

# MATLAB EXPO 2018

Model Quality Objectives to  
improve collaboration between  
manufacturers and suppliers

François Guérin



# Model Quality Objective working group

- Idea emerged from SQO success few years ago

- New working group focused on model (MQO)
  - extended to Robert Bosch
  - consensus-based decisions, ~100h of meetings over 2,5 years, many document reviews

## Software Quality Objectives for Source Code

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D. Emmanuel COUTENCEAU<sup>5</sup>, E. Olivier GUETTA<sup>3</sup>, F. Daniel MAINBERTE<sup>2</sup>,  
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ERTS 2010 conference

## Model Quality Objectives for Embedded Software Development with MATLAB and Simulink

Jérôme Bouquet (Renault), Stéphane Faure (Valeo), Florent Fève (Valeo), Matthieu Foucault (PSA Peugeot Citroën), Ursula Garcia (Robert Bosch), François Guérin (MathWorks), Thierry Hubert (PSA Peugeot Citroën), Florian Levy (Renault), Stéphane Louvet (Robert Bosch), Patrick Munier (MathWorks), Pierre-Nicolas Paton (Delphi Technologies), Alain Spiewek (Delphi Technologies)

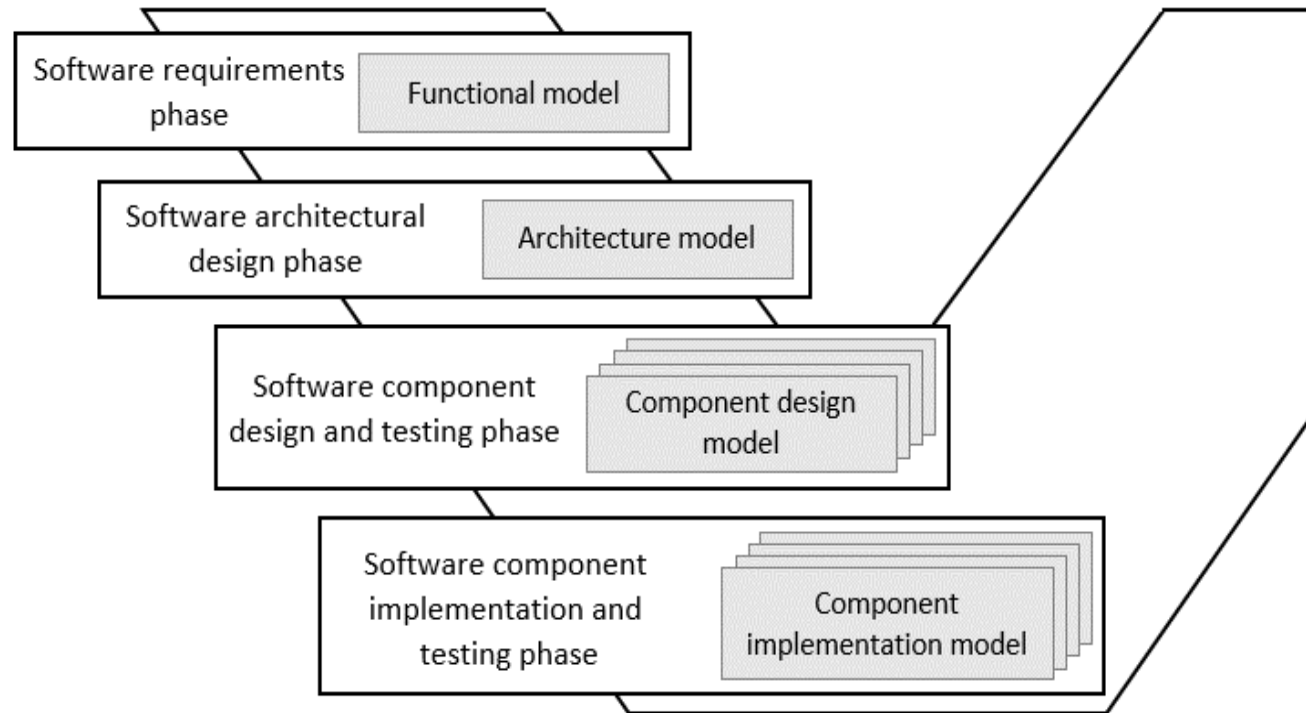
ERTS<sup>2</sup> 2018 conference

# Goals

- Agree on a state-of-the art for model-based design in the context of software development.
- Establish common expectation on model quality when doing co-development between different parties.
- Help non-software developers to understand how they contribute to software development.
- Clarify impact of successive design stages with Simulink and how to transition from early prototyping to final design.

# Model Quality Objectives – SW development process

- A software development supported by design models

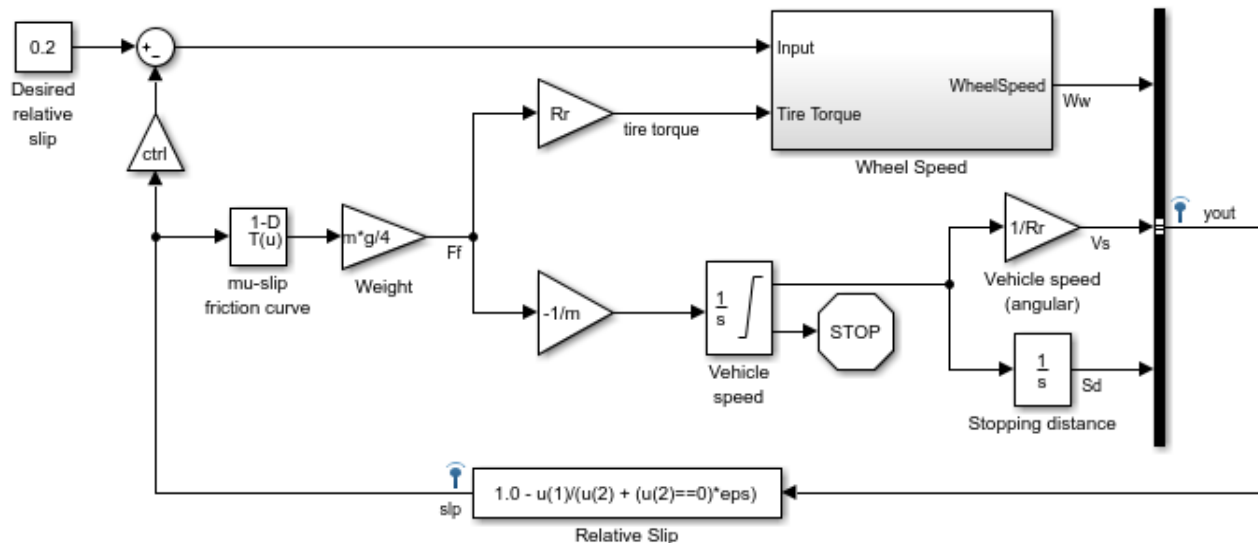
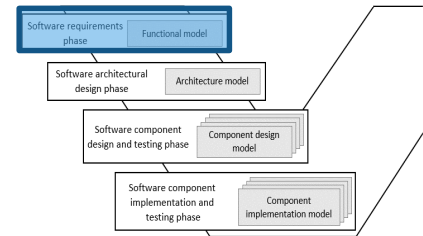


# Model Quality Objectives – SW requirements phase

- Functional model goals**

- 🕒 Accelerate the stabilization of the software functional requirements

- ✅ Improve the quality of the software functional requirements



- No data typing
- Continuous or discrete
- Focus on complex requirements



**Model does not replace the software functional requirements !**

# Model Quality Objectives – SW architectural design phase

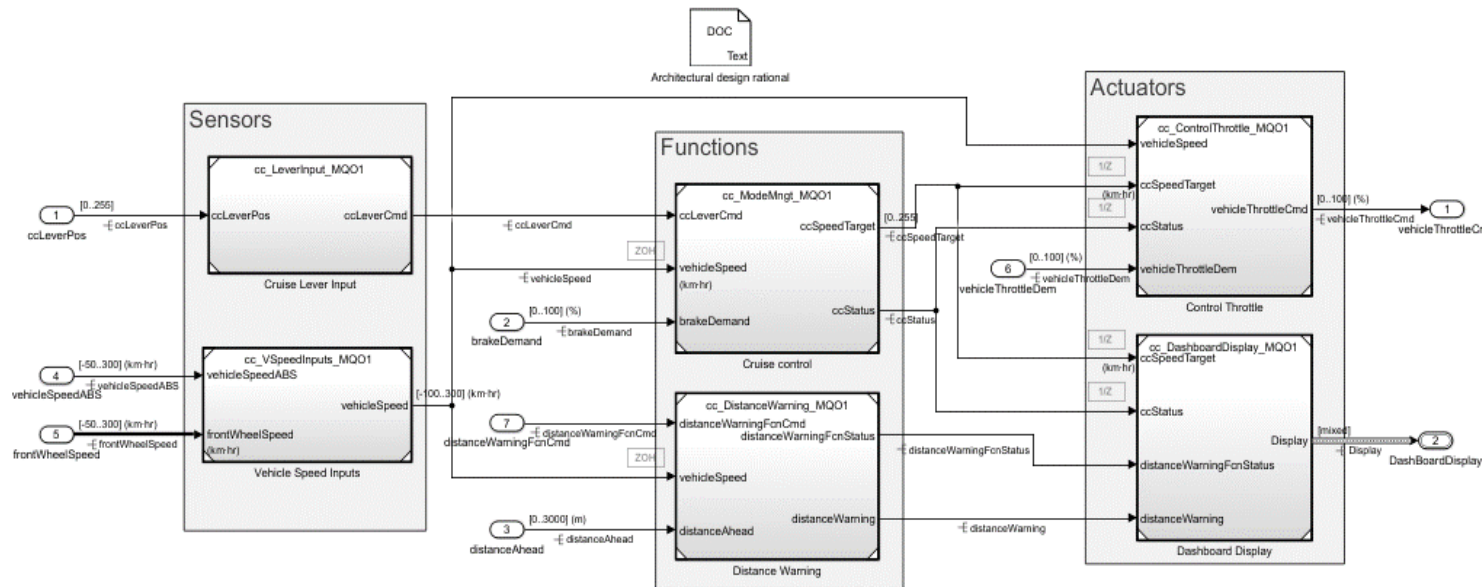
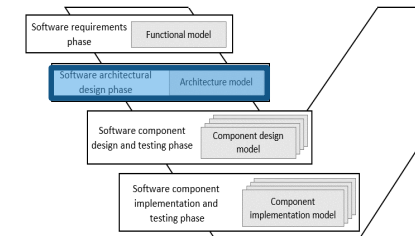
## Architecture model goals



Model and verify the component interfaces, connections and scheduling



Comply with modeling and architecture standard (e.g. AUTOSAR)



- Fully typed
- Discrete
- Assembly of model references



**Need to be traced to requirements, commented, and linked with a data dictionary**

# Model Quality Objectives – SW component design phase

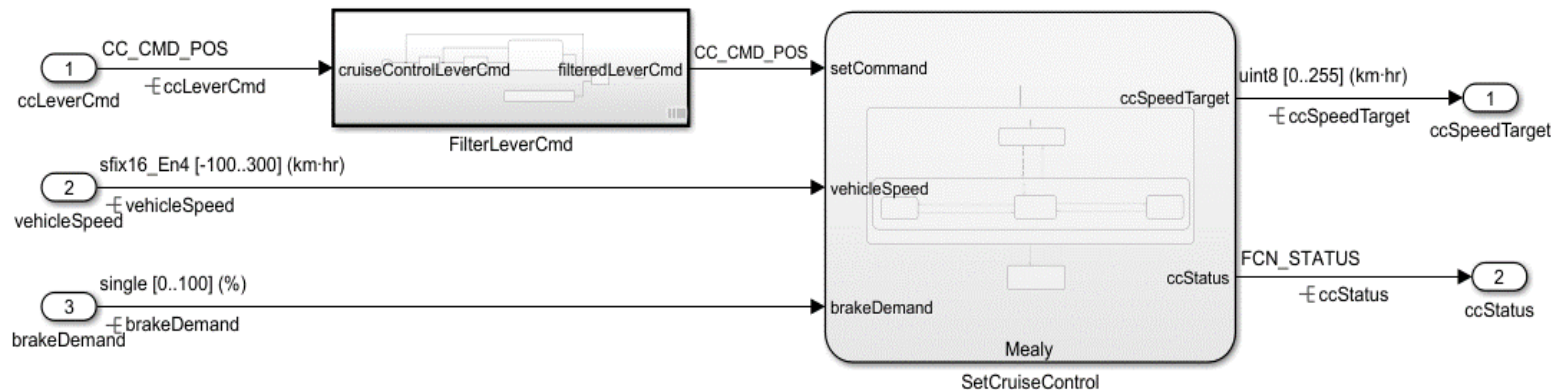
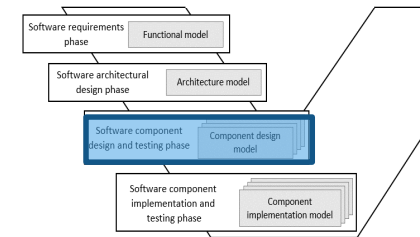
- Component design model**



Model precisely the algorithms with a rich modelling language



Is functionally correct, robust and compliant with modelling standard



- Fully typed
- Discrete
- Mix of libraries and native blocks



**Need to be fully tested with 100% of requirement and design coverage**

# Model Quality Objectives – SW component implementation phase

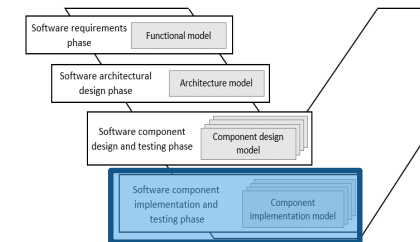
## Component implement model



Generate production code



Generates code that is correct, robust, performant and compliant with coding standard



Hardware board:

Code Generation system target file:

Device vendor:  Device type:

▼ Device details

Number of bits			Largest atomic size		
char:	<input type="text" value="8"/>	short:	<input type="text" value="16"/>	int:	<input type="text" value="32"/>
long:	<input type="text" value="32"/>	long long:	<input type="text" value="64"/>	float:	<input type="text" value="32"/>
double:	<input type="text" value="64"/>	native:	<input type="text" value="32"/>	pointer:	<input type="text" value="32"/>
size_t:	<input type="text" value="32"/>	ptrdiff_t:	<input type="text" value="32"/>	integer:	<input type="text" value="Long"/>
				floating-point:	<input type="text" value="Double"/>

Byte ordering:  Signed integer division rounds to:

Shift right on a signed integer as arithmetic shift

Support long long

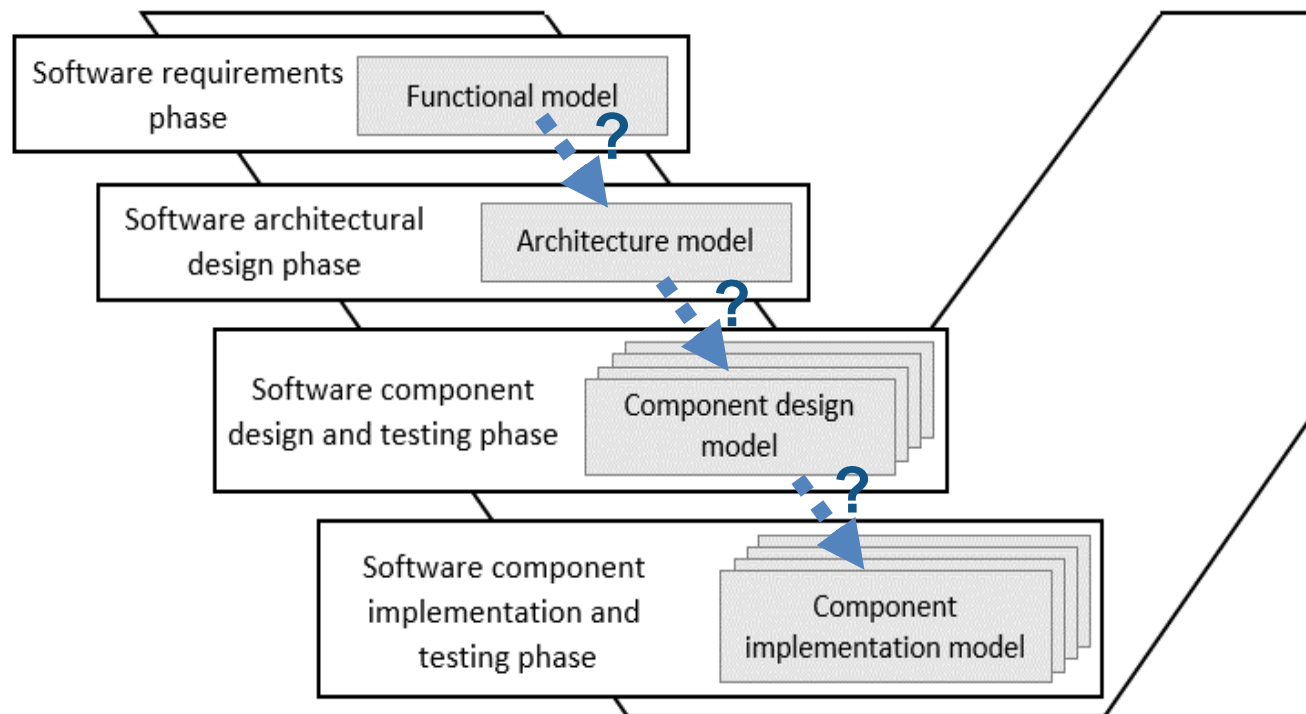
- Fully typed
- Mix of libraries, native blocks.
- Code generation configured for target hardware



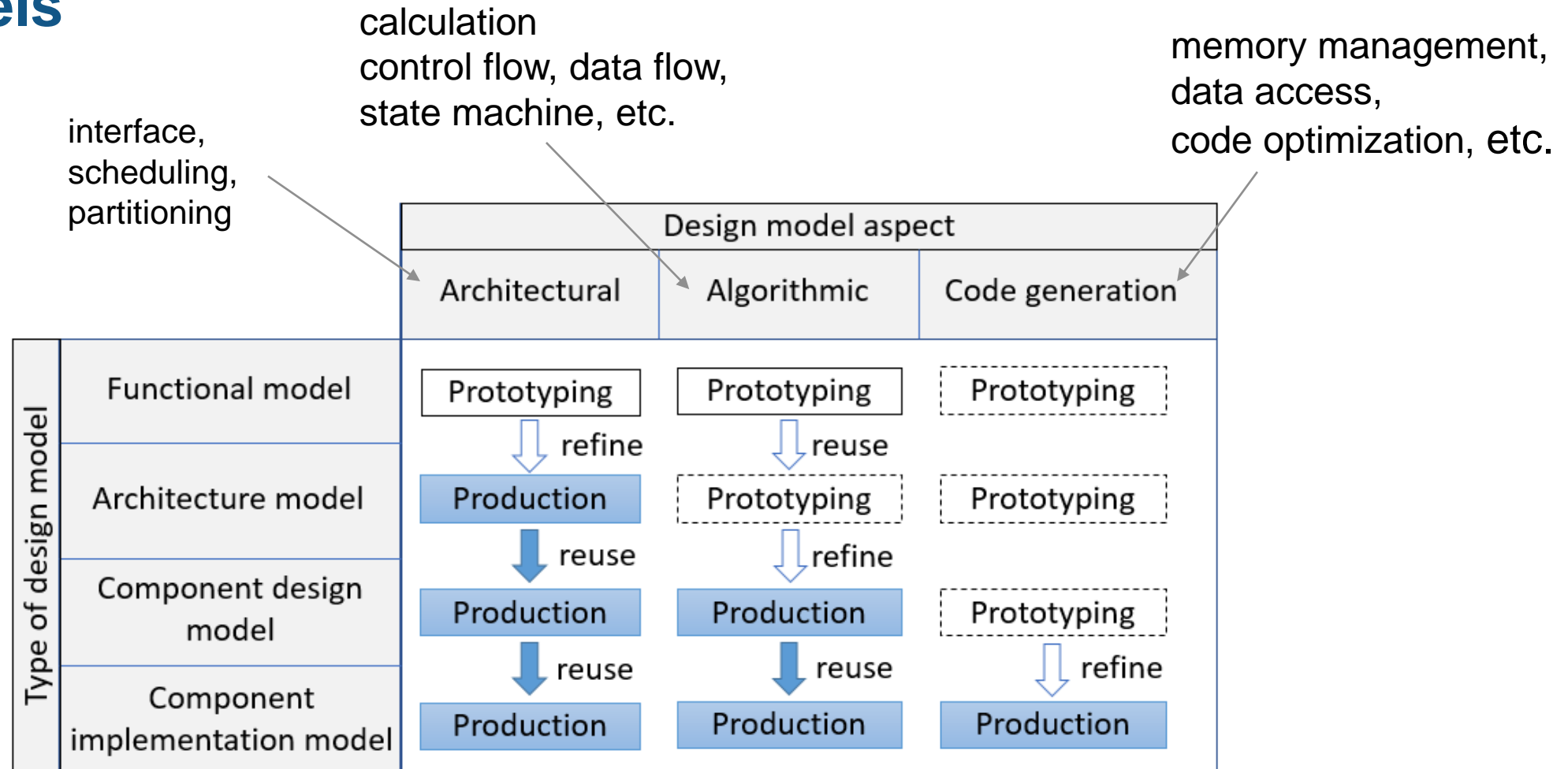
**Generated code needs to be fully tested with 100% of requirement and code coverage**



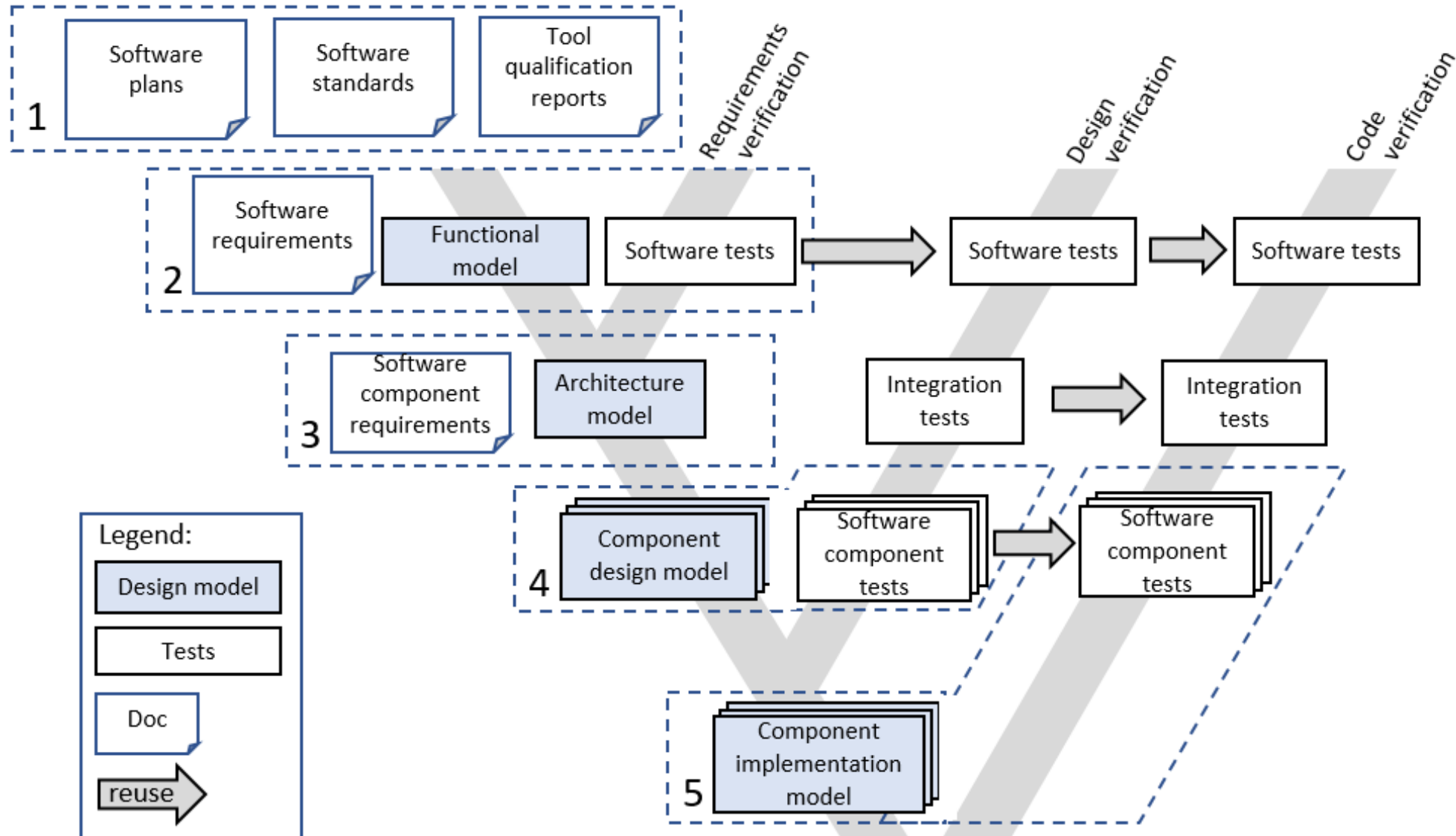
# Model Quality Objectives – Relationship between design models



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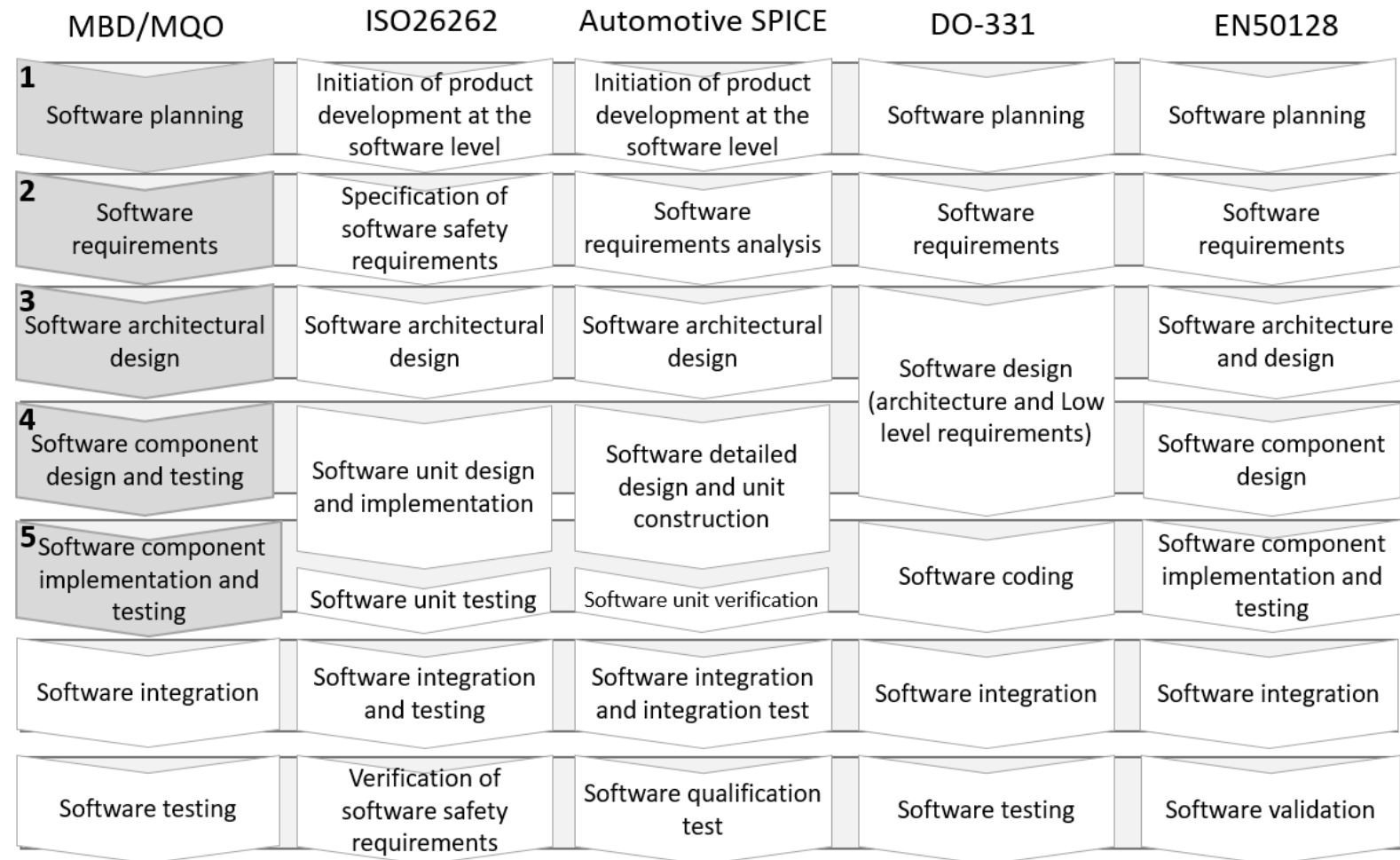


# MQO/ Model-Based Design Workflow

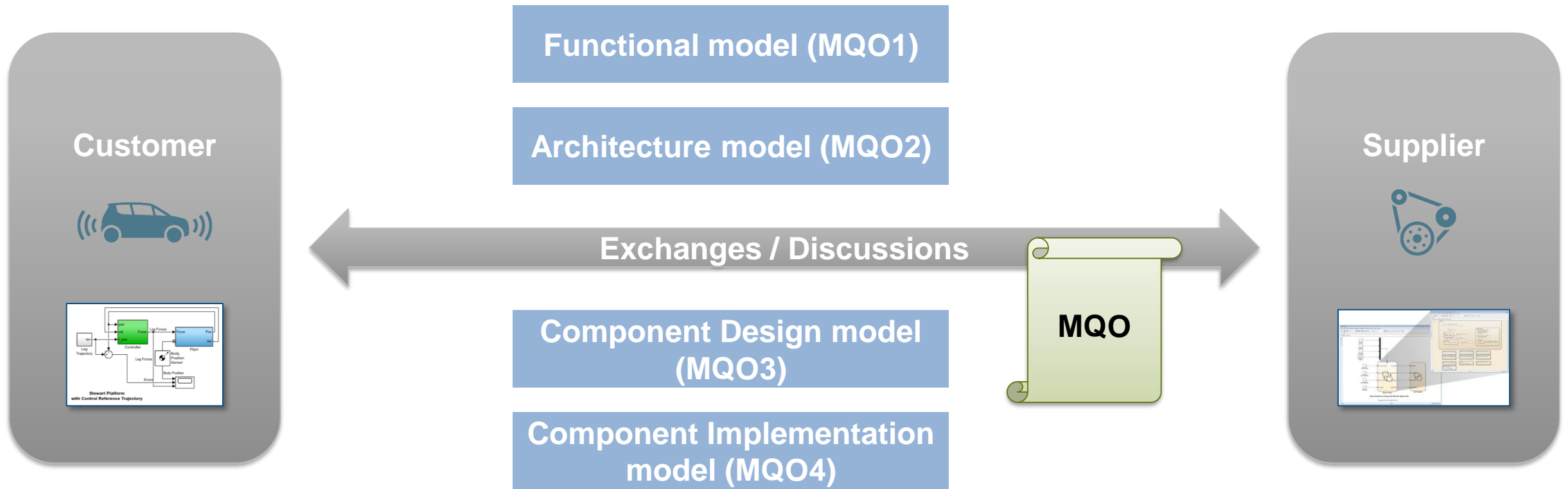


# Compatible with existing industry standards

- Complementary and compatible with existing standards
- Provide metrics and threshold to address quality requirements referred in standards
- Additional guidelines on planning phase to define responsibilities, and ensure workflow compatibility.



# MQO clarifies exchanges and discussions

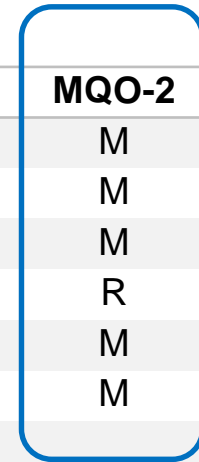


# Model Quality Objectives / Requirements

Design model name	Quality Objective
Functional model	MQO-1
Architecture model	MQO-2
Component design model	MQO-3
Component implementation model	MQO-4

Set of requirements (MQR) to be able to assess the quality of each type of model

MQR ID	MQR Title	MQO-1	MQO-2	MQO-3	MQO-4
MQR-01	Model layout	M	M	M	M
MQR-02	Model comments	M	M	M	M
MQR-03	Model links to requirements	M	M	M	M
MQR-04	Model testing against requirements	M	R	M	M
MQR-05	Model compliance with modeling standard		M	M	M
MQR-06	Model data		M	M	M
MQR-07	Model size			M	M
MQR-08	Model complexity			M	M
MQR-09	Model coverage			M	M
MQR-10	Model robustness			M	M
MQR-11	Generated code testing against requirements			R	M
MQR-12	Generated code compliance with coding standard			R	M
MQR-13	Generated code coverage			R	M
MQR-14	Generated code robustness			R	M
MQR-15	Generated code execution time				M
MQR-16	Generated code memory footprint				M



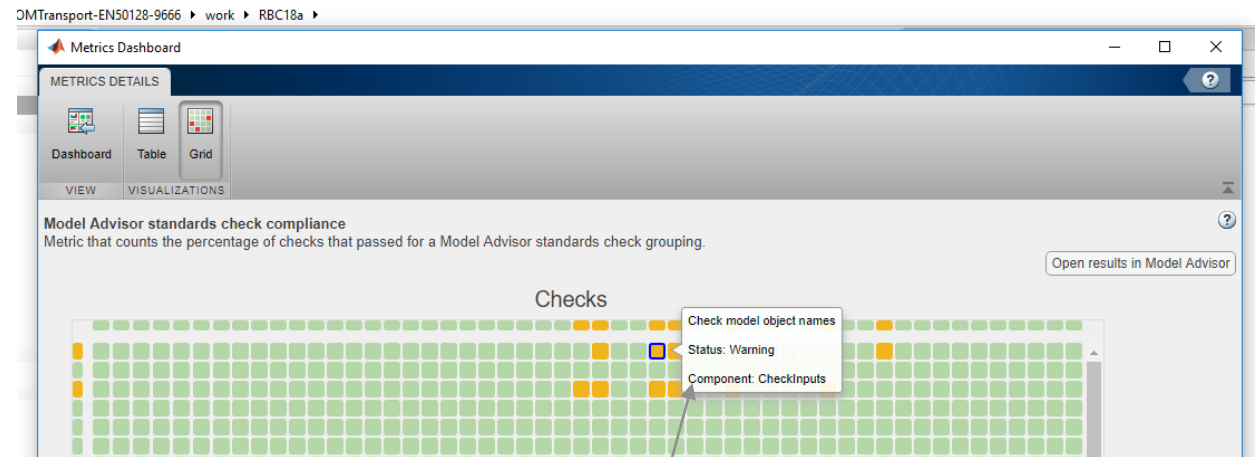
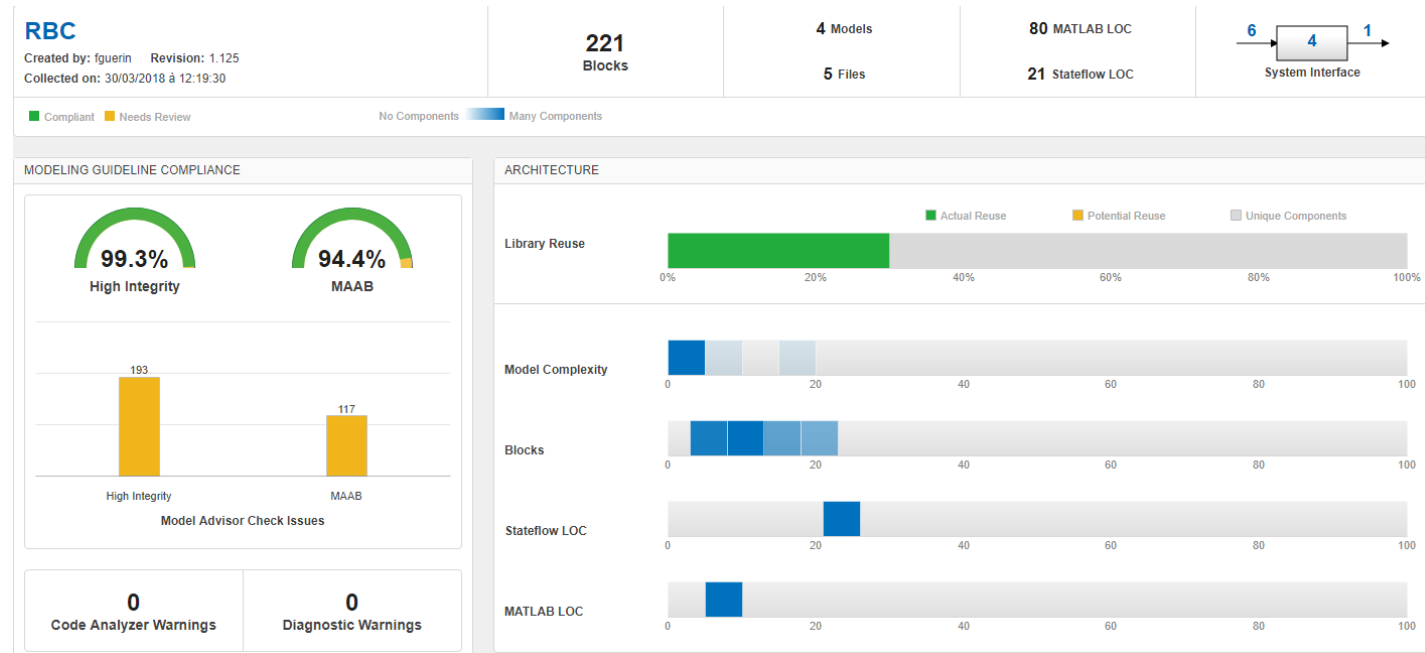
M: Mandatory  
R: Recommended

# Example of Model Quality Requirement

MQR-08	Model complexity			
Description	The model and its subsystems, Stateflow charts and MATLAB functions shall have a local cyclomatic complexity lower or equal to "30".			
Recommendation level	MQO-1	MQO-2	MQO-3	MQO-4
			<b>Mandatory</b>	<b>Mandatory</b>
Notes	<p>Local complexity is the cyclomatic complexity for objects at their hierarchical level. Aggregated cyclomatic complexity is the cyclomatic complexity of an object and its descendants.</p> <p>The threshold of 30 for local cyclomatic complexity is a recommendation and can be adapted on a project basis. The number 30 for Cyclomatic complexity has been derived from the HIS code metric (value of 10) and adapted to Model-Based Design.</p>			
References / Examples of techniques	<p>Cyclomatic complexity is a measure of the structural complexity of a model. It approximates the McCabe complexity measure for code generated from the model. The McCabe complexity measure is slightly higher on the generated code due to error checks that the model coverage analysis does not consider.</p> <p>To compute the cyclomatic complexity of an object (such as a block, chart, or state), model coverage uses the following formula:</p> $c = \sum_1^N (o_n - 1)$ <p><math>N</math> is the number of decision points that the object represents and <math>o_n</math> is the number of outcomes for the <math>n</math>th decision point. The tool adds 1 to the complexity number for atomic subsystems and Stateflow charts.</p>			
Rational	Cyclomatic complexity is a leading testability metric. Test harness can be created for simulation at model, subsystem, chart and MATLAB Function level.			
Last update	1.0			

# MathWorks metric support

- All MQR can be measured with MathWorks tools
- Simulink Check provides additional metrics for size, architecture, compliance and readability
- Metric dashboard introduced in R2017b is rapidly involving to display and navigate from metrics results to models



navigate to model block