MATLAB EXPO 2018

System modeling using Simulink and Simscape

Abhisek Roy
Sruthi Geetha
Veer Alakshendra

Multi-domain Systems

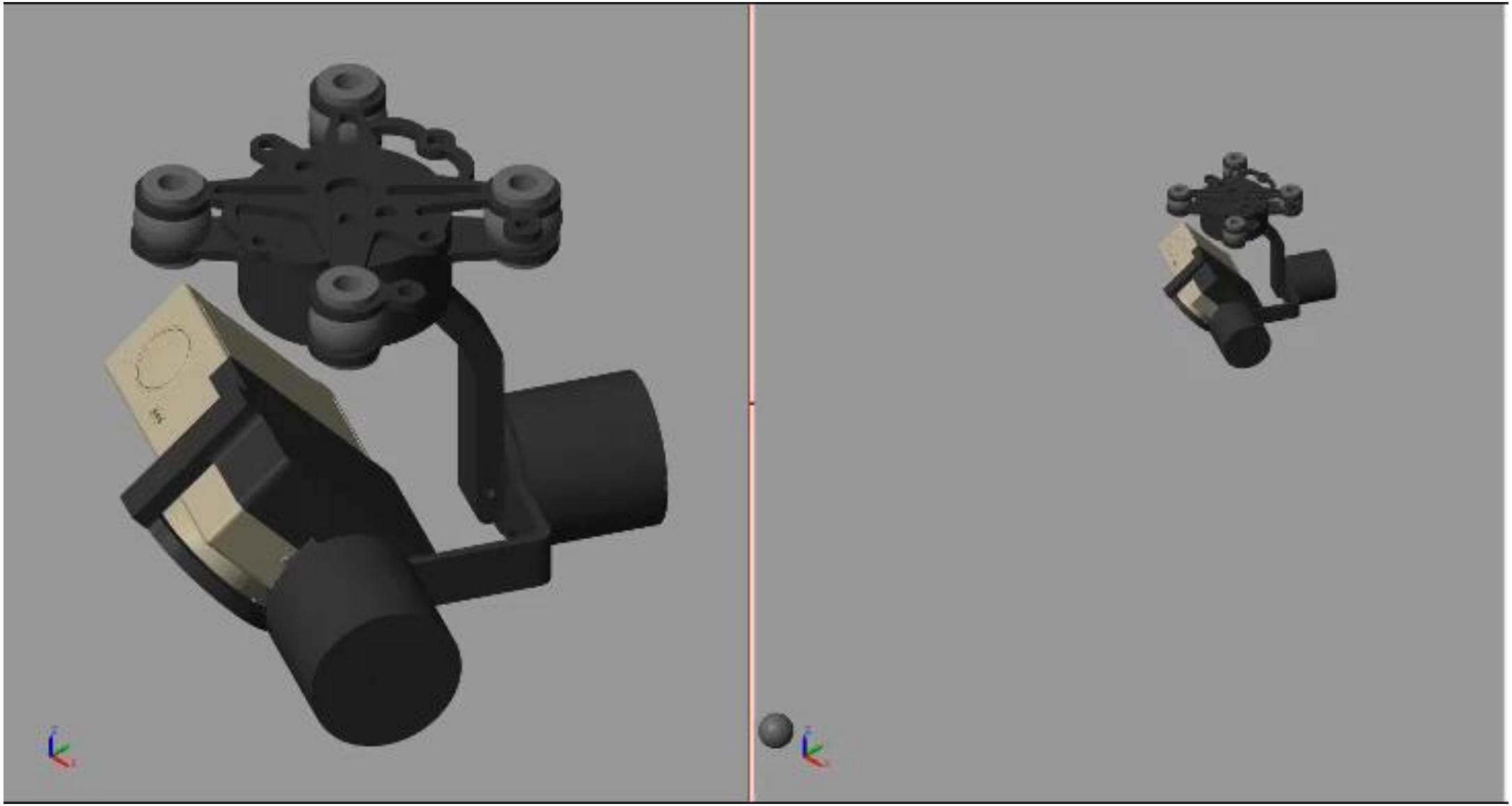
Common challenges

1. Multi-domain simulation
2. Capturing the system dynamics at desired complexity
3. Developing controls algorithm

Pointing System

Source

Pointing System

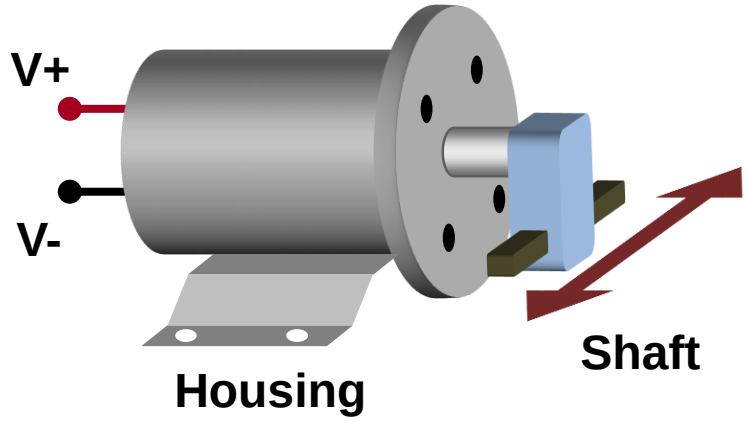


Agenda

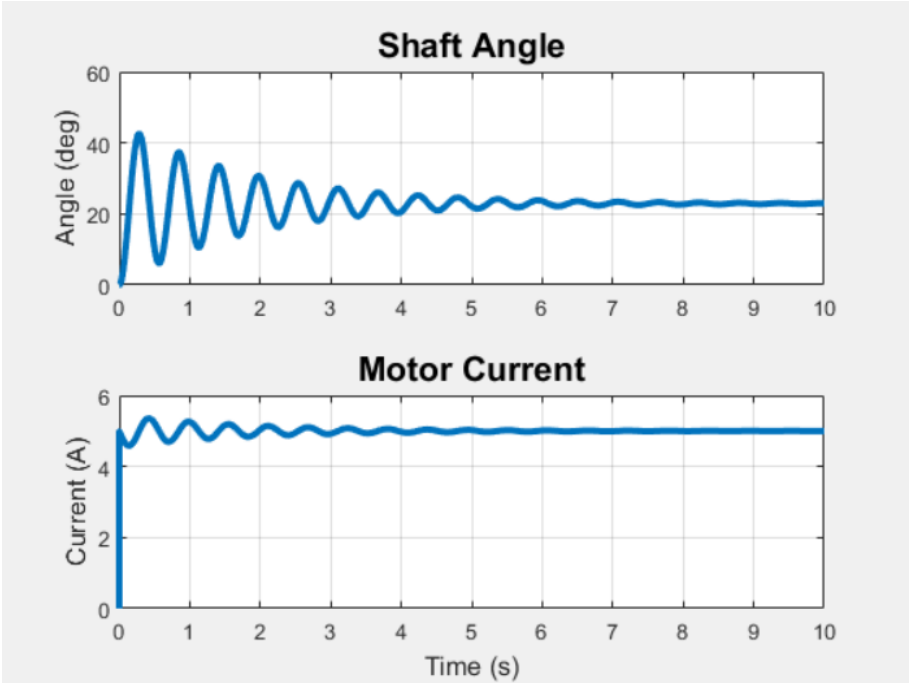
- Understanding and capturing the behavior of a system
  - Various approaches of modeling
  - Example: DC motor
- Model the Pointing System
  - Modeling the mechanism
  - Sizing Actuation System
- Developing control strategy

Modeling a DC Motor

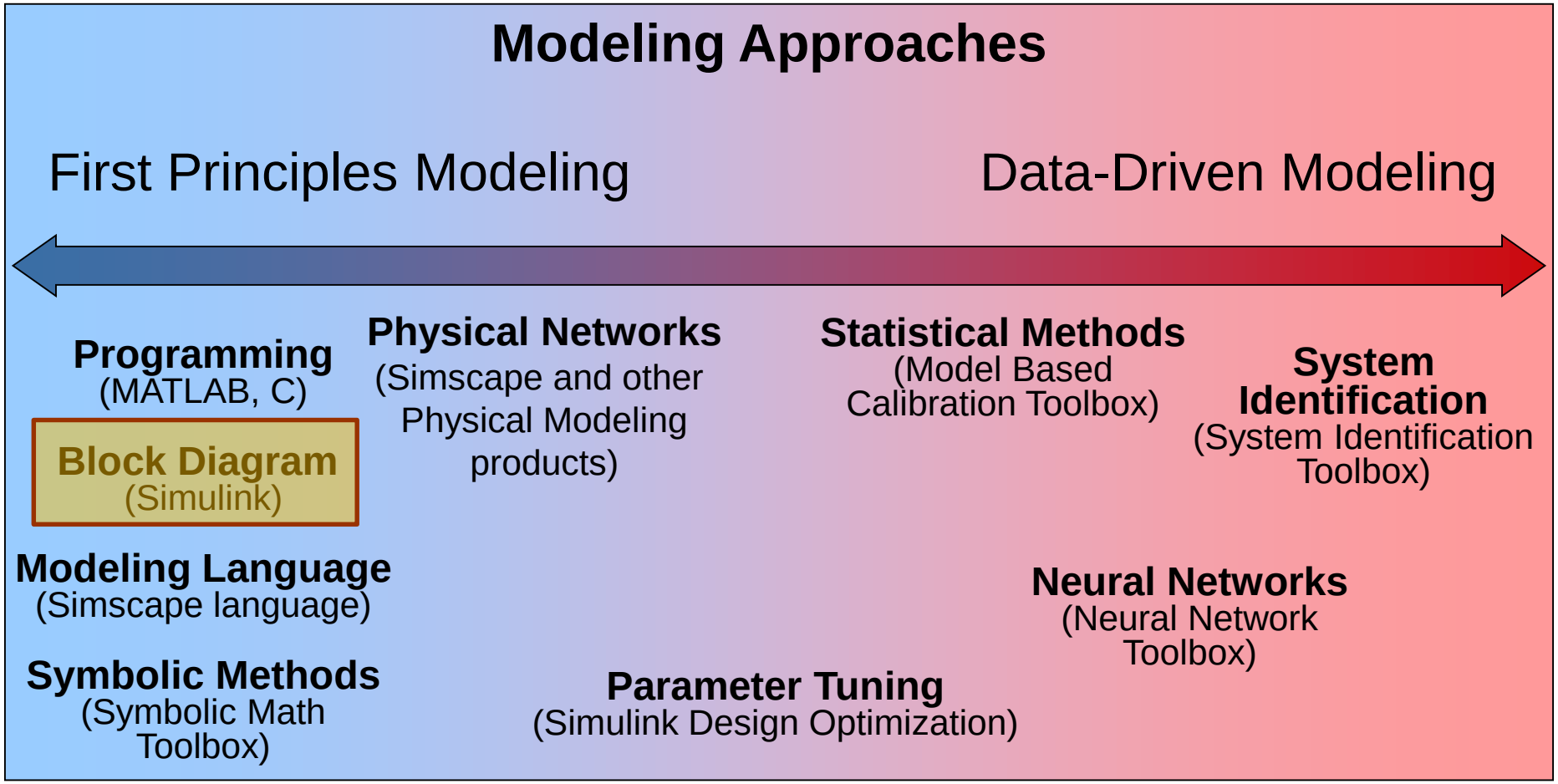
Model:



Problem: Model a DC motor with electrical and mechanical effects



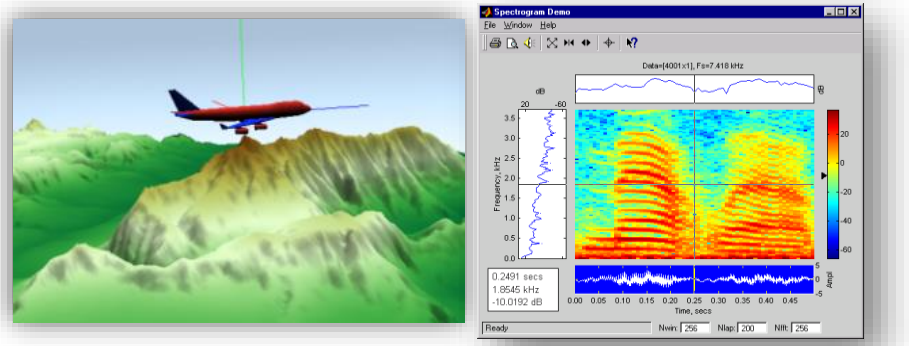
Different Approaches for Modeling Dynamic Systems

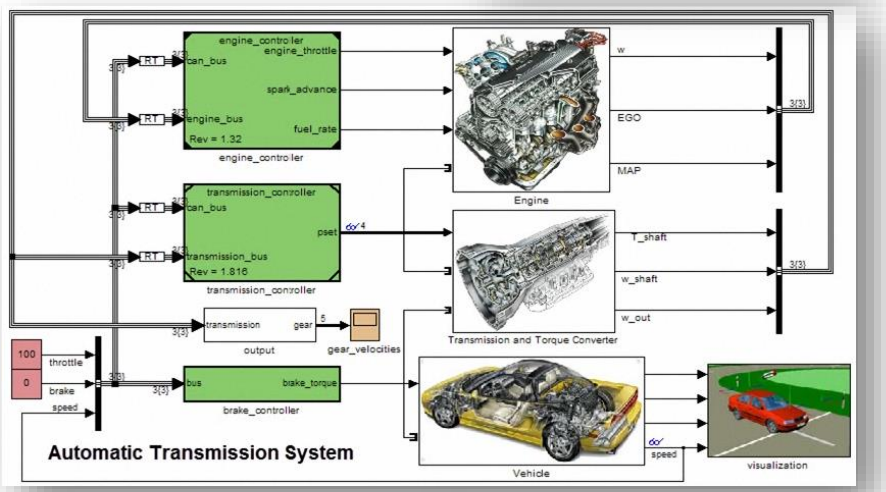


What is Simulink?

The leading environment for modeling, simulating and implementing dynamic and embedded systems

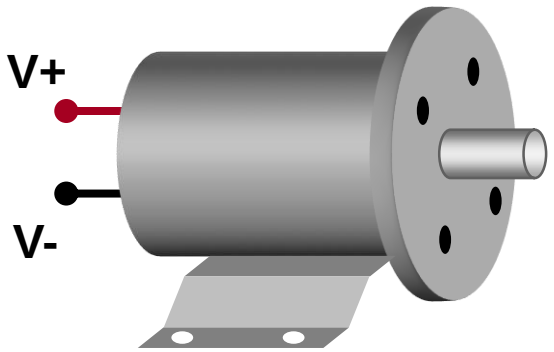
- Block-diagram environment
- Model, simulate, and analyze multi-domain systems
- Accurately design, implement, and test complex systems for:
  - Communications
  - Control
  - Signal processing
  - Video and image processing
- Platform for Model-Based Design

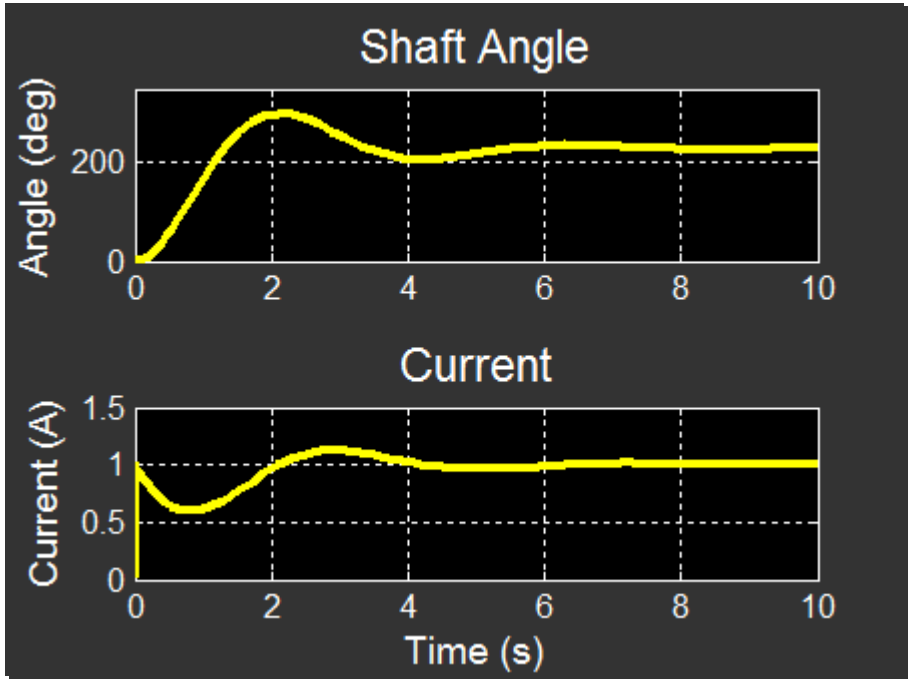




Modeling a DC Motor in Simulink

Model:





How to model a DC Motor in Simulink?

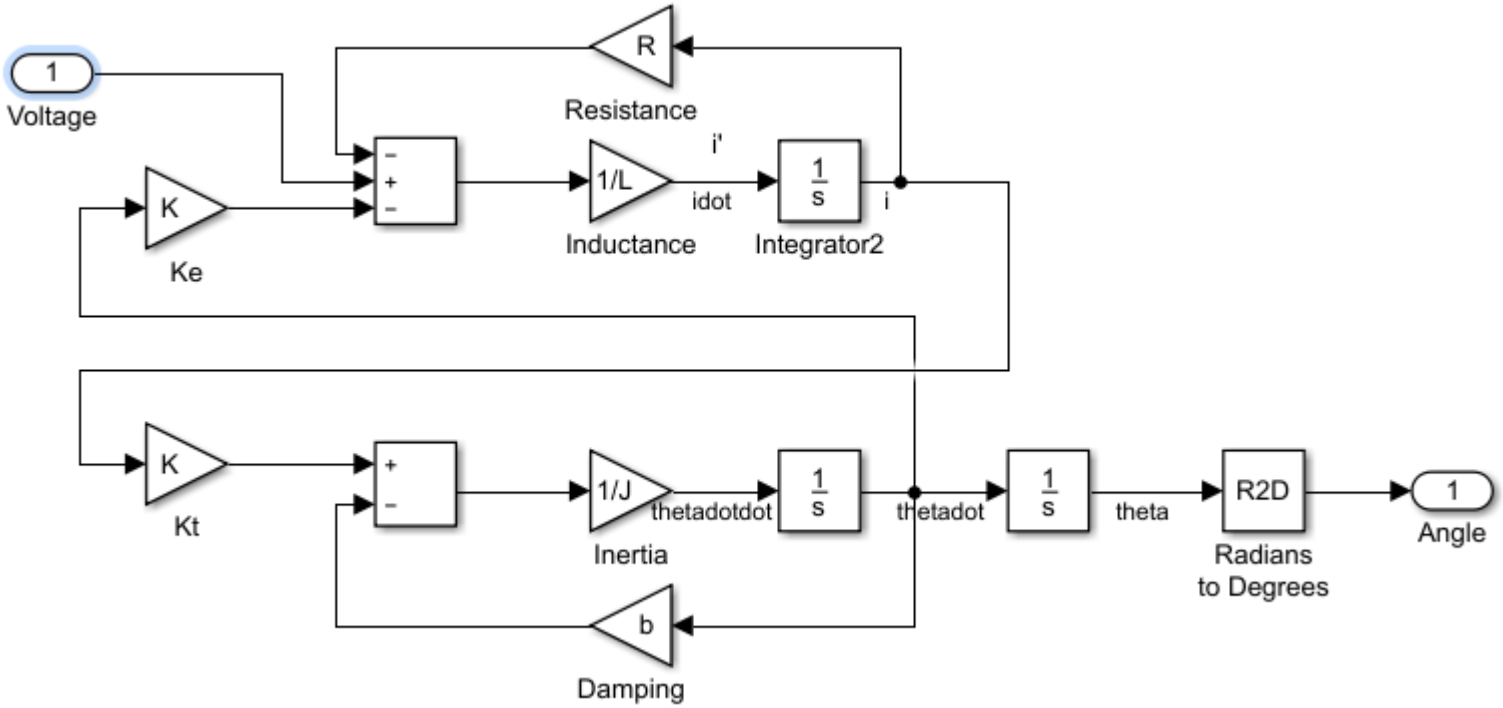
Based on its equation:

$$V = K * w + i * R + L*(di / dt)$$
$$T = Kt * i - b * w - J * (dw / dt)$$

$$di / dt = 1 / L * (- R * i + V - K * w)$$
$$dw / dt = 1 / J * (Kt * i - T - b * w)$$

$$i = integral\{ 1/L * (- R * i + V - K * w)\}$$

$$w = integral \{ 1/J * (Kt * i - T - b * w)\}$$



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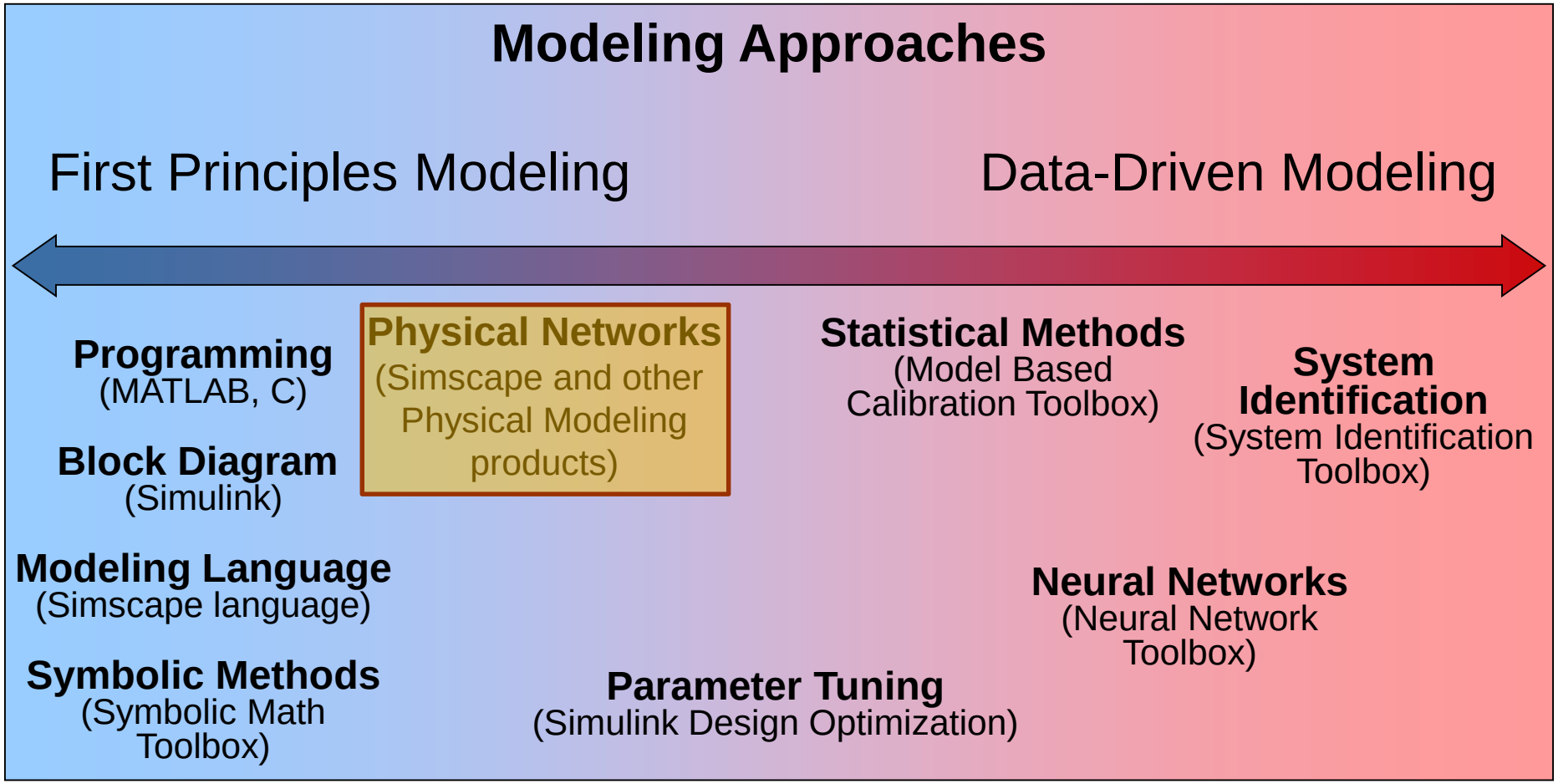
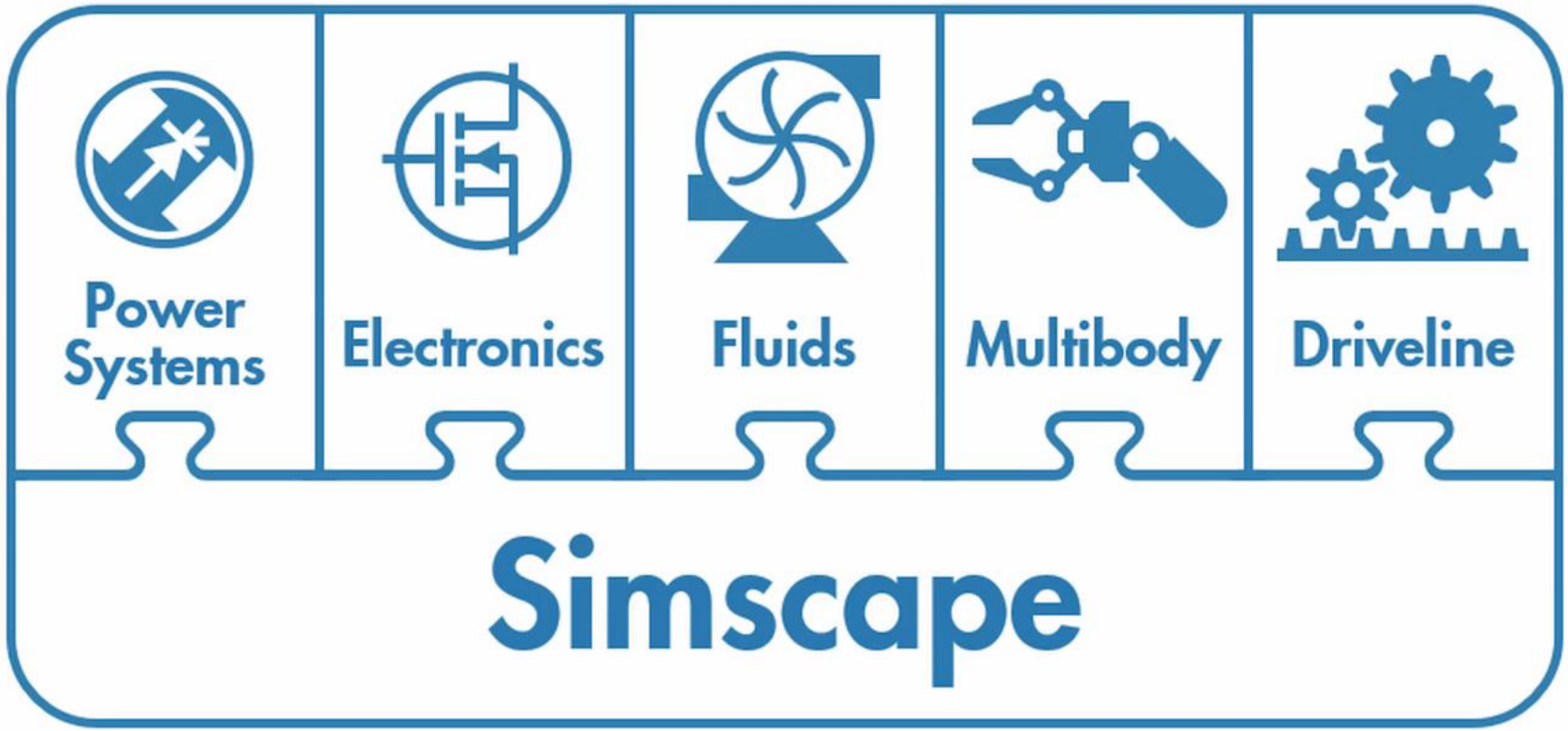
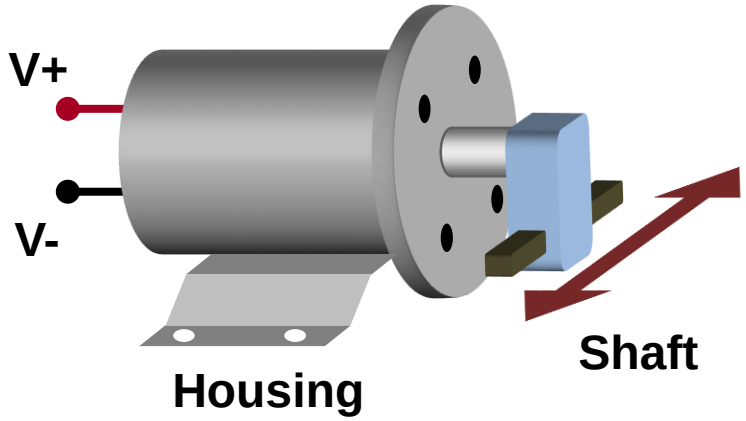


Introduction to Simscape



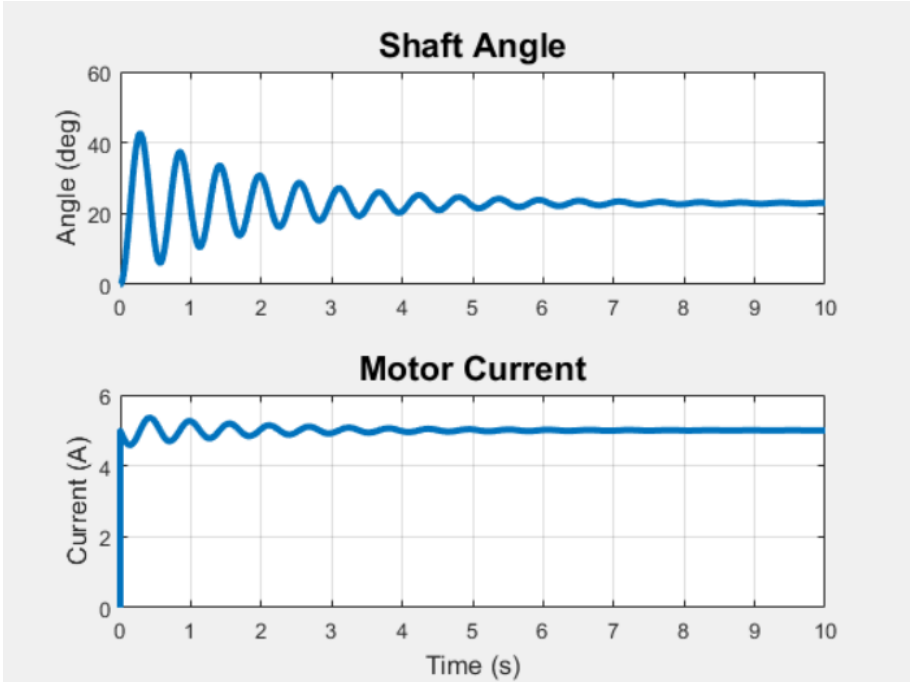
Modeling a DC Motor

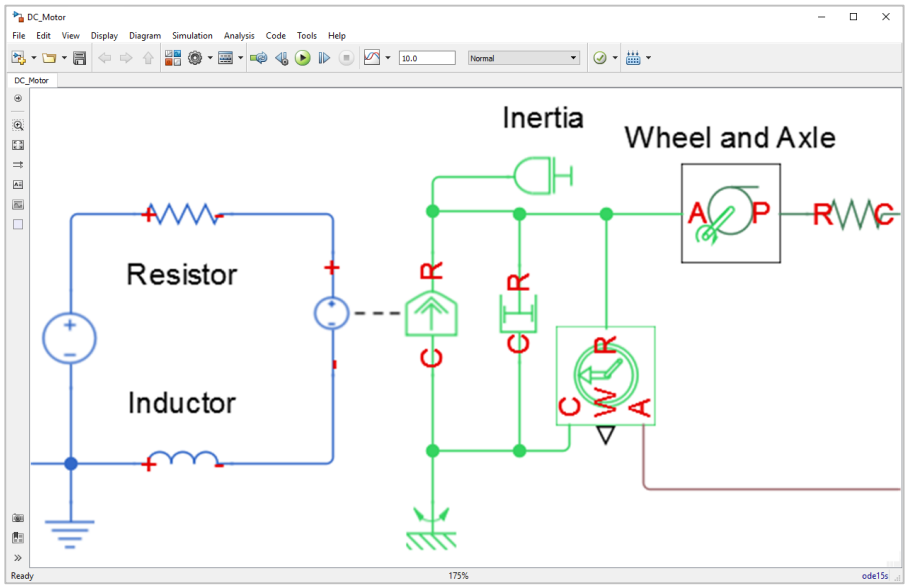
Model:



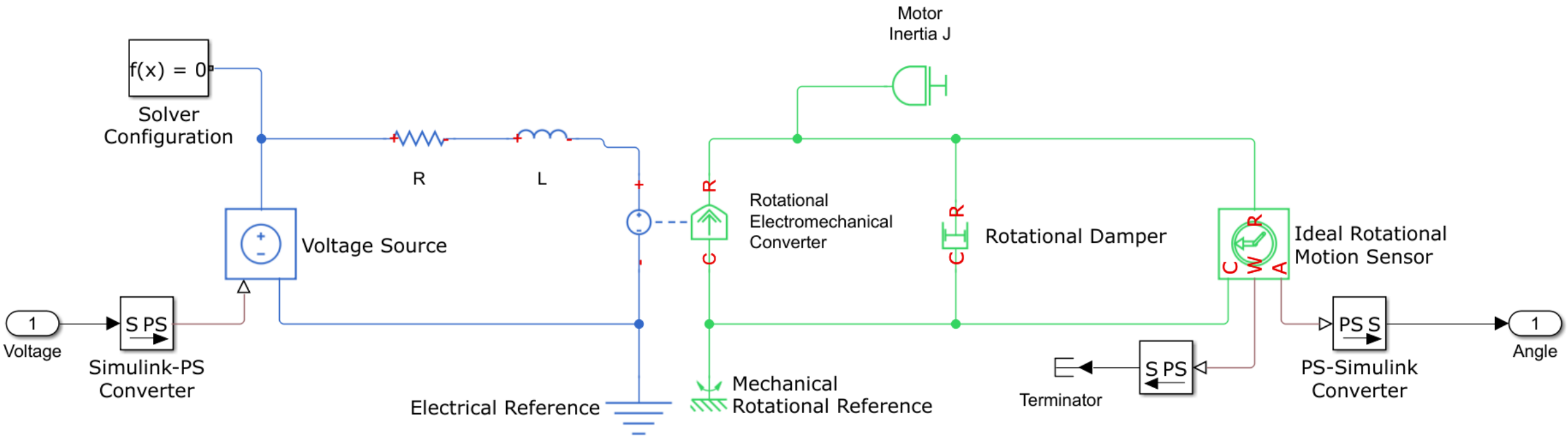
Problem: Model a DC motor with electrical and mechanical effects

Solution: Use Simscape to model the electromechanical system as a physical network



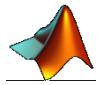


DC Motor in Simscape



Agenda

- Understanding and capturing the behavior of a system
  - Various approaches of modeling
  - Example: DC motor



Model the Pointing System
  - Modeling the mechanism
  - Sizing Actuation System

- Developing control strategy

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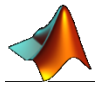
  -  Modeling the mechanism
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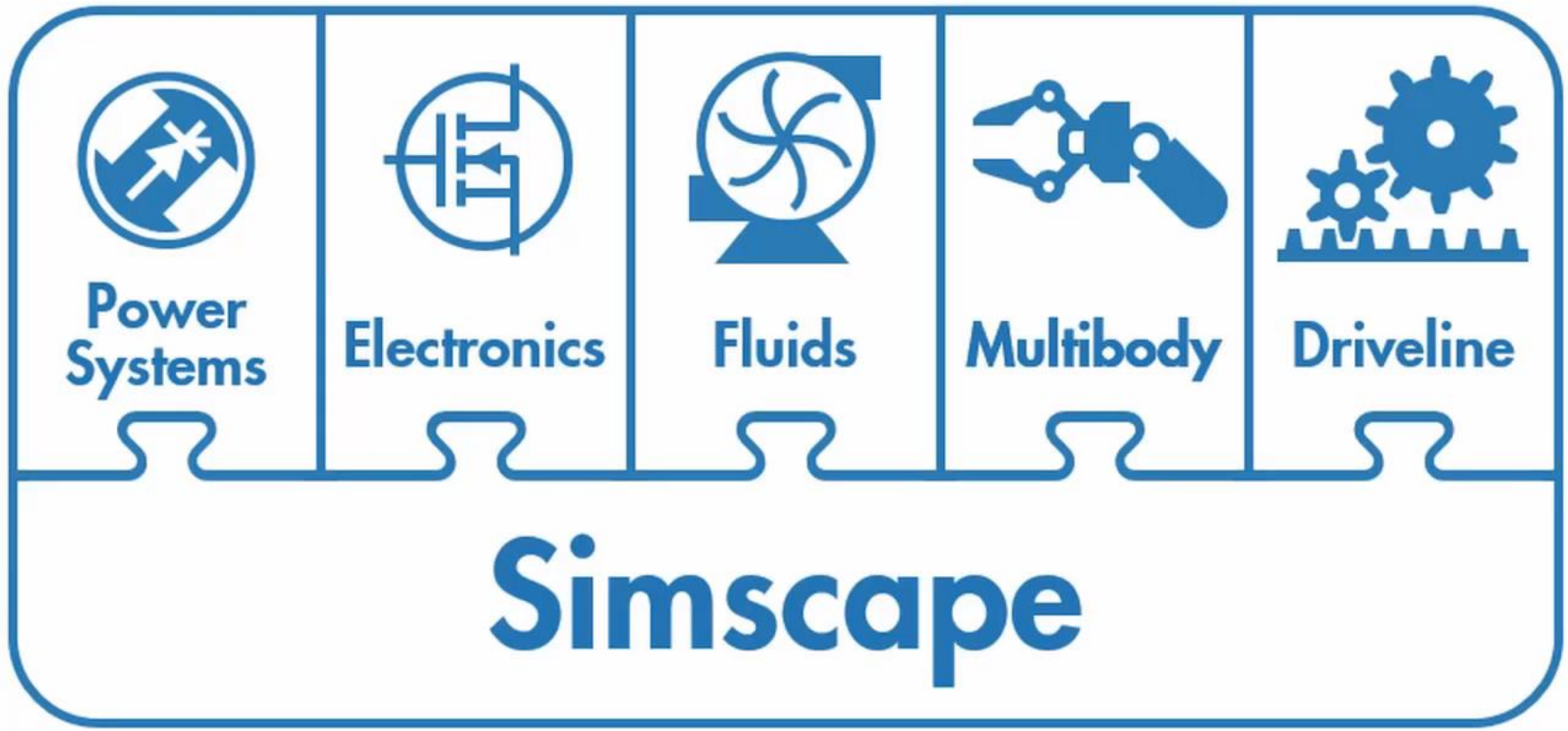
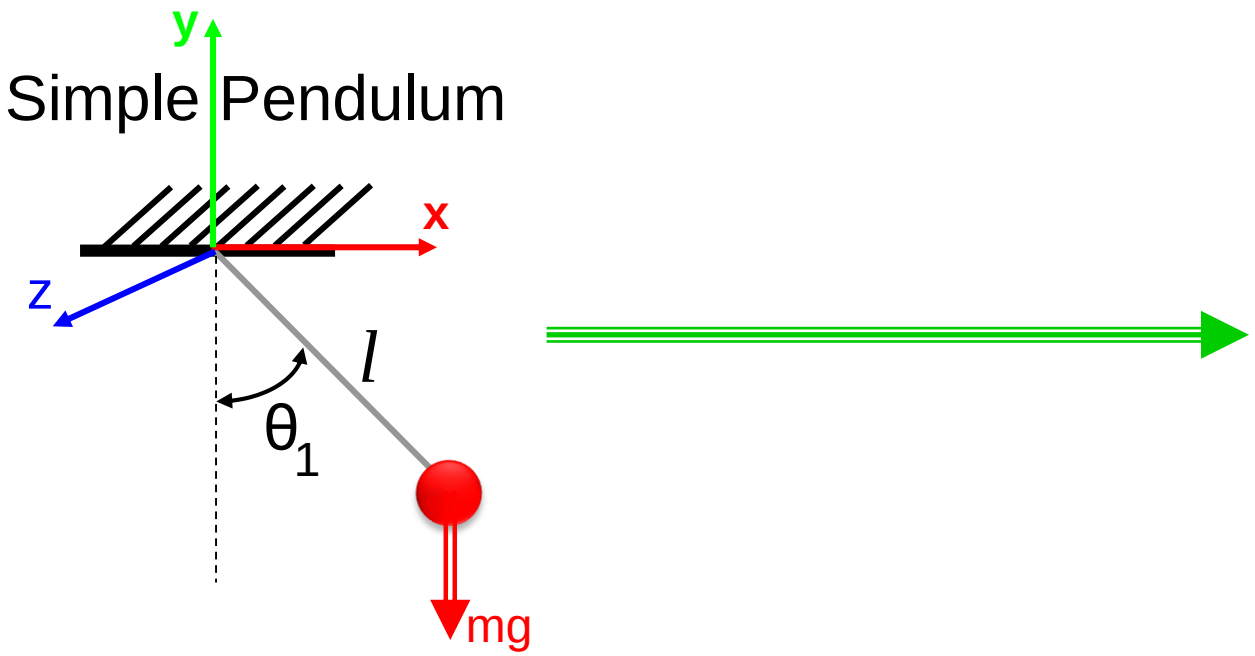
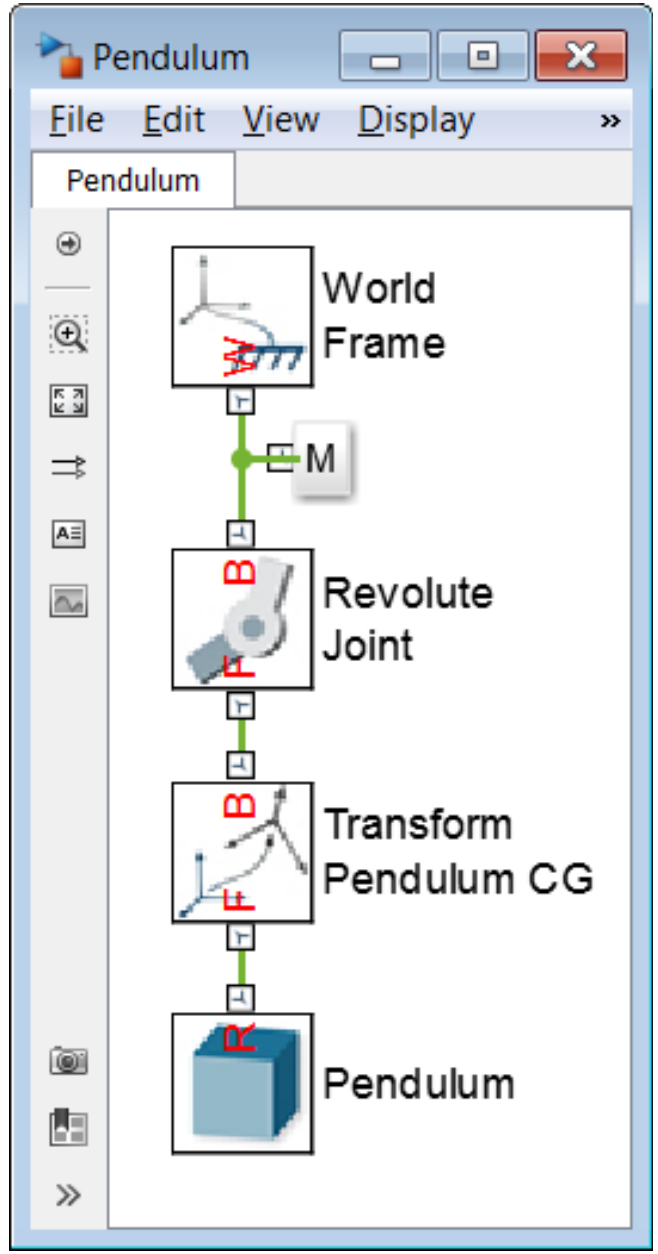
Mechanism


Power Systems
Electronics
Fluids
Multibody
Driveline
Simscape

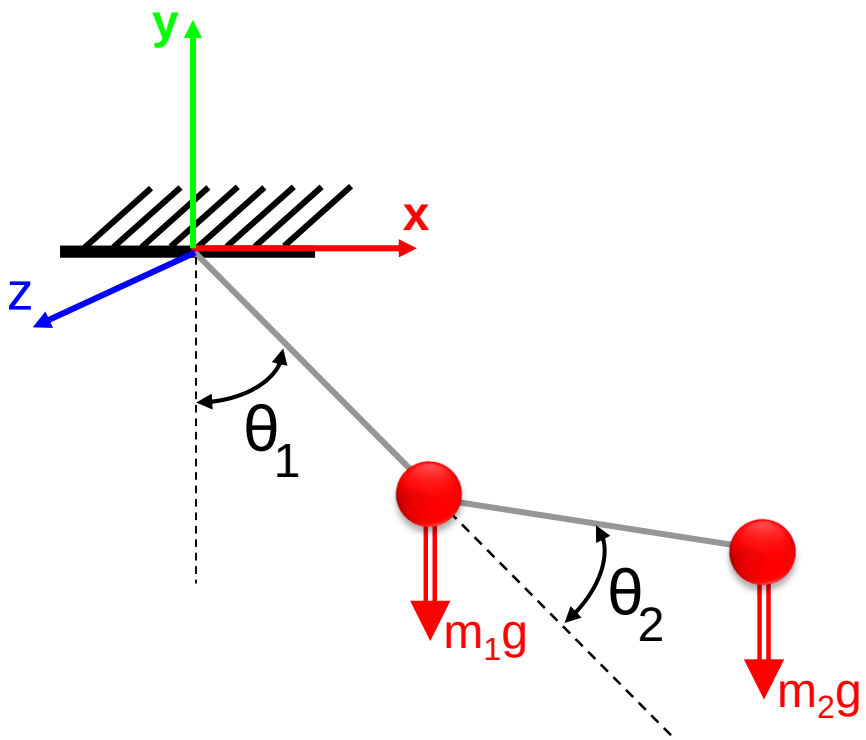
Example: Single Pendulum





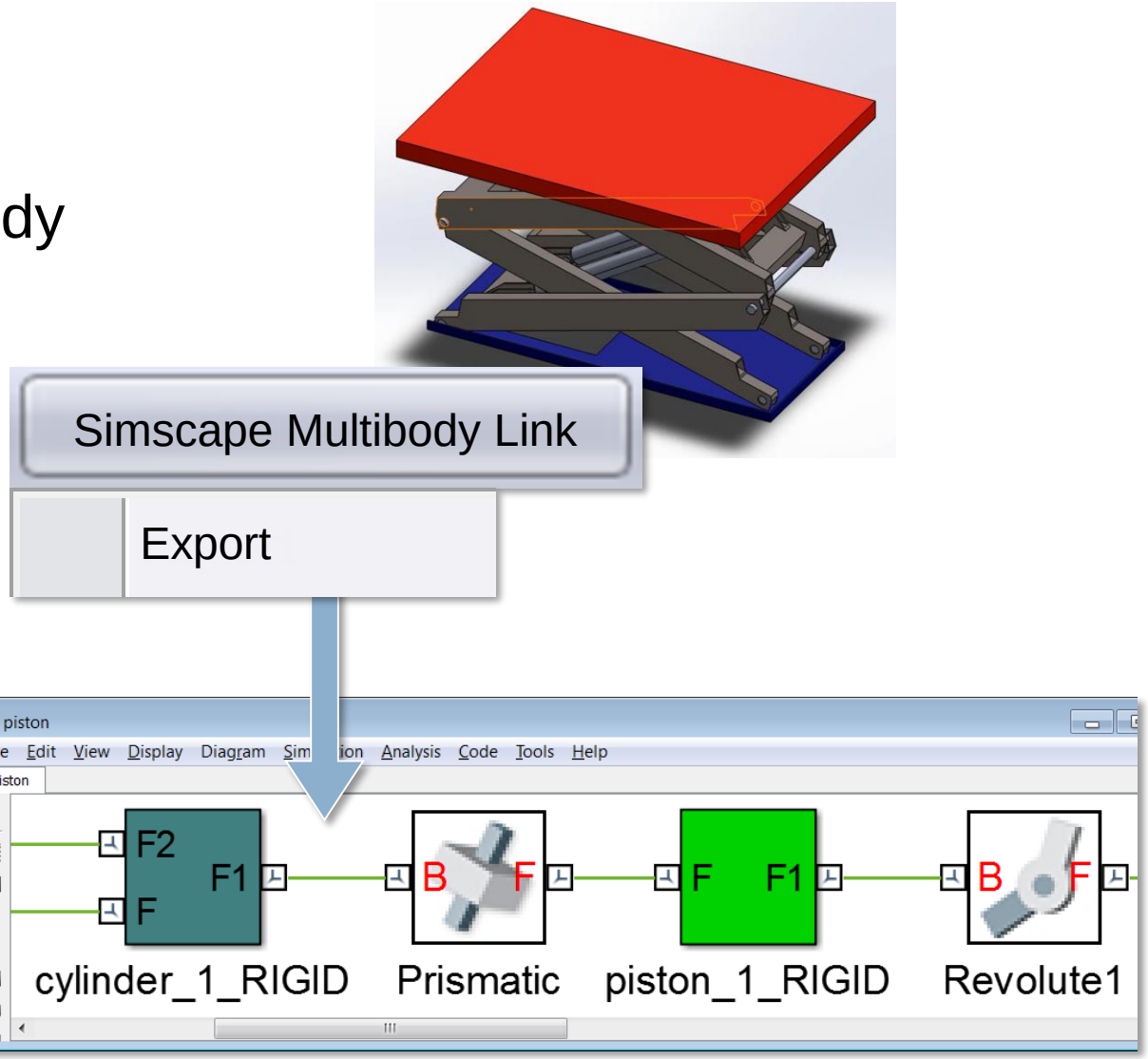
- Simscape Multibody model advantages
  - Easier to read than equations
  - Quicker to create
  - More intuitive – easier to explain to other engineers

Exercise: Double Pendulum



Import CAD Data Using Simscape Multibody Link

- Automatically create Simscape Multibody models from a CAD assembly
  - Converts mass and inertia to rigid bodies
  - Converts mate definitions to joints
  - Creates STEP files for use with Simscape Multibody visualization
- Directly connects SOLIDWORKS, PTC Creo® (Pro/ENGINEER®) and Inventor
- Free download from **www.mathworks.com**
  - Requires MATLAB



Simscape Multibody Link:
Convert CAD Assembly to Simscape Mutibody

- Use Simscape Multibody Link plugin to export from CAD to XML
- Import XML file into Simscape Multibody (**`>> smimport`**)

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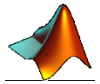
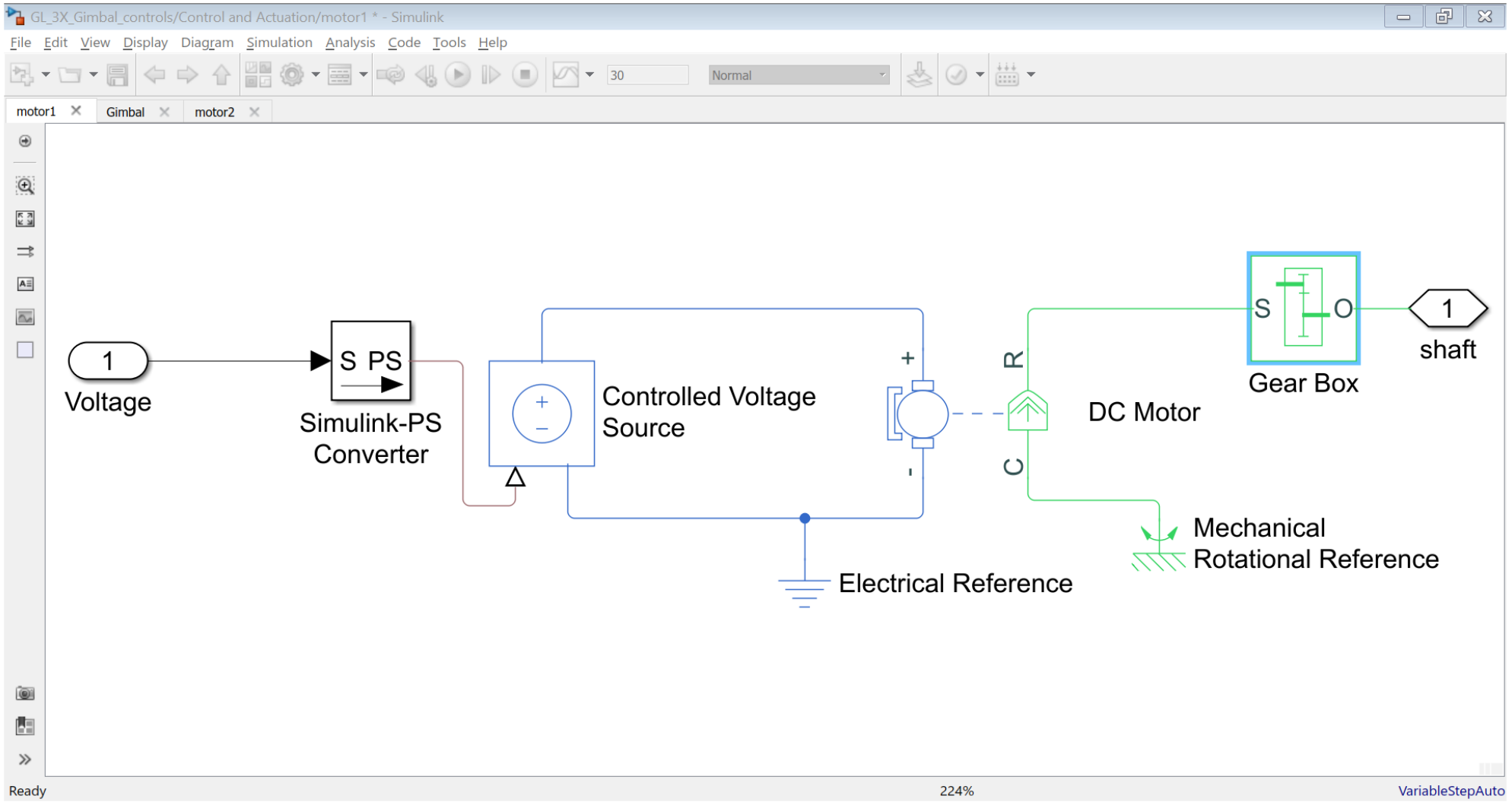
  - 
    Sizing Actuation System
- Developing control strategy

Actuation


GL_3X_Gimbal_controls/Control and Actuation/motor1 * - Simulink
File Edit View Display Diagram Simulation Analysis Code Tools Help
30
Normal
motor1
Gimbal
motor2
1
Voltage
S PS
Simulink-PS
Converter
Controlled Voltage
Source
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C
DC Motor
S
O
Gear Box
1
shaft
Mechanical
Rotational Reference
Electrical Reference
Ready
224%
VariableStepAuto

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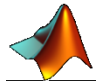
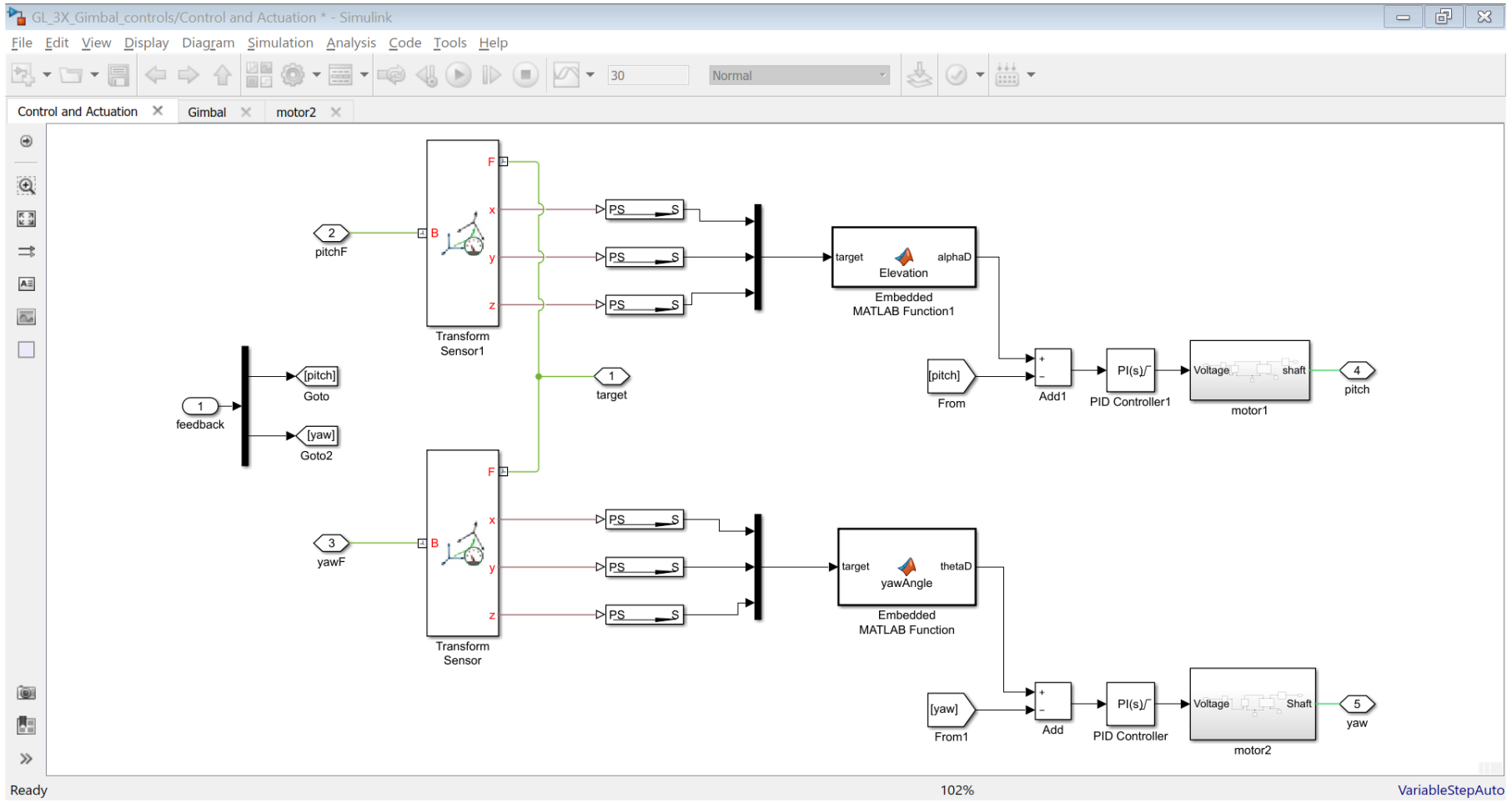


Developing control strategy

Actuation system with feedback



Call to action

- Aileron Actuator Development with Model-Based Design
- Modeling an Engine Cooling System

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% Thank you
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