MATLAB EXPO 2016

Rückwirkungsfreiheit zwischen Embedded SW-Komponenten – Polyspace hilft!

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Freedom of Interference

What is that?

When **processes and modules working together on shared resources** some **interference issues** could occur which are very hard to find...

Memory

Timing and Execution

- Deadlocks
- Race conditions
- Sequence error

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Corruption of content

Access out of bounds

Invalid r/w access



Exchange of Information

- Interface violation
- Non initialized data
- Null-Pointers
- Data size mismatch



Typical Automotive Software Architecture





ISO 26262-6: Freedom from interference (Annex D)

<u>Goal:</u> Prevent or detect faults that can cause interference between software elements (e.g. different software partitions)

| D2.2 Timing and | d execution |
|-----------------|-------------|
|-----------------|-------------|

- Deadlocks
- Race Conditions

D2.3 Memory

- corruption of content
 - out-of-bound pointers and arrays, etc.
- read or write access to memory allocated to another software element
 - exhaustive identification of unprotected shared variables
 - · documentation of read-/write access to global variable

D2.4 Exchange of information

- corruption of information
- loss of information



What you could do is...



Problem: Testing, Hardware protection, restrictions and functional protection could be:

- very expensive to implement,
- not completely protective,
- <u>reducing performance</u>.



Let's make an example...





How to reduce efforts with "Timing and Execution" Safety?



With static analysis!



Polyspace – Data race checks

| | Multitasking |
|---|--|
| | Configure multitasking manually |
| Find <u>Timing Issues</u> with Multitasking | Entry points Task |
| | bug_datarace_task1 |
| | bug_datarace_task2 |
| ② □ Variable trace | |
| ID 2: Pata race | |
| Certain operations on variable 'bad_glob2' can interfere with each other and cause unpredictable value. | Critical section details Starting procedure Ending procedure |
| To avoid interference, operations on bad_glob2' must be in the same critical section. | BEGIN_CRITICAL_SECTION END_CRITICAL_SECTION |
| Access Race Conditions | Access Pro Scope Line |
| Write #1 (non-atomic) This write in 'bug_task3()' conflicts with Read # | #1 in 'bug_task4()' No protection bug_task3() 95 |
| Read #1 (non-atomic) Operation with 64-bit variable on a 32-bit target | #1 in 'bug_task3()' No protection bug_task4() 101 |
| 91 long long <u>bad glob2</u> ; | 91 long long <u>bad_glob2</u> ; |
| 92 92 | 92 |
| 93 Vold hug_task3 (Vold) 93 | 93 void bug_task3(void) |
| 94 (| |
| 96 1 | $\frac{bad glob2}{bad glob2} += 1;$ |
| 97 | 20 } 27 |
| 98 void bug task4 (void) | 98 void bug task4 (void) |
| 99 { | 99 { |
| 100 long local_var; 10 | long long local_var; |
| 101 local var = bad glob2; | local_var = bad_glob2; |



Polyspace - Global Variable Usage Protection

| 🛱 Global Variable | 2 3 2 17 | |
|-----------------------------------|-------------------|-----------------|
| . Shared | 3 2 | |
| -Potentially unprotected variable | 3 | |
| ···· ? 💌 Variable: PowerLevel | tasks1.c | _init_globals() |
| ···· ? 💌 Variable: SHR4 | tasks1.c | _init_globals() |
| Variable: SHR2 | tasks1.c | _init_globals() |
| Protected variable | 2 | |
| ···· 🗸 💌 Variable: SHR.5 | tasks1.c | _init_globals() |
| Variable: SHR | tasks1.c | _init_globals() |
| ⊡.·Not shared | 2 17 | |
| 🖨 Unused variable | 2 | |
| Variable: second_pai | initialisations.c | _init_globals() |
| Variable:huge_val | huge_val.h | _init_globals() |
| . Used non-shared variable | 17 | |



| \checkmark | Shared protected global variable |
|--------------|--|
| | Global variables shared between multiple tasks and protected |
| | from concurrent access by the tasks |
| \checkmark | Shared unprotected global variable |
| | Global variables shared between multiple tasks but not protected |
| | from concurrent access by the tasks |
| \checkmark | Non-shared used global variable |
| | Global variables used in a single task |
| \checkmark | Non-shared unused global variable |
| | Global variables declared but not used |
| | |

| Vari Rea Wri | Protected variable ③ riable 'tasks1.SHR' is shared among several tasks. All operations on 'task ad by task: <u>tregulate</u> ritten by task: <u>server1 server2</u> | s1.SHR' are protected by critical section. | | |
|--------------------|--|--|-----------------|------|
| | Event | File | Scope | Line |
| • | Written value: 0 | tasks 1.c | _init_globals() | 30 |
| • | Written value: 22 | tasks1.c | Tserver() | 81 |
| • | Read value: 0 or 22 | tasks1.c | initregulate() | 53 |



Let's make another example...



□ Is it safe to use myarray_init Function?







Problem with testing: <u>Tests aren't exhaustive</u>

"Program testing can be used to show the presence of bugs, but never to show their absence" (Dijkstra [1])

[1] Dijkstra, "Notes On Structured Programming", 1972



How to reduce efforts with "Memory" Safety?



With static analysis!



Polyspace – Proving Memory Safety

With **Polyspace** ... you can **proof** the **existence** and **absence** of <u>memory access errors</u> like:



Memory safety

- aims to avoid software errors that cause safety and security vulnerabilities
- dealing with random-access memory (RAM) access,
- such as corruption of content and read/write access to memory allocated by another software element.

Computer **languages such as C and C++** that support arbitrary pointer arithmetic, casting, and deallocation **are typically** <u>not memory safe</u>.



Let's make one last example...





How to reduce efforts with "Exchange of Information" Safety?



With static analyis!



Example: Optimize design and architecture





Example: Optimize design and architecture





Summary

Do you have Multicore applications?
 Do you have HW/SW protections?
 Do you like to reduce testing effort?

ask for our static analysis solutions TODAY