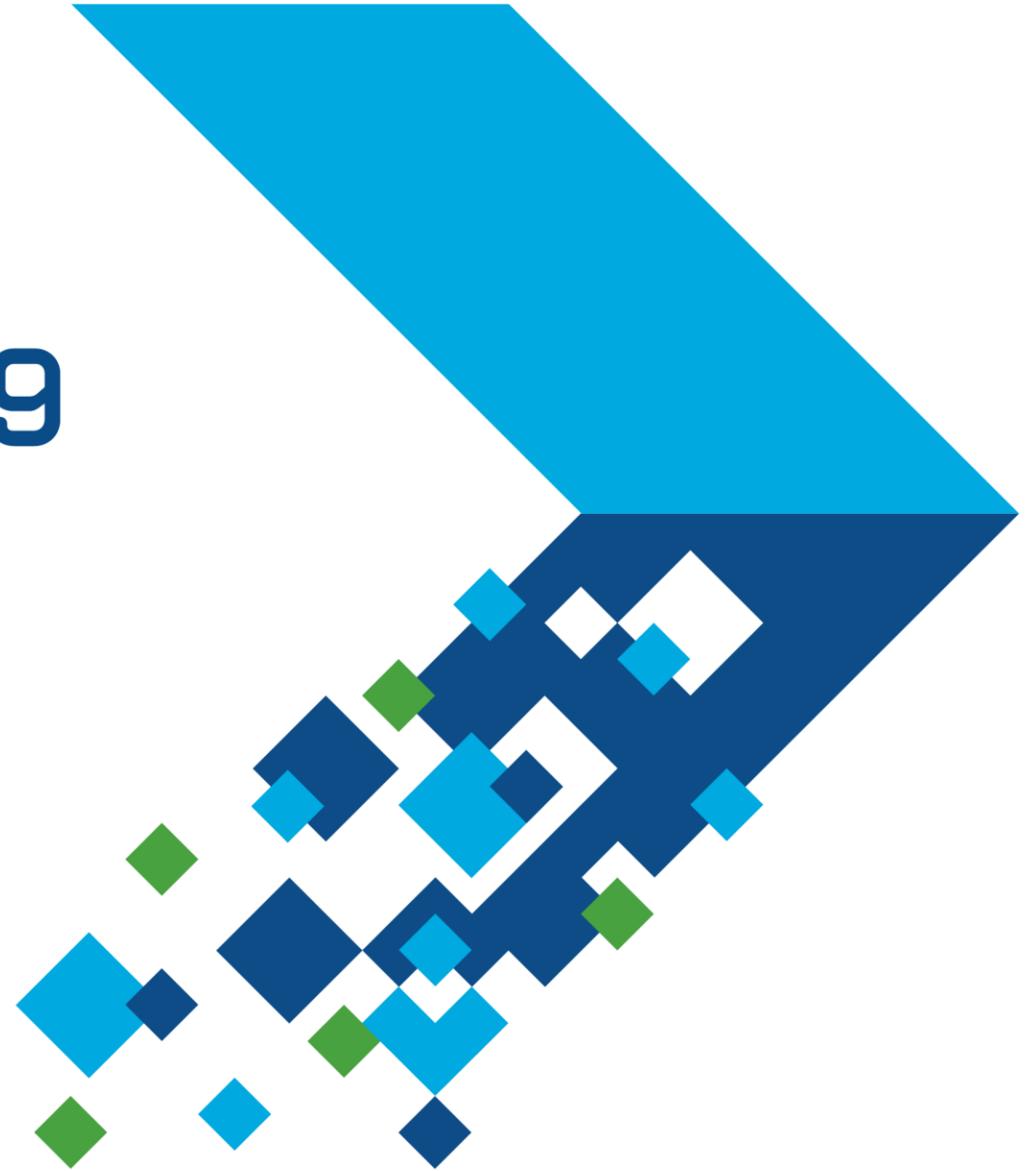
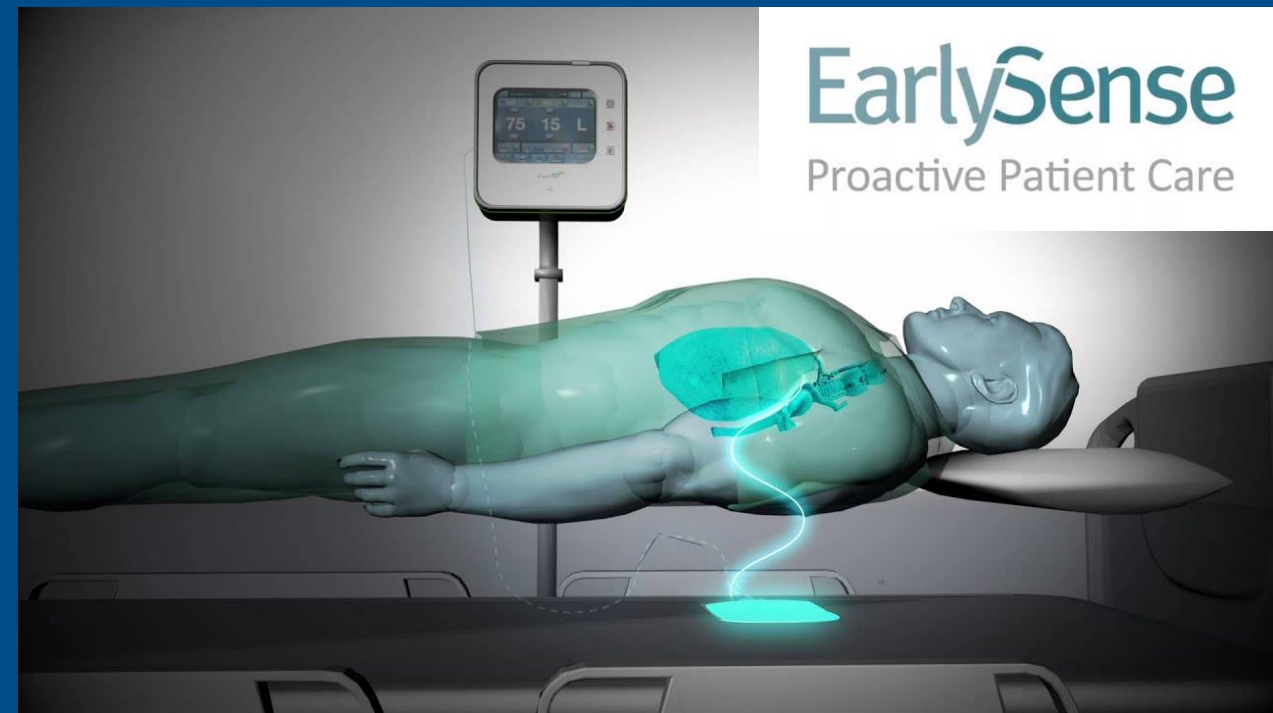


MATLAB EXPO 2019

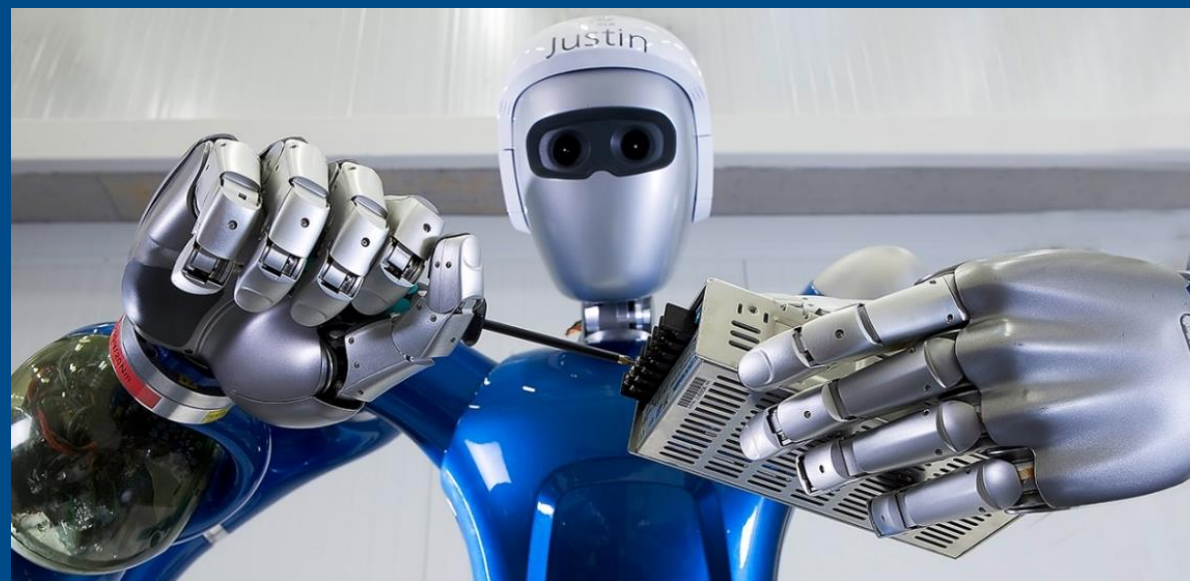
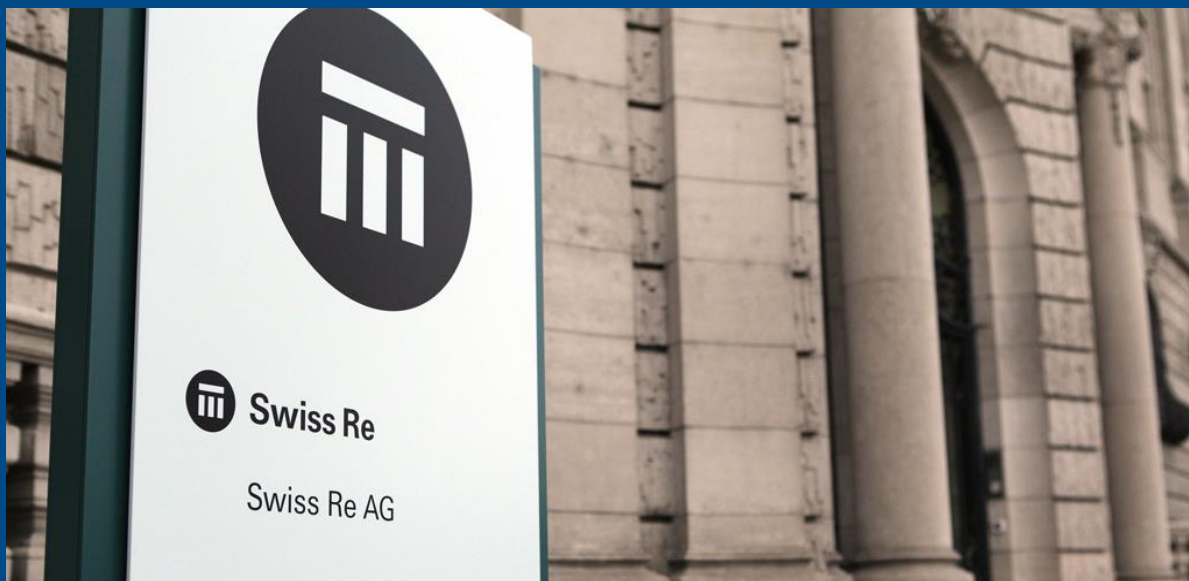
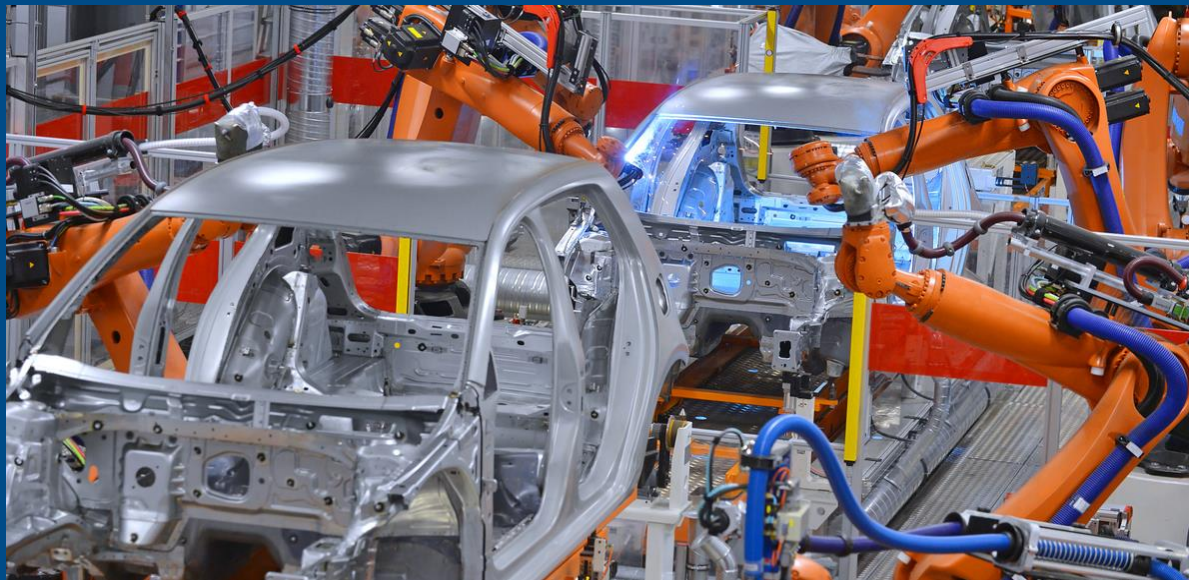
What's New in MATLAB and Simulink

Alexander Schreiber





Algorithms in Everything



Using MATLAB & Simulink to Build Algorithms in Everything

Simplifying your work...

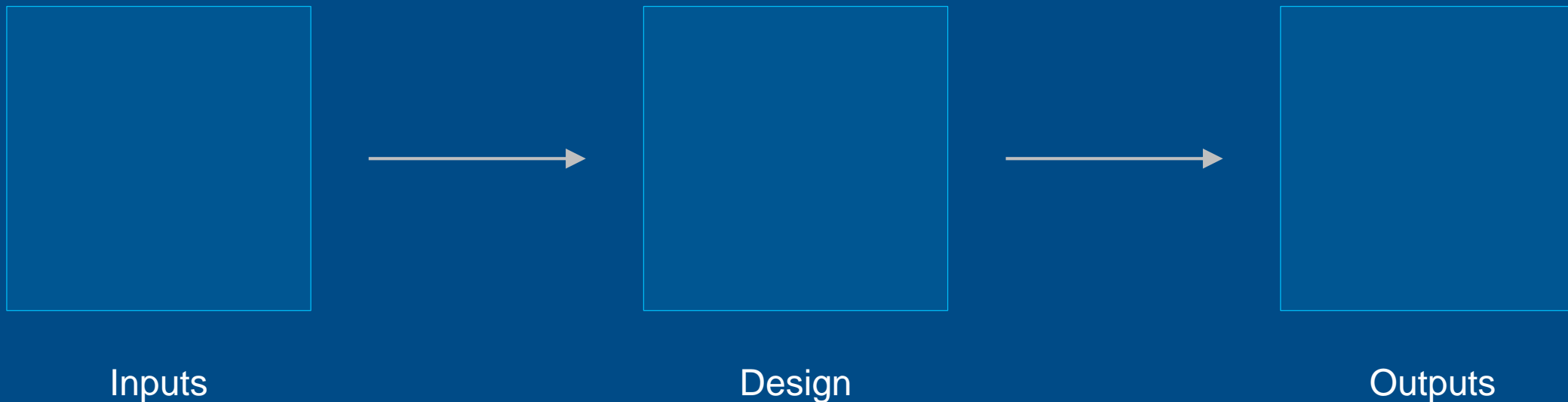
...often at higher levels of abstraction.



MATLAB®SIMULINK®



Using MATLAB & Simulink to Build Algorithms in Everything



MATLAB® & SIMULINK®



Artificial Intelligence

*The capability of a machine to
match or exceed intelligent human behavior by
training a machine
to learn the desired behavior*

There are two ways to get a computer to do what you want

Traditional Programming

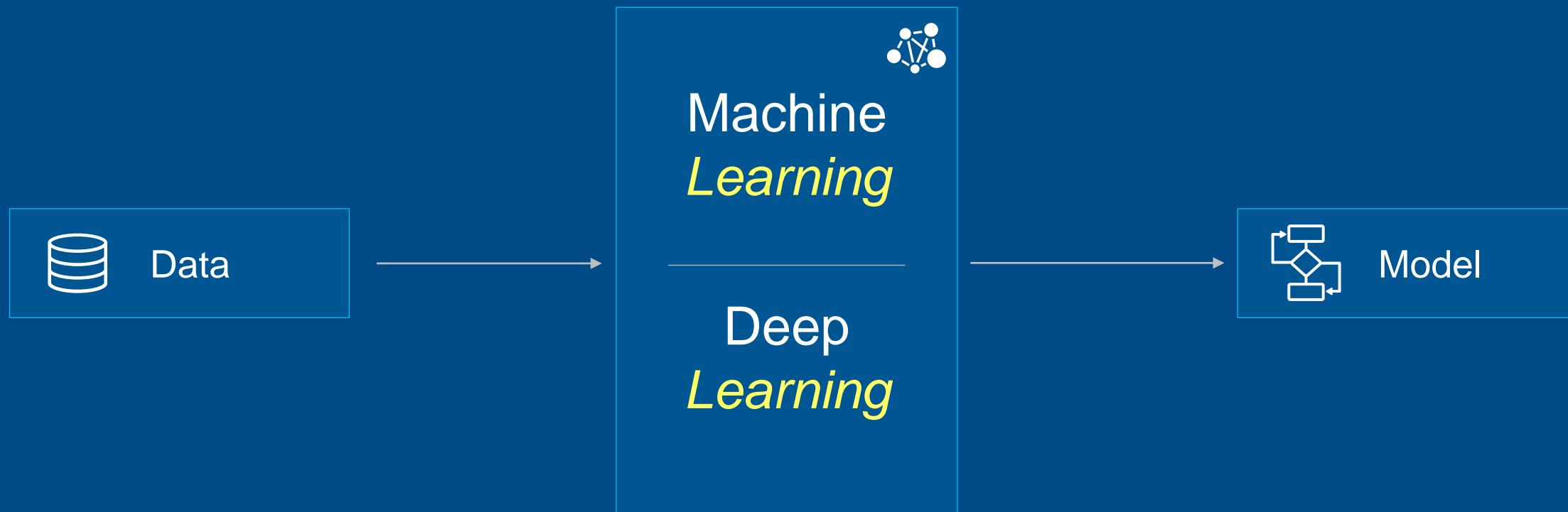


There are two ways to get a computer to do what you want

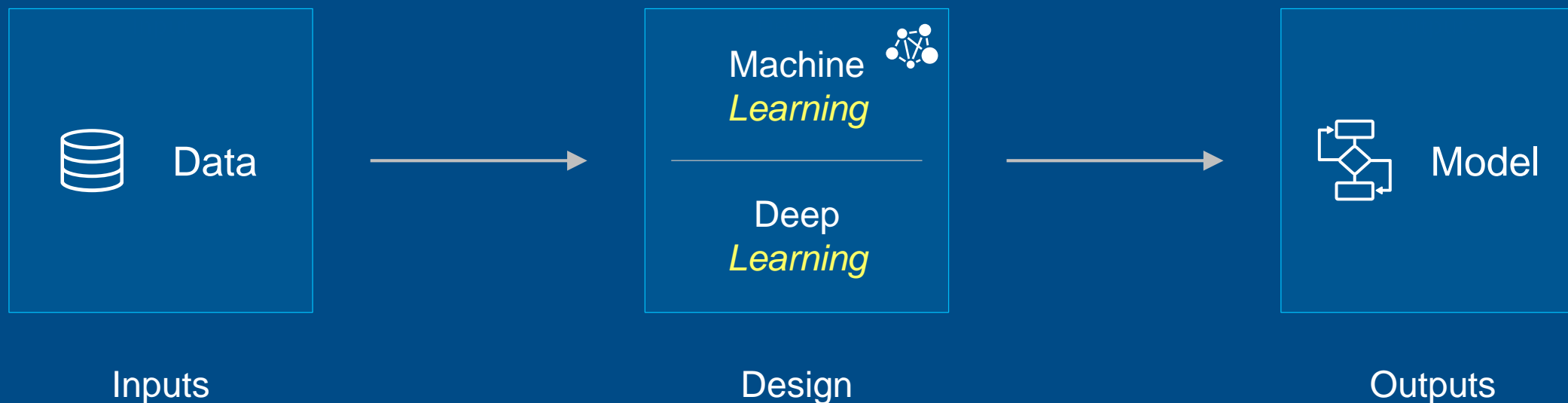
Machine Learning



Artificial Intelligence



Using MATLAB and Simulink to Build **Deep Learning Models**

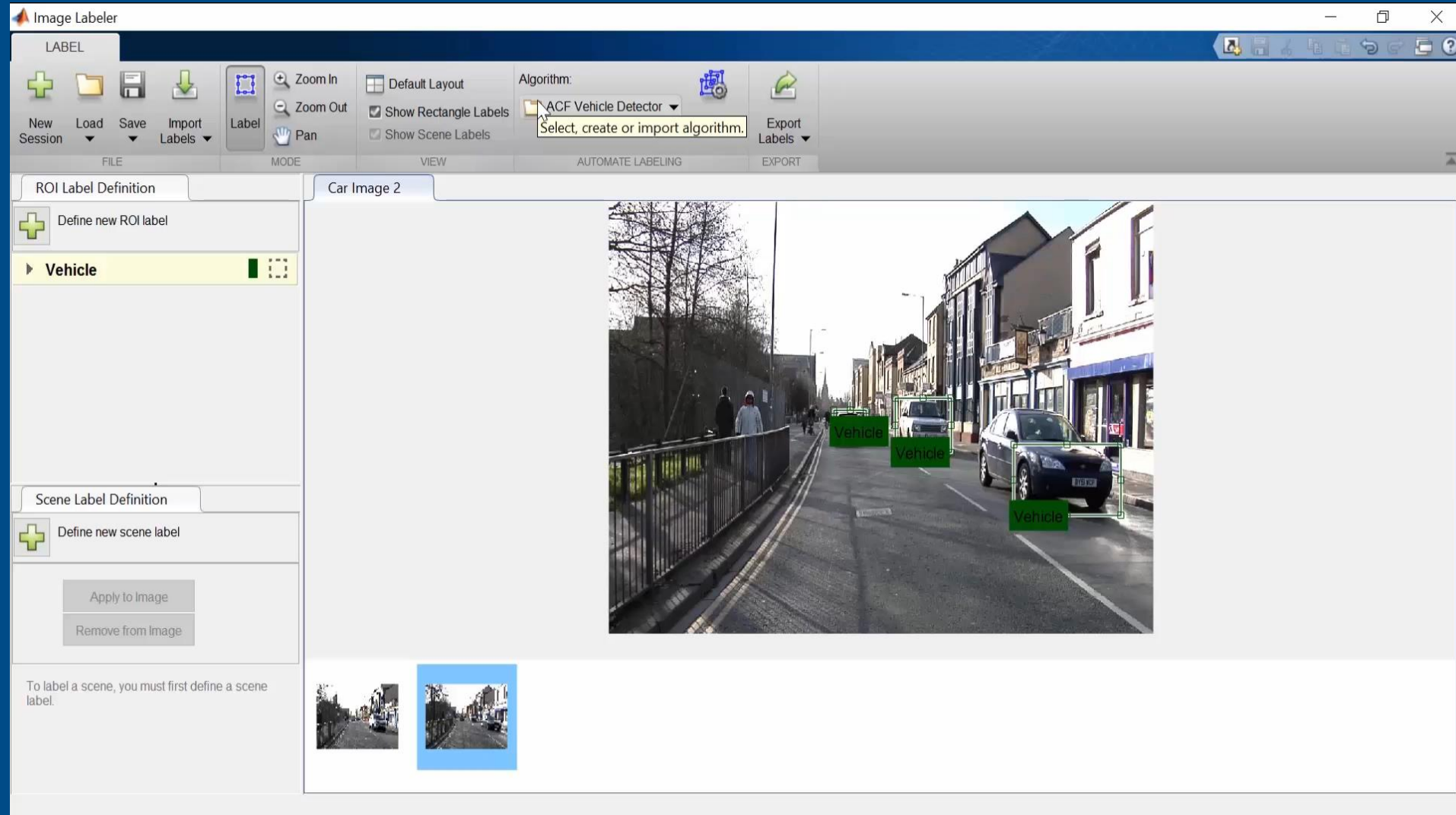


MATLAB® & SIMULINK®



Using Apps for Ground Truth Labeling Image and Video Data

Input

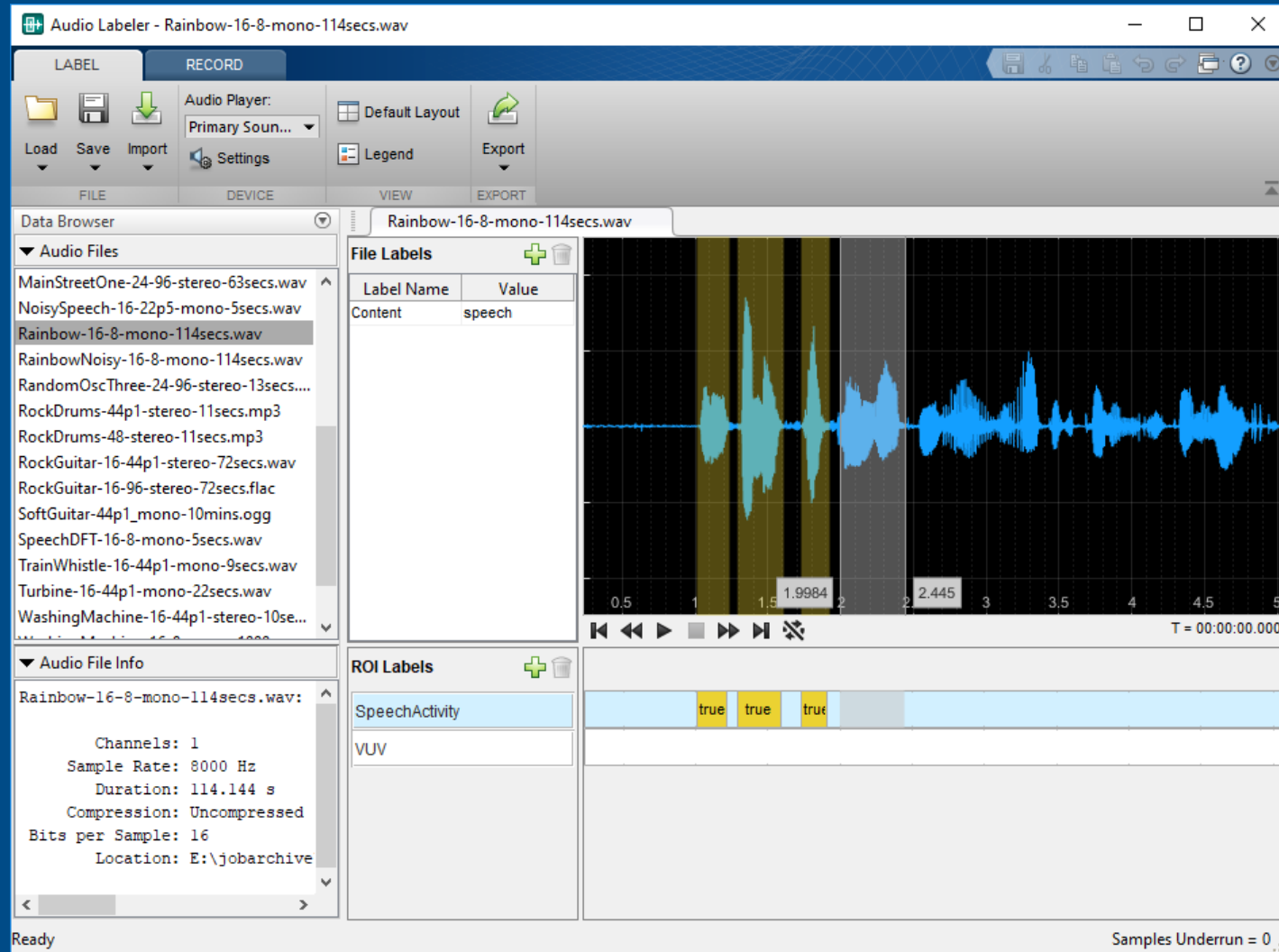
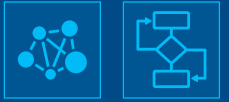


Signal Processing Toolbox

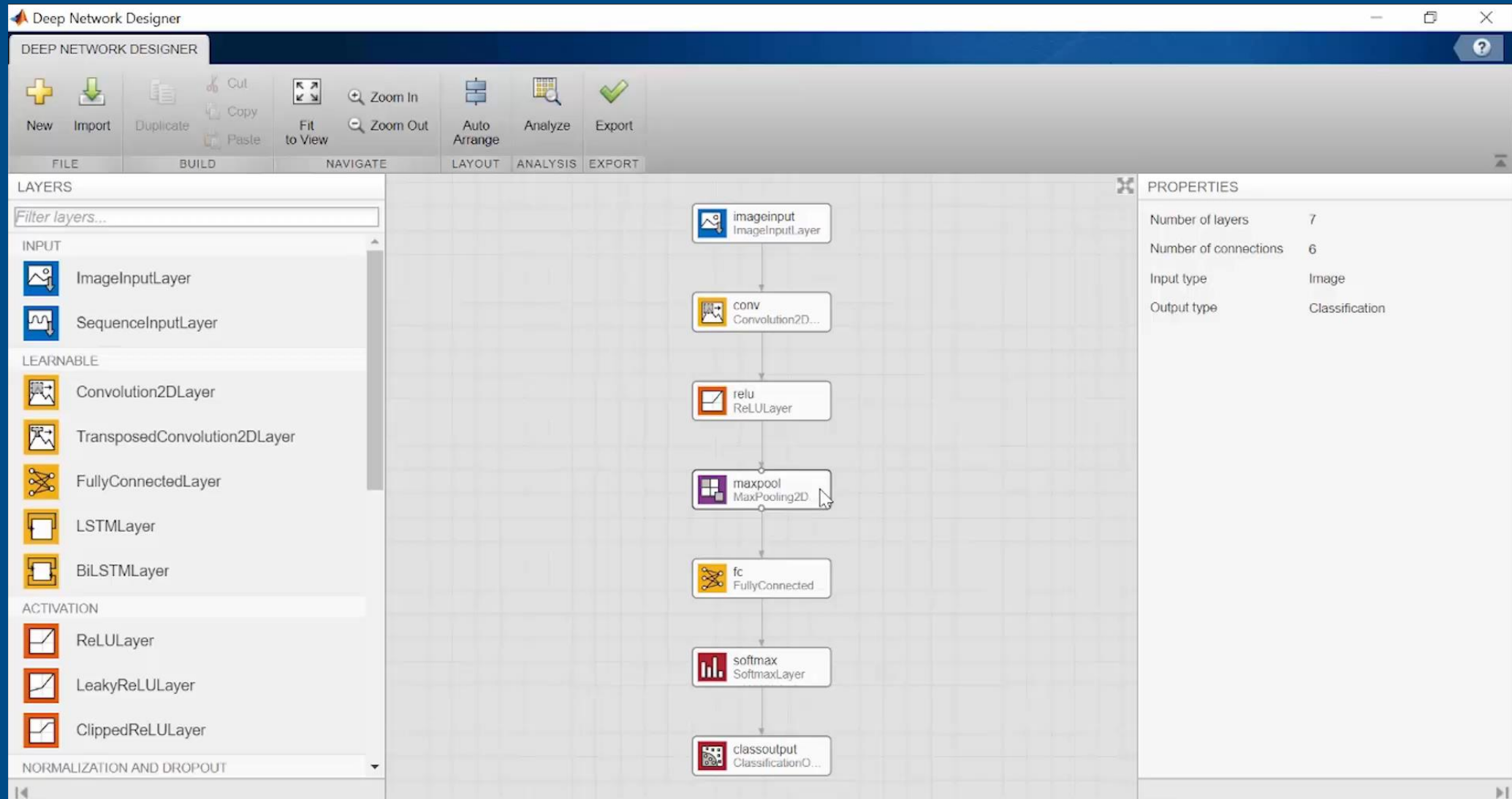


Using Apps for Ground Truth Labeling Audio Data

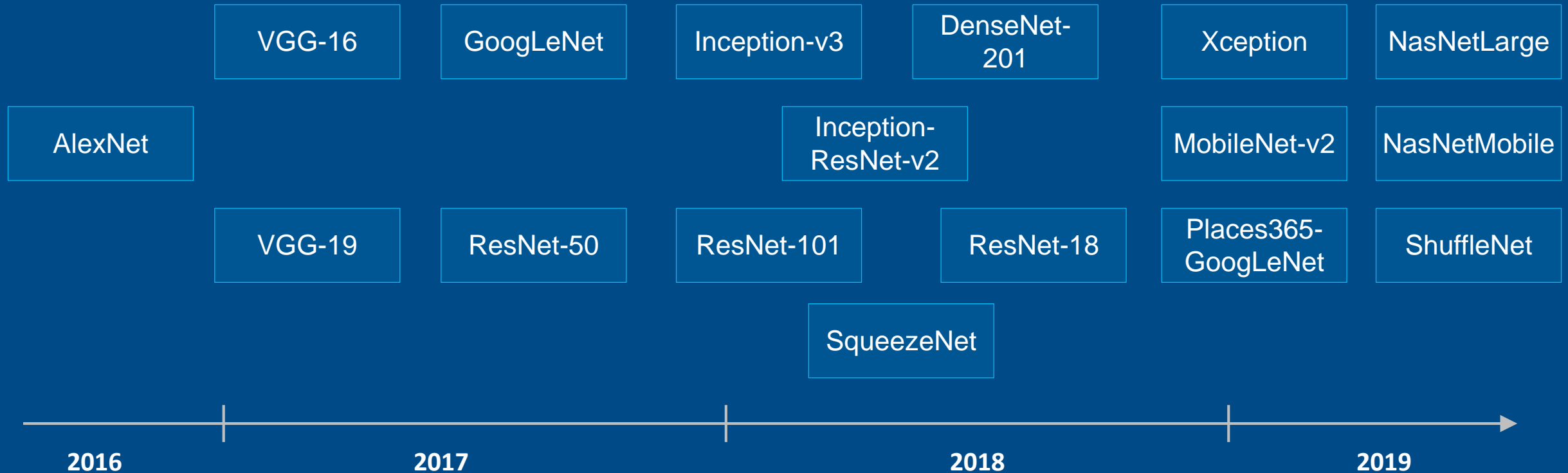
Input



Using Apps for Designing Deep Learning Networks

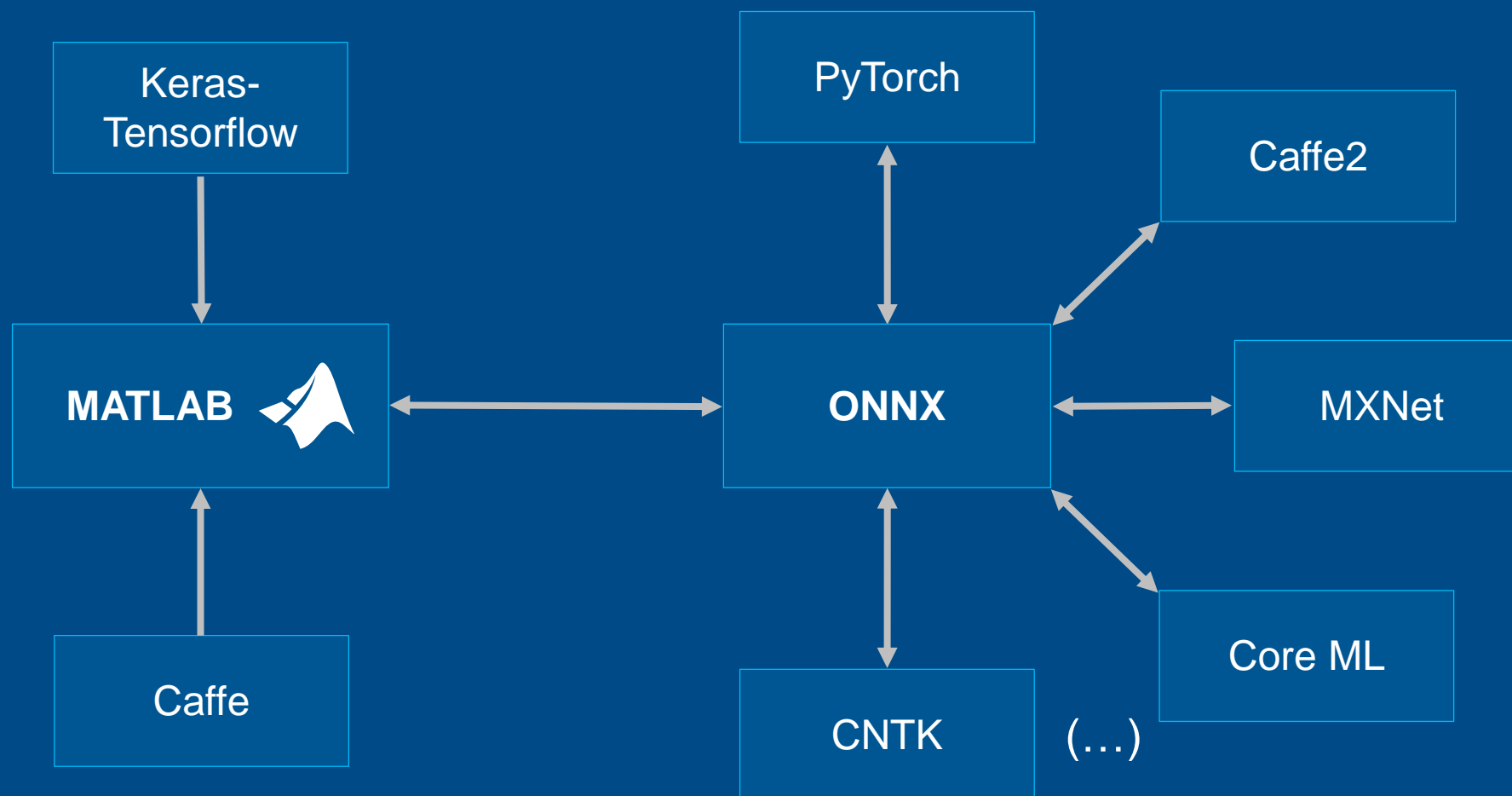


Using Transfer Learning with Pre-trained Models

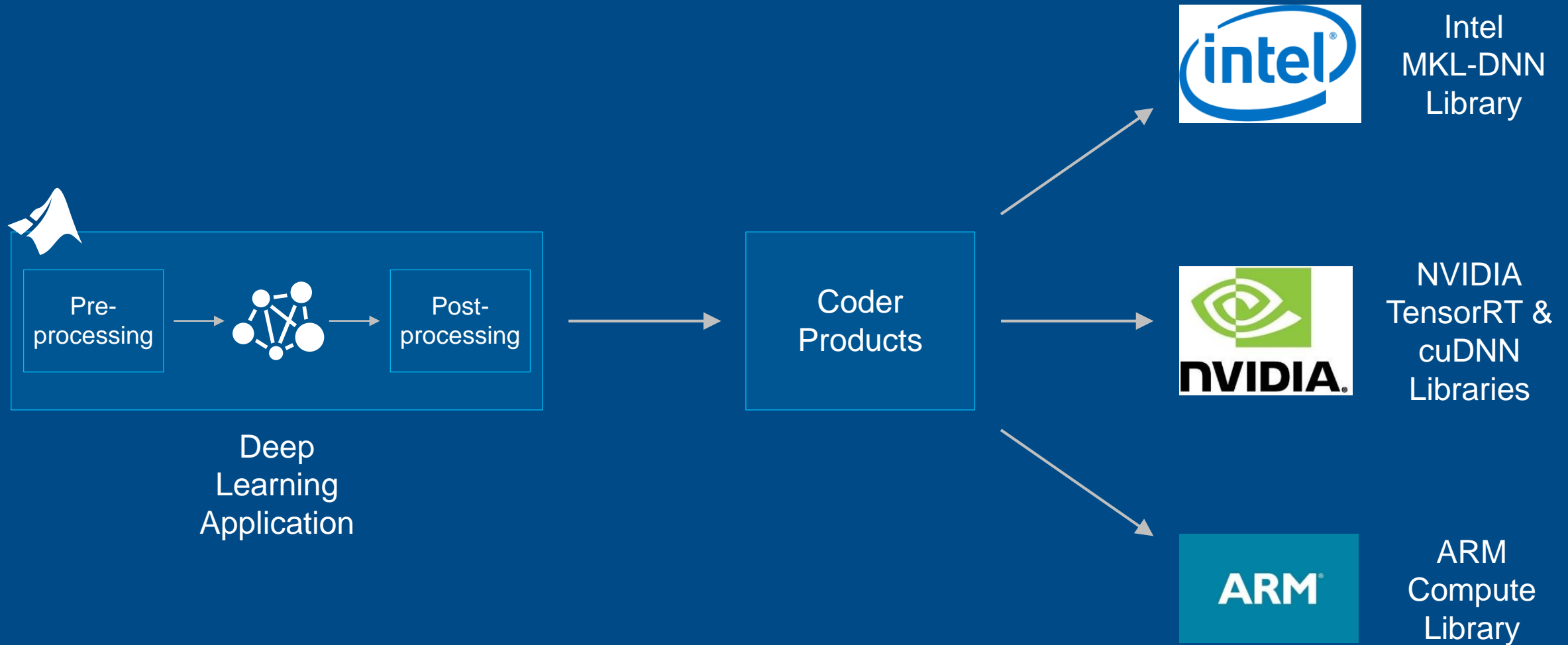




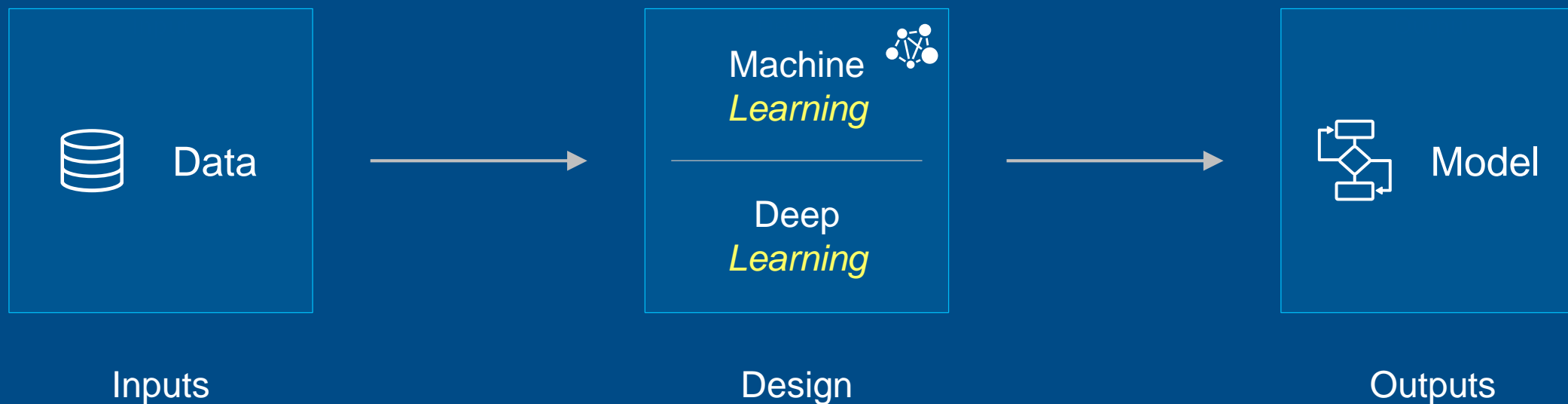
Using Models from Other Frameworks



Deploying Deep Learning Applications



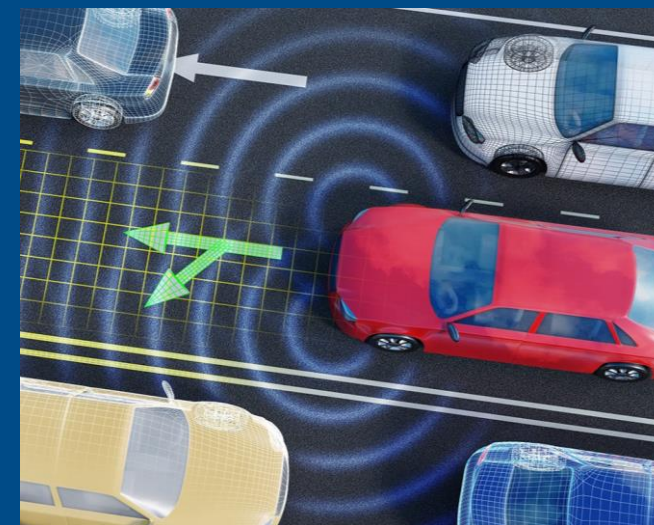
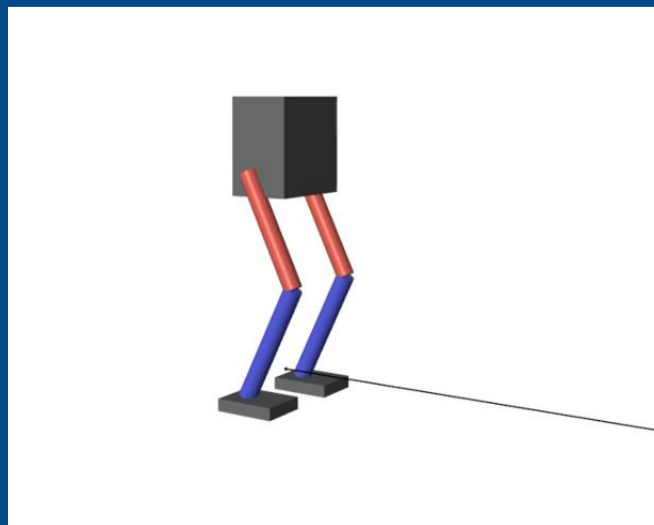
Using MATLAB and Simulink for Reinforcement Learning



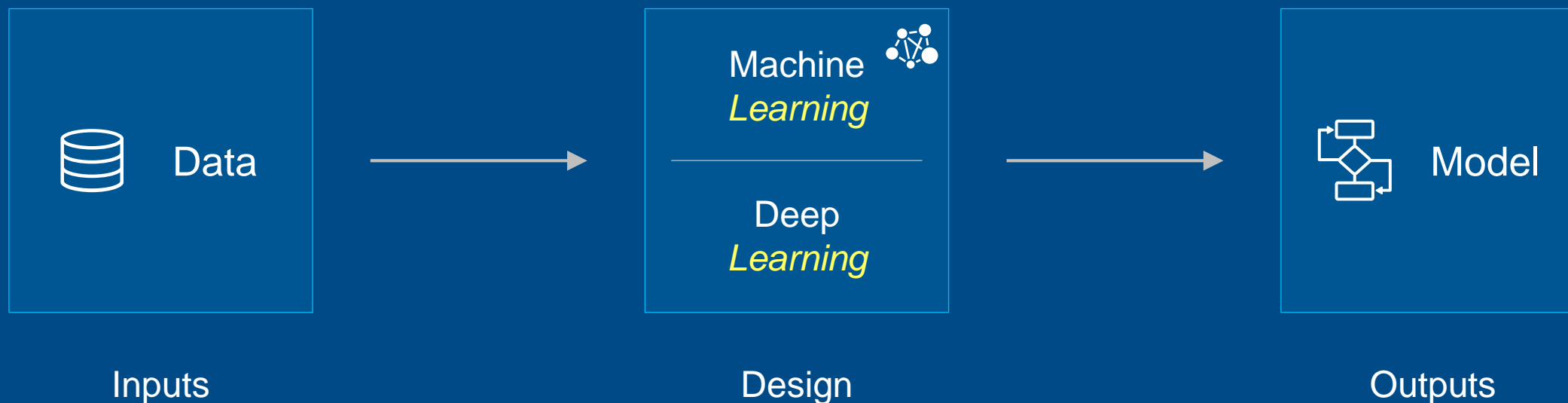
MATLAB® & SIMULINK®



Using MATLAB and Simulink for Reinforcement Learning



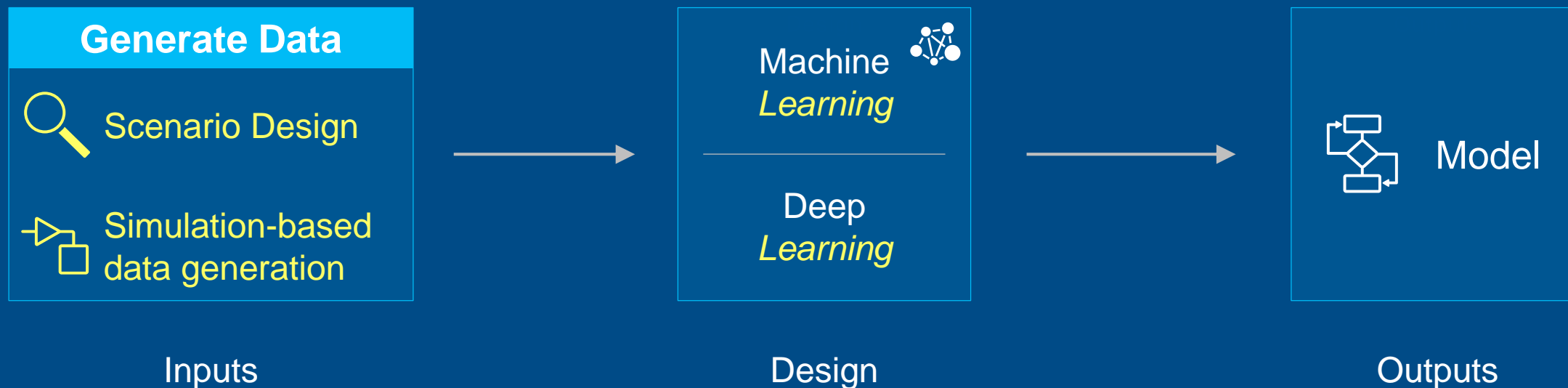
Using MATLAB and Simulink for Reinforcement Learning



MATLAB® & SIMULINK®



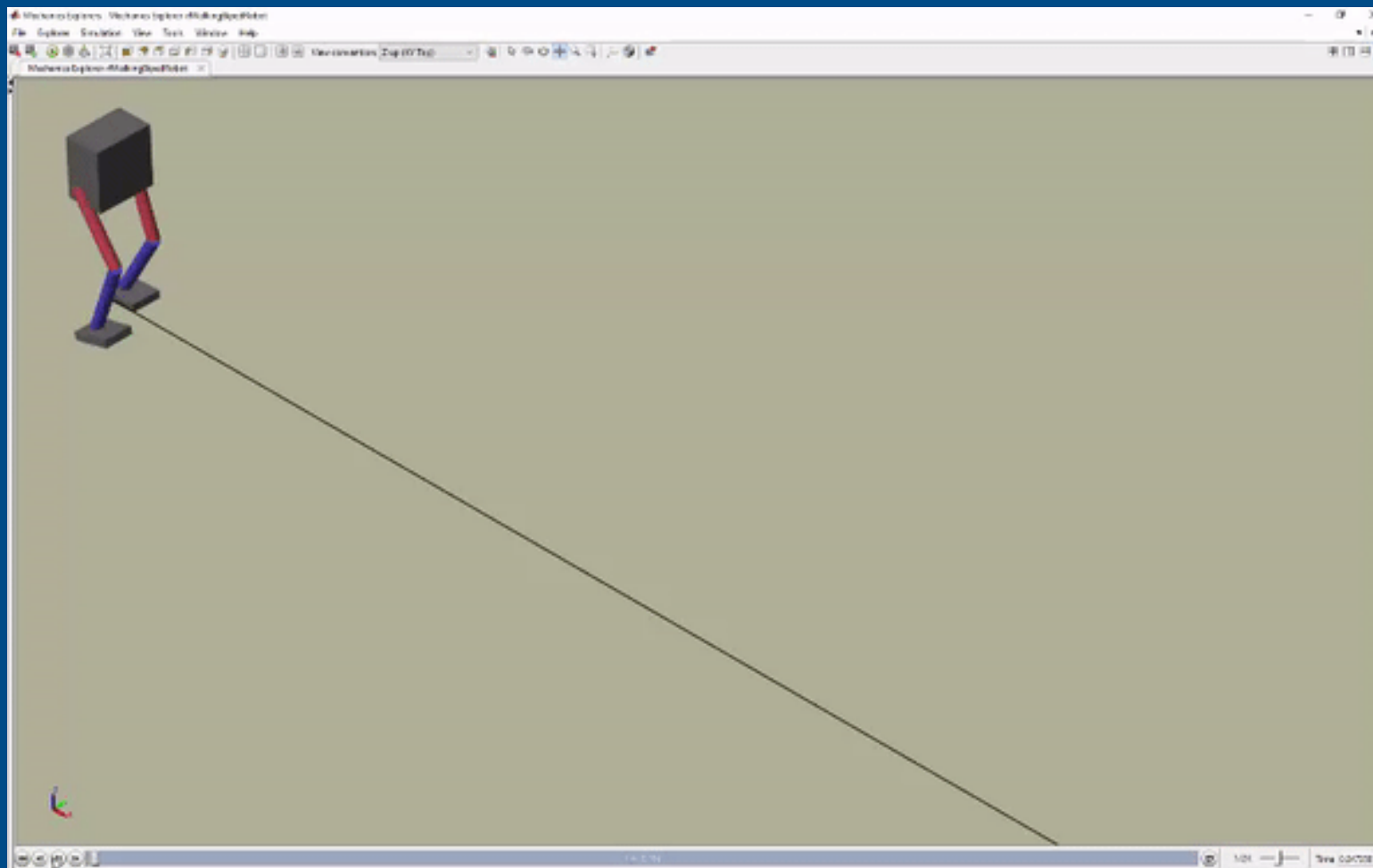
Using MATLAB and Simulink for Reinforcement Learning



MATLAB® & SIMULINK®



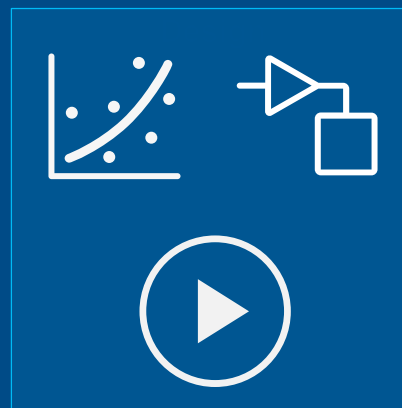
Using MATLAB and Simulink for Reinforcement Learning



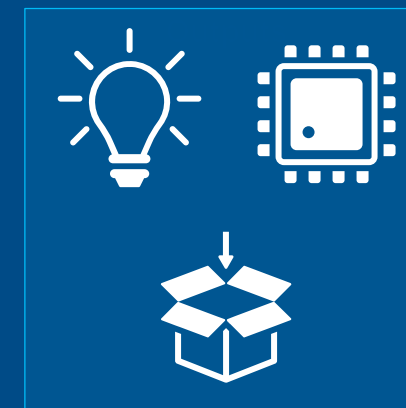
Using MATLAB & Simulink to Build Algorithms in Everything



Inputs



Design



Outputs



MATLAB® & SIMULINK®



Working with Text Data



```

Vehicle_Repairs.csv
Dept,JobDate,jobno,VehicleId,UnitNo,Reason,Notes,CostParts,CostLabor,CostTotal
1020,01/06/2015 12:00:00 AM,14073,118743,14,04 DRIVER'S REPORT,"PM SERVICE, CHECK TURN SIGNAL, CLUNKING NOISE WHEN DRIVING",493.85,0,493.85
1020,01/14/2015 12:00:00 AM,14232,230973,13,08 PM SERVICE ***,"SERVICEROB,EXT,5604",38.869999999999997,0,38.869999999999997
2111,01/02/2015 12:00:00 AM,14006,1243,116,04 DRIVER'S REPORT,NEED 4 PLOW PINS,45,0,45
2111,01/02/2015 12:00:00 AM,14140,B39109 ,178,04 DRIVER'S REPORT,INSTALL SPINNER ASSY,0,0,0
2111,01/03/2015 12:00:00 AM,14163,574950,215,13 SNOW BREAKDOWN,DONT START,0,0,0
2111,01/05/2015 12:00:00 AM,14169,A00413 ,283,04 DRIVER'S REPORT,DOG BONE PIN BROKEN,20,0,20
2111,01/06/2015 12:00:00 AM,14000,766153,248,08 PM SERVICE ***,"NEED SERVICE, CHECK BRAKES",387.17,0,387.17
2111,01/06/2015 12:00:00 AM,14155,525670,232,04 DRIVER'S REPORT,HYD CAP CHECK ENGINE LIGHT ON,12.95,0,12.95
2111,01/06/2015 12:00:00 AM,14157,621909,213,40 NEGLIGENCE,TARP VALVE STICKINGRIGHT SIDE MIRROR BRACKET BROKEN,50.02,0,50.02
2111,01/06/2015 12:00:00 AM,14164,1226,117,13 SNOW BREAKDOWN,HANDLES IN CAB LOOSE,0,0,0
2111,01/06/2015 12:00:00 AM,14165,525999,114,04 DRIVER'S REPORT,NO PLOW LIGHTS,0,0,0
2111,01/06/2015 12:00:00 AM,14172,B34632 ,276,10 ROADCALL,WILL NOT START,0,0,0
2111,01/06/2015 12:00:00 AM,14174,1469,122,10 ROADCALL,WILL NOT START,0,0,0
2111,01/06/2015 12:00:00 AM,14175,68932,147,10 ROADCALL,WILL NOT START,0,0,0
2111,01/06/2015 12:00:00 AM,14176,68933,148,10 ROADCALL,WILL NOT START,0,0,0
2111,01/06/2015 12:00:00 AM,14177,621907,208,10 ROADCALL,WILL NOT START,0,0,0
2111,01/06/2015 12:00:00 AM,14181,337657,218,04 DRIVER'S REPORT,CONVEORY NOT WORKING,0,0,0
2111,01/06/2015 12:00:00 AM,14182,D-1920 ,164,10 ROADCALL,DONT START,0,0,0
2111,01/06/2015 12:00:00 AM,14183,525998,217,10 ROADCALL,DONT START,0,0,0
2111,01/06/2015 12:00:00 AM,14184,526000,225,10 ROADCALL,DONT START,0,0,0
2111,01/06/2015 12:00:00 AM,14185,621921,214,04 DRIVER'S REPORT,CONVORY NOT WORKING,0,0,0
2111,01/07/2015 12:00:00 AM,14188,001469 ,201,04 DRIVER'S REPORT,needs def/jim f,0,0,0
2111,01/07/2015 12:00:00 AM,14190,337656,219,04 DRIVER'S REPORT,NEEDS FLOOR MATTS,65.069999999999993,0,65.069999999999993
2111,01/07/2015 12:00:00 AM,14191,B34632 ,276,10 ROADCALL,DONT START,0,0,0
2111,01/07/2015 12:00:00 AM,14196,1222,118,04 DRIVER'S REPORT,HARDWARE FOR REAR SPRINGS,14.32,0,14.32
2111,01/07/2015 12:00:00 AM,14199,52565,626,04 DRIVER'S REPORT,WASHER FLUIDDEF,28.88,0,28.88
2111,01/09/2015 12:00:00 AM,14107,1467,121,08 PM SERVICE ***,"REMOVE & REPLACE REAR SPRINGS, CHECK COOLANT TUBESPM SERVICE",4697.55,0,

```

Working with Text Data

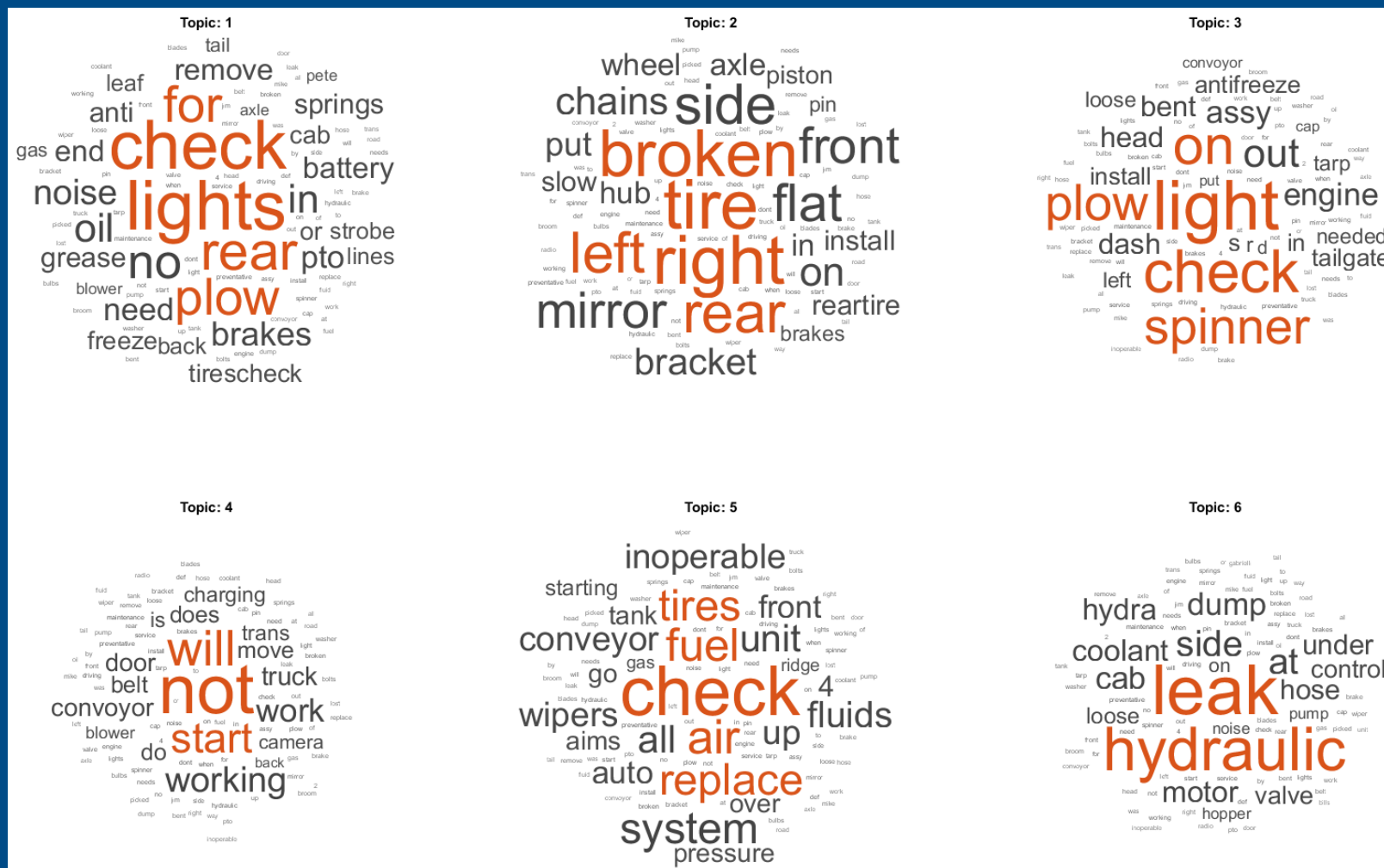
Input



```
t = readtable(filename, 'TextType', 'string');
disp(t(1:20,6:7))
```

	Reason		Notes
"04	DRIVER'S REPORT"		"PM SERVICE, CHECK TURN SIGNAL, CLUNKING NOISE WHEN DRIVING"
"08	PM SERVICE	***"	"SERVICEROB,EXT,5604"
"04	DRIVER'S REPORT"		"NEED 4 PLOW PINS"
"04	DRIVER'S REPORT"		"INSTALL SPINNER ASSY"
"13	SNOW BREAKDOWN"		"DONT START"
"04	DRIVER'S REPORT"		"DOG BONE PIN BROKEN"
"08	PM SERVICE	***"	"NEED SERVICE, CHECK BRAKES"
"04	DRIVER'S REPORT"		"HYD CAP CHECK ENGINE LIGHT ON"
"40	NEGLIGENCE"		"TARP VALVE STICKINGRIGHT SIDE MIRROR BRACKET BROKEN"
"13	SNOW BREAKDOWN"		"HANDLES IN CAB LOOSE"
"04	DRIVER'S REPORT"		"NO PLOW LIGHTS"
"10	ROADCALL"		"WILL NOT START"
"10	ROADCALL"		"WILL NOT START"
"10	ROADCALL"		"WILL NOT START"
"10	ROADCALL"		"WILL NOT START"
"10	ROADCALL"		"WILL NOT START"
"04	DRIVER'S REPORT"		"CONVEORY NOT WORKING"
"10	ROADCALL"		"DONT START"
"10	ROADCALL"		"DONT START"
"10	ROADCALL"		"DONT START"

Input



Nouns



いかなる 苦い あじなかい

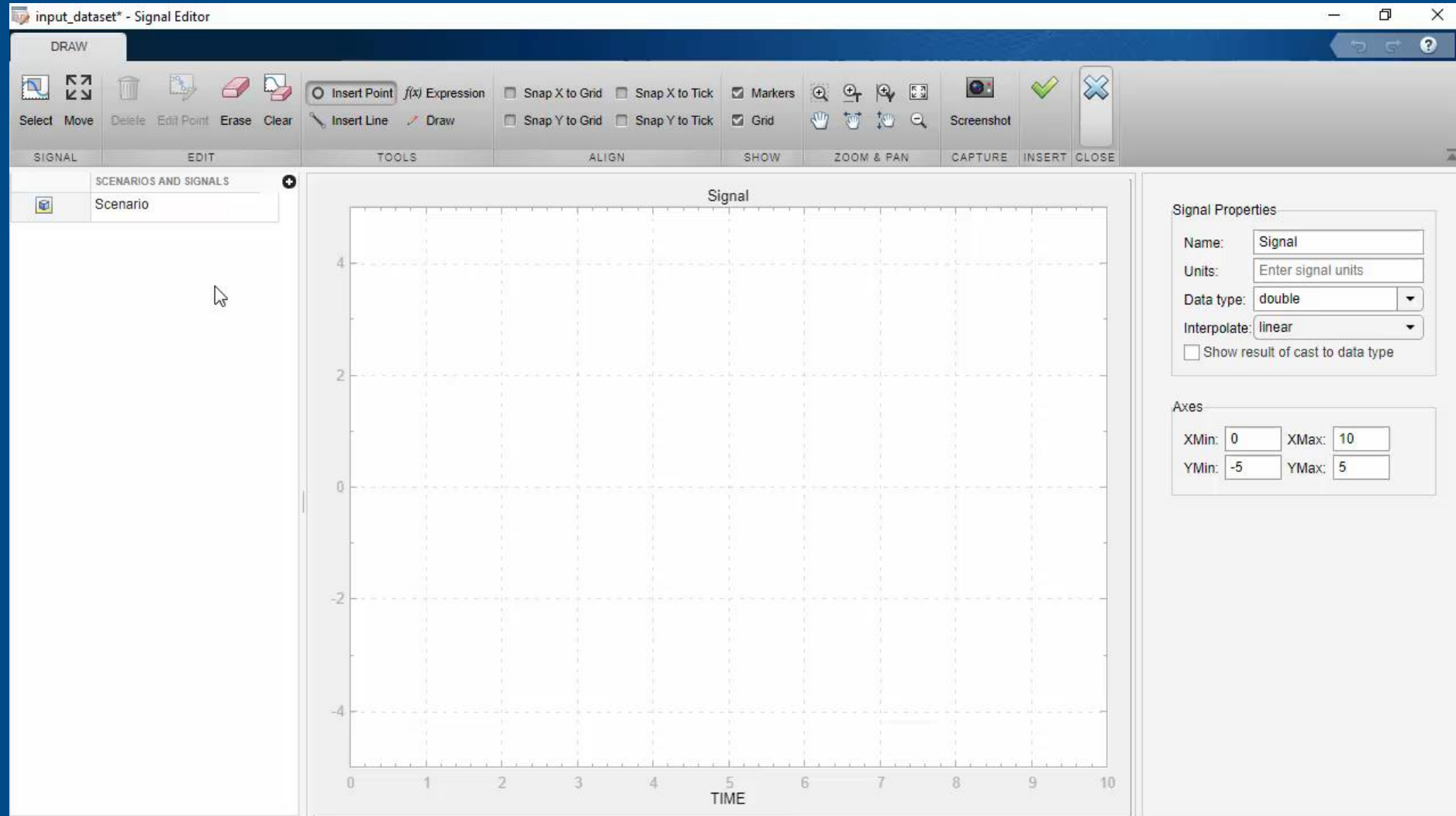


Adjectives

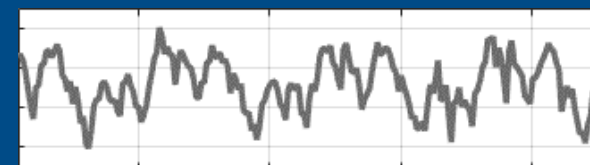
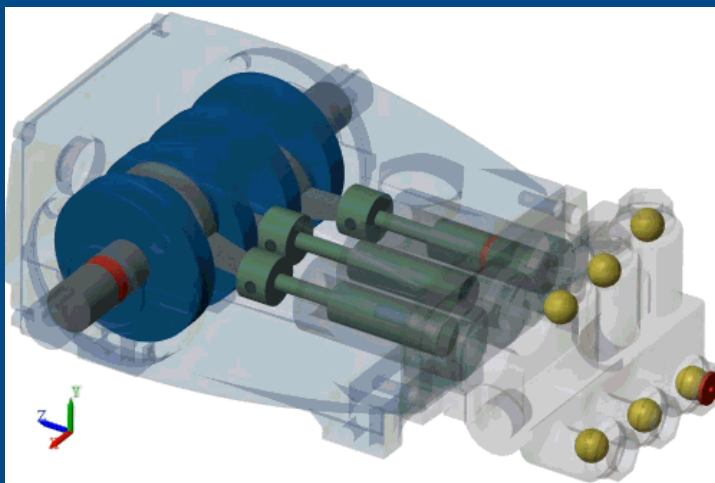


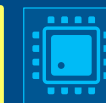
Creating Your Own Data

Input

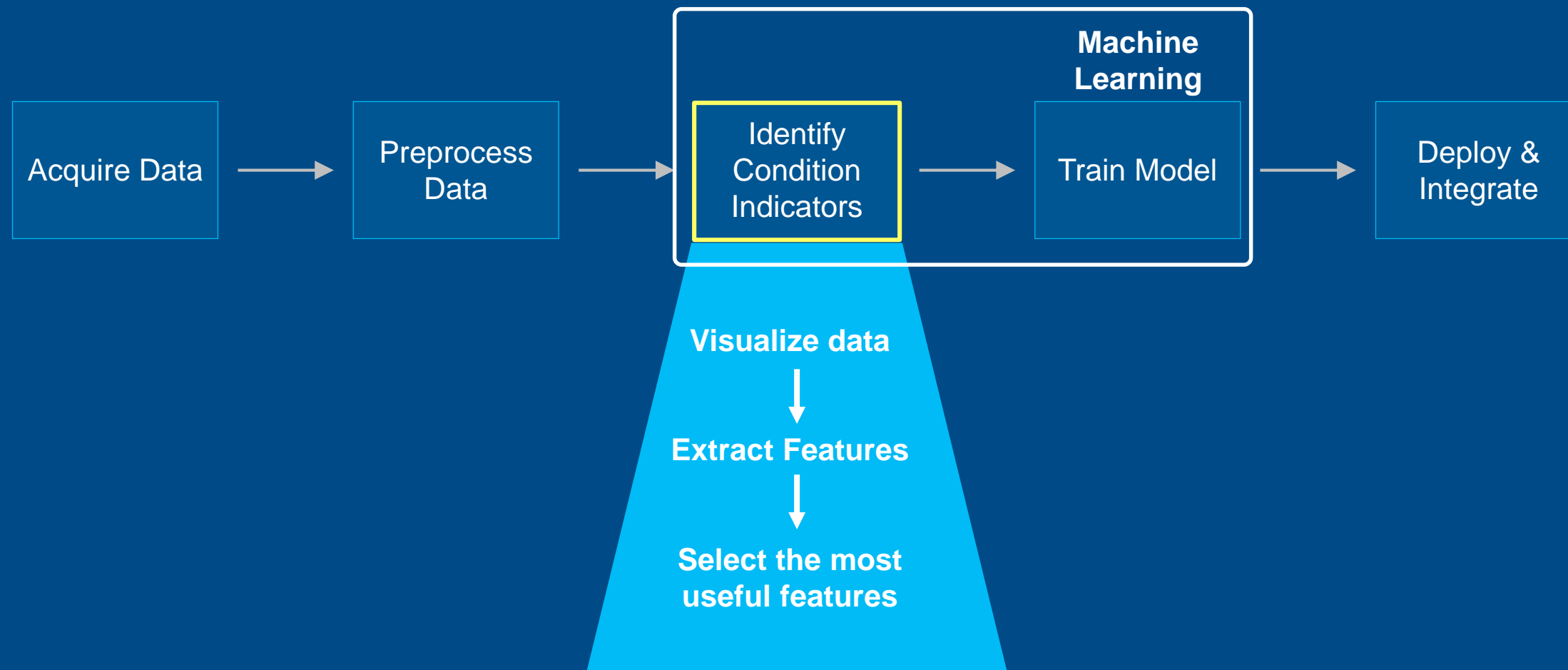


Input

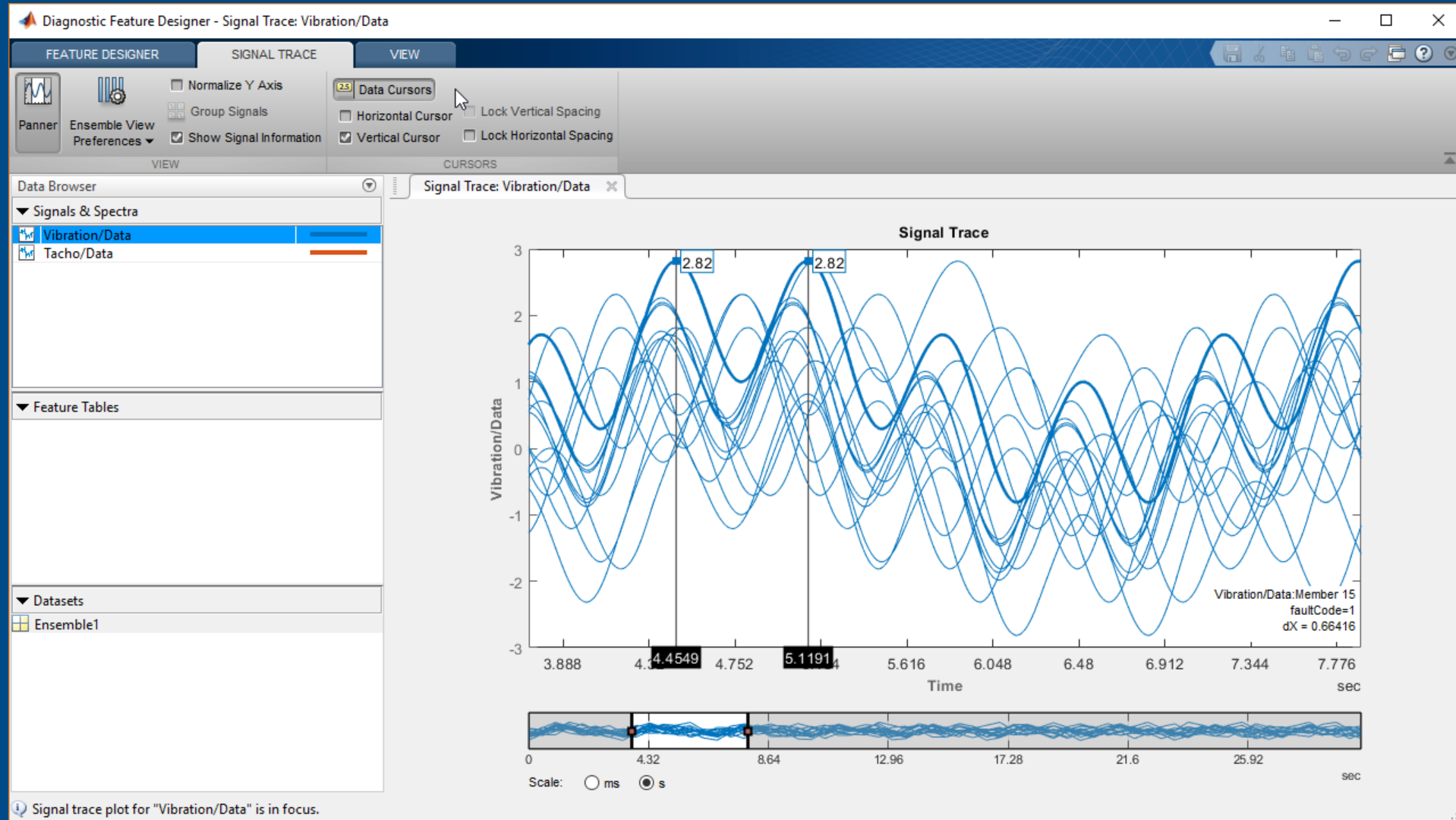




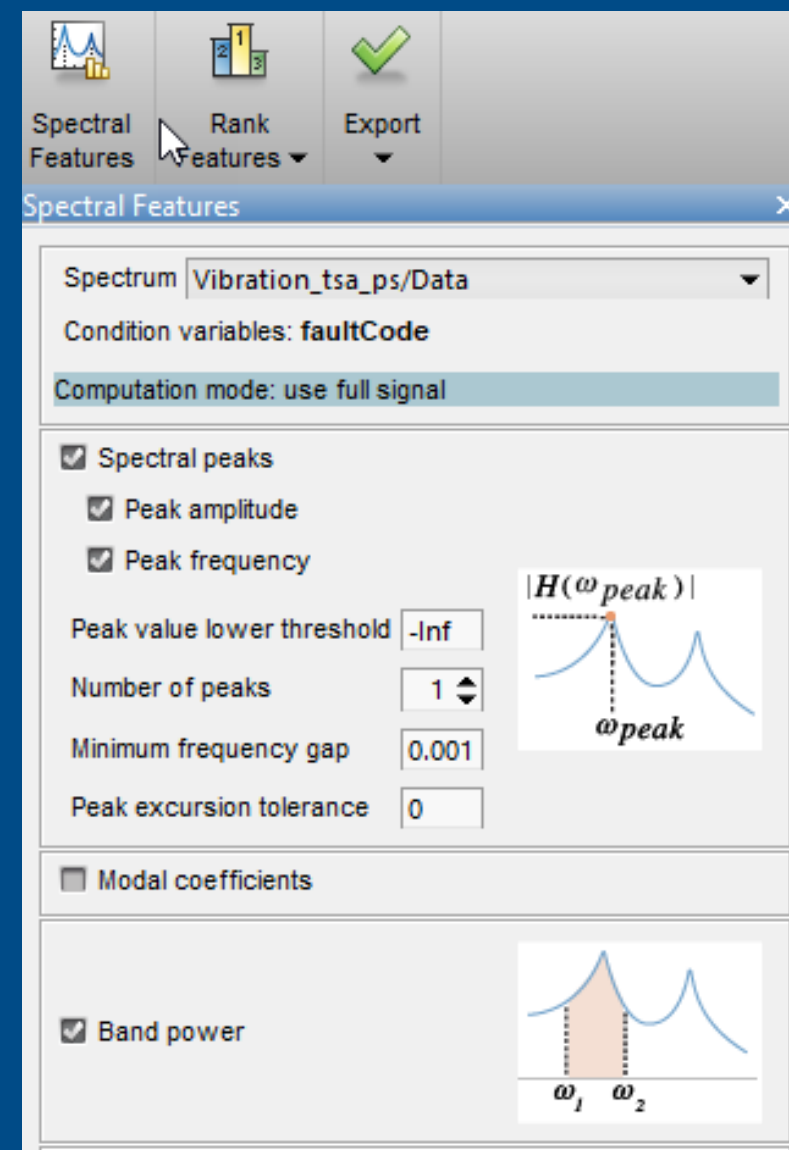
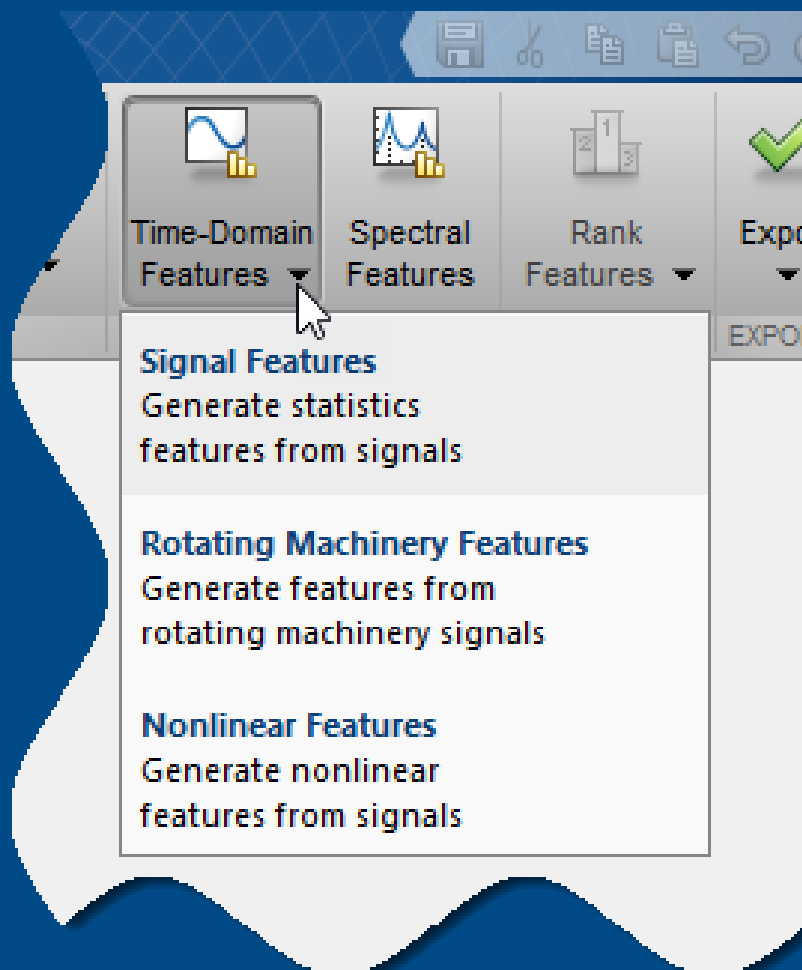
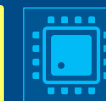
Identifying the Useful Data



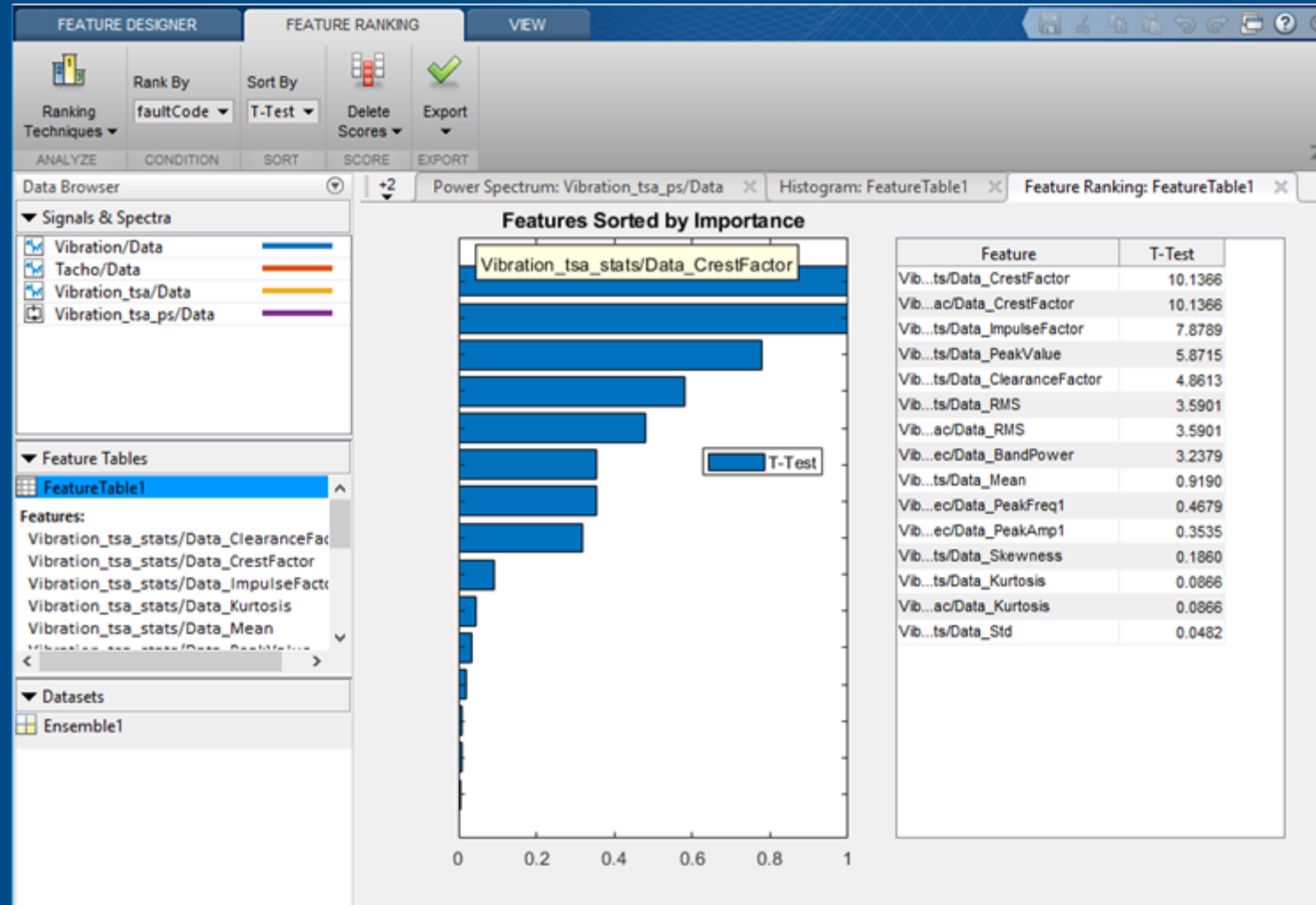
Identifying the Useful Data

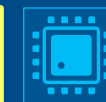


Identifying the Useful Data



Identifying the Useful Data



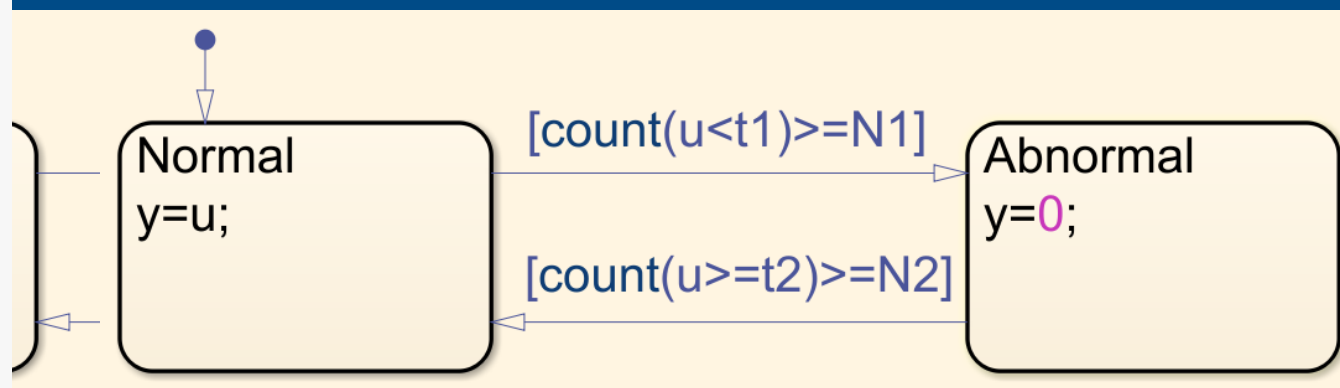


Designing Decision Logic with Stateflow

```

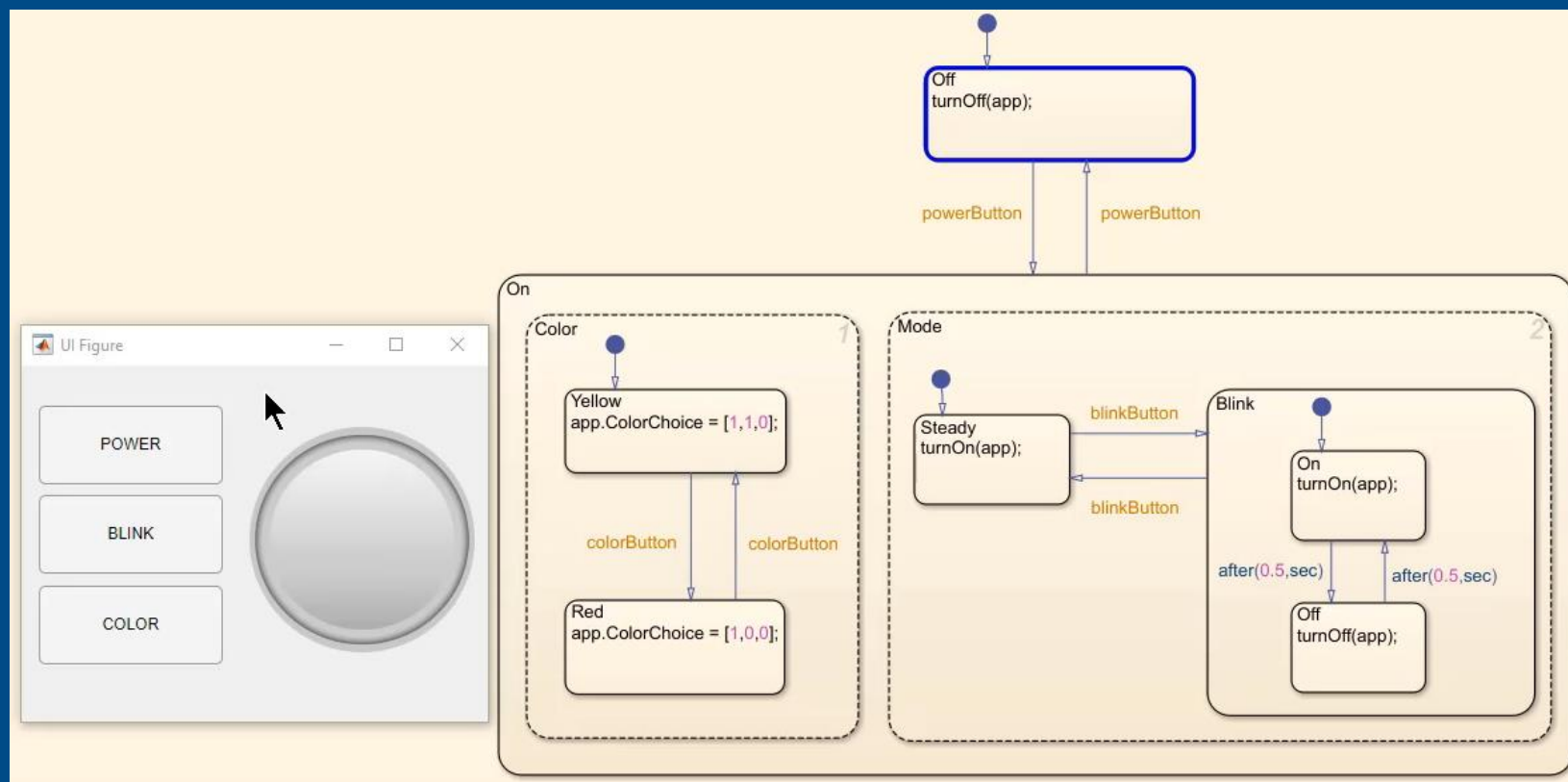
inNormalRegion = true;
counter = 0;
for i=1:length(inData)
    if(inNormalRegion)
        if(inData(i)<t1)
            counter = counter+1;
            if(counter>=N1)
                inNormalRegion = false;
            end
        else
            counter = 0;
        end
    else
        if(inData(i)>=t2)
            counter = counter+1;
            if(counter>=N2)
                inNormalRegion = true;
            end
        else
            counter = 0;
        end
    end
    if(inNormalRegion)
        outData(i) = inData(i);
    else
        outData(i) = 0;
    end
end

```





Using Stateflow in MATLAB



```
% Callbacks that handle component events
methods (Access = private)

% Code that executes after component creation
function startupFcn(app)
    app.LanternLogic = BlinkLanternLogic('app',app);
end

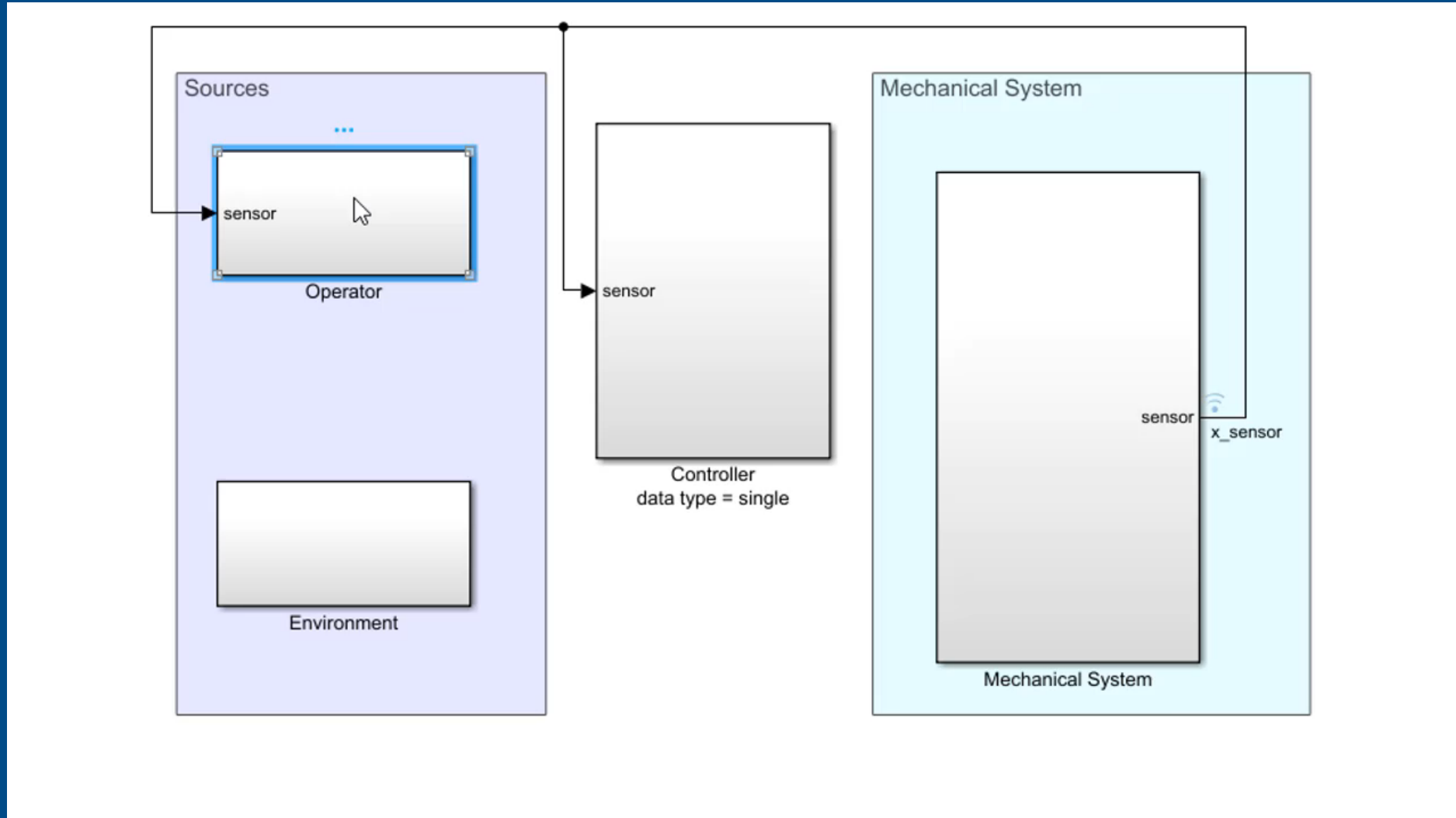
% Button pushed function: POWERButton
function POWERButtonPushed(app, event)
    app.LanternLogic.powerButton();
end

% Button pushed function: COLORButton
function COLORButtonPushed(app, event)
    app.LanternLogic.colorButton();
end

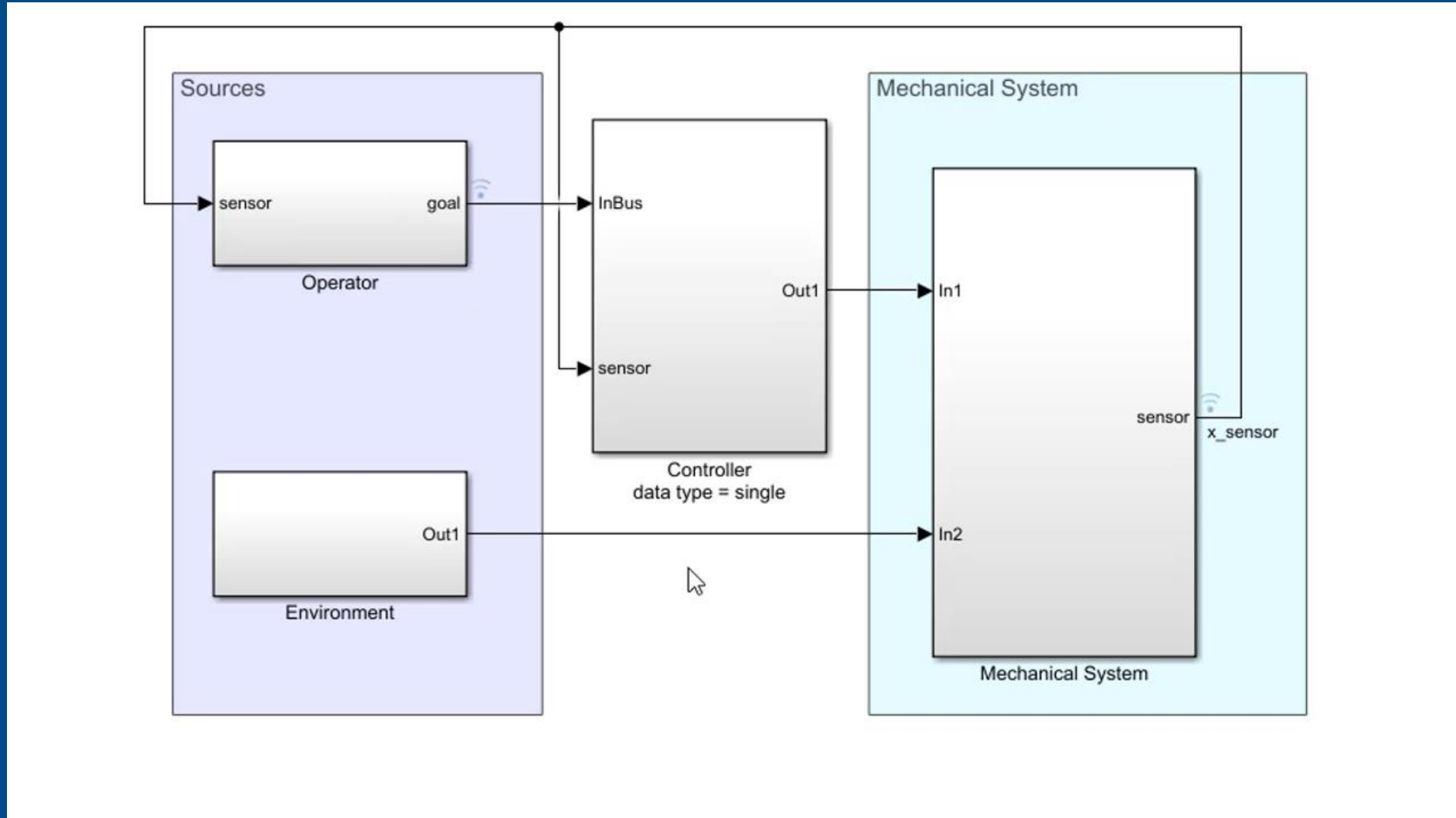
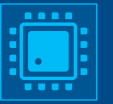
% Close request function: UIFigure
function UIFigureCloseRequest(app, event)
    delete(app.LanternLogic);
    delete(app);
end

% Button pushed function: BLINKButton
function BLINKButtonPushed(app, event)
    app.LanternLogic.blinkButton();
end
end
```

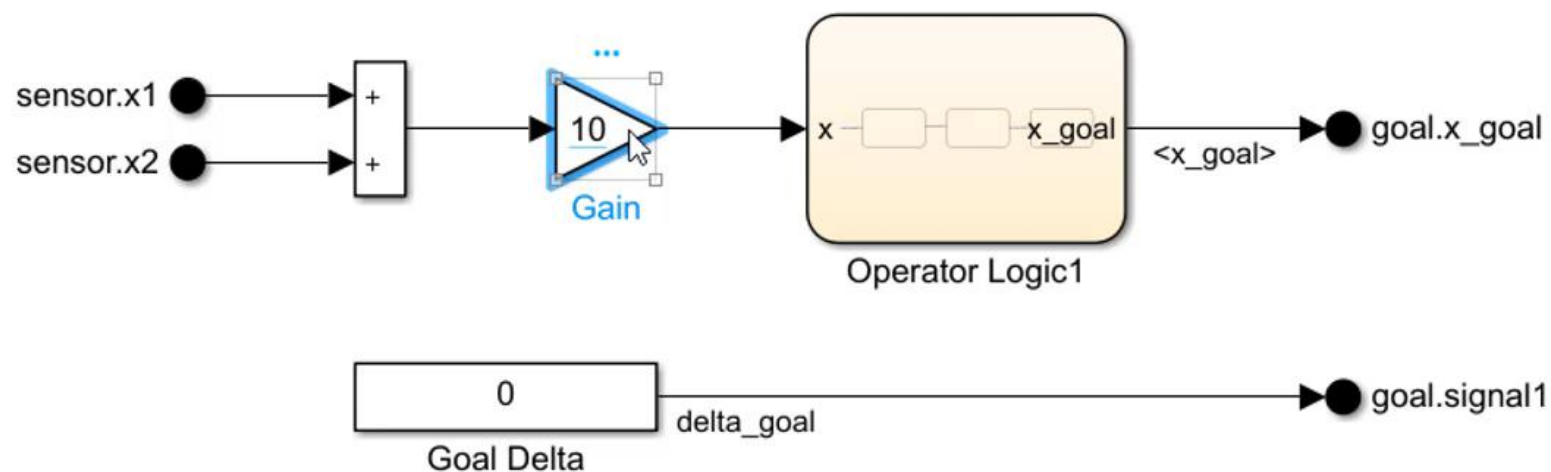
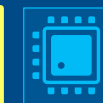
Editing at the Speed of Thought



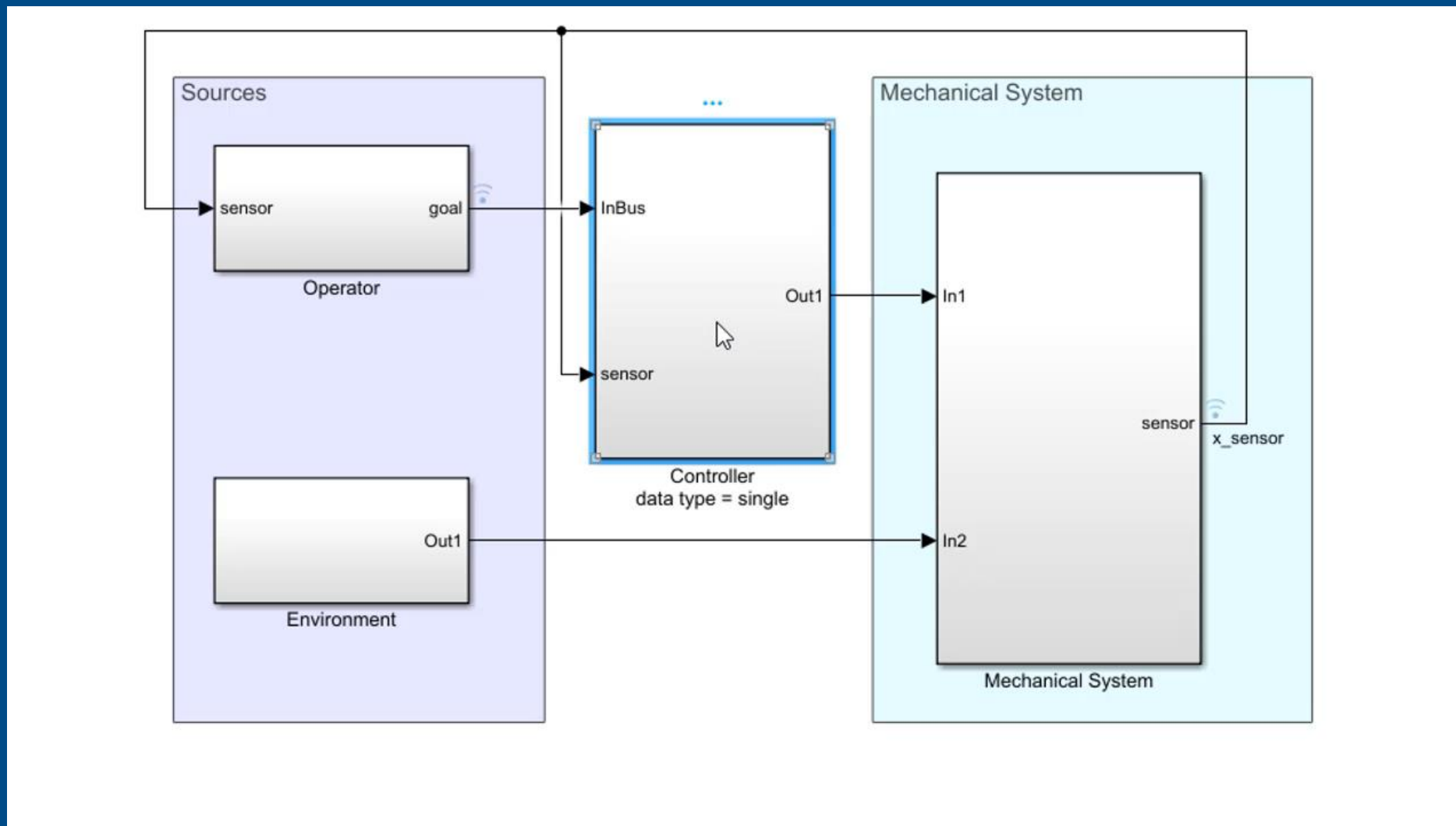
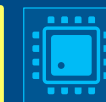
Editing at the Speed of Thought



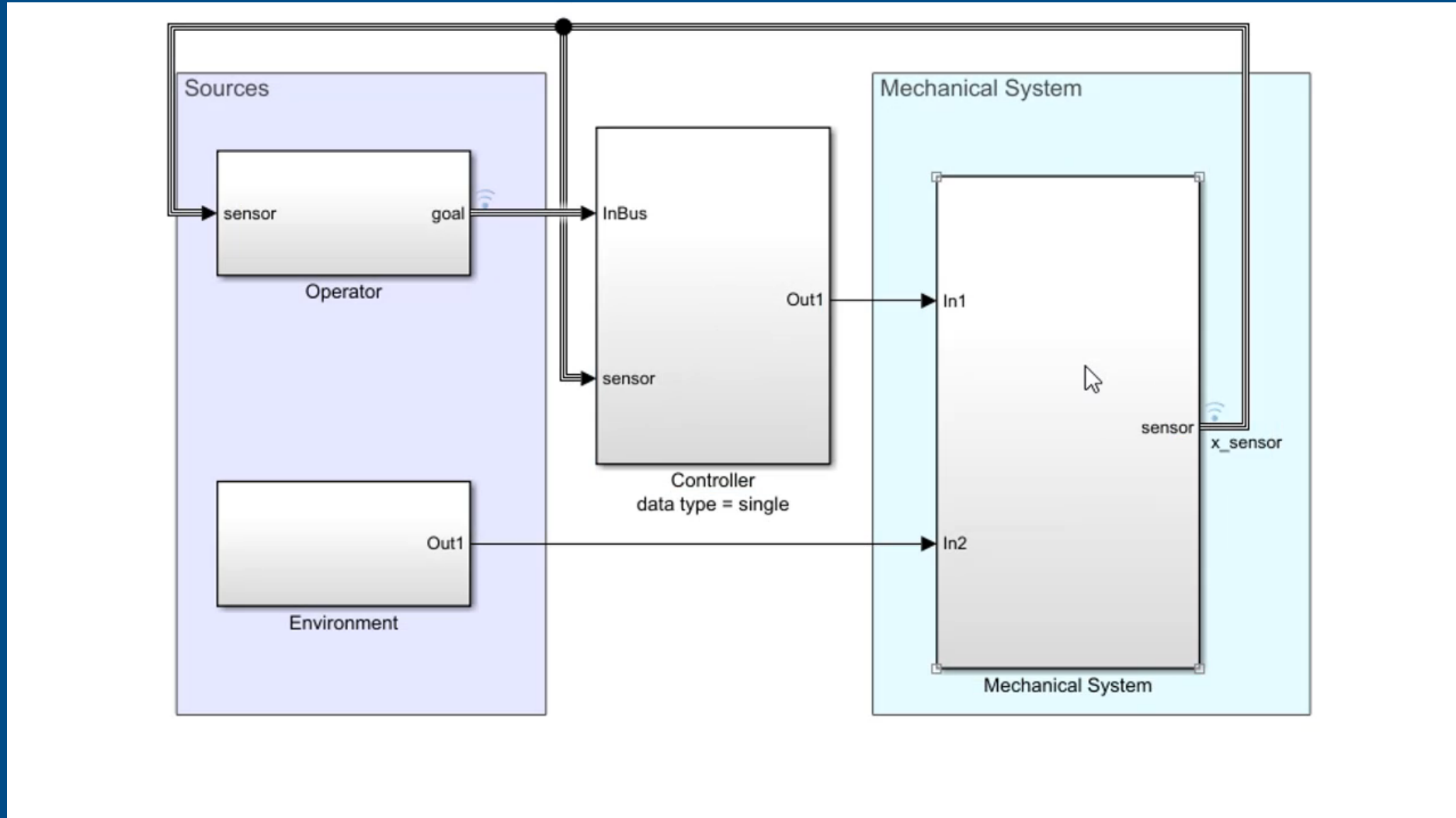
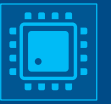
Editing at the Speed of Thought

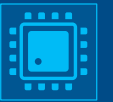


Editing at the Speed of Thought



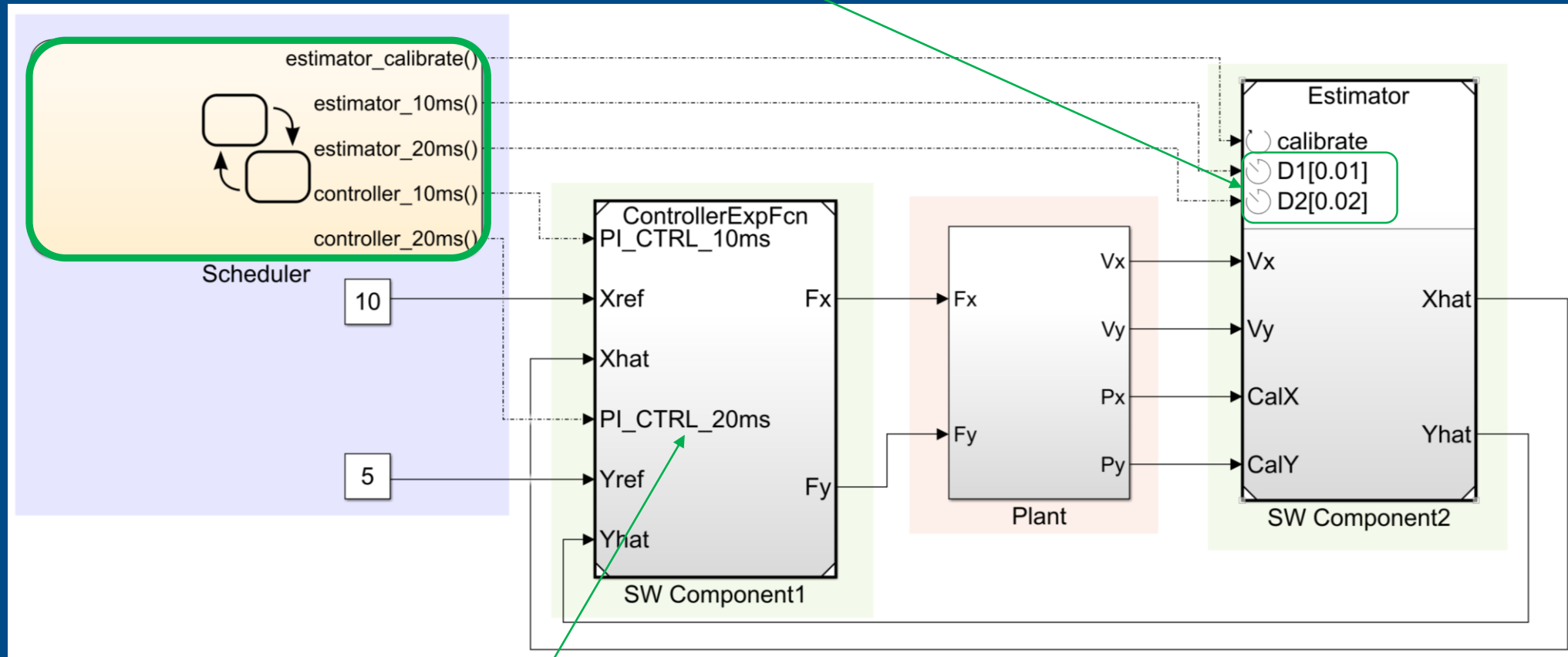
Editing at the Speed of Thought





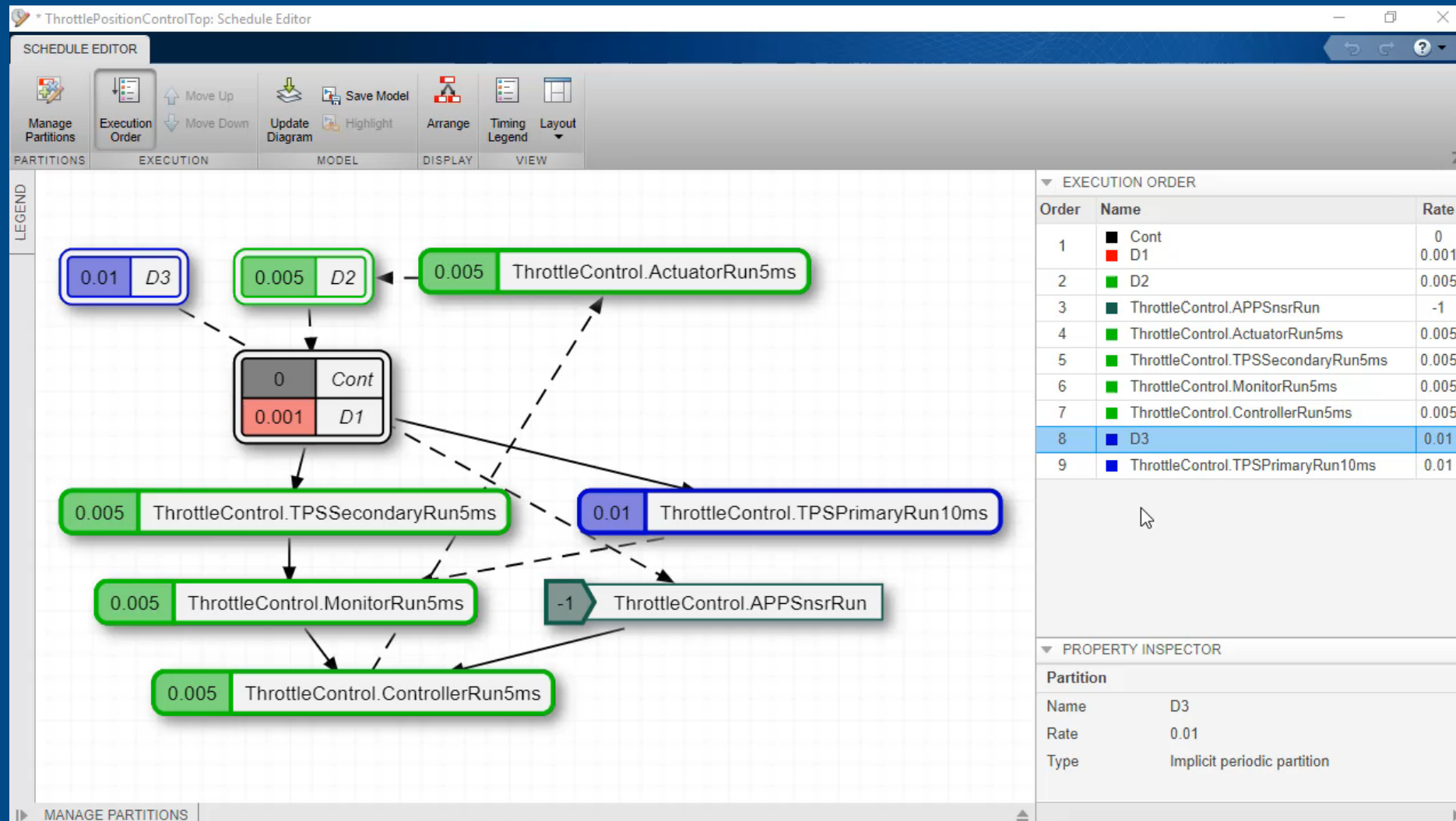
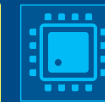
Controlling the Execution of Model Components

Schedulable Rate-Based Model

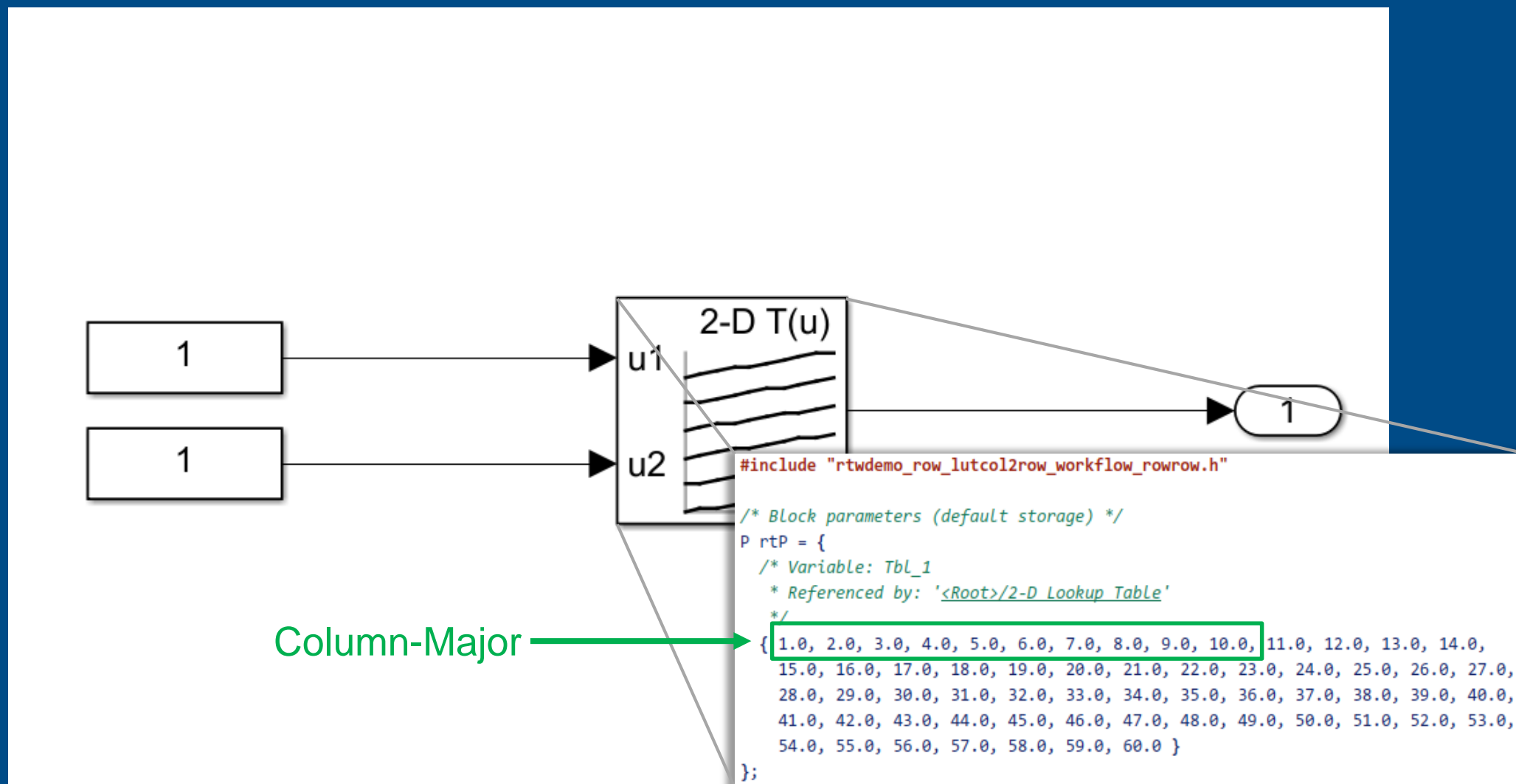


Export Function Model

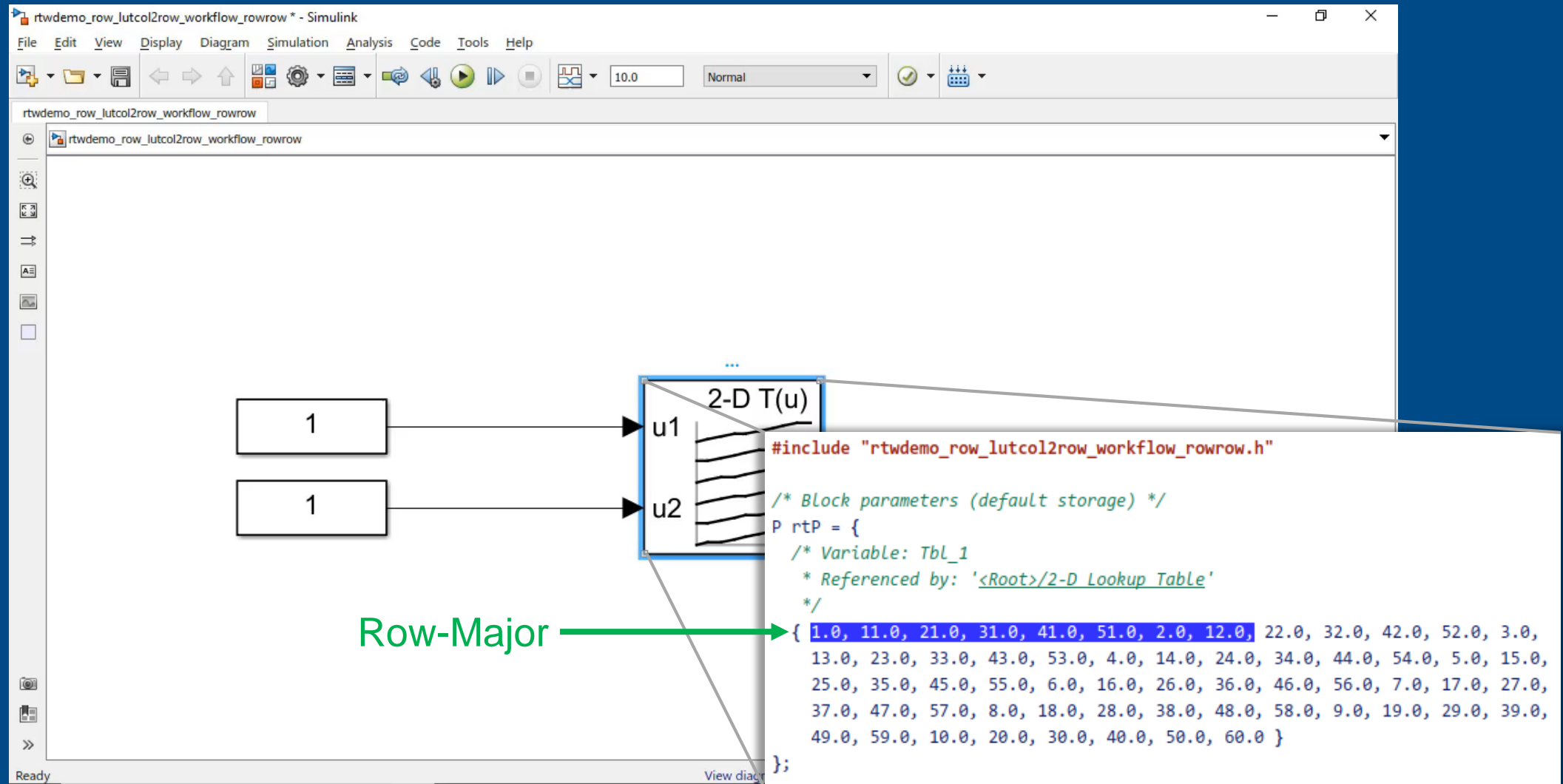
Controlling the Execution of Model Components



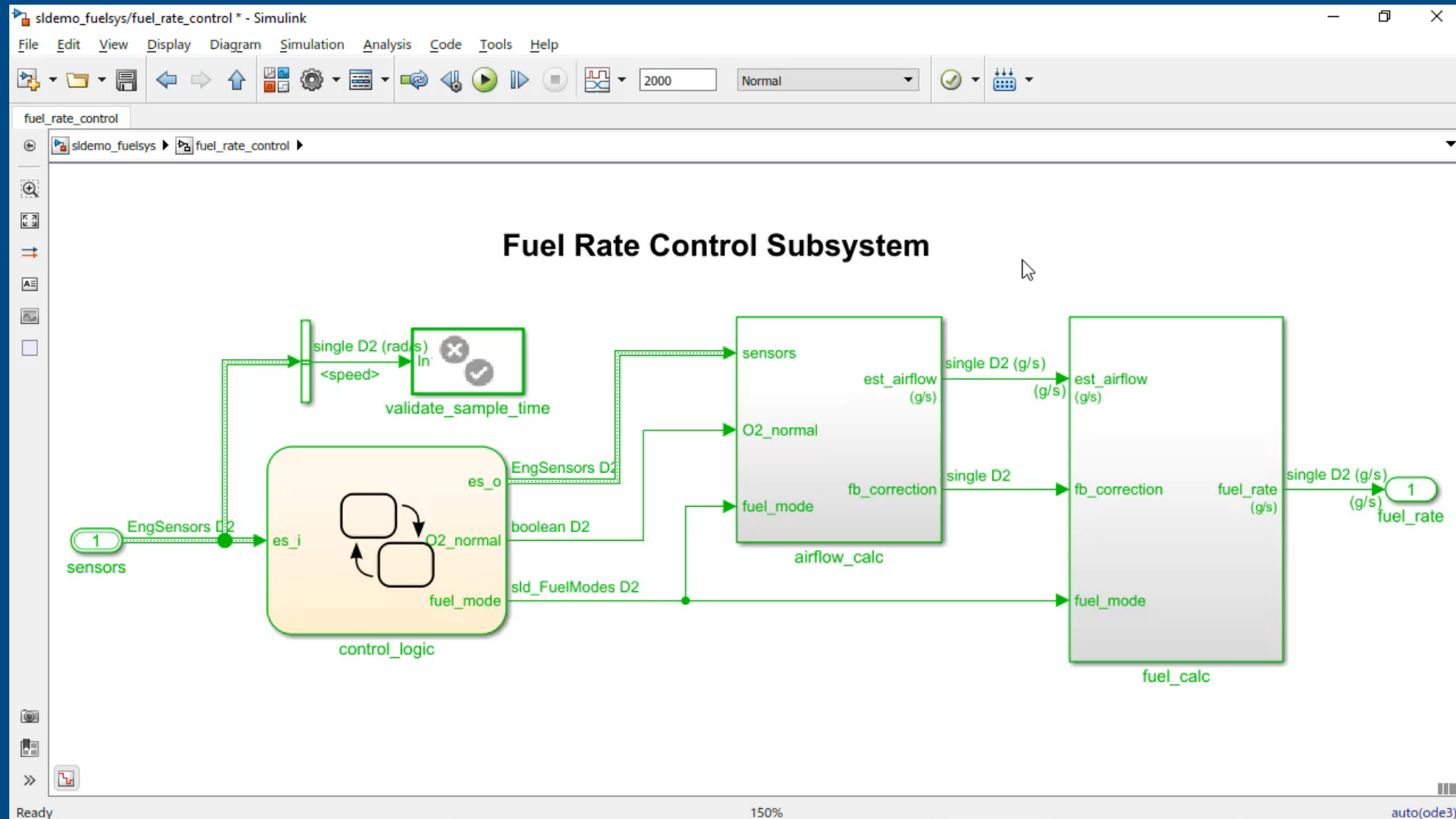
Simplifying Integration with External C/C++ Code



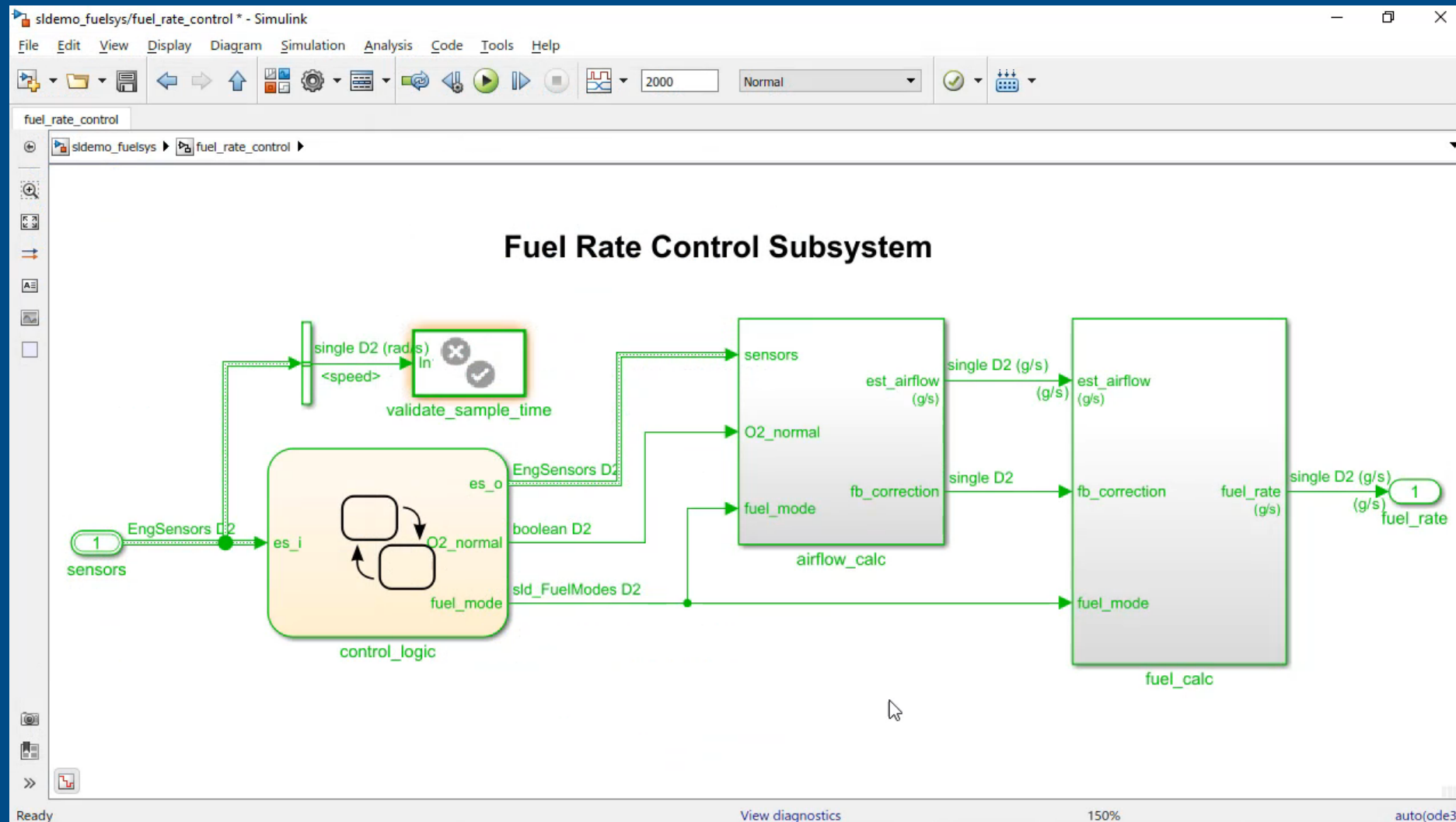
Simplifying Integration with External C/C++ Code



Viewing Generated Code Alongside the Model



Viewing Generated Code Alongside the Model



Sharing Live Scripts



Live Editor - C:\MATLAB\SunriseSunset_final.mlx *

FILE NAVIGATE TEXT CODE SECTION RUN

Find Files Find Compare Go To Find

Text **B I U M**



Code Control Refactor

Run Section Run and Advance Run to End

Run Step Stop

SunriseSunset_final.mlx *

Estimating Sunrise and Sunset

Using the latitude (ϕ), the sun's declination (δ) and the solar time correction (SC) we can calculate sunrise and sunset times.

$$\text{sunrise} = 12 - \frac{\cos^{-1}(-\tan \phi \tan \delta)}{15^\circ} - \frac{SC}{60}$$

$$\text{sunset} = 12 + \frac{\cos^{-1}(-\tan \phi \tan \delta)}{15^\circ}$$

Refer to [this page](#) for background and details on the equations used.

script



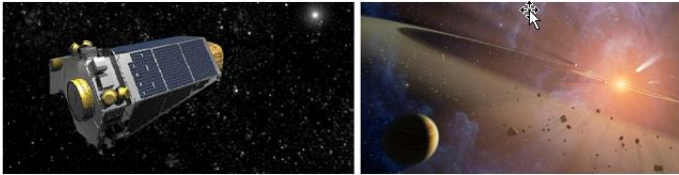
Sharing Live Scripts

AutoSave ExploringExoplanets.docx - Compatibility Mode David Garrison

File Home Insert Design Layout References Mailings Review View Help Tell me what you want to do Share

Clipboard Font Paragraph Styles Editing

Exploring Exoplanets



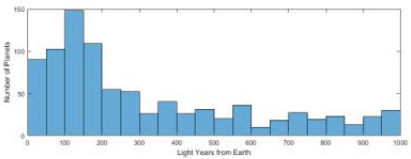
In this example we will explore some data on exoplanets - planets outside our own solar system. The data used here is a subset of data from the [NASA Exoplanet Archive](#). We will start by using the data to answer some questions about the set of exoplanets in the archive. Then we will do some calculations to try to identify planets in the archive that might be capable of supporting life.

```
exoplanets = readtable("exoplanets.xlsx");
exoplanets(1:10,:);
```

How Far Away Are these Planets?

There are 90 exoplanets within 50 light-years of earth and 450 exoplanets within 200 light-years.

```
histogram(3.26*exoplanets.st_distance, 'BinWidth', 50)
xlim([0 1000])
ylabel 'Number of Planets'
xlabel 'Light Years from Earth'
```

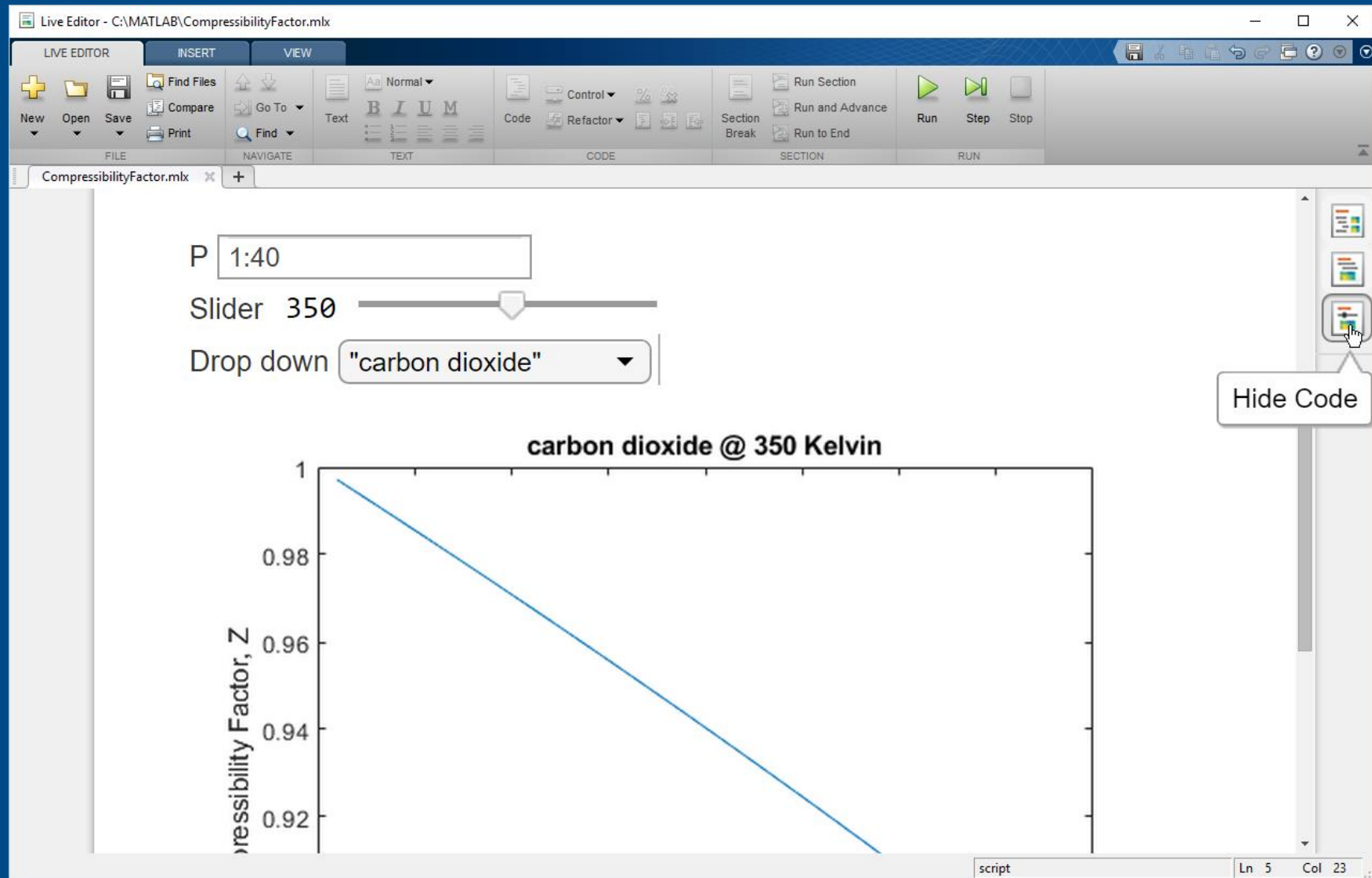


Where is the nearest exoplanet?

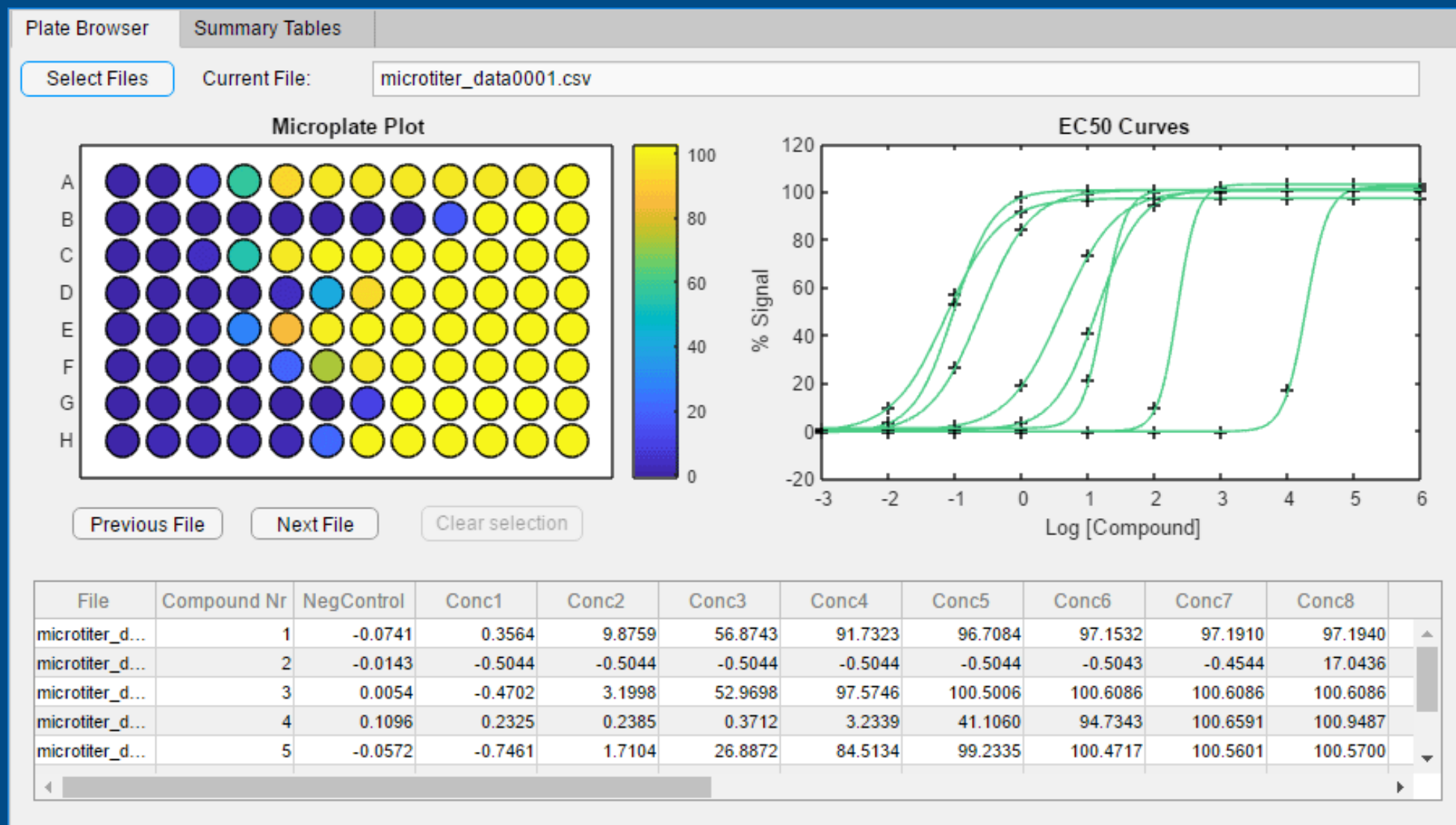
```
idx = find(exoplanets.st_distance == min(exoplanets.st_distance));
name = char(exoplanets{idx, 'st_name'});
```

Page 1 of 7 1468 words

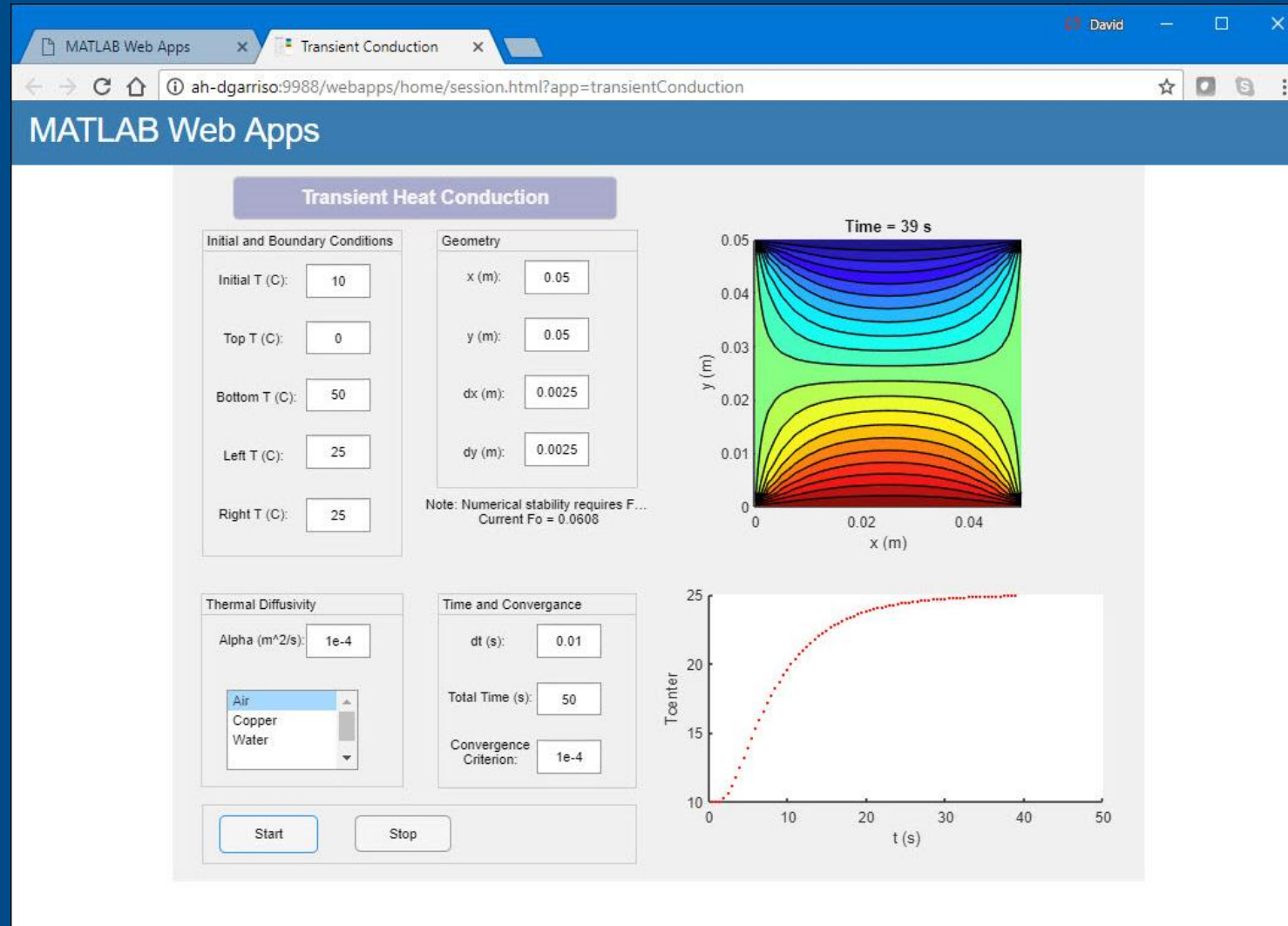
Sharing Live Scripts



Creating Apps



Deploying Web Apps



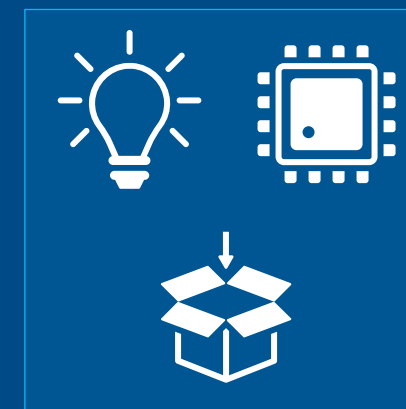
Using MATLAB & Simulink to Build Algorithms in Everything



Inputs



Design



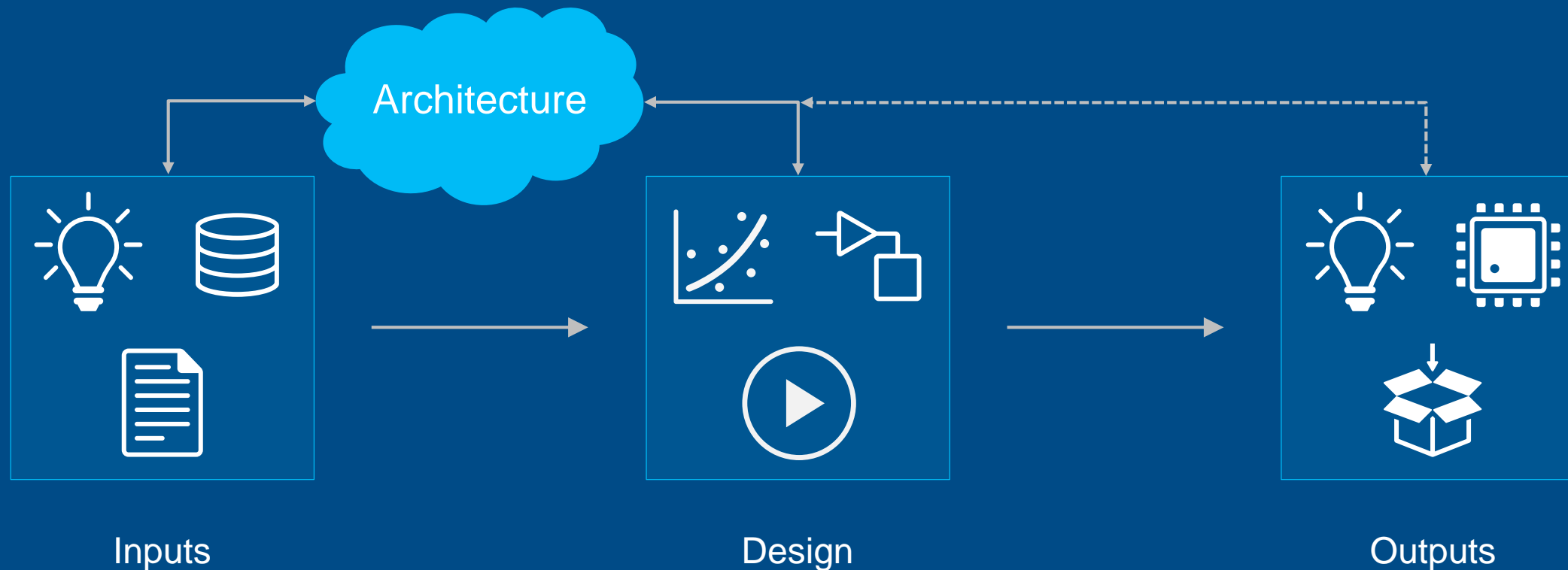
Outputs



MATLAB® & SIMULINK®



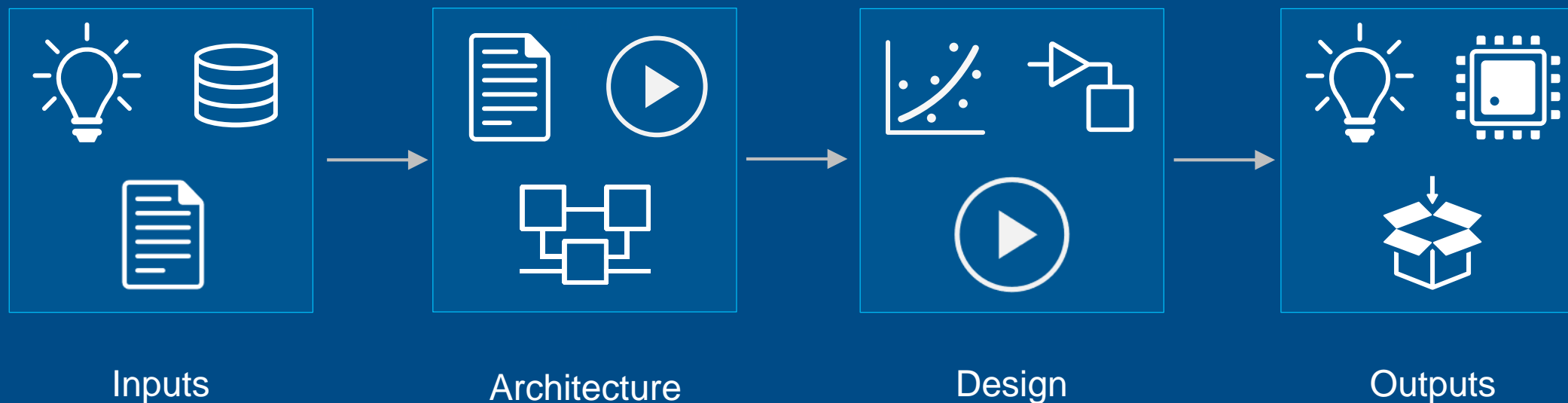
Evaluating Architectures



MATLAB® & SIMULINK®



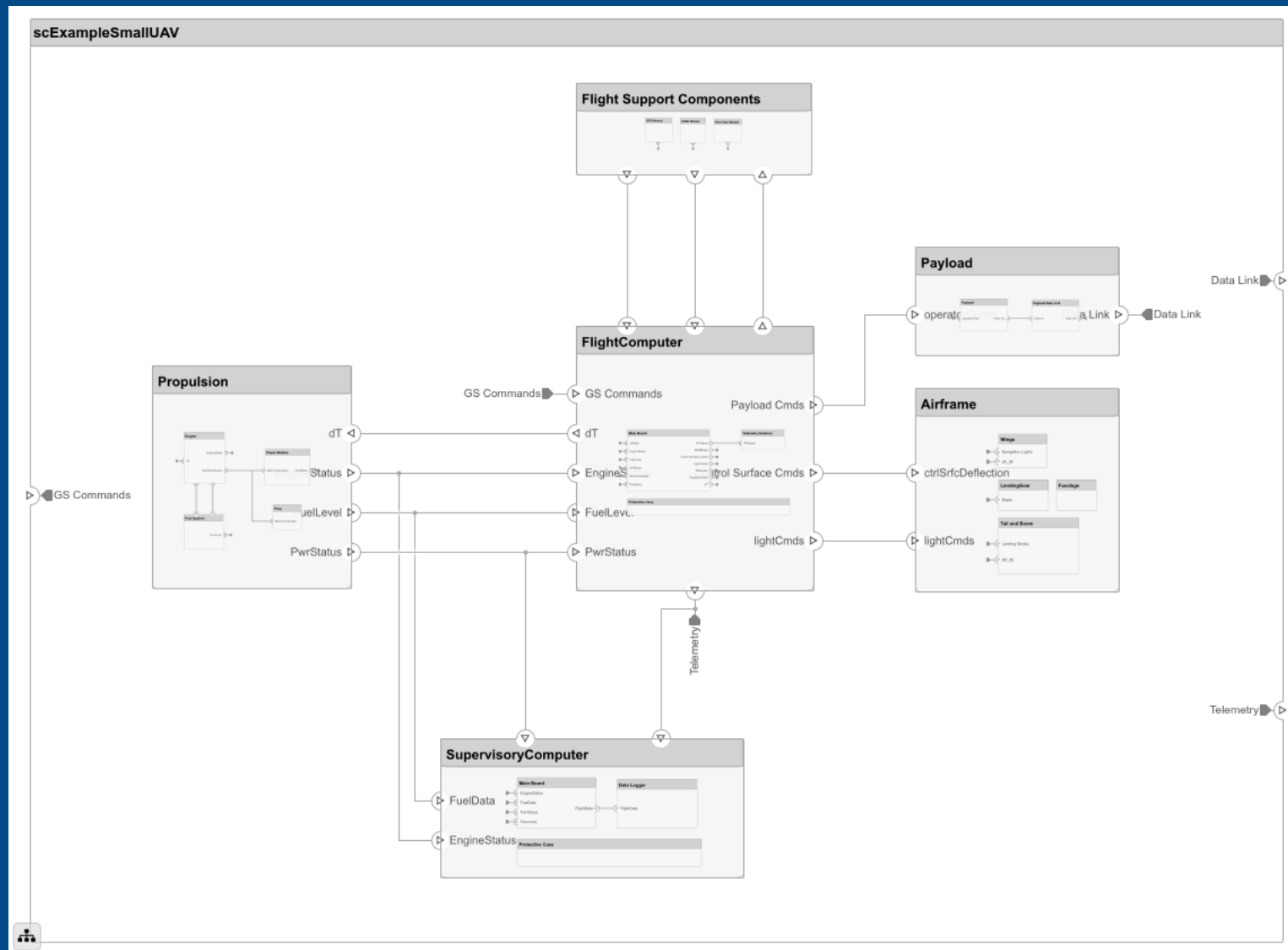
Evaluating Architectures

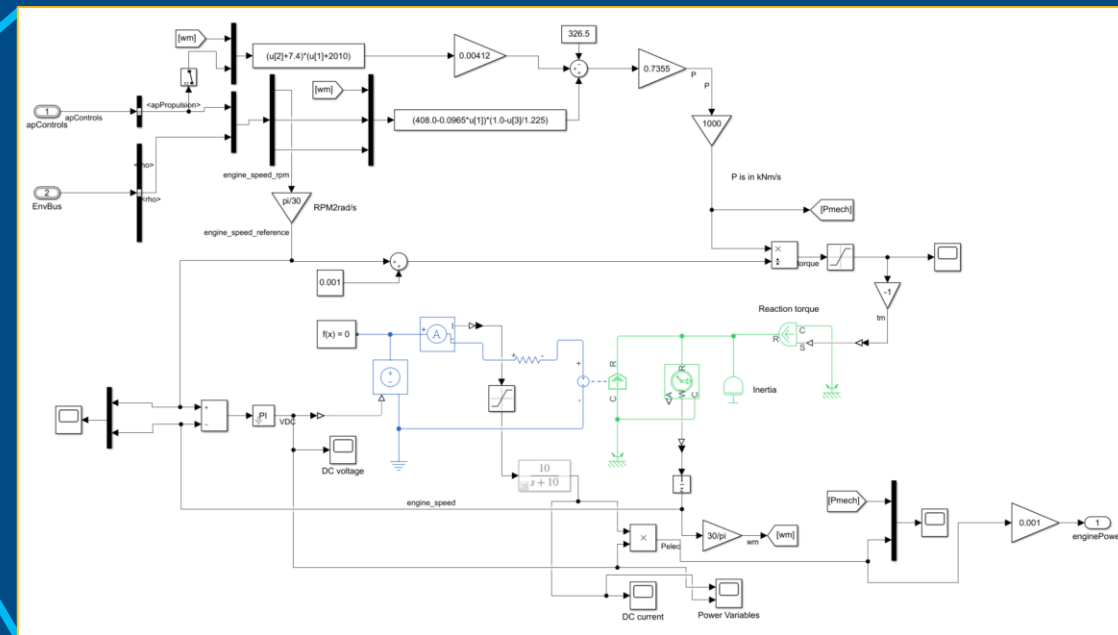


MATLAB® & SIMULINK®



Designing System and Software Architectures



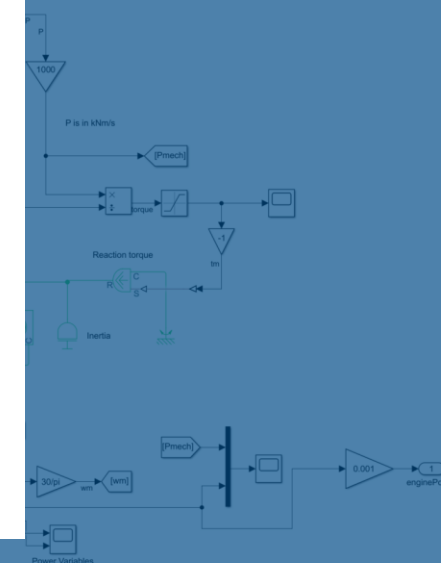


Designing System and Software Architectures



Find out more:
Systems Engineering – von den
Anforderungen über die Architektur
zur Simulation

Adam Whitmill, MathWorks
Sicherheitskritische Anwendungen



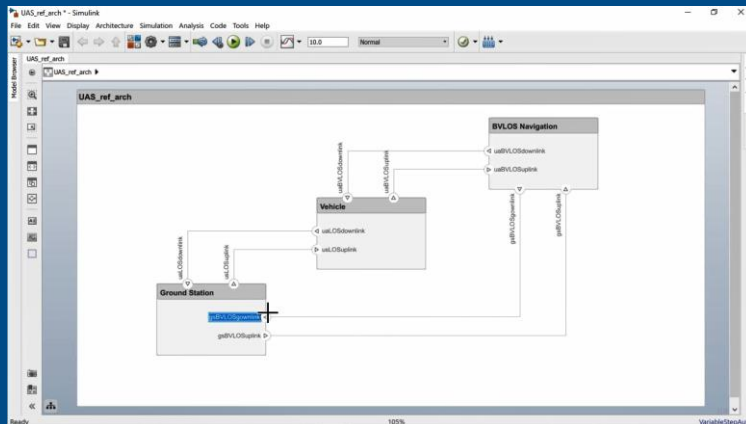
Designing **Beyond** System and Software Architectures



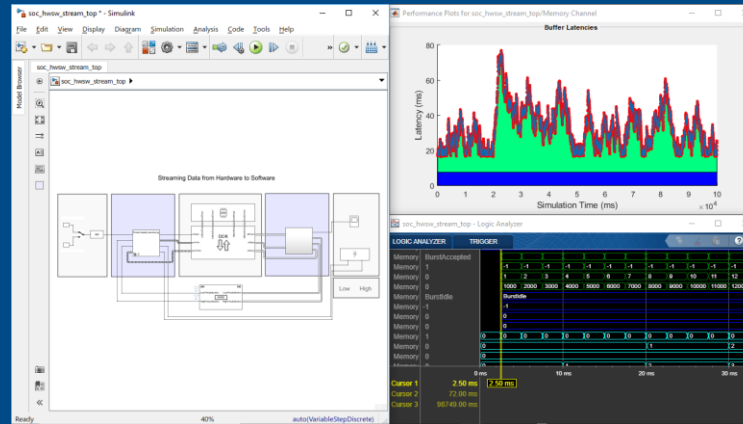
Systems and
Software

SoC Hardware
and Software

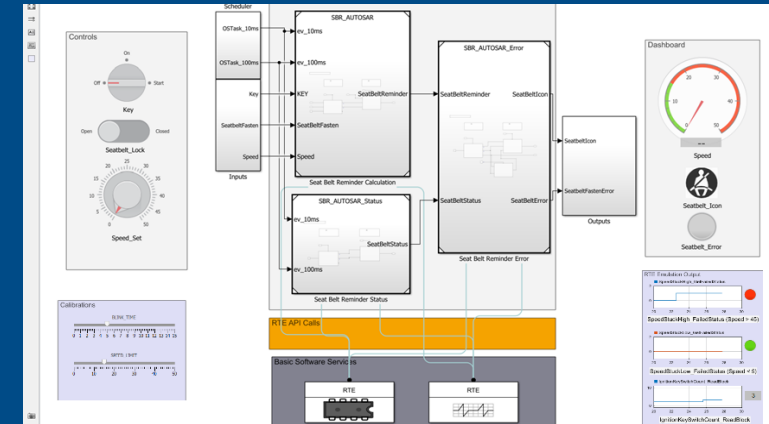
AUTOSAR Software



System Composer

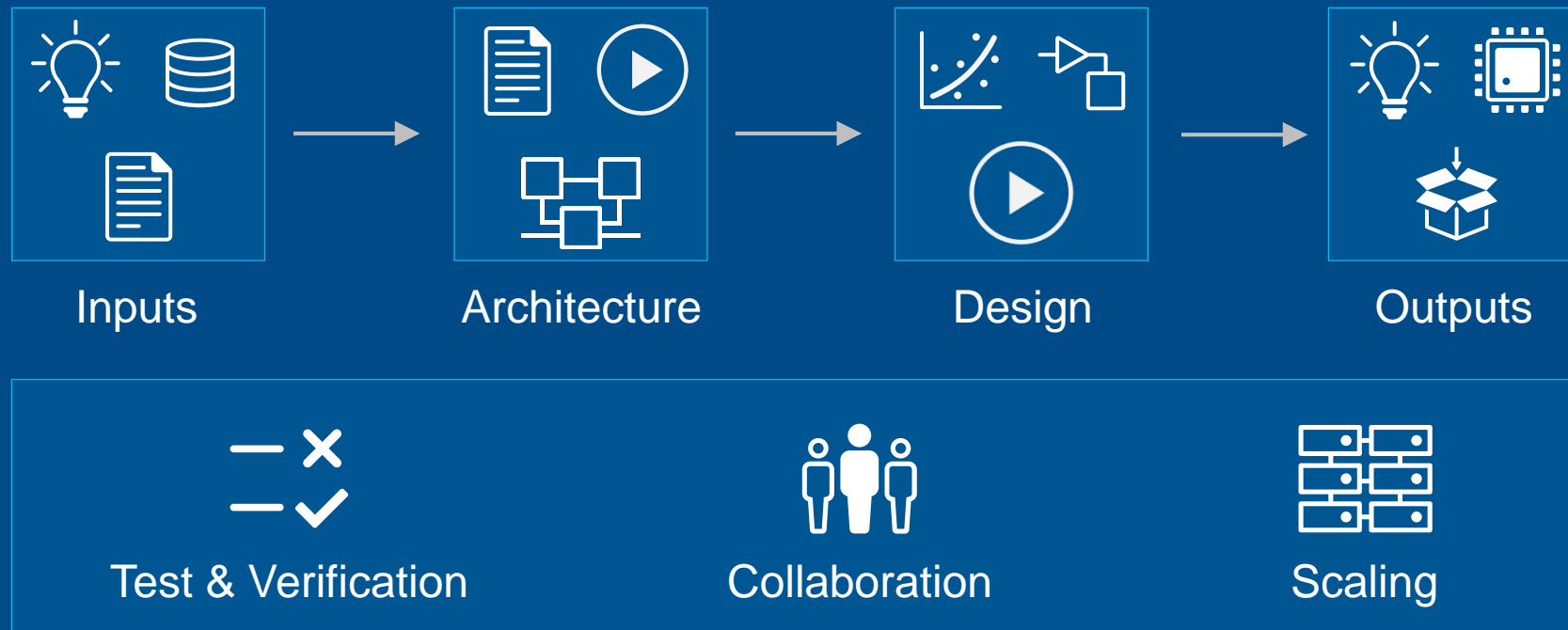


SoC Blockset



AUTOSAR Blockset

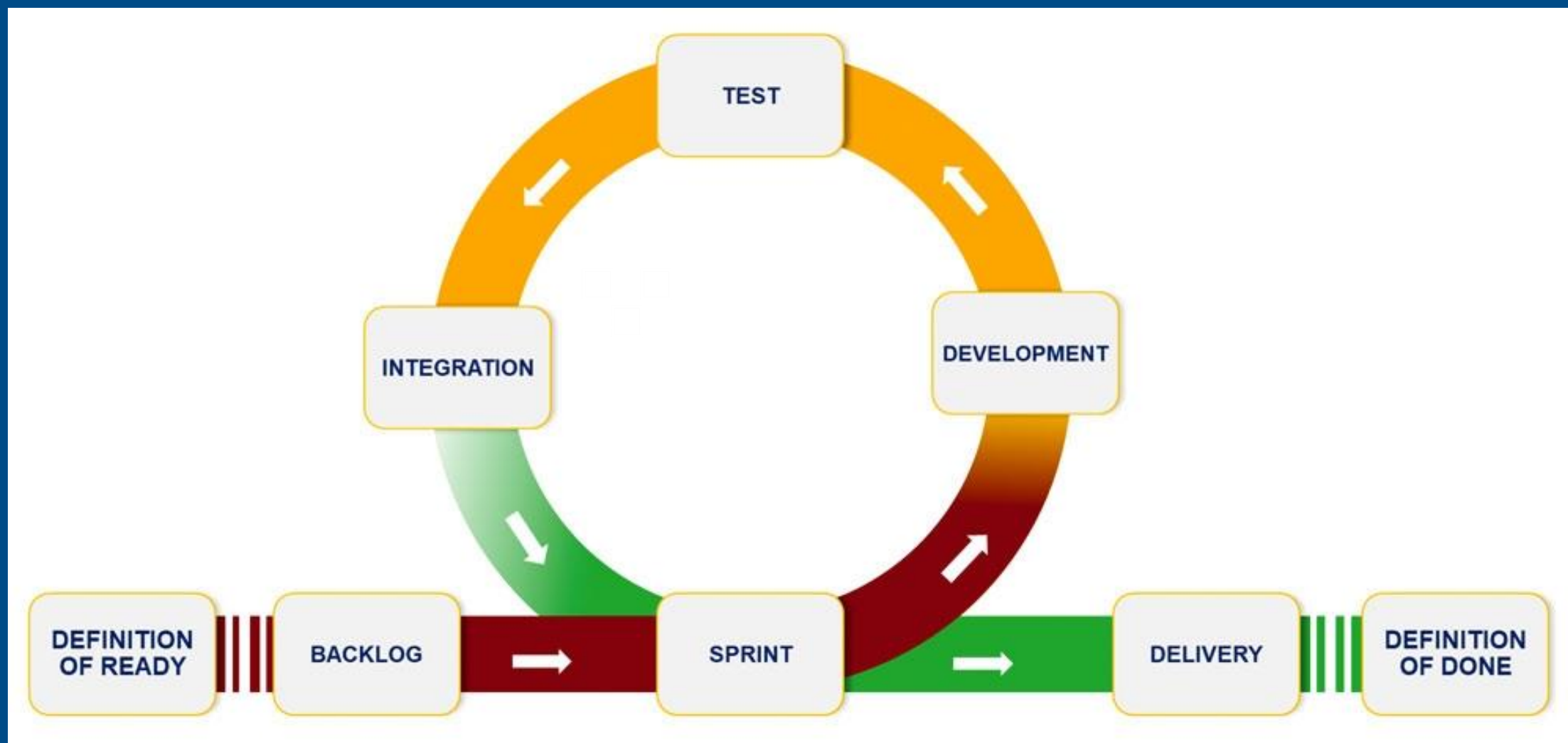
Using MATLAB & Simulink to Build Algorithms in Everything



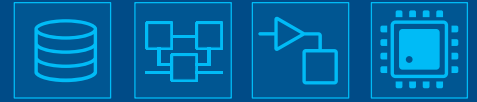
MATLAB® & SIMULINK®



Using MATLAB & Simulink to Build Algorithms in Everything



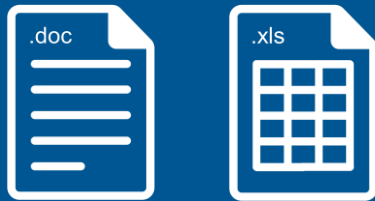
Integrating with Third-party Requirements Tools



↔

Test & Verification

External Requirements



Requirements
Management
Tools

R2019a**ReqIF**

Simulink Requirements

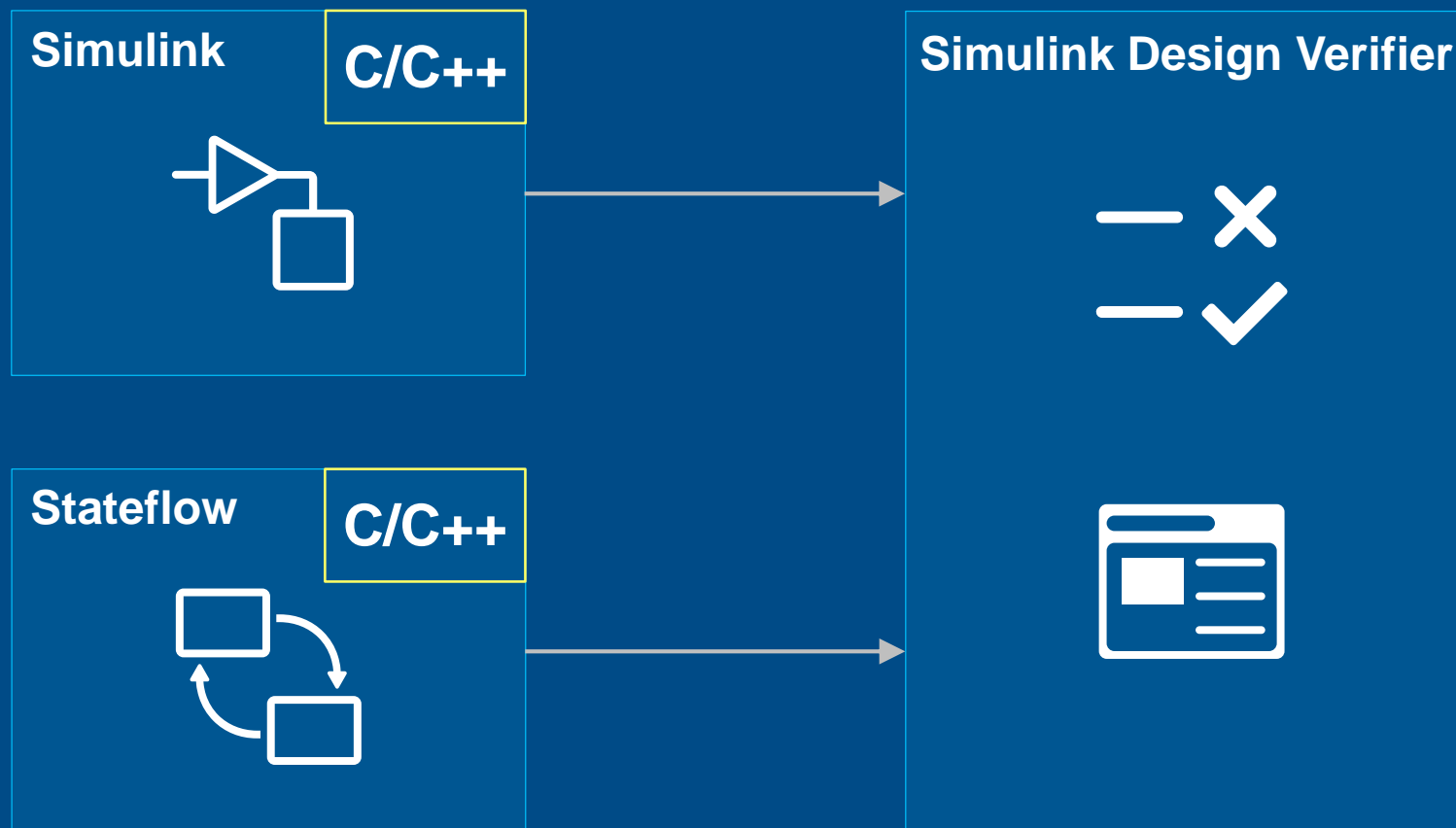
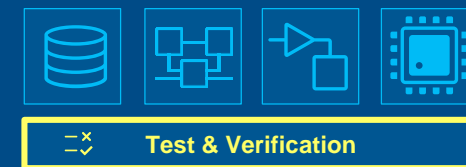
External Requirements



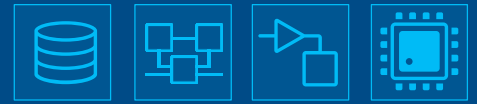
Authored Requirements



Include Custom Code in Test & Verification



Using the MATLAB Unit Test Framework



Test & Verification

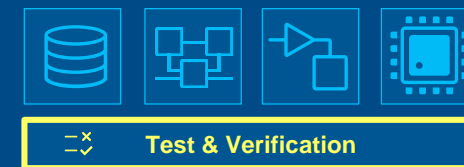
```
>> result.table
```

```
ans =
```

```
2x6 table
```

Name	Passed	Failed	Incomplete	Duration	Details
'test_Predictions/Test_ModelType'	true	false	false	0.12241	[1x1 struct]
'test_Predictions/Test_Prediction'	false	true	true	0.11542	[1x1 struct]

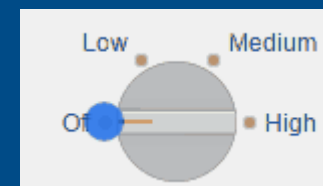
Using the MATLAB App Testing Framework



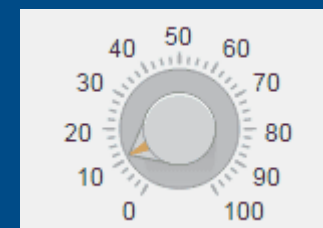
```
testCase.press(myApp.checkbox)
```



```
testCase.choose(myApp.discreteKnob, "Medium")
```



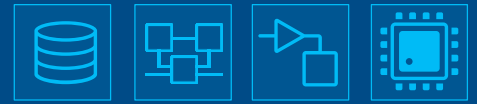
```
testCase.drag(myApp.continuousKnob, 10, 90)
```



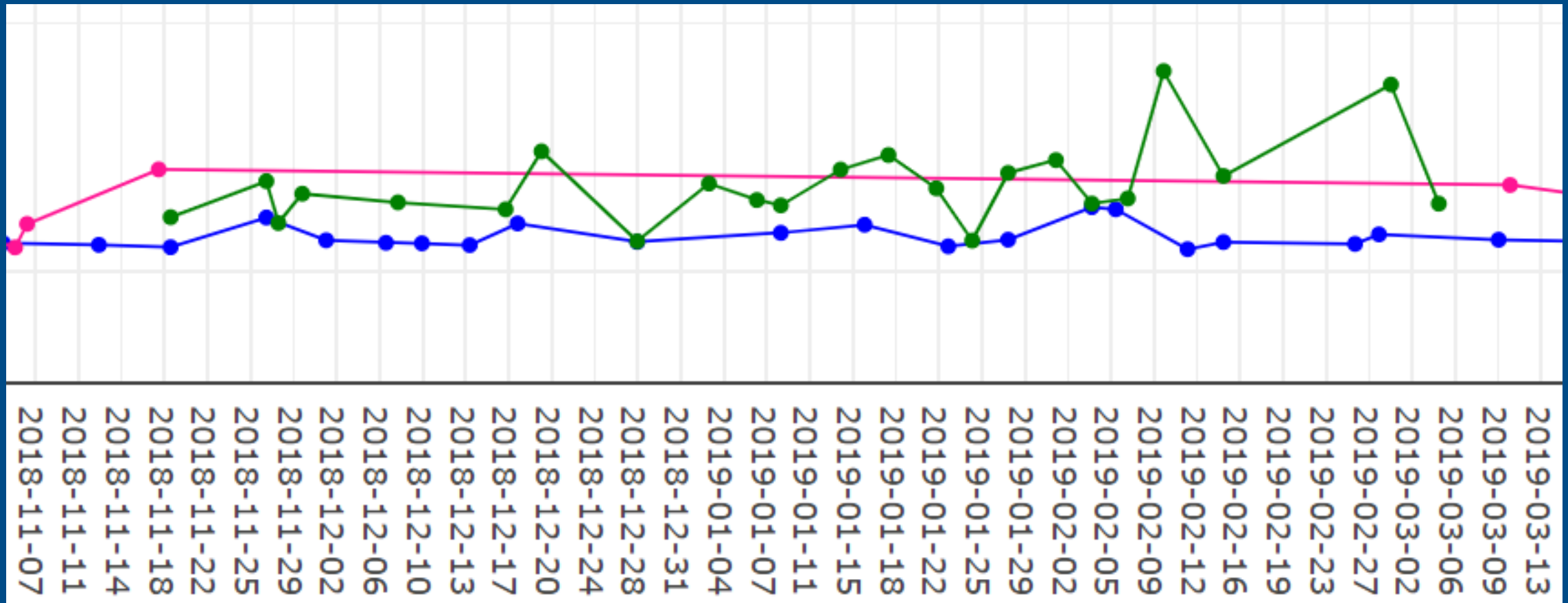
```
testCase.type(myApp.editfield, myTextVar)
```



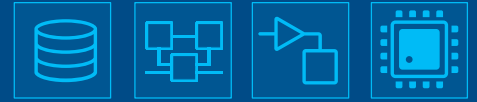
Using the MATLAB Performance Testing Framework



↕ Test & Verification



Using Continuous Integration



Test & Verification

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Plugins Index

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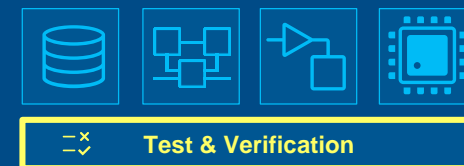
Browse categories

- Platforms
- User interface
- Administration
- Source code management

New Plugins

- QRebel
- MATLAB**
- MISRA Compliance Report
- Zoom
- VectorCAST Execution
- Klocwork Community
- JQuery
- Analysis Model API

Using Continuous Integration



JenkinsBlogDocumentation ▾

← Find plugins

MATLAB^{1.0.0}

Minimum Jenkins requirement: 2.7.3
ID: matlab

Installs: No usage data available
[GitHub →](#)
Last released: 2 days ago

Maintainers
MathWorks

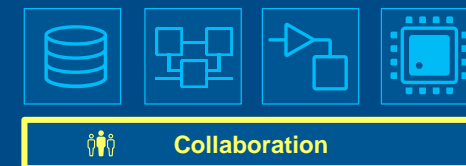
Dependencies
[bouncycastle API v.2.16.0](#) (implied) (what's this?)
[Command Agent Launcher v.1.0](#) (implied) (what's this?)
[JDK Tool v.1.0](#) (implied) (what's this?)
[JAXB v.2.3.0](#) (implied) (what's this?)

The Jenkins plugin for MATLAB® enables you to easily run your MATLAB tests and generate test artifacts in formats such as JUnit, TAP, and Cobertura code coverage reports.

Features

- Support to run MATLAB tests, present in the Jenkins workspace automatically. (This also includes the tests present in .prj files)
- Generate tests artifacts in JUnit, TAP & Cobertura code coverage formats.
- Support to run tests, using custom MATLAB command or custom MATLAB script file.

Using Projects in MATLAB



TOOLS				ENVIRONMENT		SOURCE CONTROL			
Search	Custom Tasks	Run Checks	References	Details	Project Path Startup Shutdown	Git Details	Refresh	Commit	Fetch Push Pull Remote Branches
All Project (226) Modified (344)									
Name	Status	Git	Classification						
+Test	✓	■	Test						
ACI	✓	•							
Dashboard	✓	•							
Documents	✓	•							
Elasticsearch	✓	•							
MachineLearning	✓	■							
MATLAB_Kafka_Producer_Java	✓	•							
mps_stream	✓	■							
SimExecutable	✓	•							
Simulation	✓	•							
DocExample_MultiClassFaultDetectionUsi...	✓	●	Design						
genPumpData.m	✓	●	Design						
javasetup.m	✓	+	Design						
Main_ExampleWorkflow.mlx	✓	●	Design						
MLModels.mat	✓	●	Design						
rawdata.mat	✓	●	Design						
README.md	✓	●							

Using Projects in MATLAB

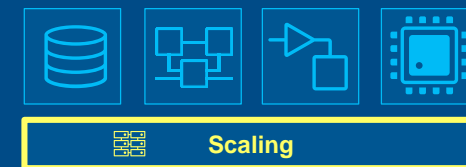


Collaboration

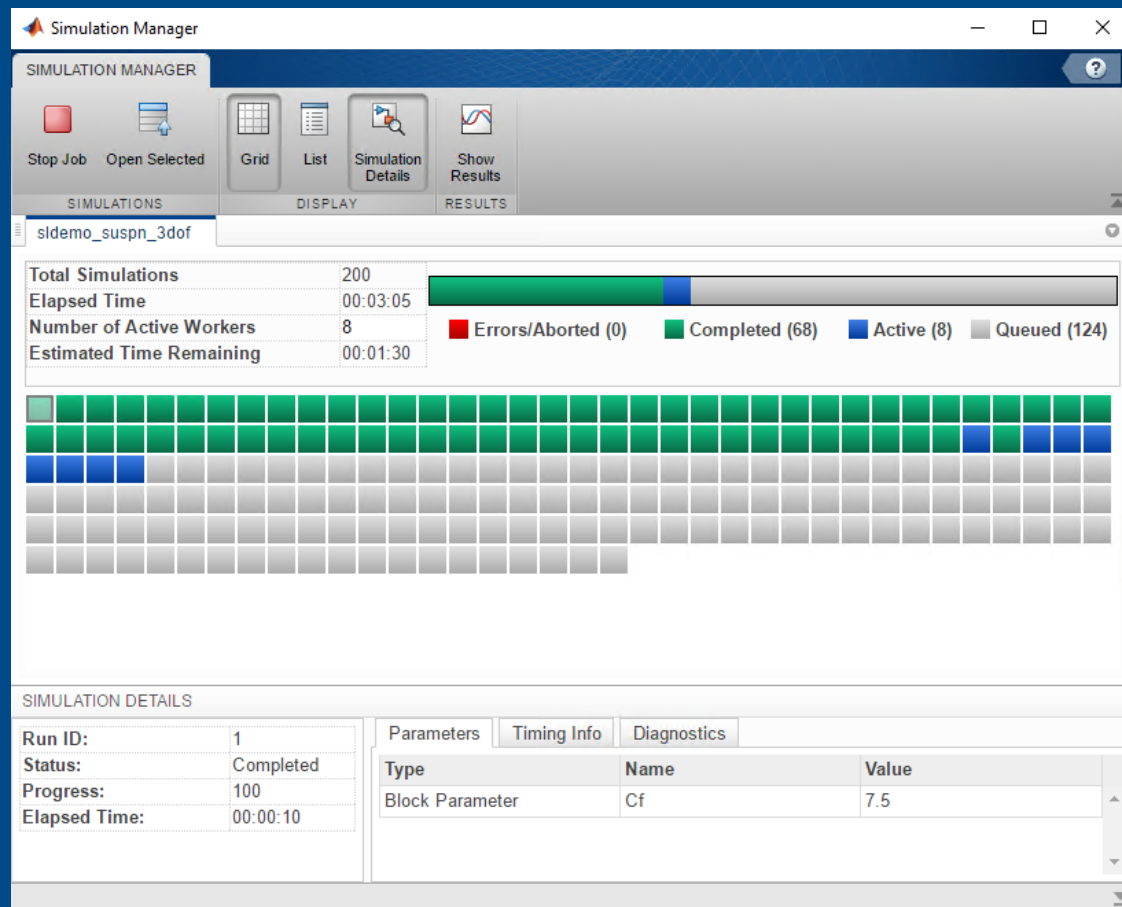
Find out more:
Techniken der Software-Entwicklung mit MATLAB

Elmar Tarajan, MathWorks
Master Class – Software-Entwicklung

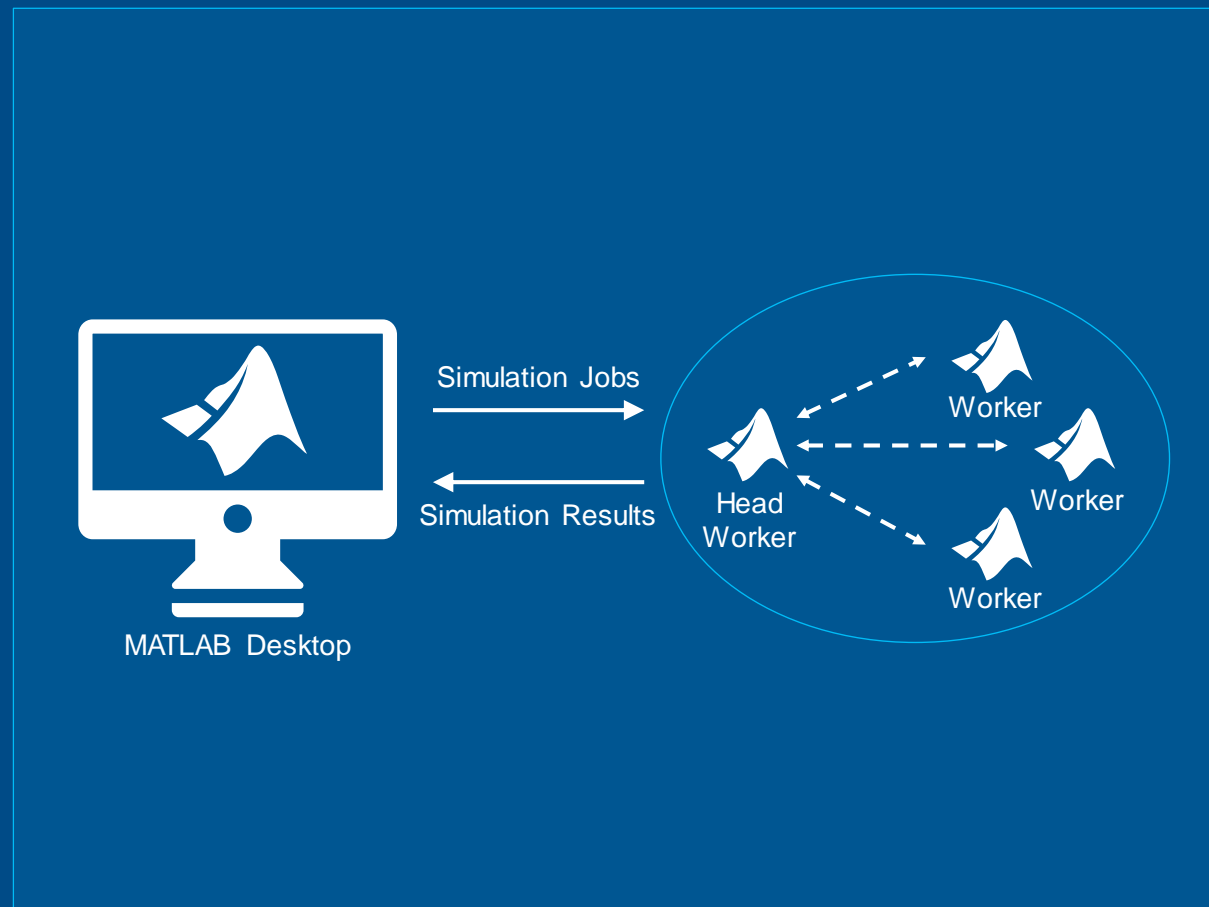
Parallel Simulations in Simulink



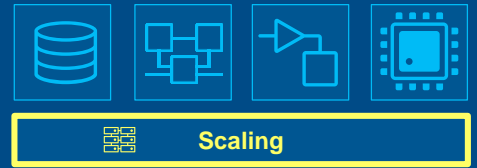
Simulation Manager



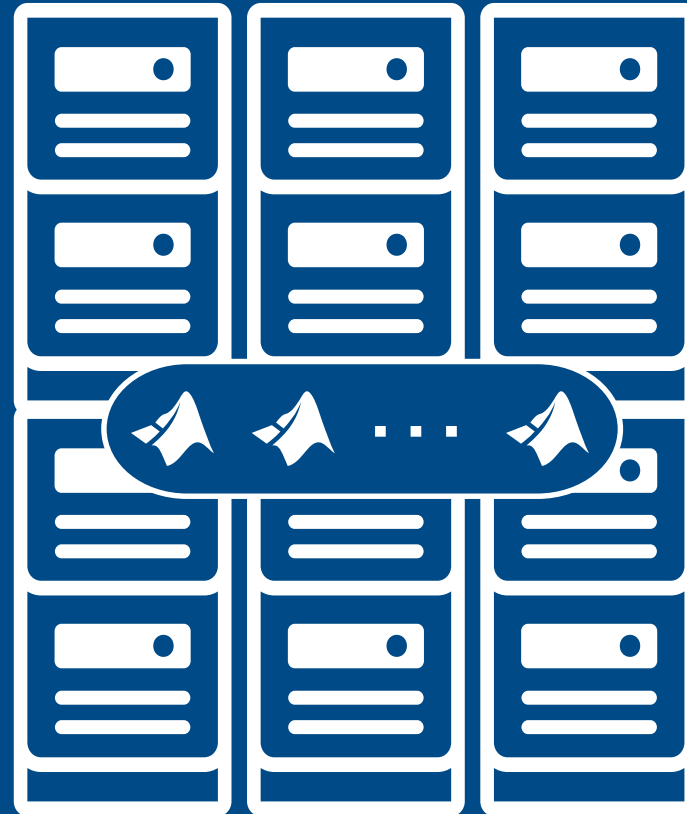
batchsim



Scaling Computations on Clusters and Clouds



MATLAB



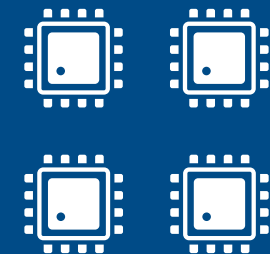
MATLAB Parallel Server



Cloud



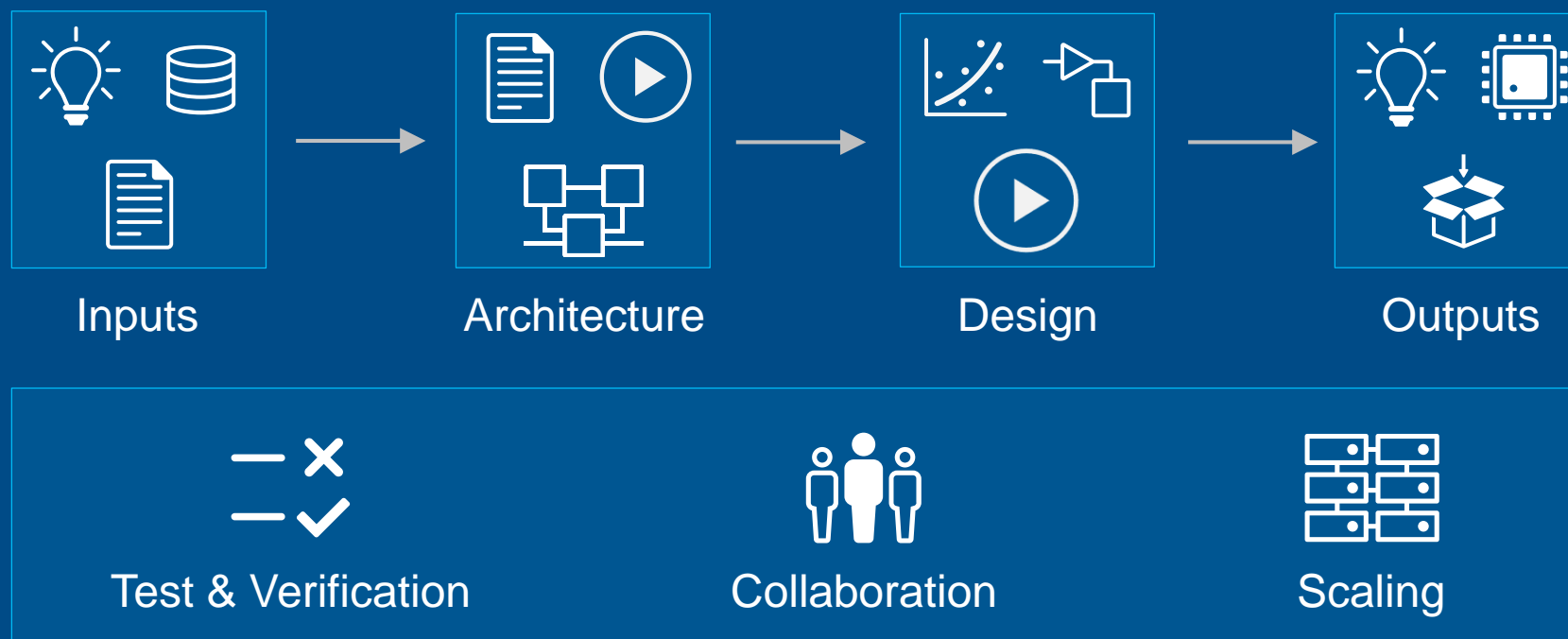
GPU



Multi-core CPU

Parallel Computing Toolbox

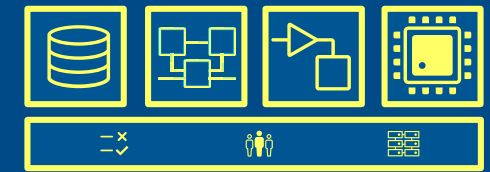
Using MATLAB & Simulink to Build Algorithms in Everything



MATLAB® & SIMULINK®



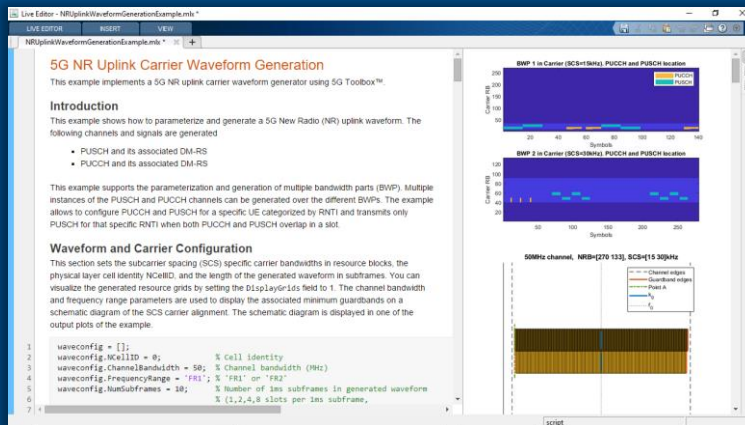
Specialized Tools for Building Algorithms in Everything



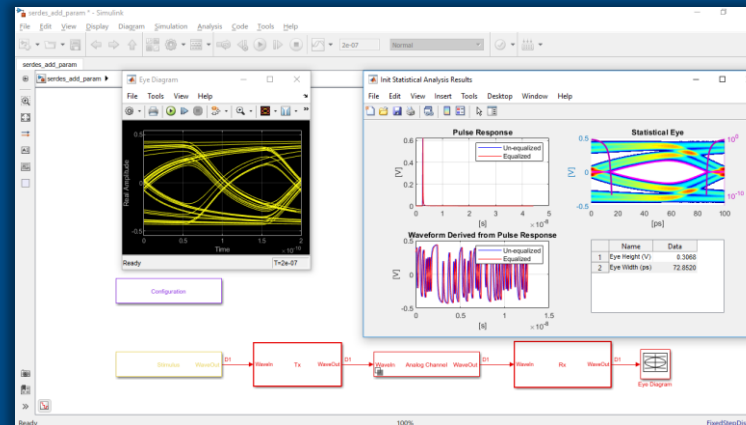
Communications

Physical interconnects

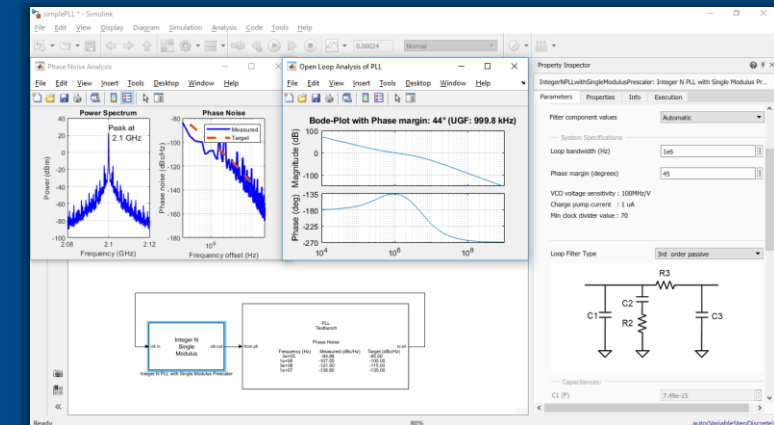
Analog Mixed-Signal



5G Toolbox

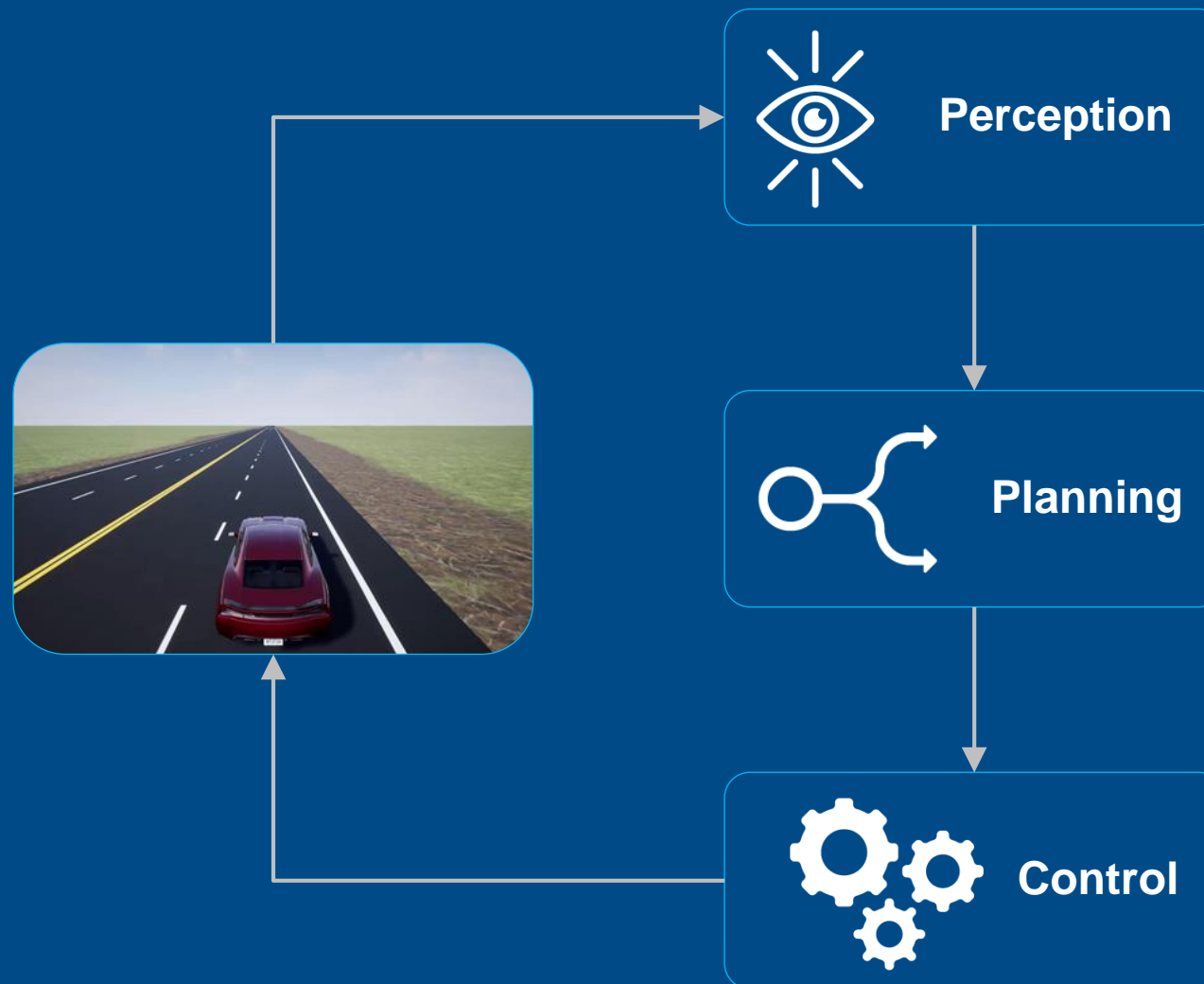


SerDes Toolbox

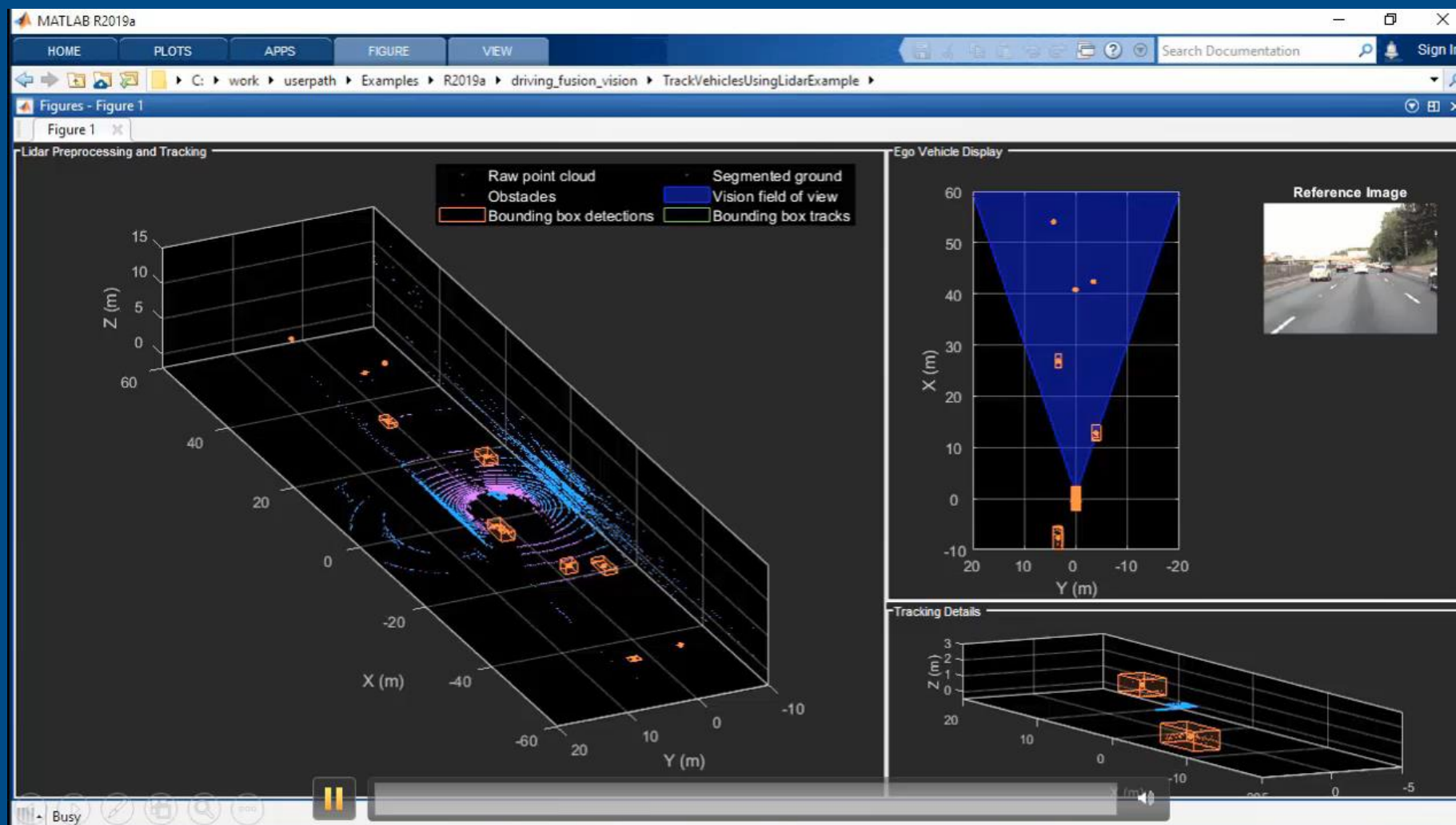
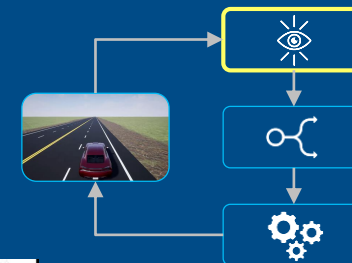


Mixed-Signal Blockset

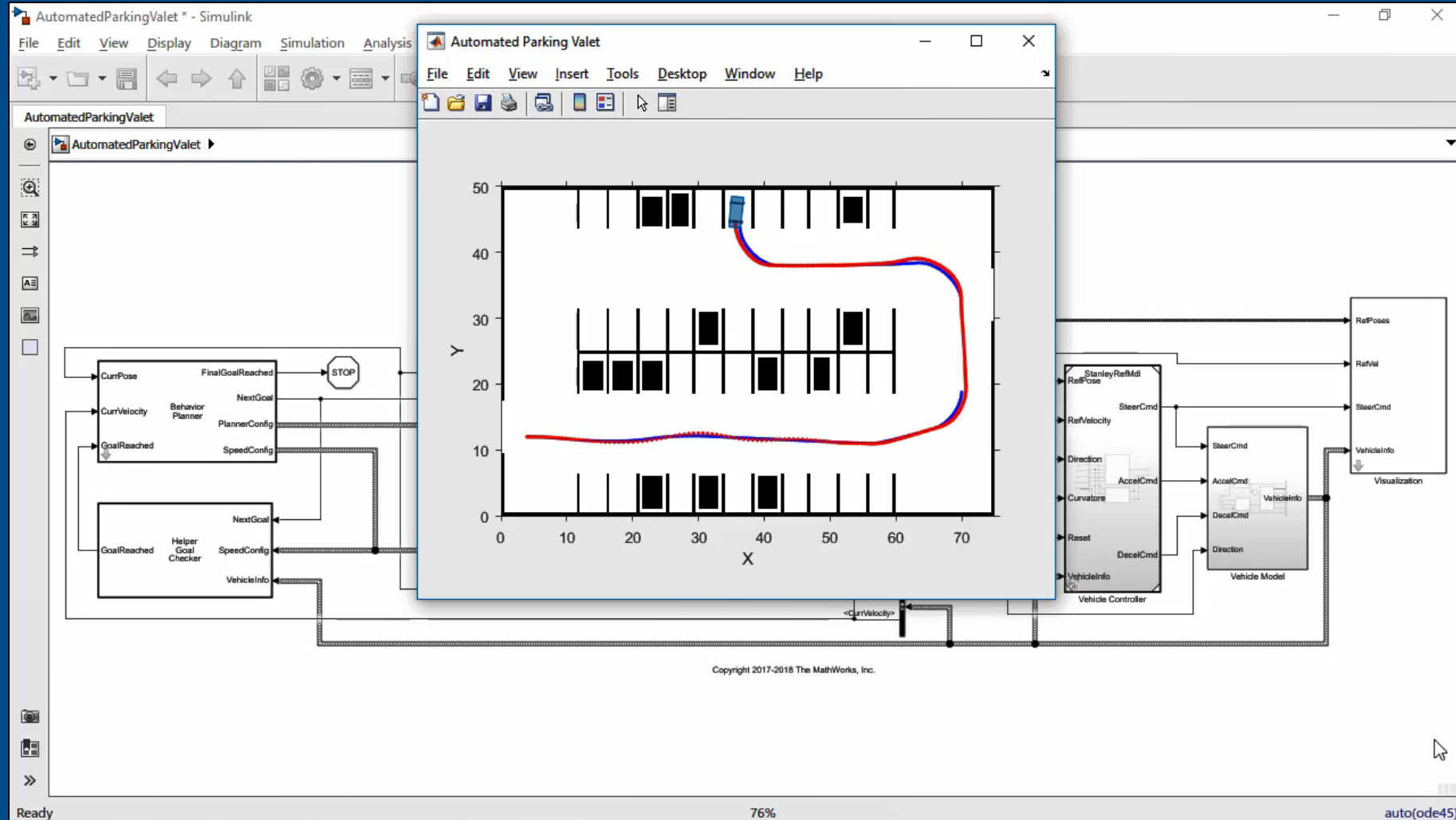
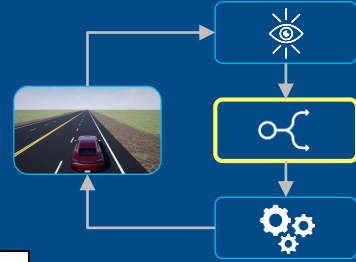
Developing Autonomous Systems



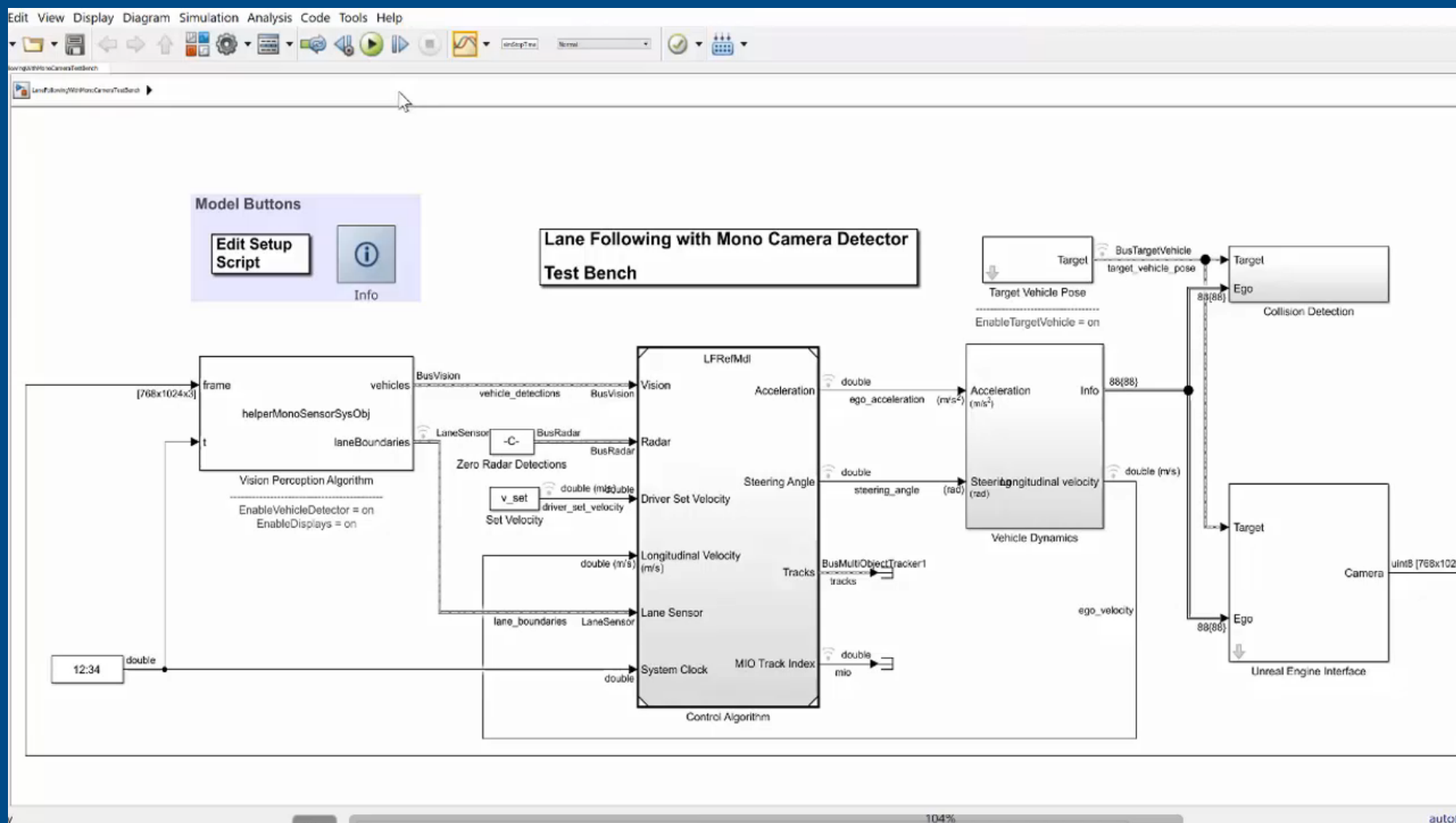
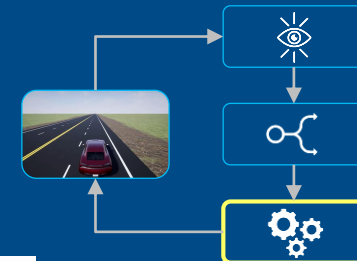
Evaluate Sensor Fusion Architectures



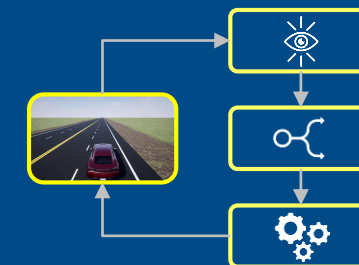
Simulate Path Planning Algorithms



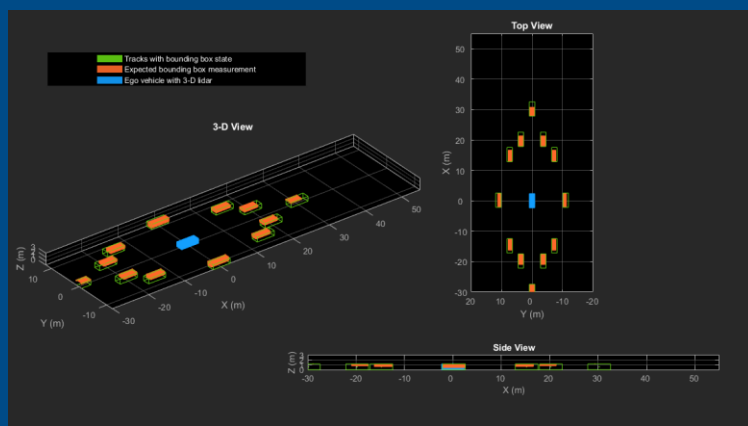
Design Lane-following and Spacing Control Algorithms



Developing Autonomous Systems

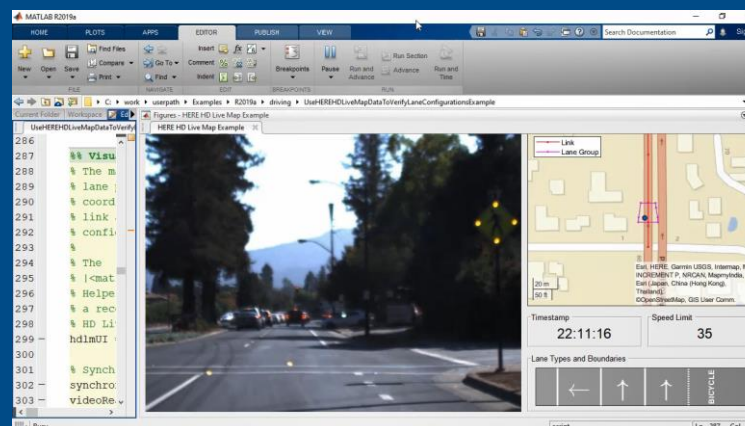


Lidar Processing & Tracking



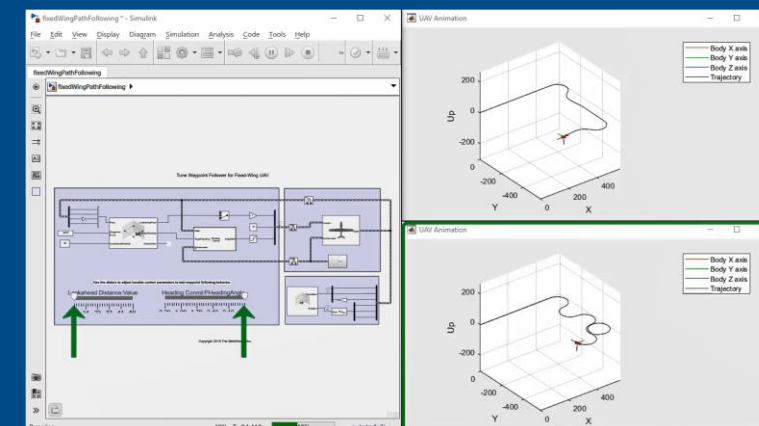
Computer Vision Toolbox

HERE HD Maps & OpenDRIVE Roads



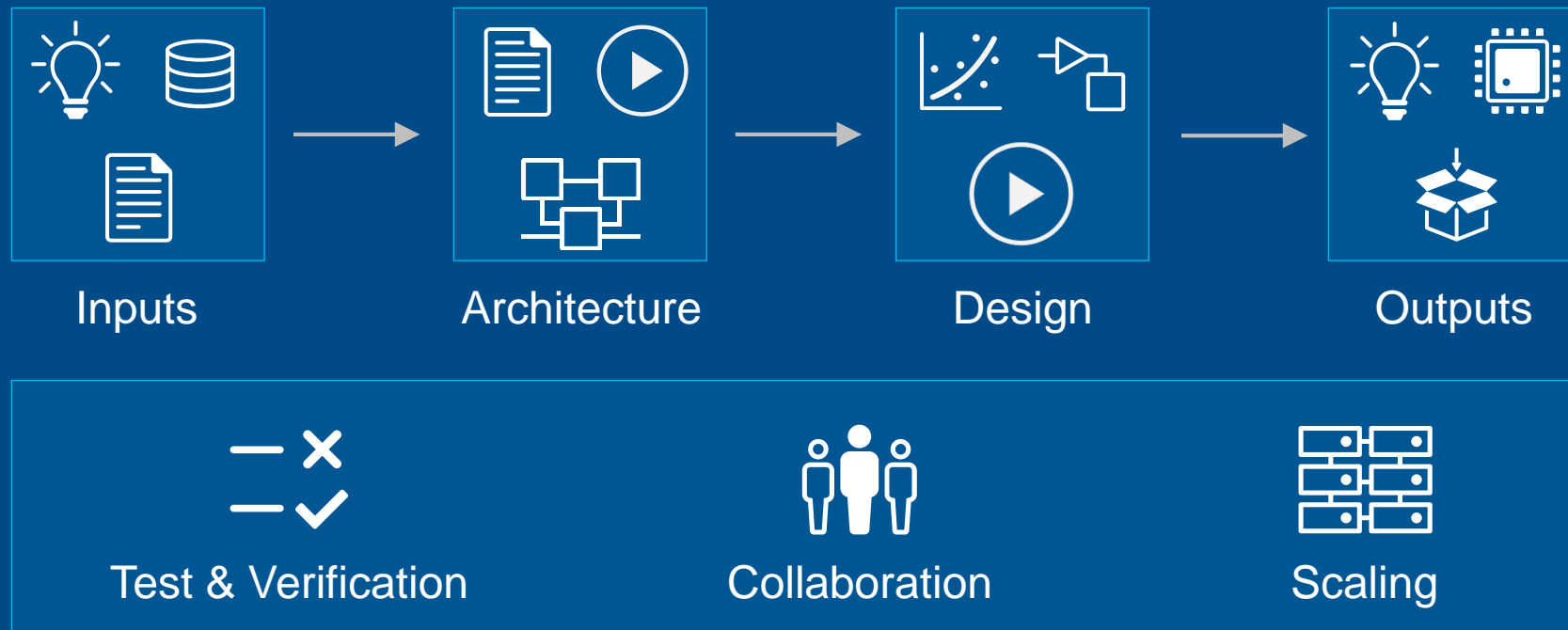
Automated Driving Toolbox

UAV Algorithms



Robotics System Toolbox

Using MATLAB & Simulink to Build Algorithms in Everything



MATLAB® & SIMULINK®



Attend Sessions this Morning

10:40	Kaffeepause und Ausstellung				
	Einführung in MATLAB und Poster-Session zu Hochschulprojekten	Data Analytics in Produktionsumgebungen	Modellierung physikalischer Systeme	Autonomes Fahren	Sicherheitskritische Anwendungen
11:15	Fit für die MATLAB EXPO: Eine kurze Einführung in MATLAB (45 Minuten) <i>Sebastian Bomberg, MathWorks</i>	MLaaS (Machine Learning as a Service) mit MATLAB Production Server <i>Muhammad Faizan Aslam, Infineon Technologies AG</i>	Entwicklung von dezentralen elektrischen Energiesystemen für Verkehrsflugzeuge <i>Robert Doering, TU Hamburg</i>	Roborace @ TUM – Entwicklung autonomer Fahrfunktionen für die Rennstrecke <i>Alexander Wischnewski, TU München</i>	Systems Engineering – von den Anforderungen über die Architektur zur Simulation <i>Adam Whitmill, MathWorks</i>
11:45	Kurzvorträge zu den Beiträgen der Posterausstellung (Start 12:00)	Neural Automation – Optimal Control durch Maschinelles Lernen <i>Dr. Fabian Bause, Beckhoff Automation GmbH & Co. KG</i>	Optimieren von Robotersystemen mit Simscape <i>Eva Pelster, MathWorks</i>	Entwurf und Simulation von Systemen im Bereich des automatisierten Fahrens mit MATLAB und Simulink <i>Shashank Sharma, MathWorks</i>	Prozess zur Generierung einer sicherheitsrelevanten PLC-Applikation im Bahnbereich <i>Angelika Döbrössy, Knorr Bremse</i>
12:15		Bildanalyse zur Unterstützung der Carbonfaser Produktion <i>Bojan Jokanovic, SGL Carbon GmbH</i>	Kontaktkraftsimulation bei komplexen Oberflächenformen mit Simscape Multibody <i>Sam Nezhat, SANEON GmbH</i>	<u>Systematische Generierung von Szenarien für die Absicherung von autonomen Fahrfunktionen</u> <i>Demin Nalic, Technische Universität Graz</i>	Entwicklung von medizinischen Algorithmen für die Kardiologie gestern und heute <i>Dr. Antoun Khawaja, Khawaja MedTech</i>
12:45	Mittagspause und Ausstellung				
	Women in Tech Forum: Mittagessen und Networking <i>Eva Pelster, MathWorks</i>				

Attend Sessions this Afternoon (Part 1)

12:45	Mittagspause und Ausstellung				
	Women in Tech Forum: Mittagessen und Networking <i>Eva Pelster, MathWorks</i>				
	MATLAB an Universitäten und Hochschulen	Anwendungen in der Luftfahrt	Batterie-Modellierung	Verifikation und Validierung	Industrie 4.0
14:00	How the Brain Shapes Its Own Input – Using Stateflow to Study Behavior <i>Dr. Shubo Chakrabarti, Universität Tübingen</i>	Modellbasierte Entwicklung von Flugführungsalgorithmen für unbemannte Hubschrauber <i>Roland Leitner, IABG mbH</i>	Stochastische Filter zur Ladezustandsbestimmung von Lithium-Ionen-Batterien <i>Prof. Simon Schwunk, Rheinische Fachhochschule Köln</i>	Anforderungsbasierte Verifikation einfach gemacht mit modellbasierter Entwicklung <i>Dr. Jacob Palczynski, MathWorks</i>	Framework für verteilte Co-Simulationen – Ein Ansatz für Simulationen cross-industrieller Netzwerke <i>Henning Wagner, ThyssenKrupp Transrapid GmbH</i>
14:30	50 Jahre Mondlandung – Lehrprojekte zur Modellierung der Mondlandung mit Simulink <i>Prof. Frank Slomka, Universität Ulm</i>	FitlabGui – Datenanalyse, Systemidentifizierung und Flugeigenschaftsbewertung <i>Susanne Seher-Weiß, DLR e.V.</i>	Modular BMS Development for Use in Rapid Prototyping of Automotive Electrical and Electronic Systems <i>Keane Fernandes, csi entwicklungstechnik</i>	Modellbasierte Evaluierung von Anforderungen in Kombination mit Polarion <i>Vitus Meidinger, TU München</i>	Industrie 4.0 und digitale Zwillinge <i>Dr. Rainer Mümmeler, MathWorks</i>
15:00	Einsatz von MATLAB Grader zur Ergänzung der akademischen Lehre <i>Dr. Jörn Kretschmer, HS Furtwangen</i>	Software zur Instandsetzungsplanung von Triebwerksflotten <i>Niklas Theilig, Lufthansa Technik AG</i>	Schnellladung ohne Alterung – wie virtuelle Li-Ionen-Batterien das Dilemma lösen können <i>Jan Richter, Batemo GmbH</i>	Validierung einer MATLAB-Toolkette – Notwendiges Übel oder Allheilmittel? <i>Reinhard Jeschull, Validas</i>	Plattformübergreifende MATLAB/Simulink-Umgebung zur KUKA Roboter Programmierung <i>Prof. Rolf Biesenbach, Hochschule Bochum</i>
15:30	Kaffeepause und Ausstellung				

Attend Sessions this Afternoon (Part 2)

15:30	Kaffeepause und Ausstellung				
	Master Class - Akademische Lehre, Forschung und Kooperation	Master Class - Software-Entwicklung	Wireless Communications	Master Class - Deep Learning	Analyse von 3D-Signalen
16:00	Preparing Future Engineers and Scientists for the Challenges of Digital Transformation (in English) <i>Jim Tung, MathWorks</i>	Techniken der Software-Entwicklung mit MATLAB <i>Elmar Tarajan, MathWorks</i>	Analyse der Mehrwege-Kanaleigenschaften mit Hilfe der WLAN Paketpräambel <i>Alper Akbilek, perisens GmbH</i>	Deep Learning leicht gemacht <i>Dr. Yvonne Blum, MathWorks</i>	PIVlab – Visualisierung und Evaluation von Strömungen für Forschung, Industrie und Lehre <i>Dr. William Thielicke, OPTOLUTION Messtechnik GmbH</i>
16:30			Technische Grundlagen des neuen 5G-Funkstandards <i>Marco Roggero, MathWorks</i>		3D Indoor Audio Localization of Moving Objects <i>René Erler, TU Chemnitz</i>
17:00	Get Together				

Read the Release Notes

R2019a at a Glance

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R2019a

Release Highlights



Deep Learning

Develop controllers and decision making systems using reinforcement learning, train deep learning models on NVIDIA DGX and cloud platforms, and apply deep learning to 3-D data.

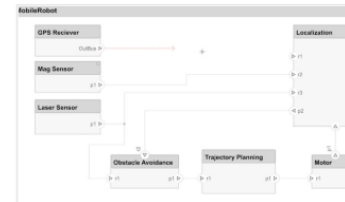
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Automotive

Design and simulate AUTOSAR software, interface with HERE HD maps, and generate energy balance reports.

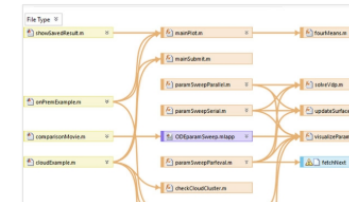
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Systems Engineering

Design and analyze system and software architectures with System Composer.

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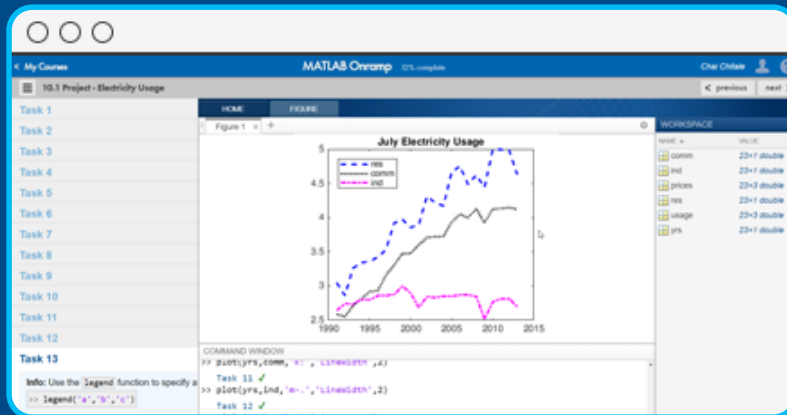


Projects

Use projects in MATLAB and Simulink to organize, manage, and share your work.

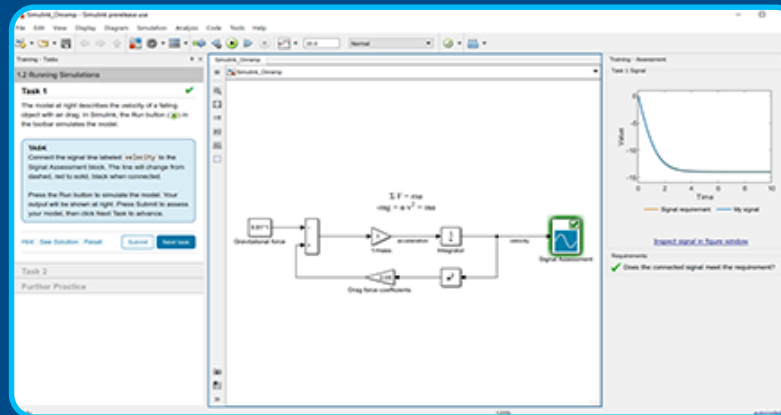
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Get Started



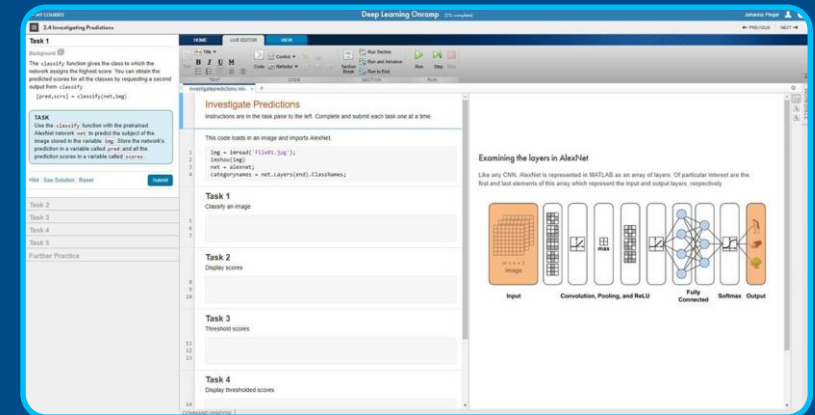
MATLAB Onramp

Quickly learn the essentials of MATLAB.



Simulink Onramp

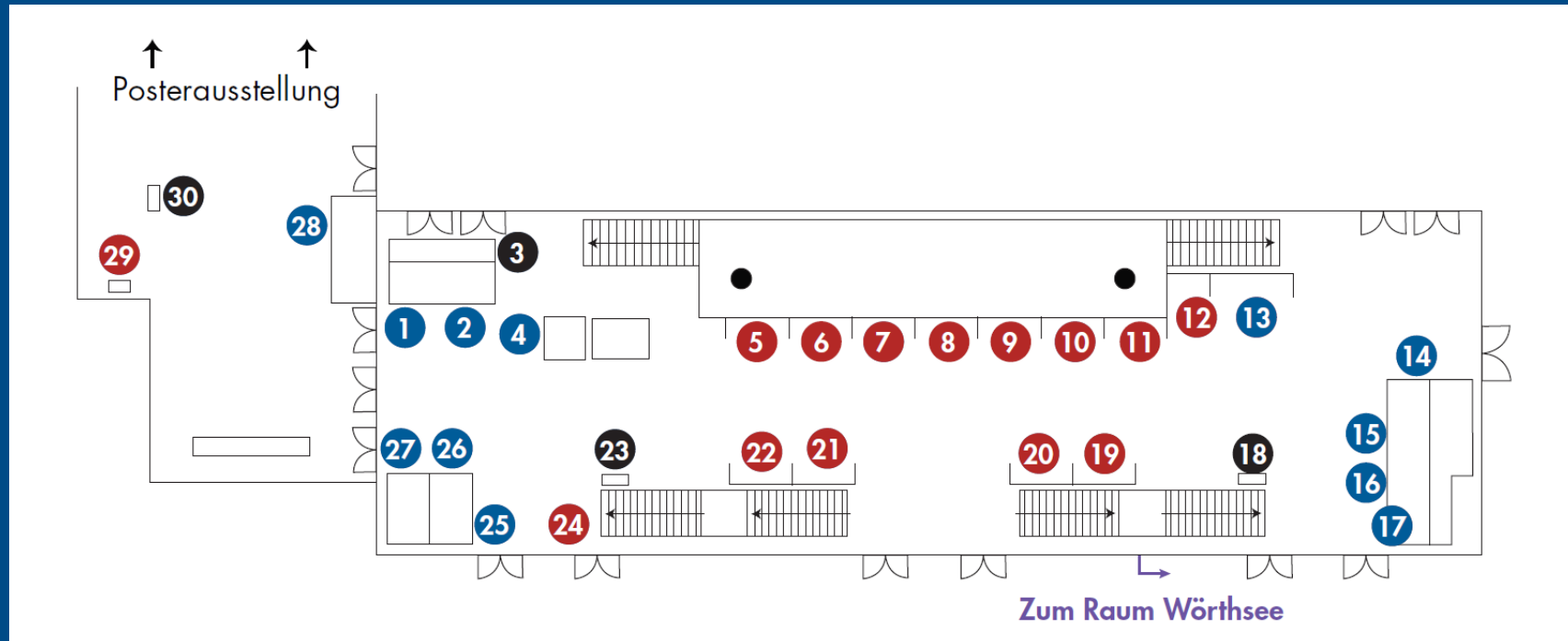
Learn to create, edit, and troubleshoot Simulink models.



Deep Learning Onramp

Learn to use deep learning techniques in MATLAB for image recognition.

Meet the Experts in the Exhibition Area



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