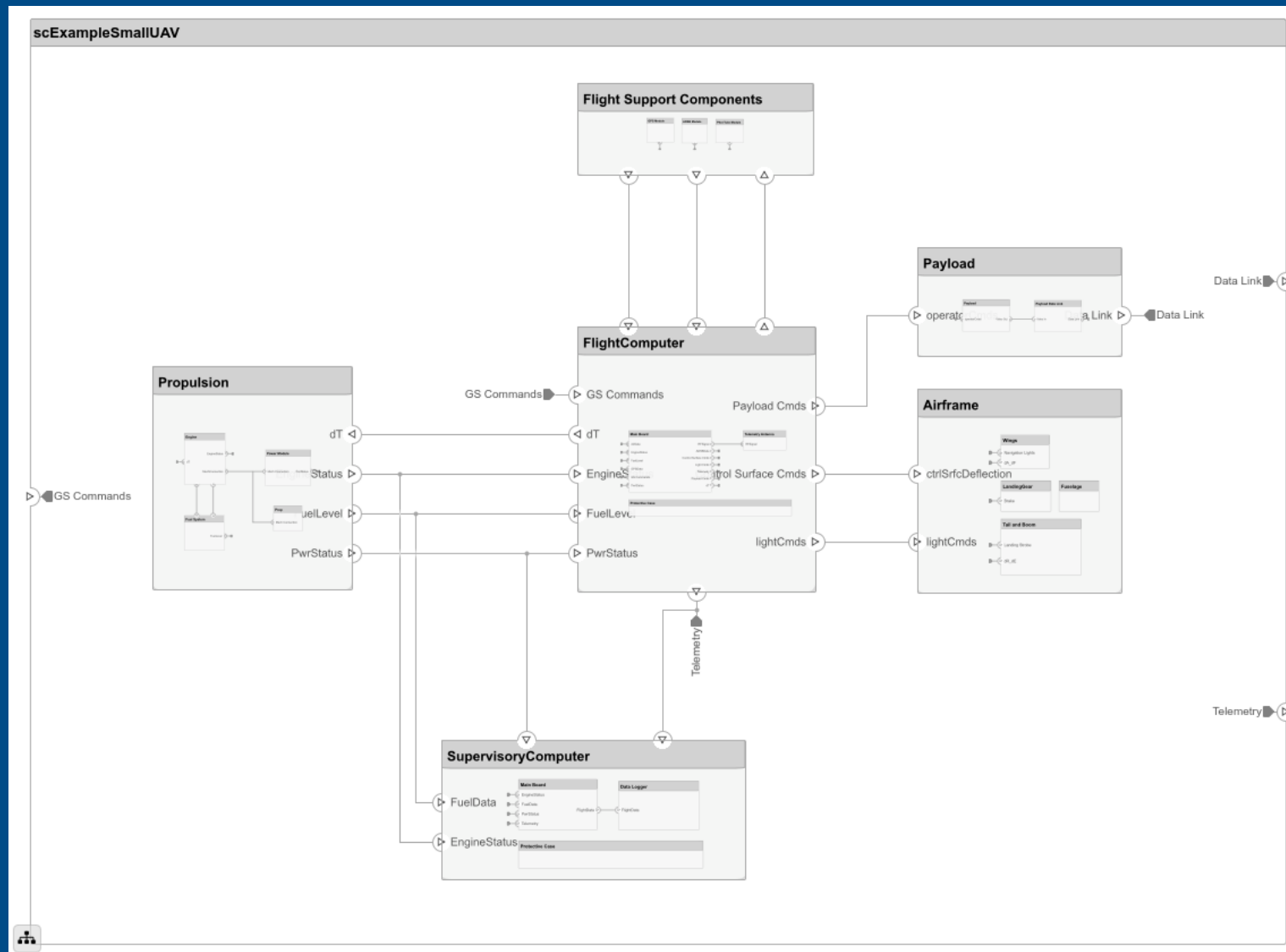
Evaluating Architectures



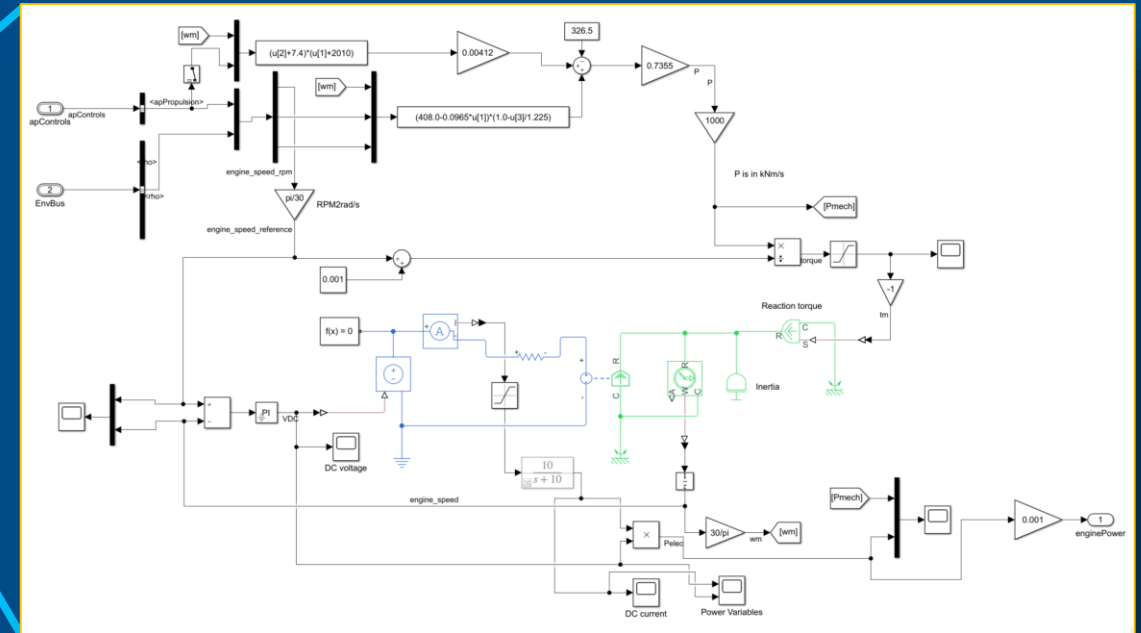
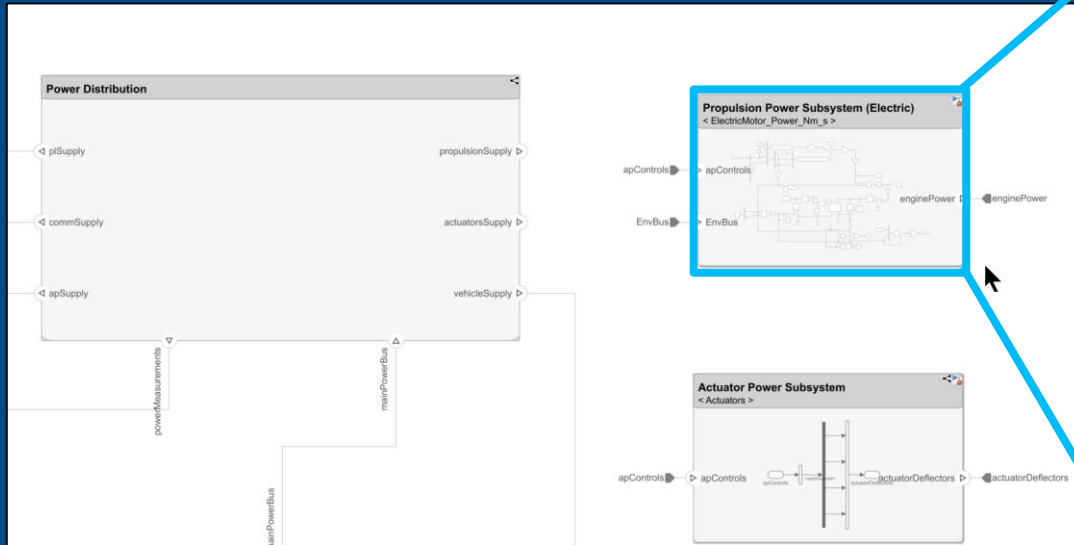
MATLAB® & SIMULINK®



Designing System and Software Architectures



Designing System and Software Architectures

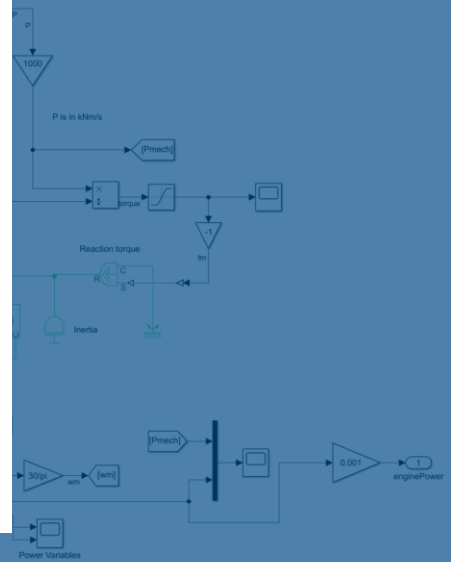


Designing System and Software Architectures



Find out more:
Systems Engineering:
Requirements to Architecture
to Simulation

Gaurav Dubey
Systems Modeling, Implementation, and
Verification Track



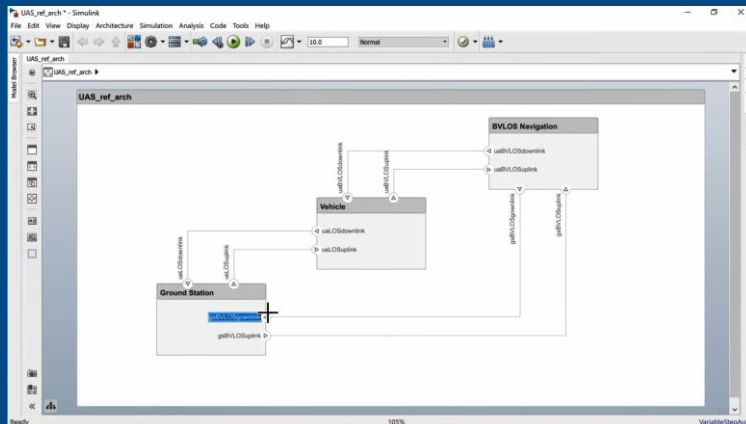
Designing **Beyond** System and Software Architectures



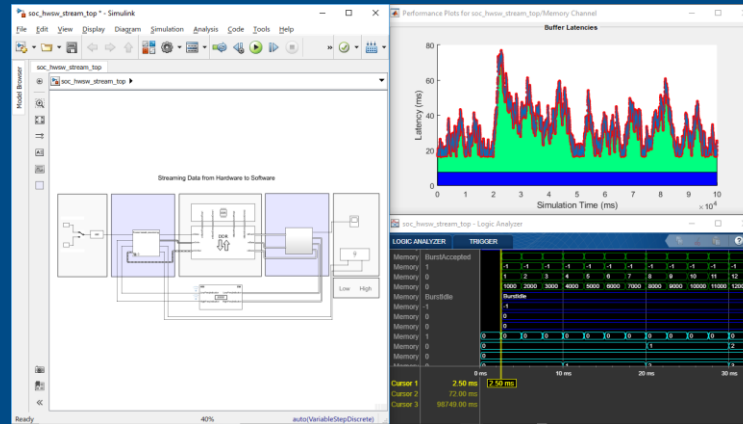
Systems and Software

SoC Hardware and Software

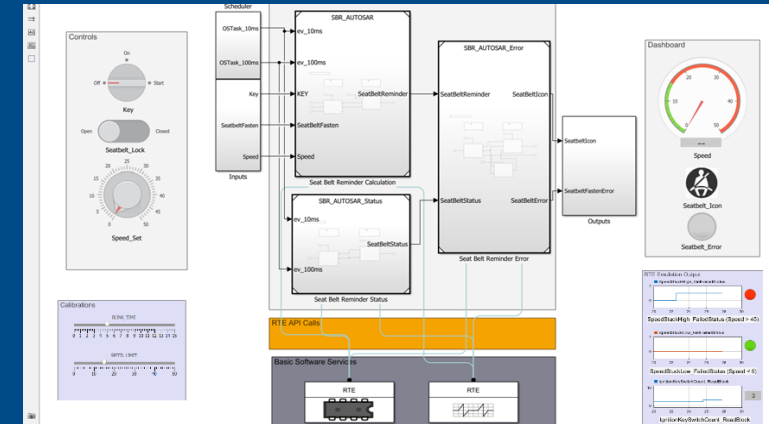
AUTOSAR Software



System Composer

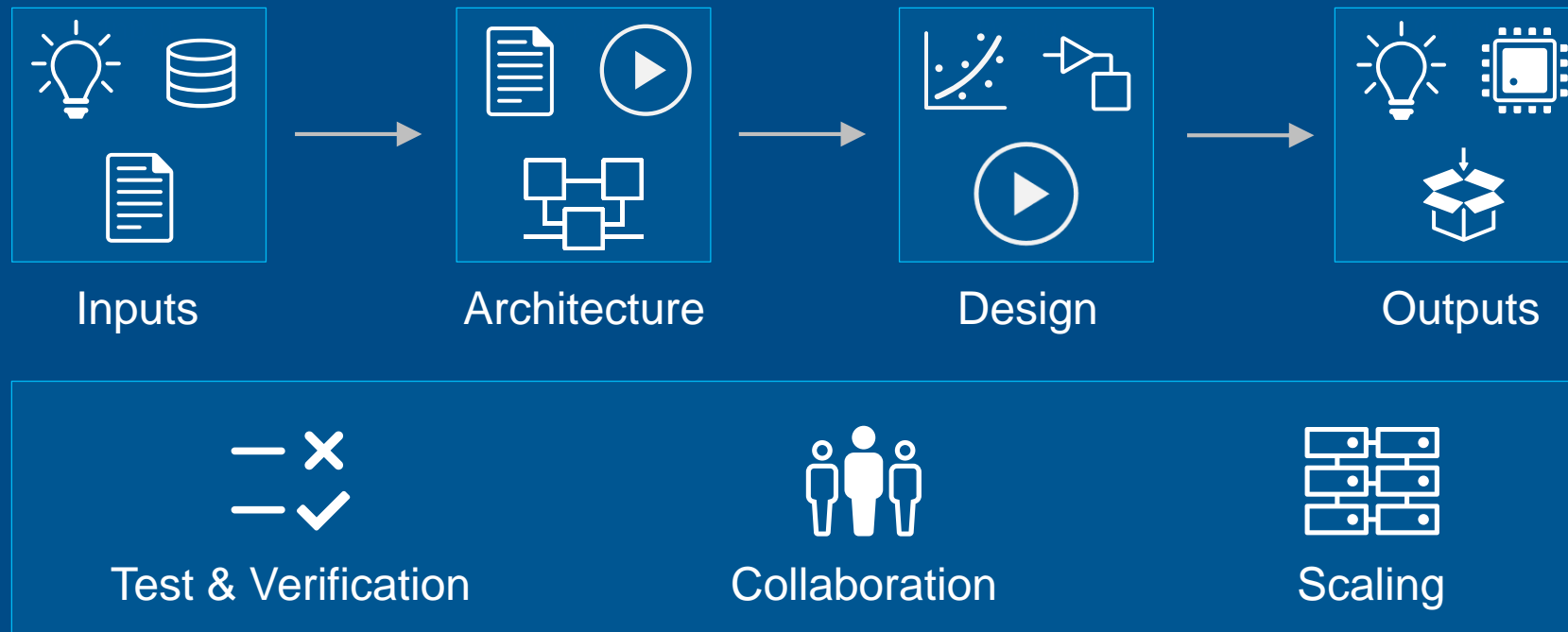


SoC Blockset



AUTOSAR Blockset

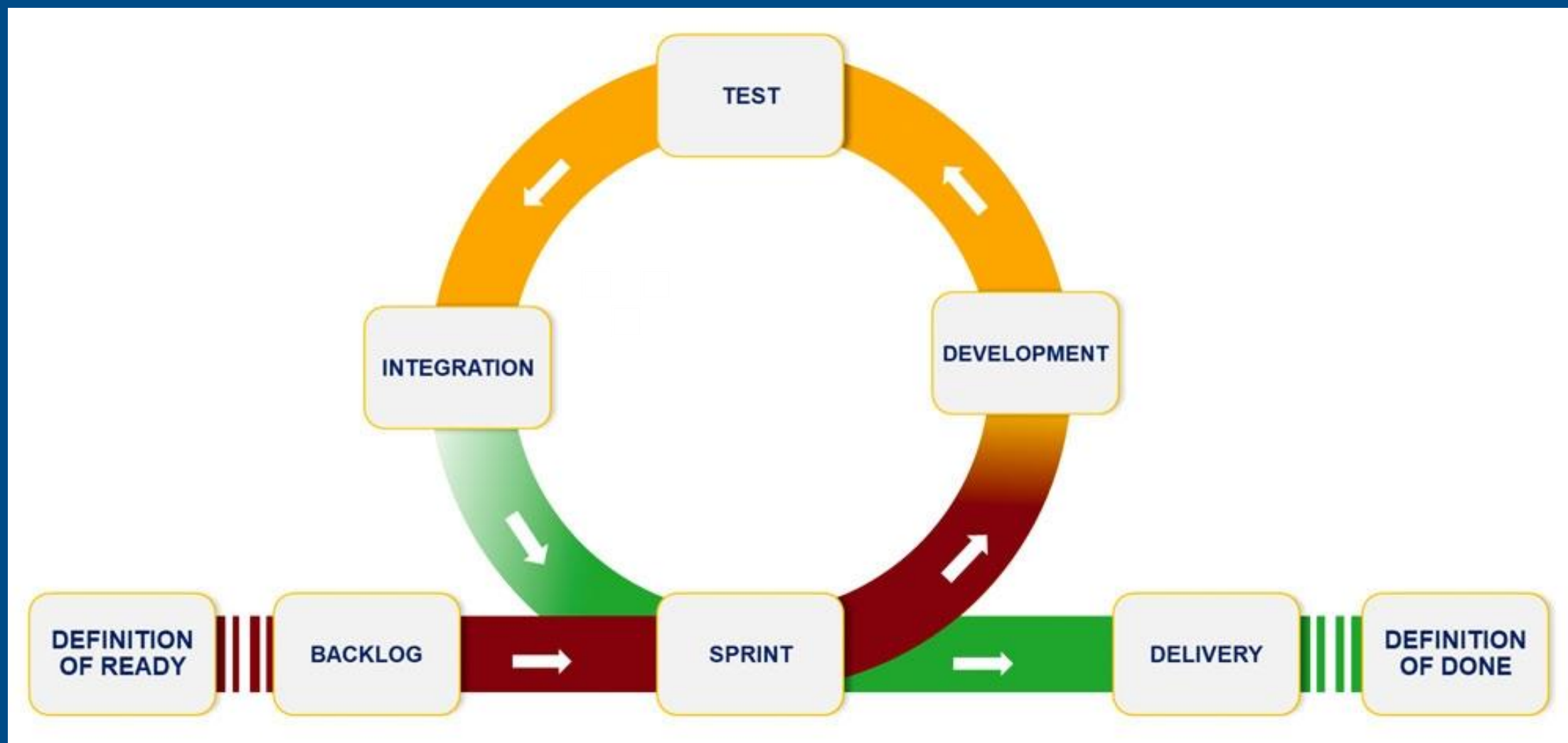
Using MATLAB & Simulink to Build Algorithms in Everything



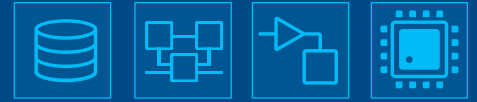
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Using MATLAB & Simulink to Build Algorithms in Everything



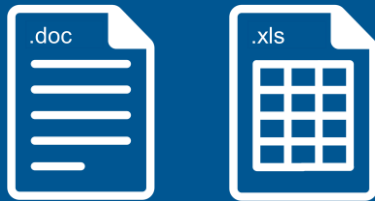
Integrating with Third-party Requirements Tools



↔

Test & Verification

External Requirements



Requirements
Management
Tools

R2019a**ReqIF**

Simulink Requirements

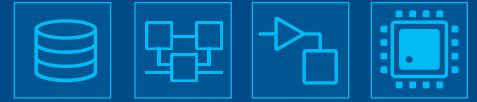
External Requirements



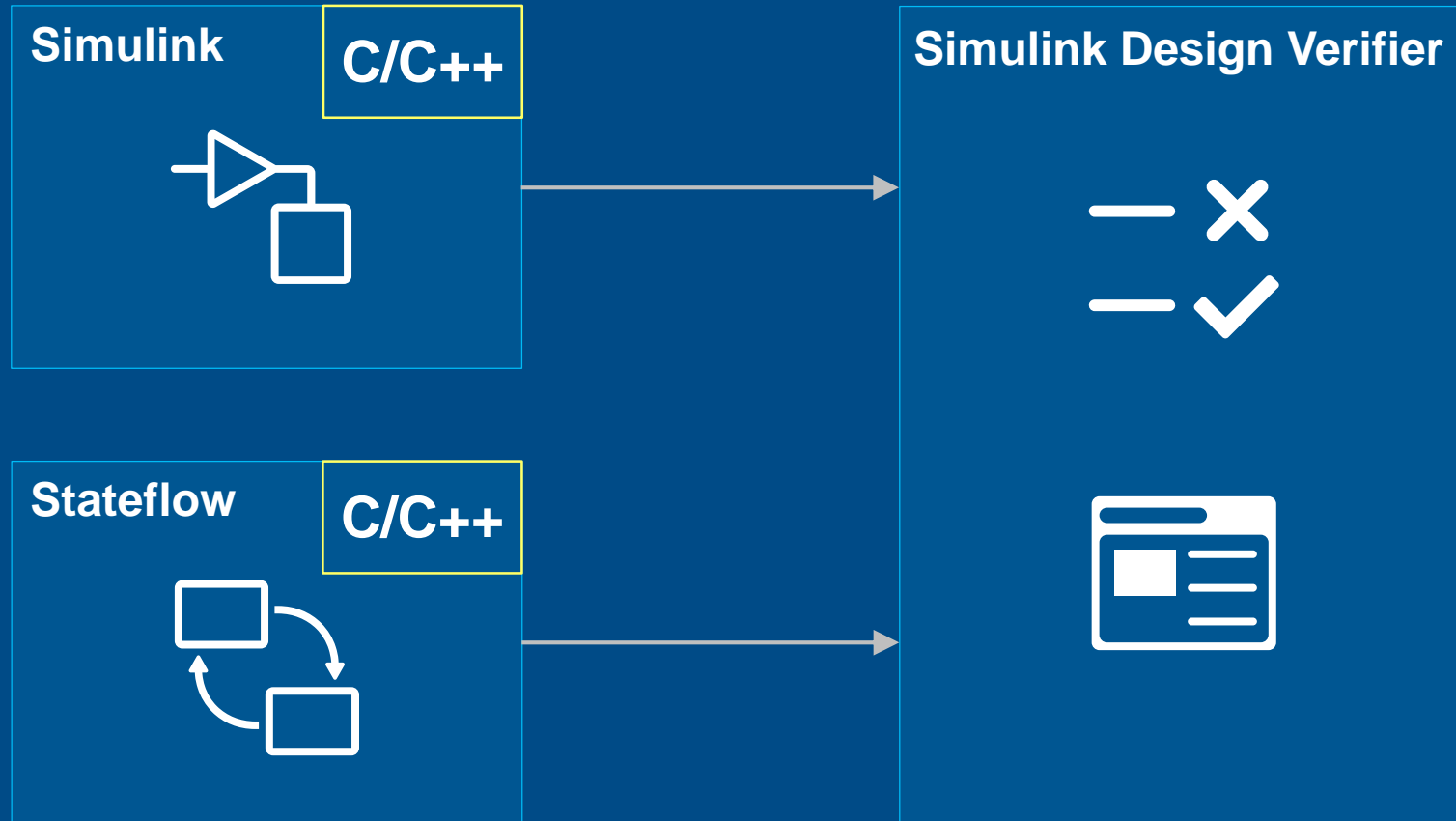
Authored Requirements



Include Custom Code in Test & Verification



Test & Verification



Include Custom Code in Test & Verification



Simulink

C/C++

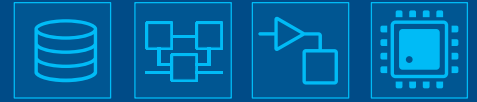
Simulink Design Verifier

Find out more:
**Simplifying Requirements-Based
Verification with Model-Based Design**

Vamshi Kumbham
**Systems Modeling, Implementation, and
Verification Track**



Using the MATLAB Unit Test Framework



Test & Verification

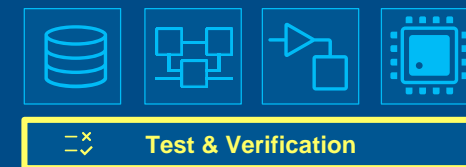
```
>> result.table
```

```
ans =
```

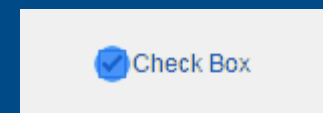
```
2x6 table
```

Name	Passed	Failed	Incomplete	Duration	Details
'test_Predictions/Test_ModelType'	true	false	false	0.12241	[1x1 struct]
'test_Predictions/Test_Prediction'	false	true	true	0.11542	[1x1 struct]

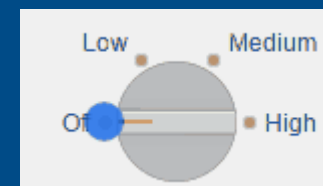
Using the MATLAB App Testing Framework



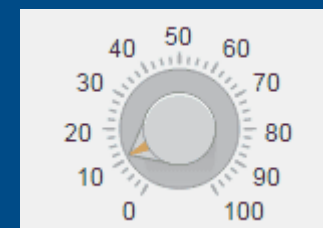
```
testCase.press(myApp.checkbox)
```



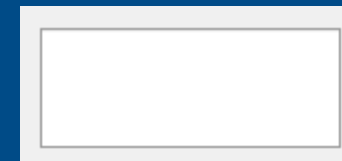
```
testCase.choose(myApp.discreteKnob, "Medium")
```



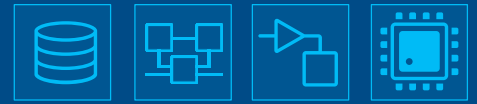
```
testCase.drag(myApp.continuousKnob, 10, 90)
```



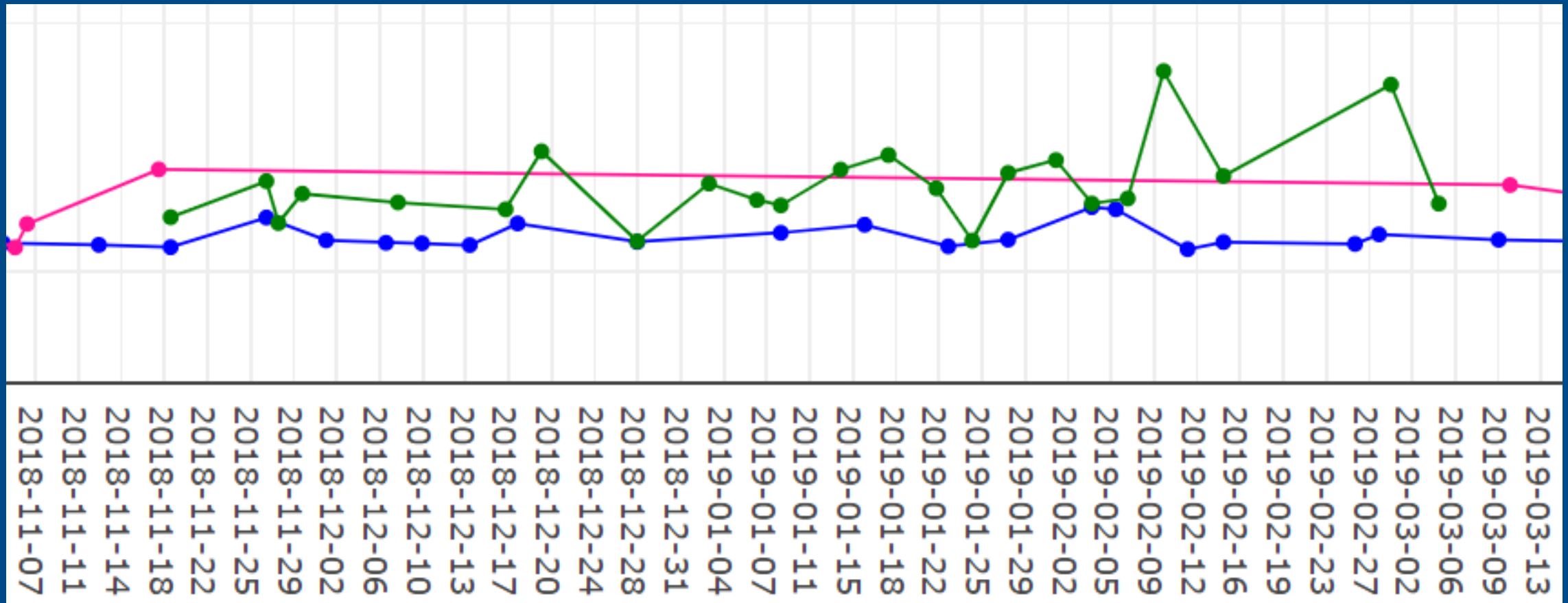
```
testCase.type(myApp.editfield, myTextVar)
```



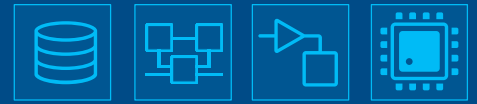
Using the MATLAB Performance Testing Framework



Test & Verification



Using Continuous Integration



Test & Verification

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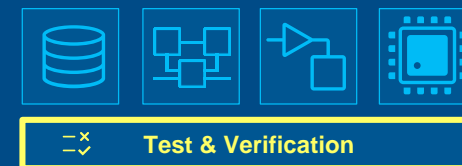
- Platforms
- User interface
- Administration
- Source code management

New Plugins

- QRebel
- MATLAB**
- MISRA Compliance Report
- Zoom
- VectorCAST Execution
- Klocwork Community
- JQuery
- Analysis Model API

MATLAB

Using Continuous Integration



JenkinsBlogDocumentation ▾

← Find plugins

MATLAB^{1.0.0}

Minimum Jenkins requirement: 2.7.3
ID: matlab

Installs: No usage data available
[GitHub →](#)
Last released: 2 days ago

Maintainers
MathWorks

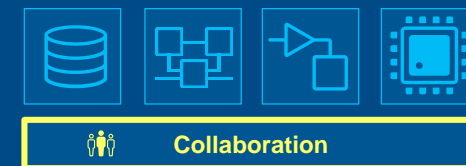
Dependencies
[bouncycastle API v.2.16.0](#) (implied) (what's this?)
[Command Agent Launcher v.1.0](#) (implied) (what's this?)
[JDK Tool v.1.0](#) (implied) (what's this?)
[JAXB v.2.3.0](#) (implied) (what's this?)

The Jenkins plugin for MATLAB® enables you to easily run your MATLAB tests and generate test artifacts in formats such as JUnit, TAP, and Cobertura code coverage reports.

Features

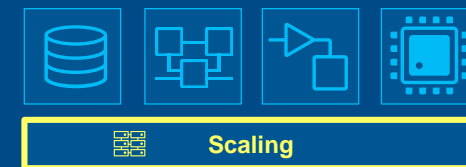
- Support to run MATLAB tests, present in the Jenkins workspace automatically. (This also includes the tests present in .prj files)
- Generate tests artifacts in JUnit, TAP & Cobertura code coverage formats.
- Support to run tests, using custom MATLAB command or custom MATLAB script file.

Using Projects in MATLAB

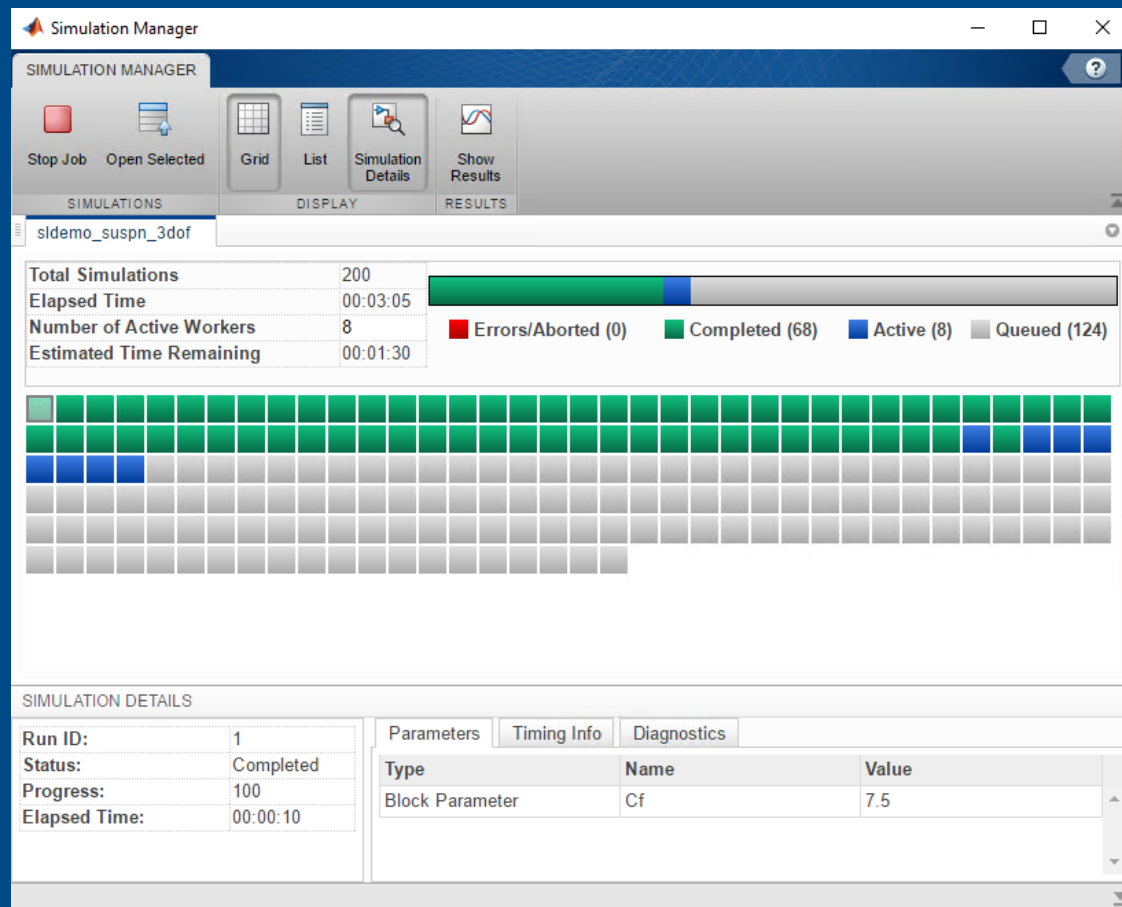


TOOLS				ENVIRONMENT		SOURCE CONTROL			
Search	Custom Tasks	Run Checks	References	Details	Project Path Startup Shutdown	Git Details	Refresh	Commit	Fetch Push Pull Remote Branches
All Project (226) Modified (344)									
Name	Status	Git	Classification						
+Test	✓	■	Test						
ACI	✓	•							
Dashboard	✓	•							
Documents	✓	•							
Elasticsearch	✓	•							
MachineLearning	✓	■							
MATLAB_Kafka_Producer_Java	✓	•							
mps_stream	✓	■							
SimExecutable	✓	•							
Simulation	✓	•							
DocExample_MultiClassFaultDetectionUsi...	✓	●	Design						
genPumpData.m	✓	●	Design						
javasetup.m	✓	+	Design						
Main_ExampleWorkflow.mlx	✓	●	Design						
MLModels.mat	✓	●	Design						
rawdata.mat	✓	●	Design						
README.md	✓	●							

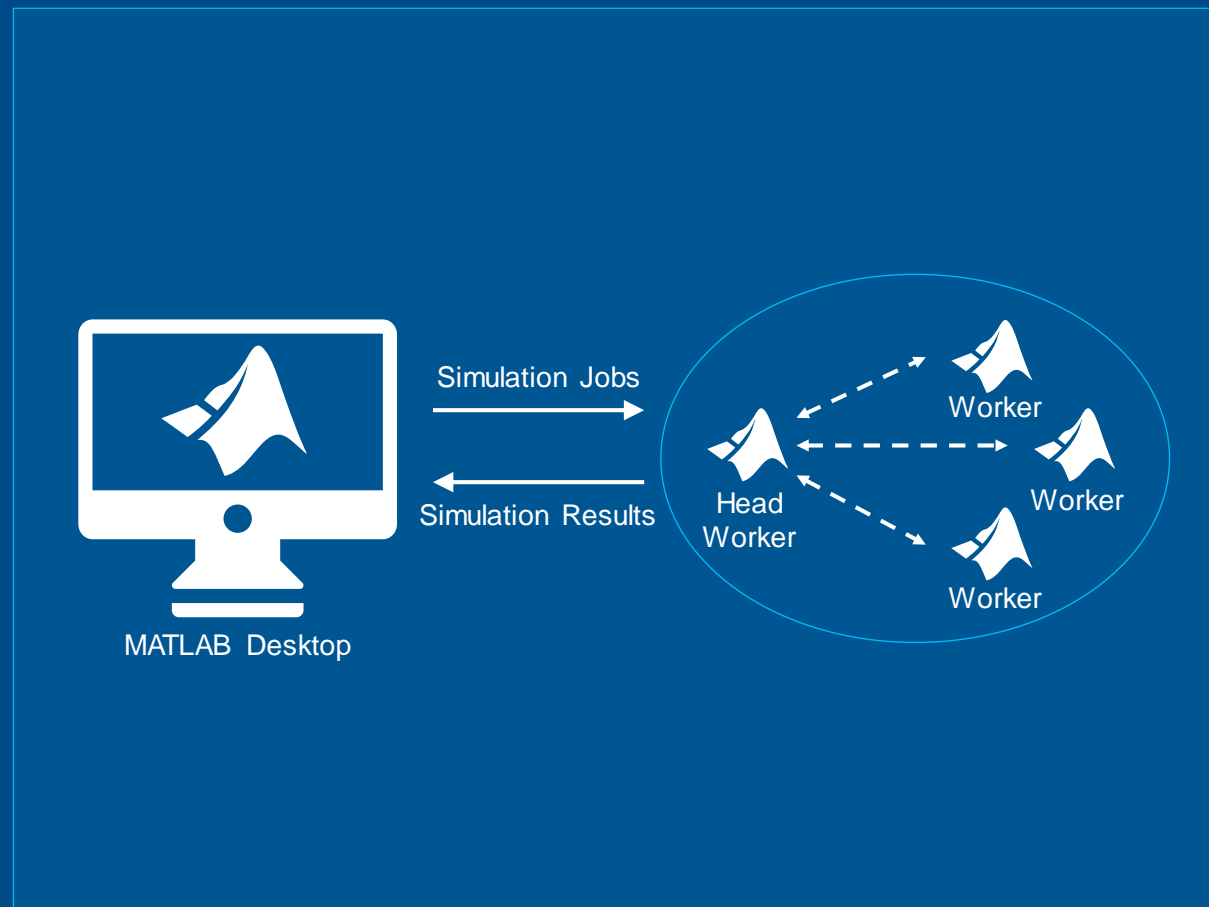
Parallel Simulations in Simulink



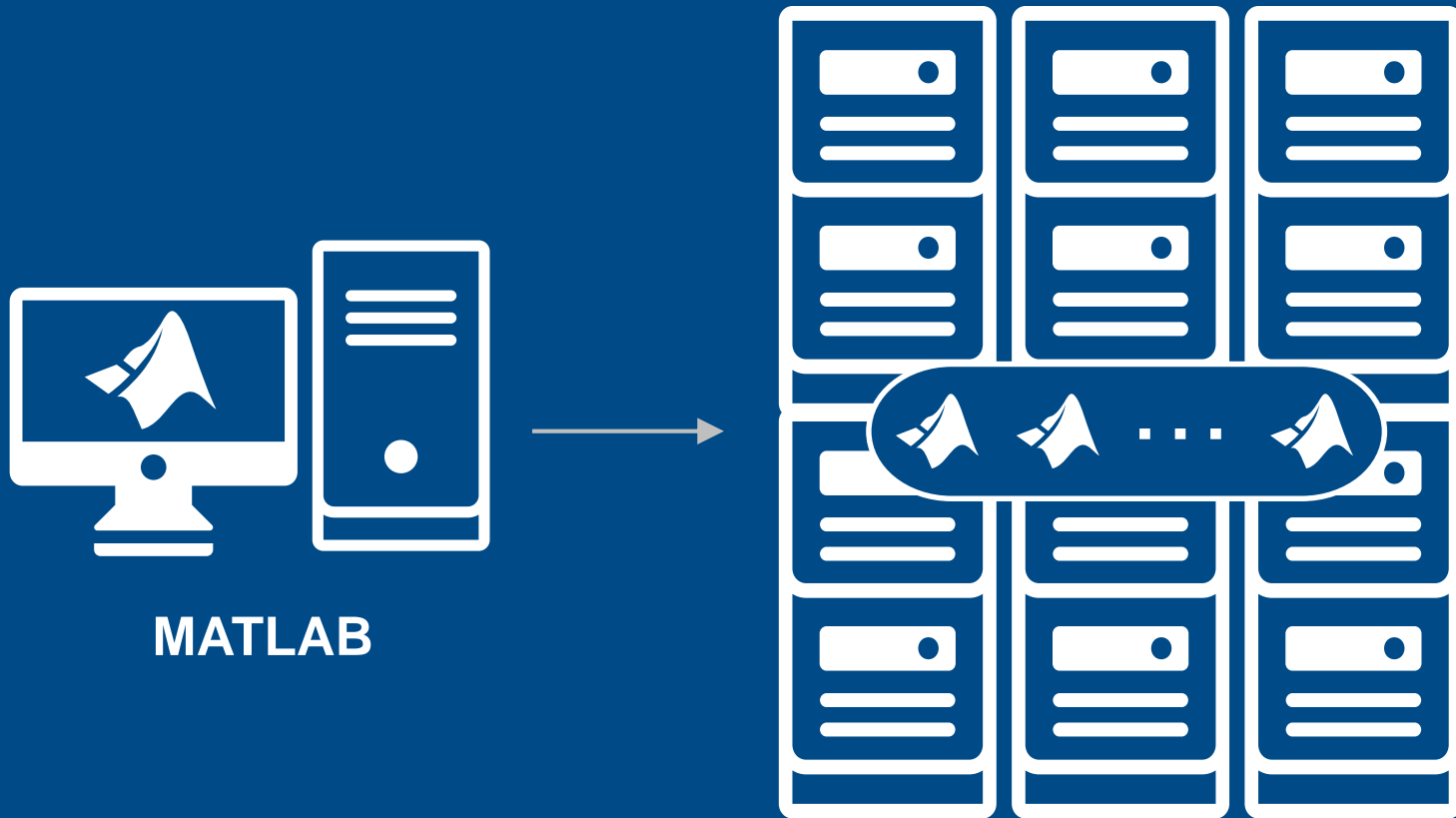
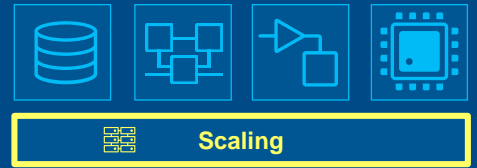
Simulation Manager



batchsim



Scaling Computations on Clusters and Clouds



MATLAB

Parallel Computing Toolbox

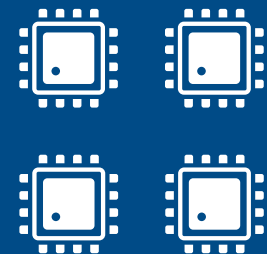
MATLAB Parallel Server



Cloud

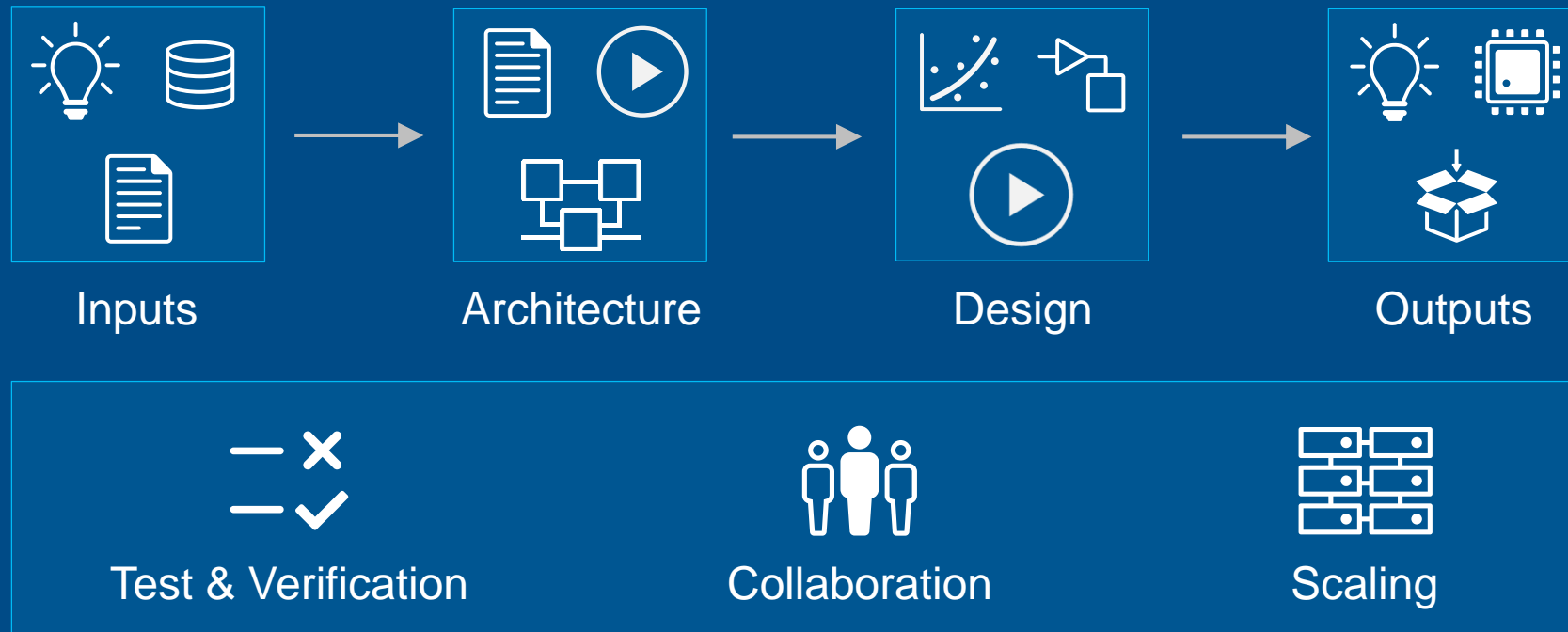


GPU



Multi-core CPU

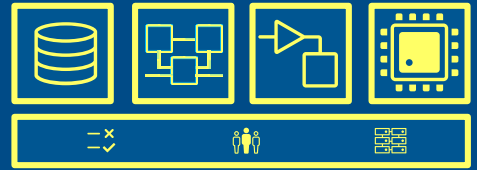
Using MATLAB & Simulink to Build Algorithms in Everything



MATLAB® & SIMULINK®



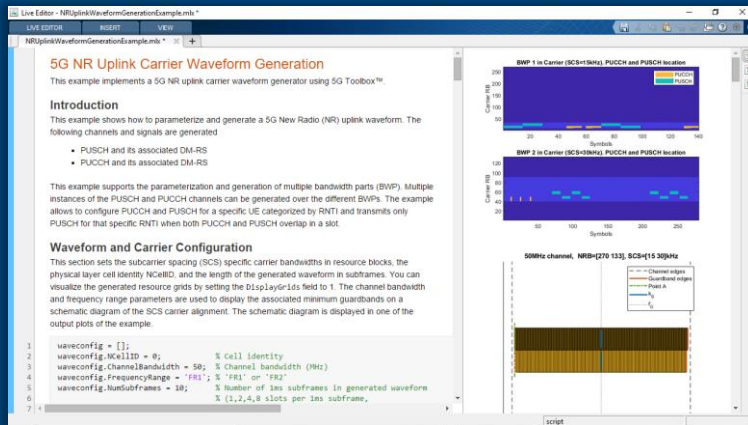
Specialized Tools for Building Algorithms in Everything



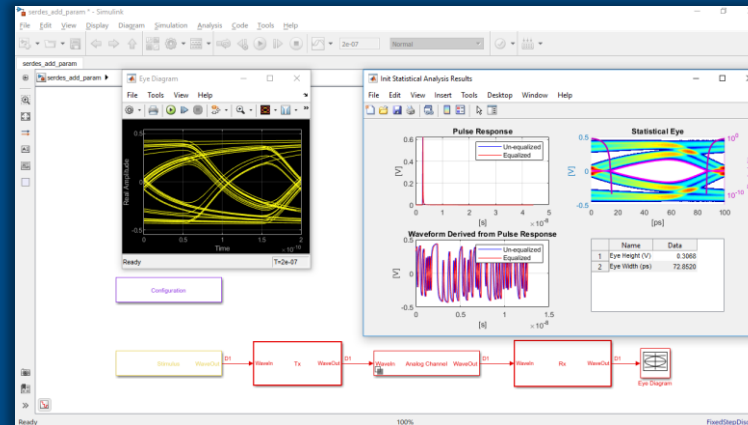
Communications

Physical interconnects

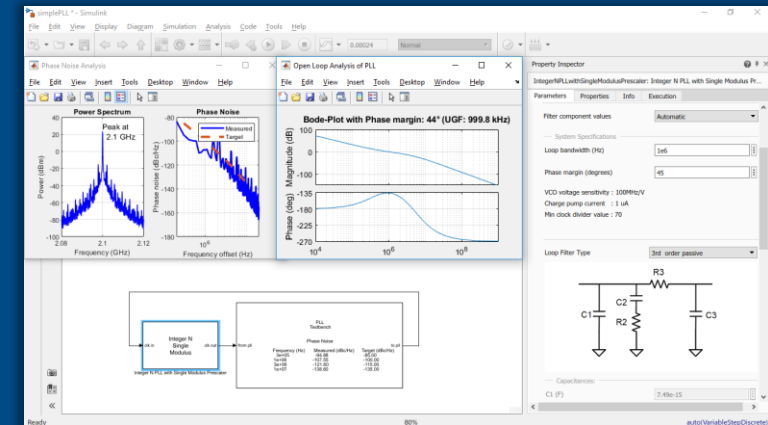
Analog Mixed-Signal



5G Toolbox

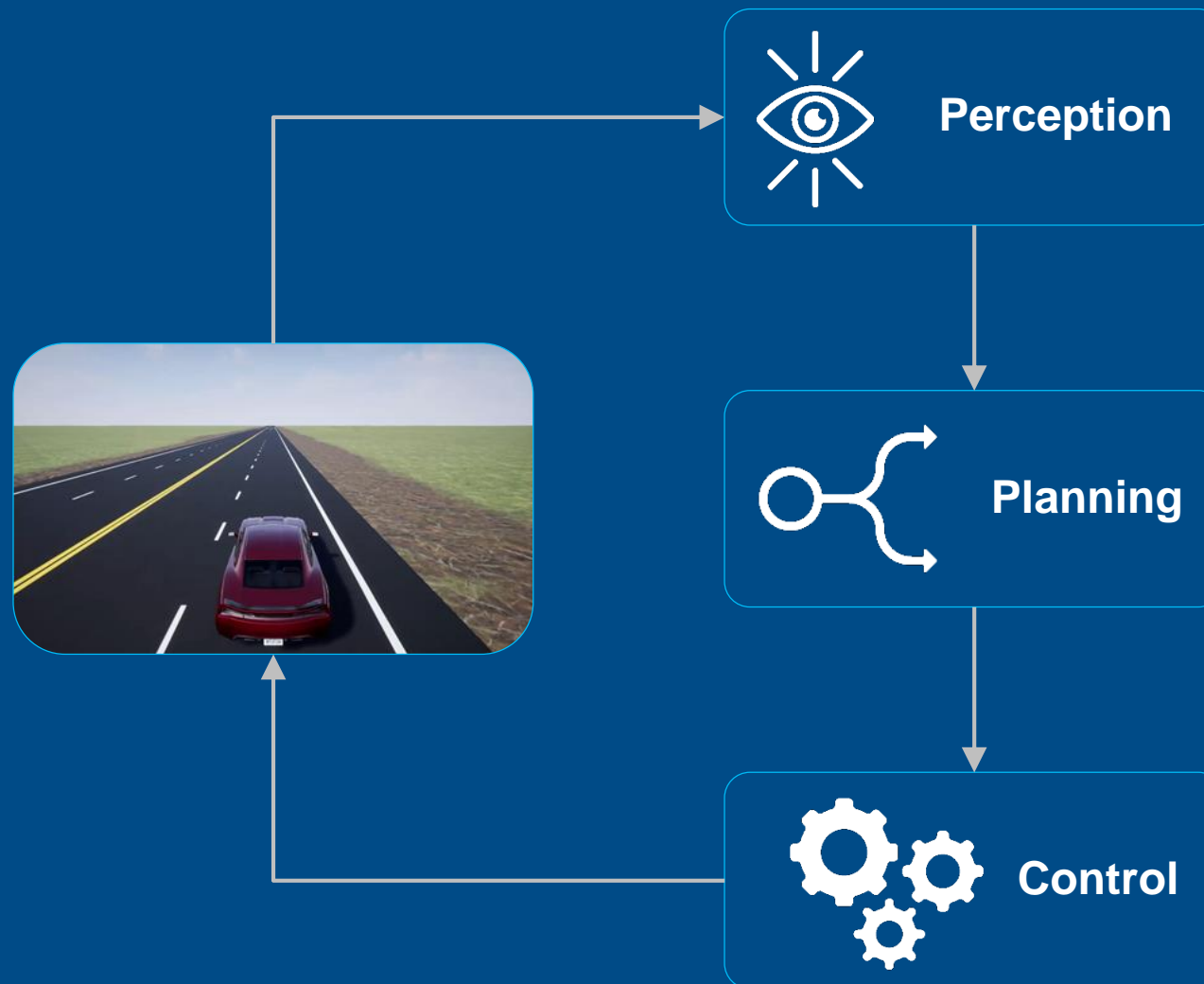


SerDes Toolbox

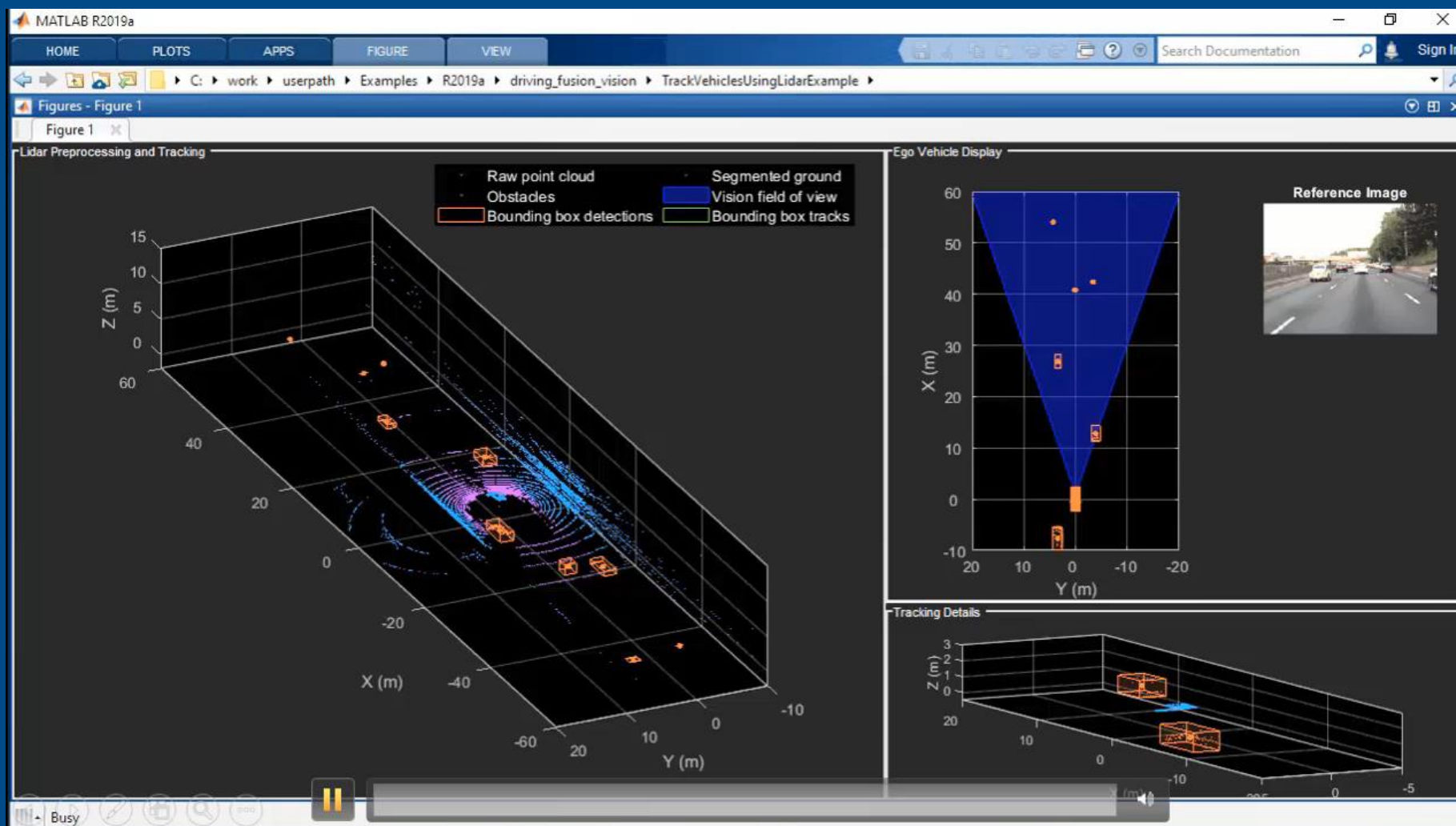
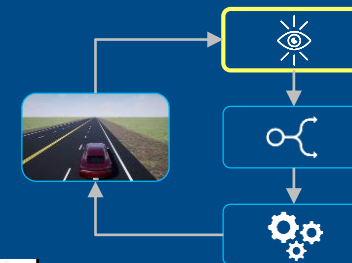


Mixed-Signal Blockset

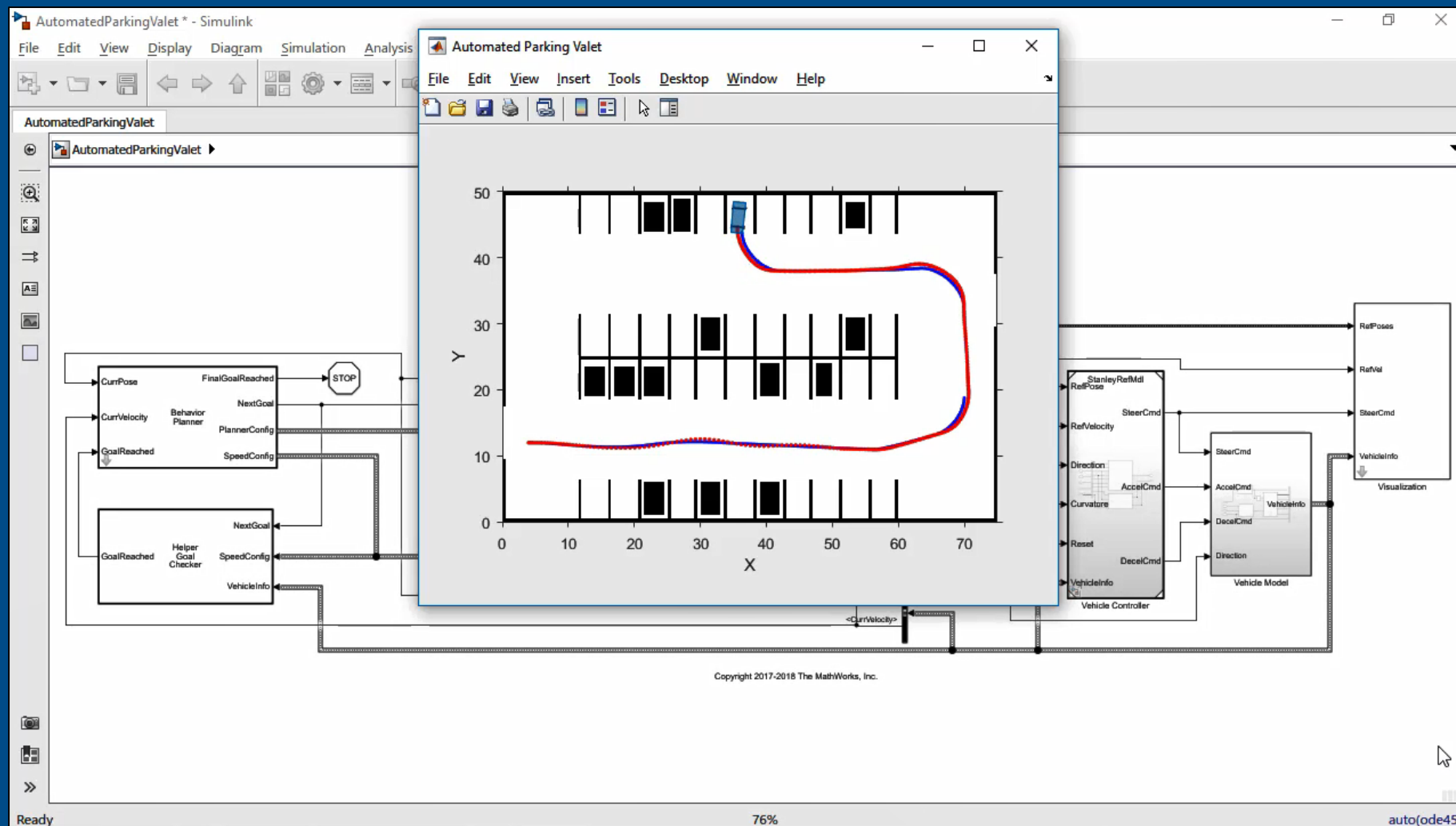
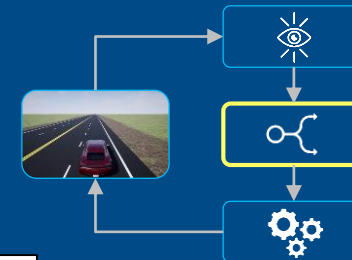
Developing Autonomous Systems

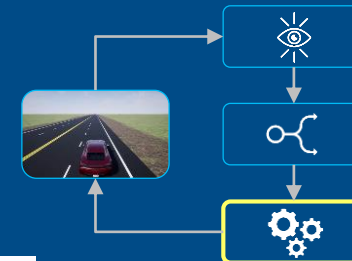


Evaluate Sensor Fusion Architectures

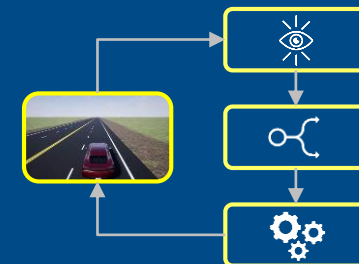


Simulate Path Planning Algorithms

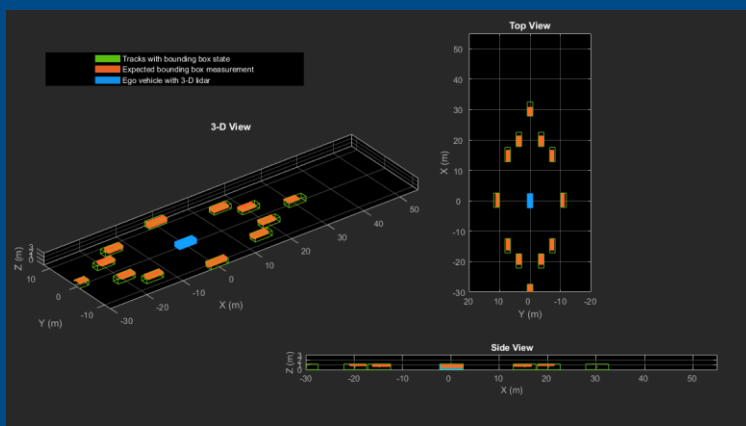




Developing Autonomous Systems

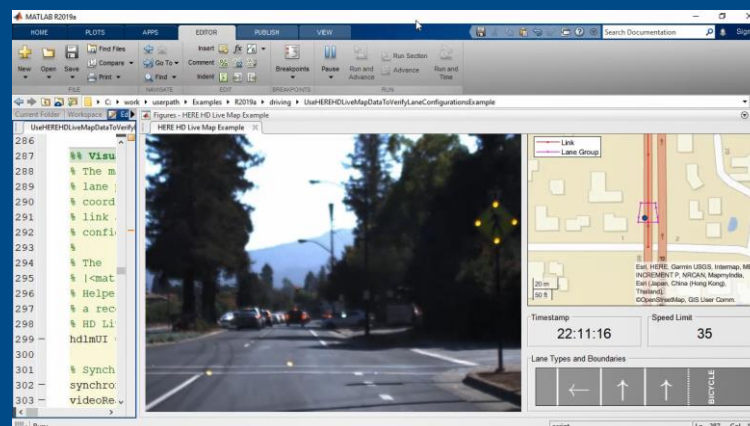


Lidar Processing
& Tracking



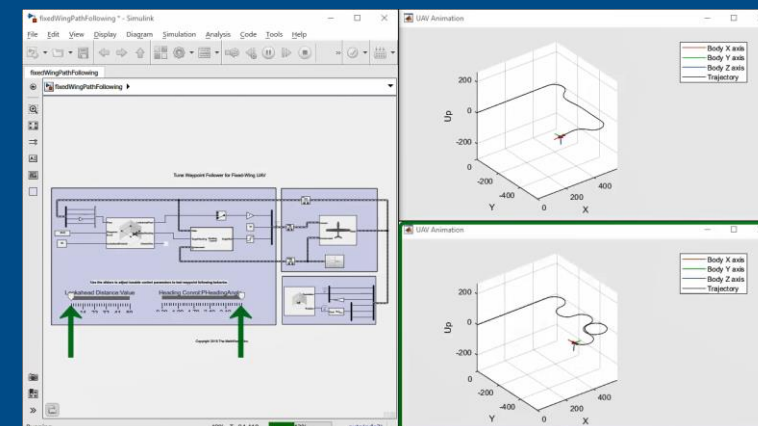
Computer Vision Toolbox

HERE HD Maps &
OpenDRIVE Roads



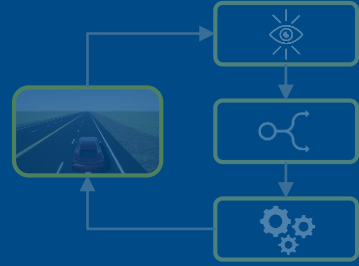
Automated Driving Toolbox

UAV Algorithms



Robotics System Toolbox

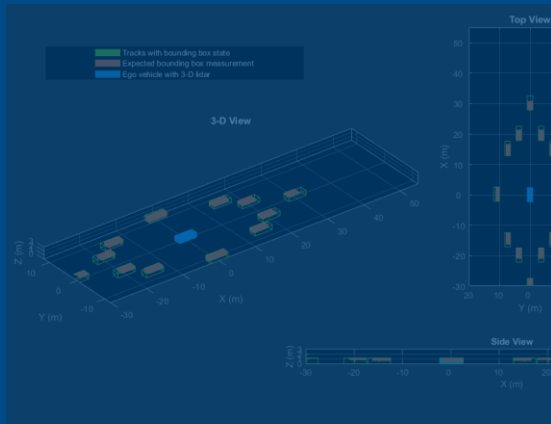
Developing Autonomous Systems



Lidar Processing
& Tracking

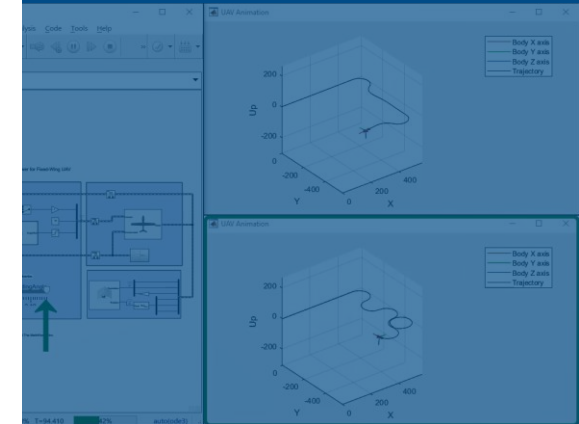
HERE HD Maps &

UAV Algorithms



Find out more:
**Automated Driving System Design
and Simulation**

Dr. Amod Anandkumar
**Deep Learning and Autonomous Systems
Track**

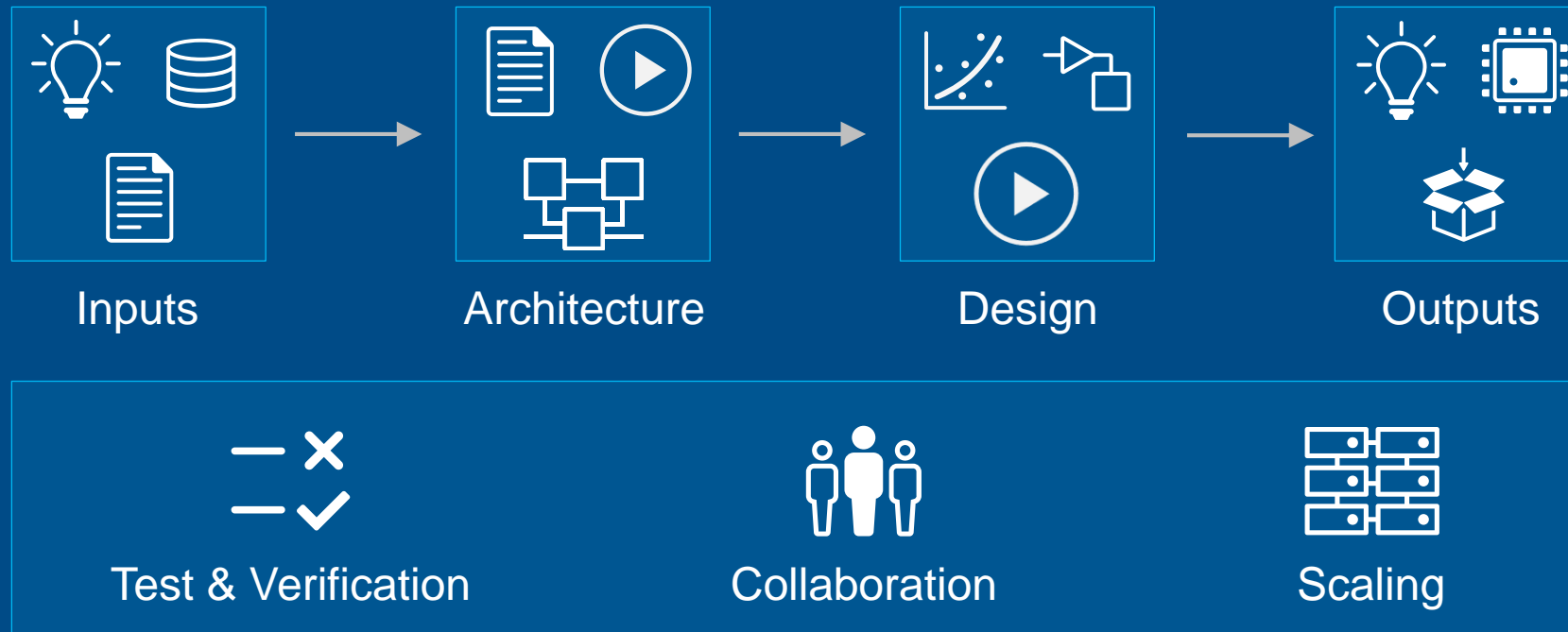


Computer Vision Toolbox

Automated Driving Toolbox

Robotics System Toolbox

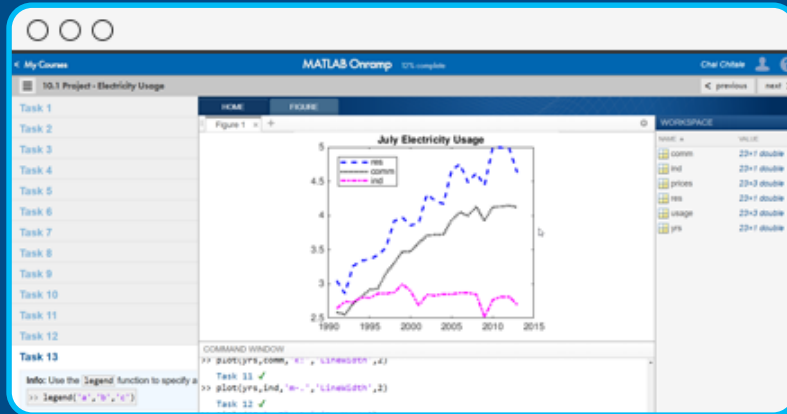
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MATLAB® & SIMULINK®

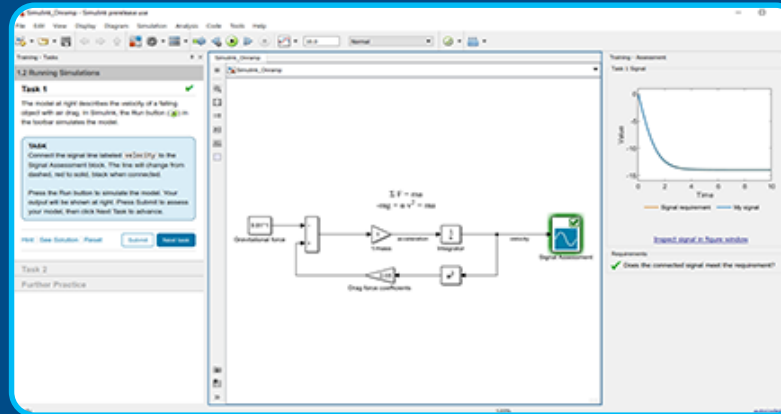


Get Started



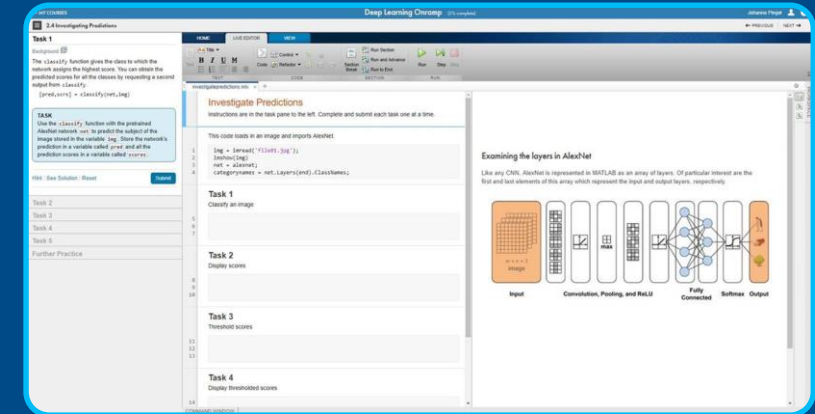
MATLAB Onramp

Quickly learn the essentials of MATLAB.



Simulink Onramp

Learn to create, edit, and troubleshoot Simulink models.



Deep Learning Onramp

Learn to use deep learning techniques in MATLAB for image recognition.

MATLAB EXPO 2019

