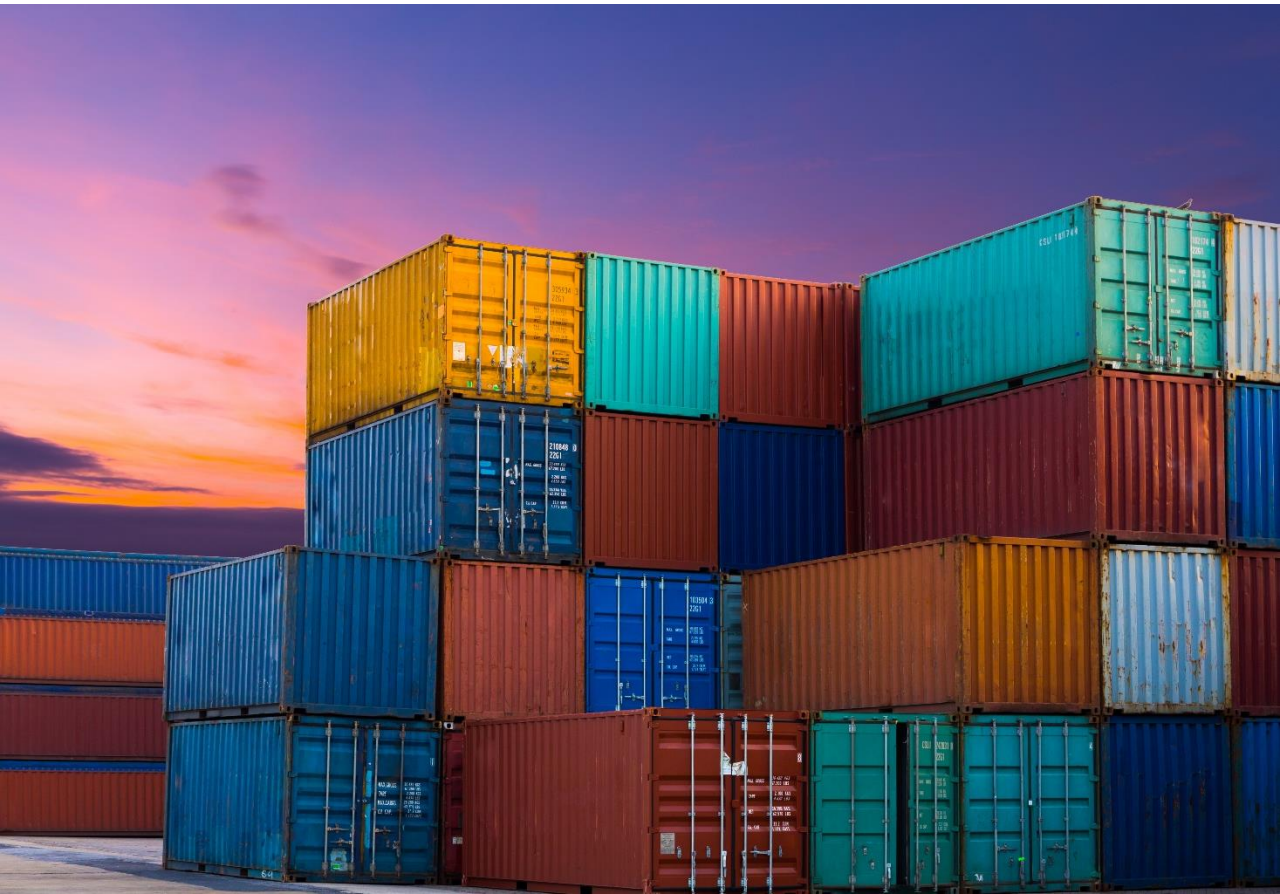
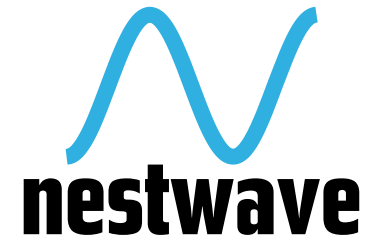


Geolocation for the IoT

Never lost again in the Internet of Things



Where's the bike?



“even with GPS integration...the bikes weren't at their supposed locations”



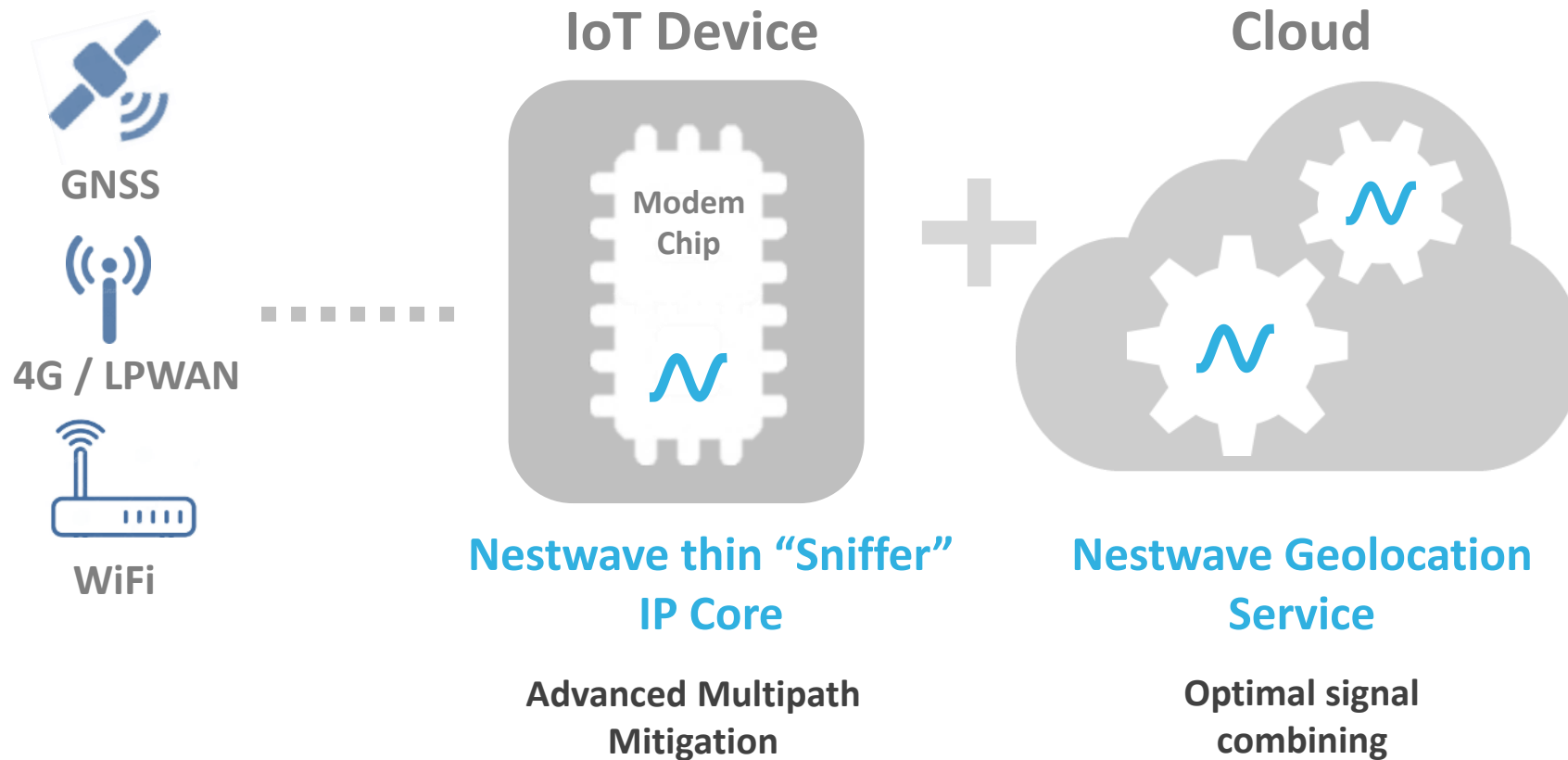
“Eight out of 10 times, those who tried Mobike could not find the bicycle.”

Company Overview

- Nestwave develops signal processing technology and solutions enabling **accurate, low-power geolocation, both indoor and outdoor**
- Over 10 patents granted, pending or being filed
- Our company is based in Paris (2014)

Our Solution

Low power, multi-signal beacon receiver IP and cloud service:
GPS/4G/WiFi/LoRa sniffing with cloud offloading



Powered by Technology

10 Patents granted & pending

+ Timestamp Algorithms

+ Multilateration Solution

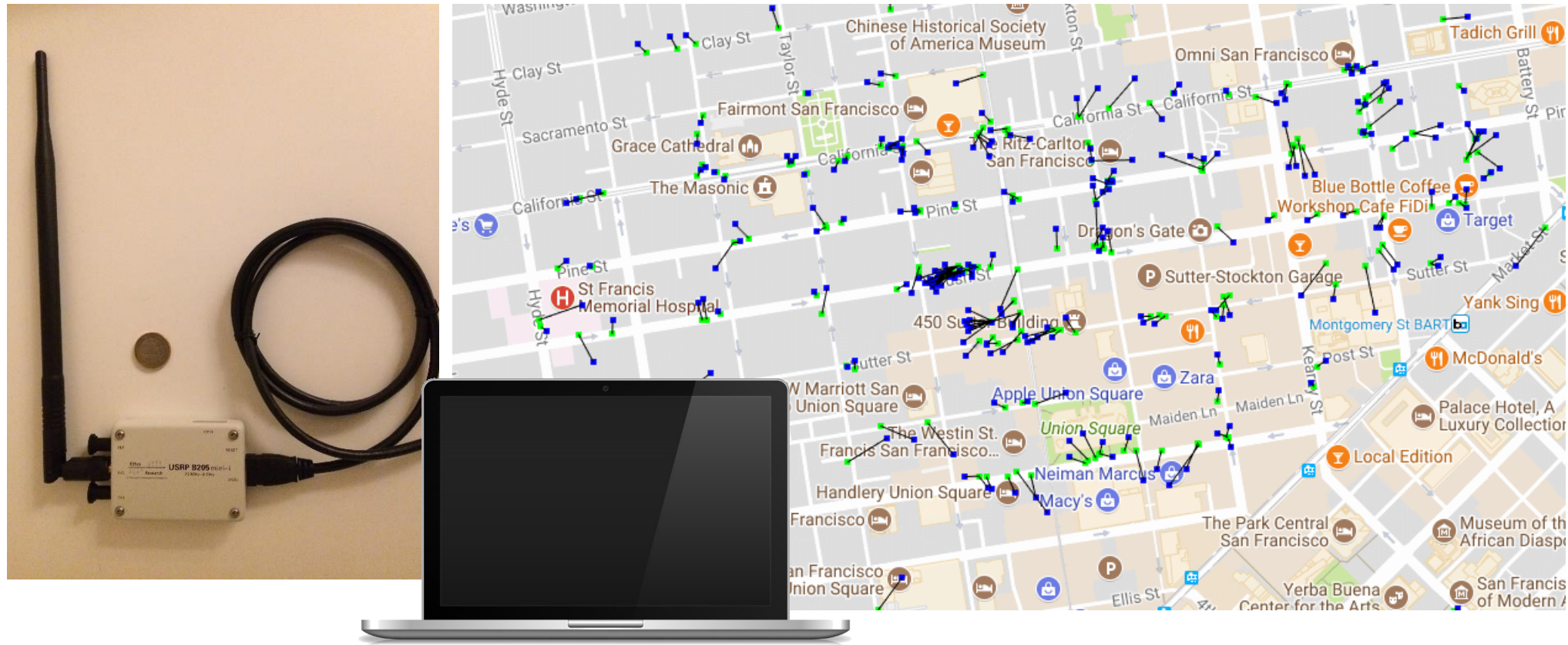
+ System and antenna database optimization

= Dramatic accuracy gains in high multipath and low signal environments, and reduced power consumption

Fast Prototyping with MATLAB

MATLAB enables very efficient development cycle of novel algorithms and solutions:

Research → Prototyping → Field Test → Analysis → Research

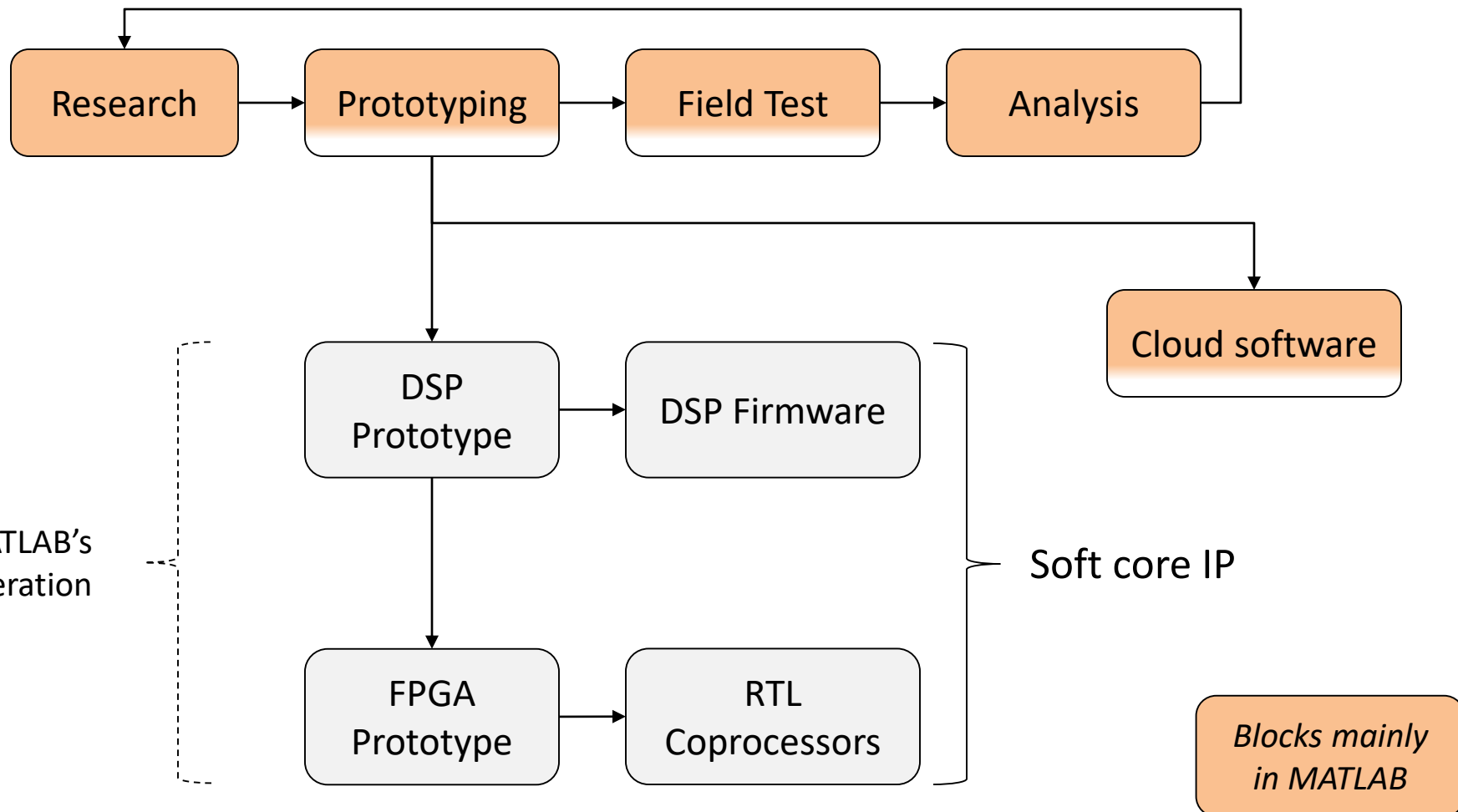


Easy deployment with MATLAB

- MATLAB allows a direct and quick path from prototype to production
- Native vectorization in MATLAB
- Parallel and GPU computing also supported
- ➔ Server software mainly written in MATLAB: extremely fast deployment, maintenance, evolution and upgrade

End-to-End Solution using MATLAB

Fast end-to-end development cycle from research to product

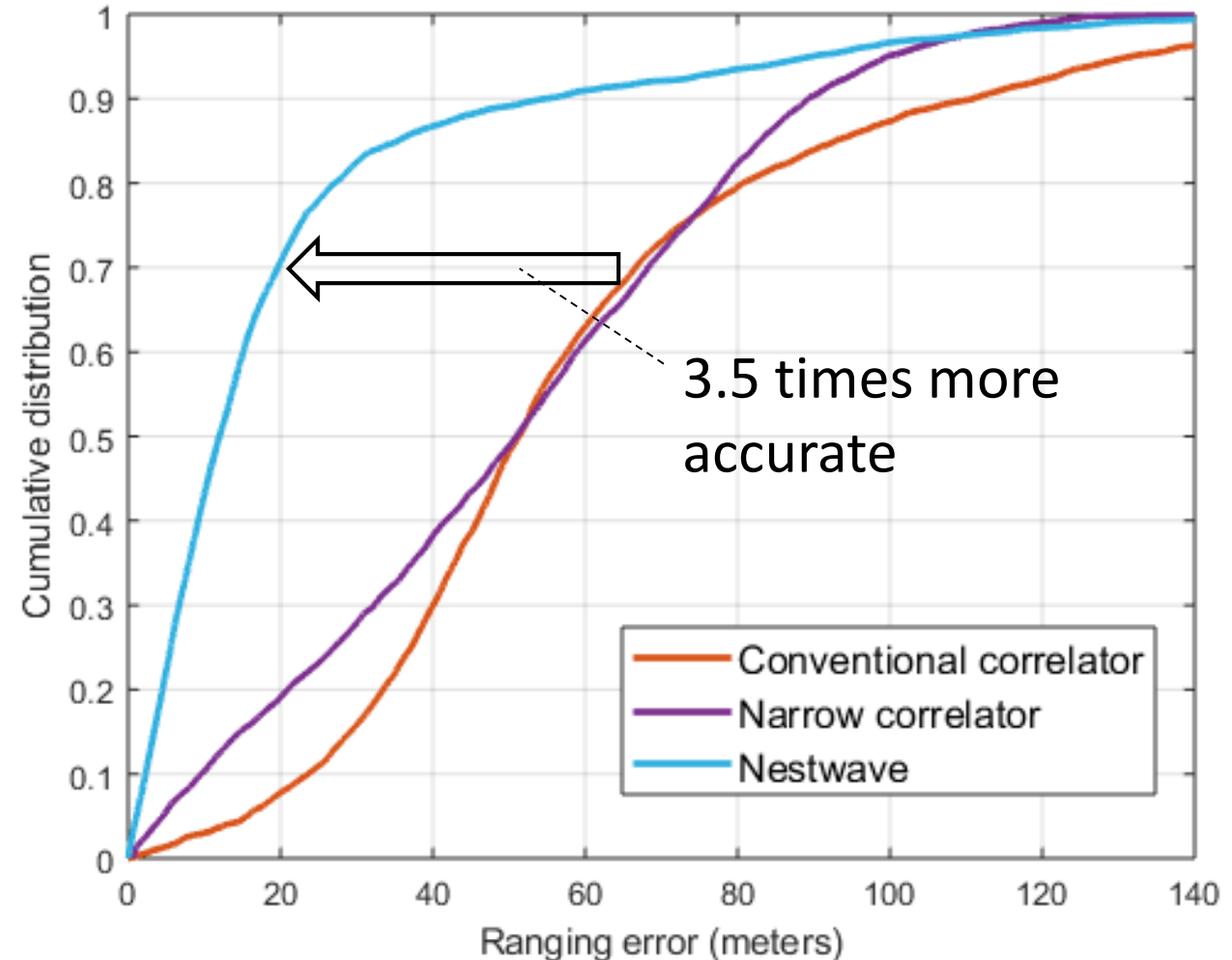
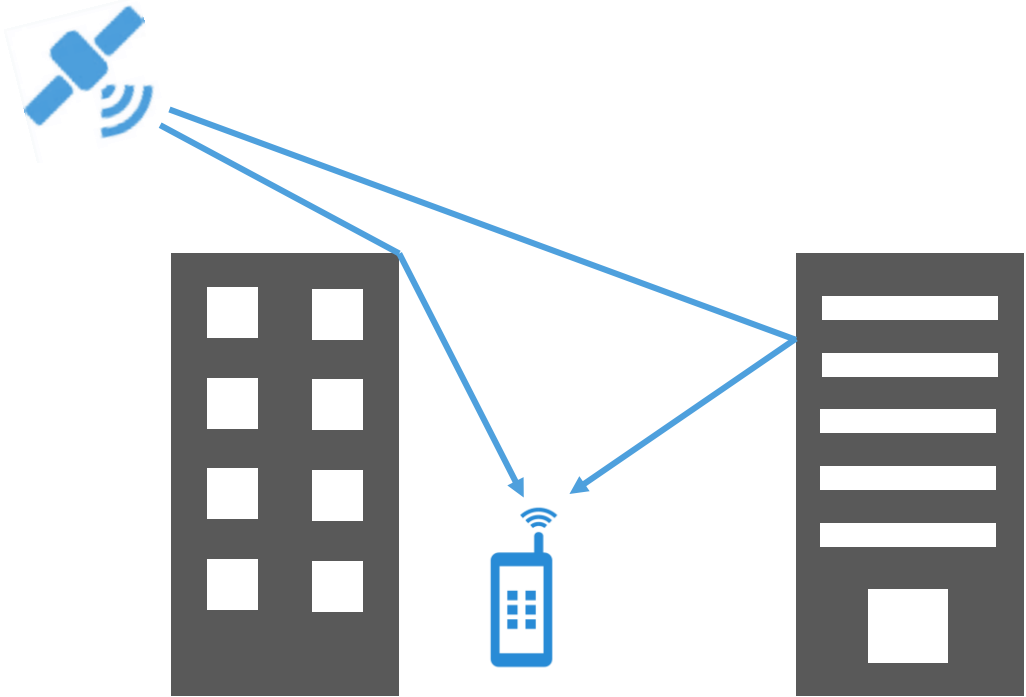


Support from MATLAB's automatic code generation



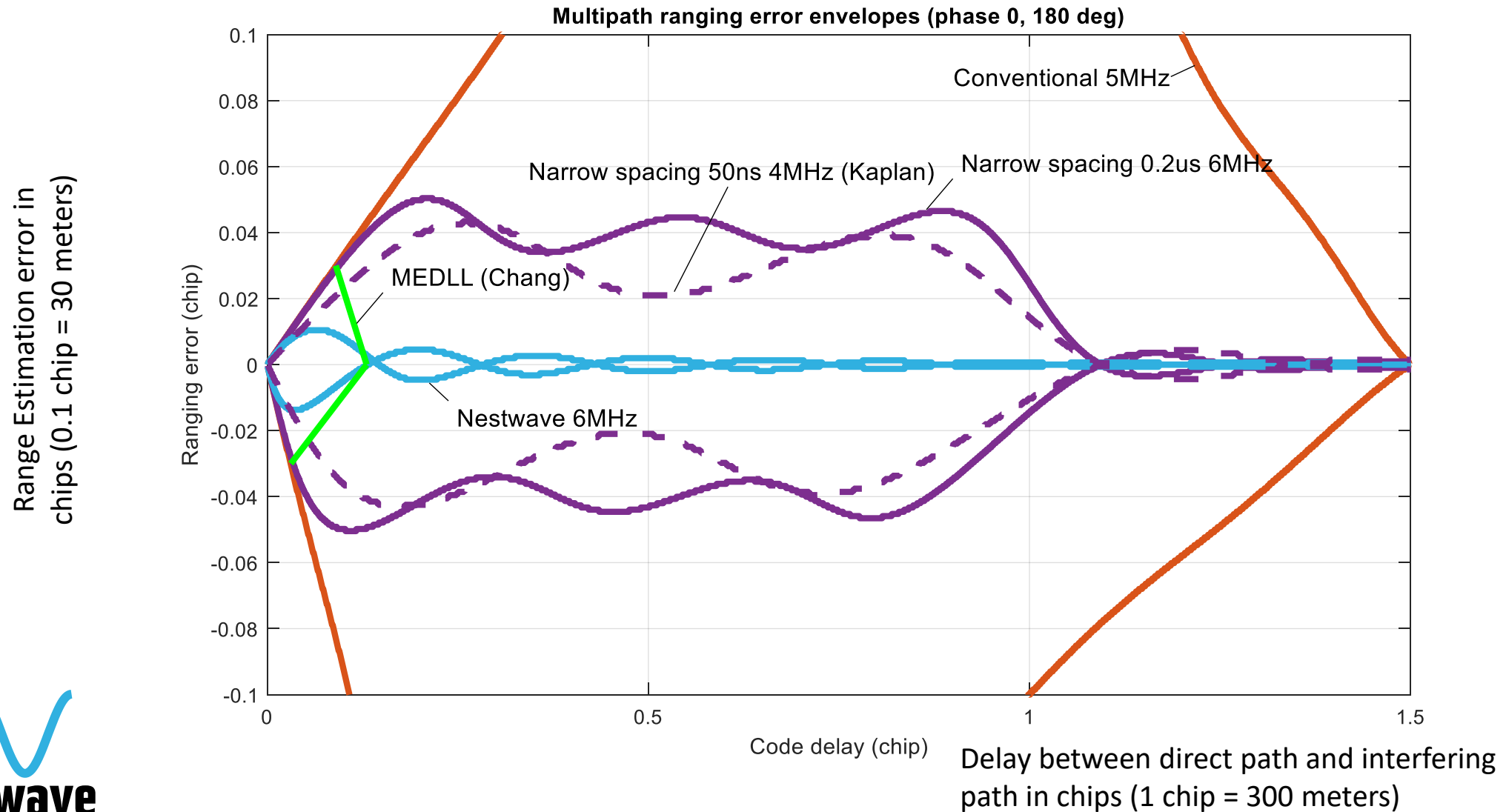
Our Multipath Mitigation in GPS

- Simulation of multipath mitigation at low SNR with 2 interfering paths
- Current multipath mitigation algorithms fail at low SNR



Our Multipath Mitigation in GPS

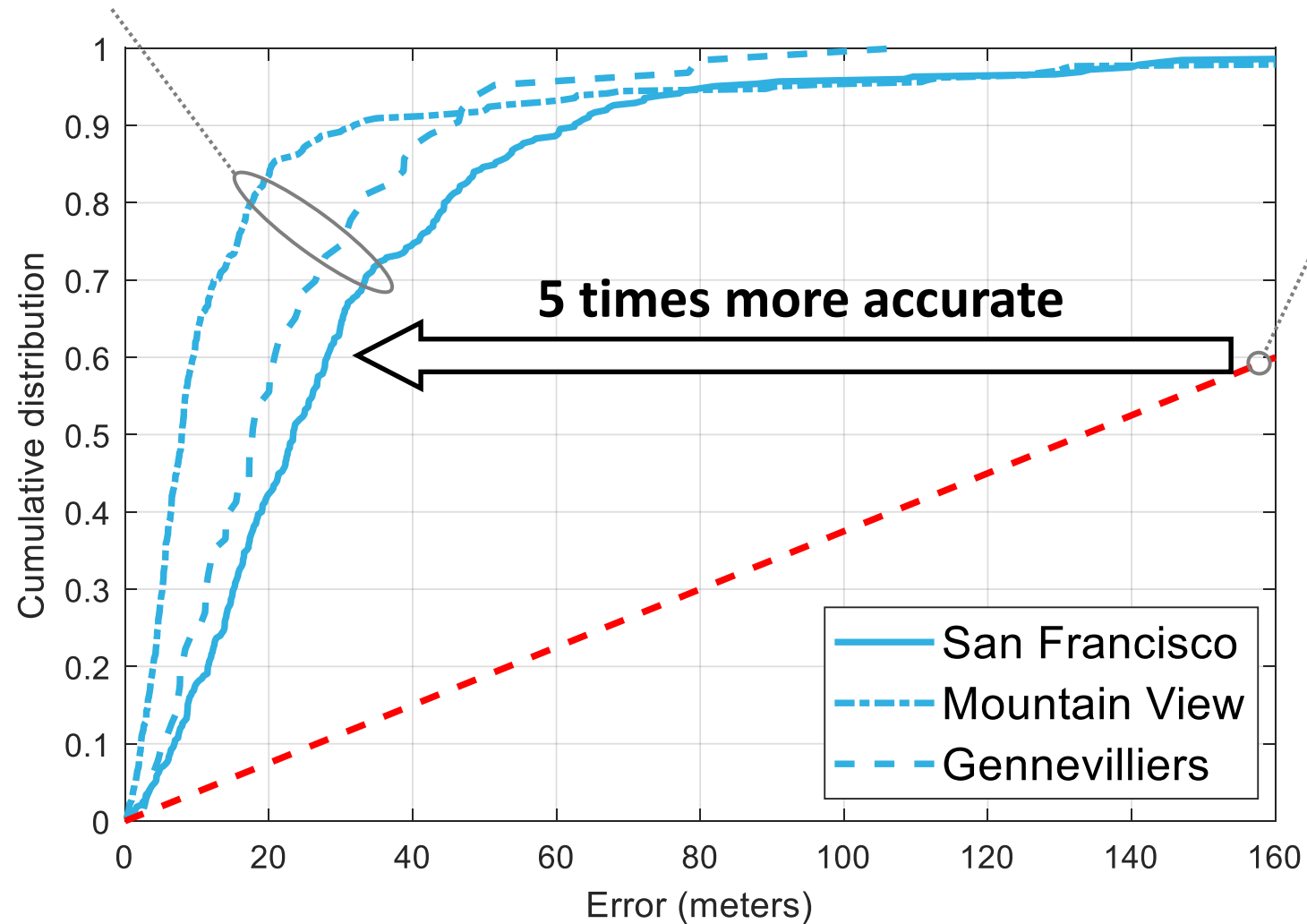
Standard comparison of ranging error envelopes for 1 interfering path



Our Indoor & Outdoor Field Results

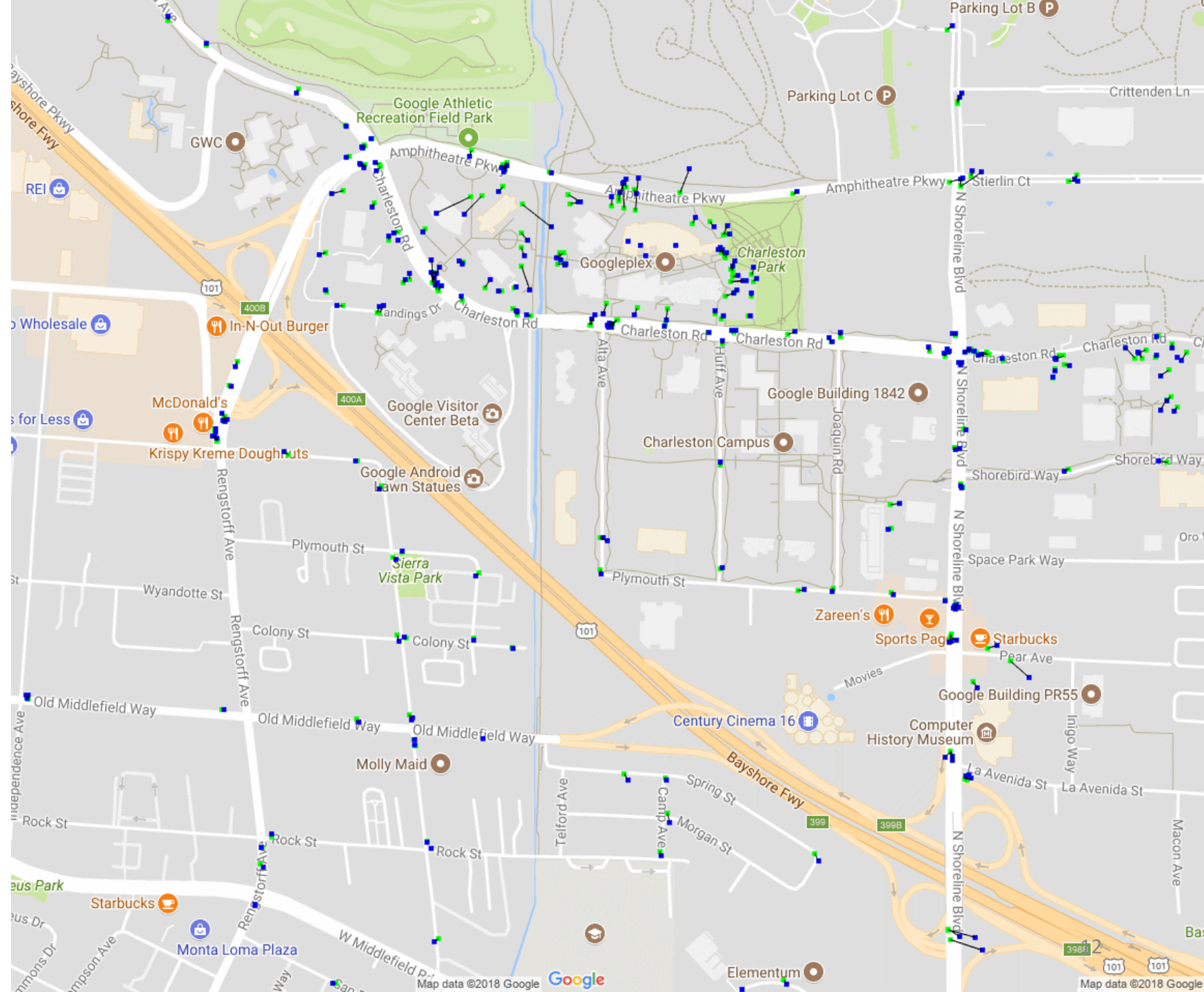
Our Solution

Competition in 2013



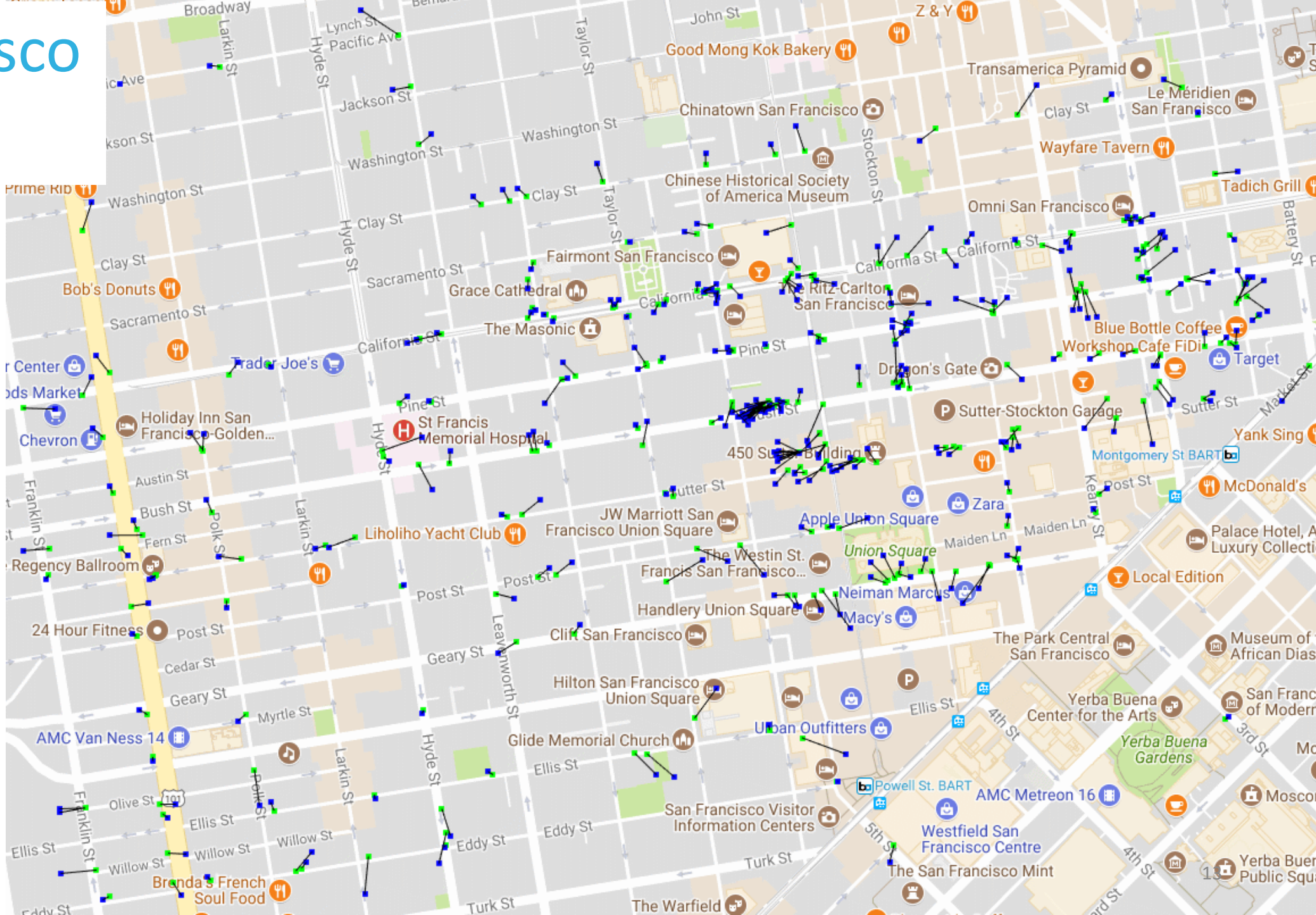
Mountain View 4G Trial

- True position
- Estimated position



San Francisco 4G Trial

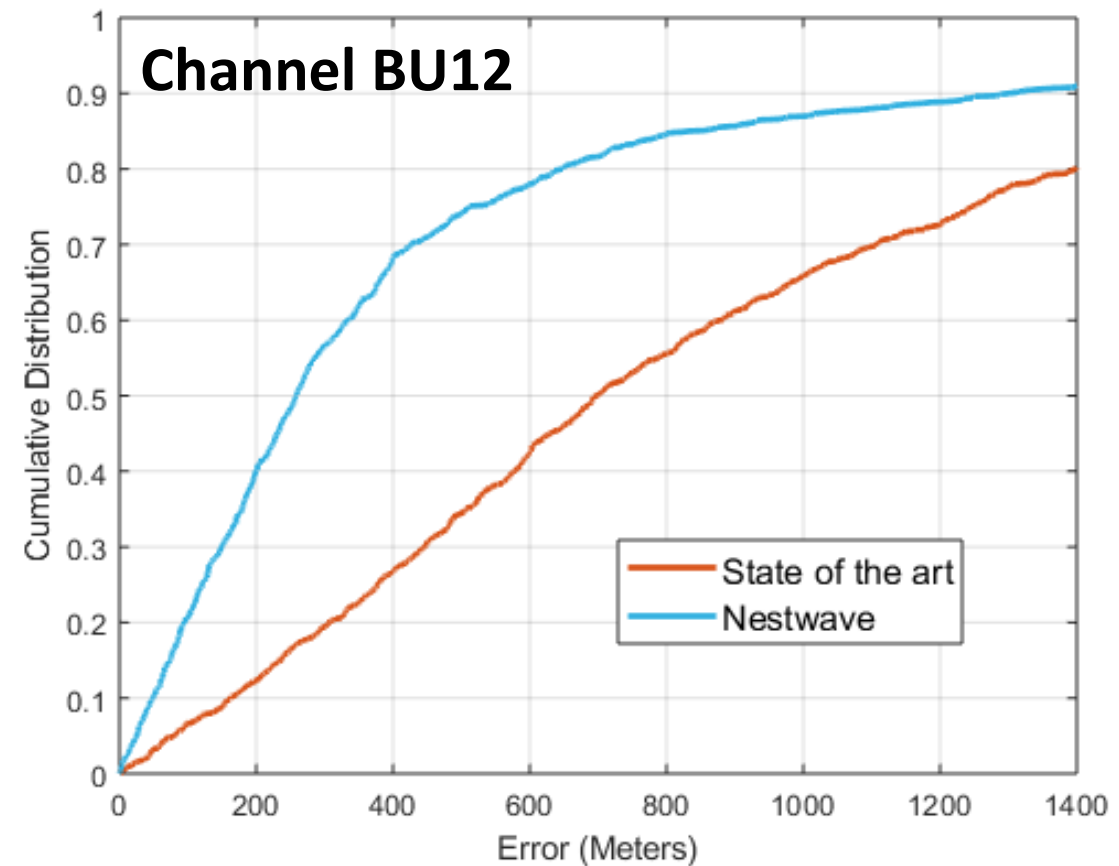
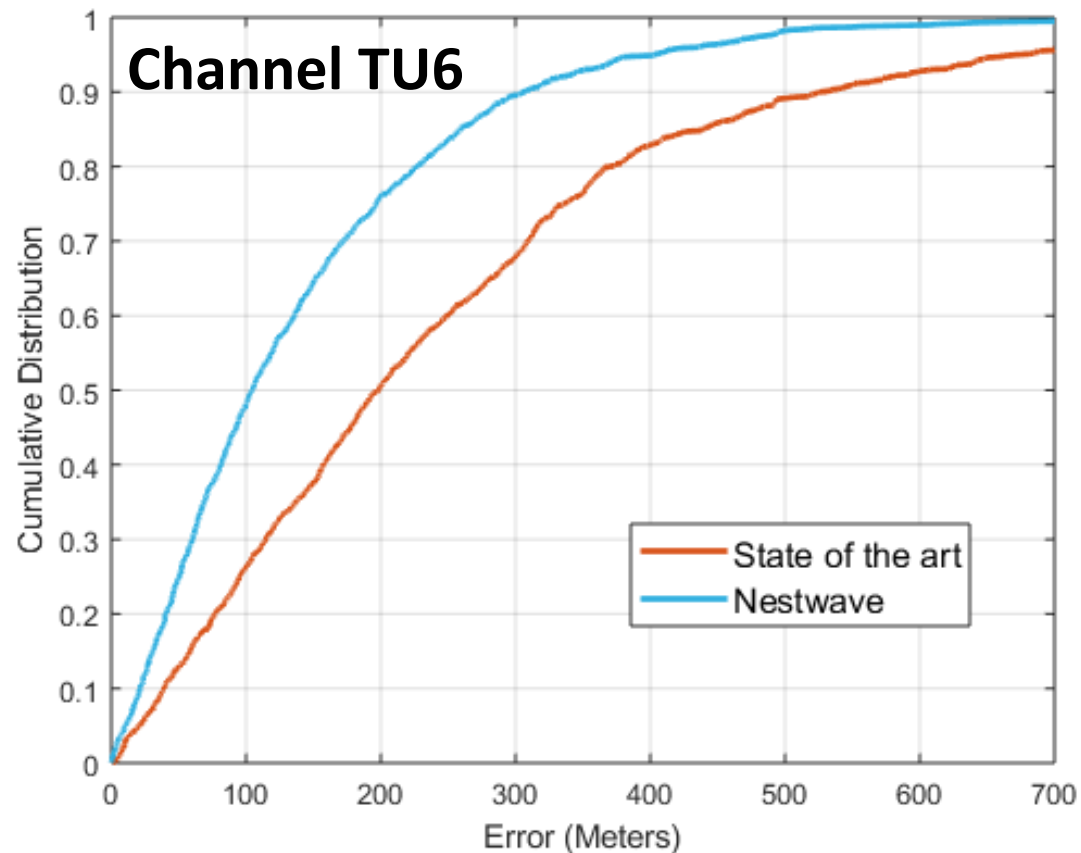
- True position
- Estimated position



Multipath Mitigation in LoRa

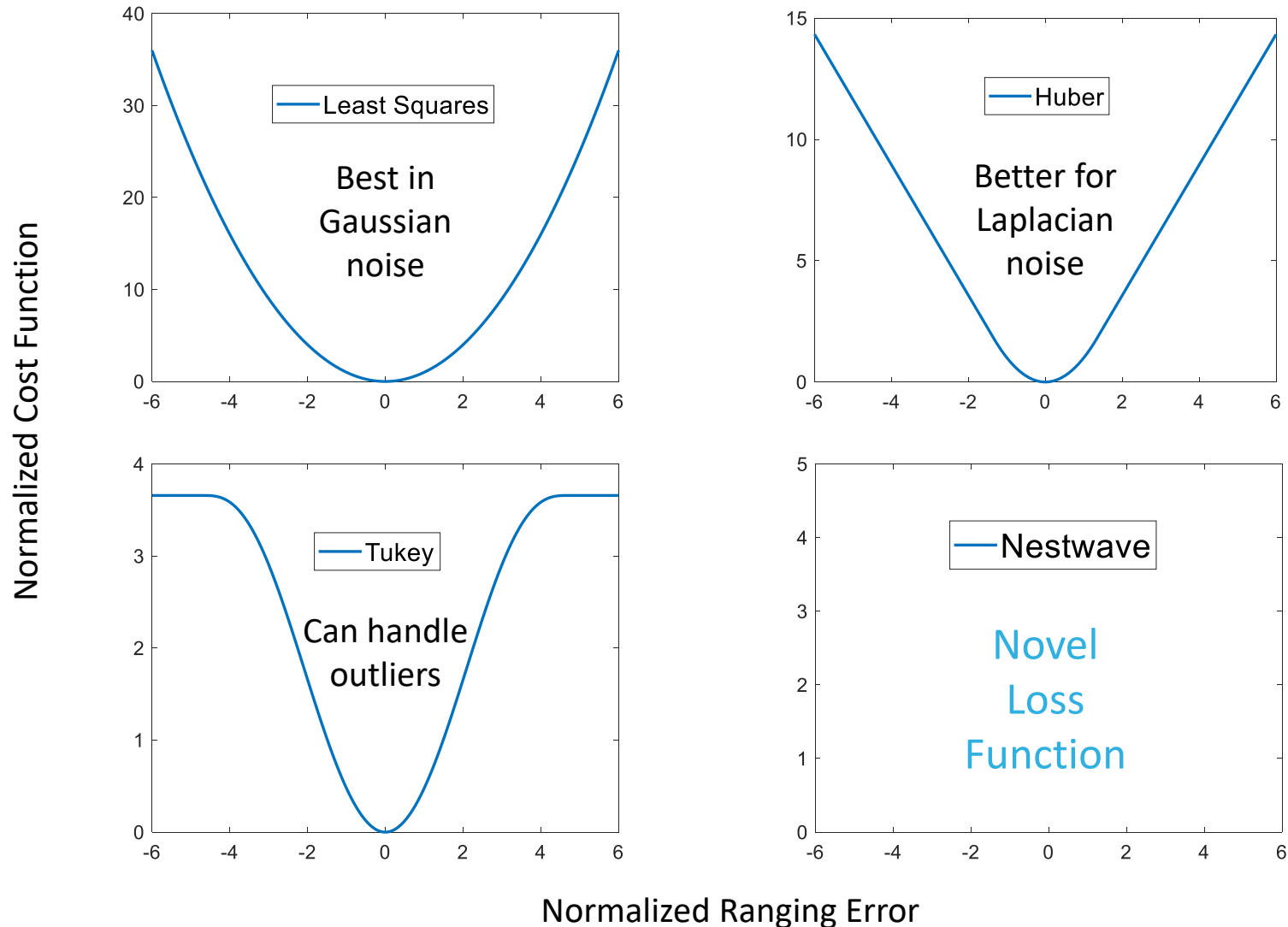
Timestamp Estimation: simulation comparison for LoRa in two different channels

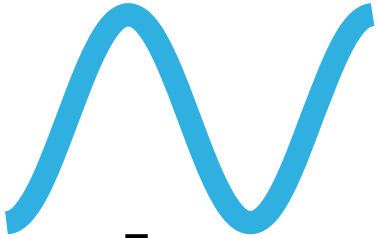
Nestwave's algorithm achieves strong gains in difficult channels (i.e. in worst case scenarios)



Multilateration Solver

Our multilateration Solver for GPS, 4G and LoRa incorporates several advanced features such as novel M-Estimation





nestwave



FOUND

