

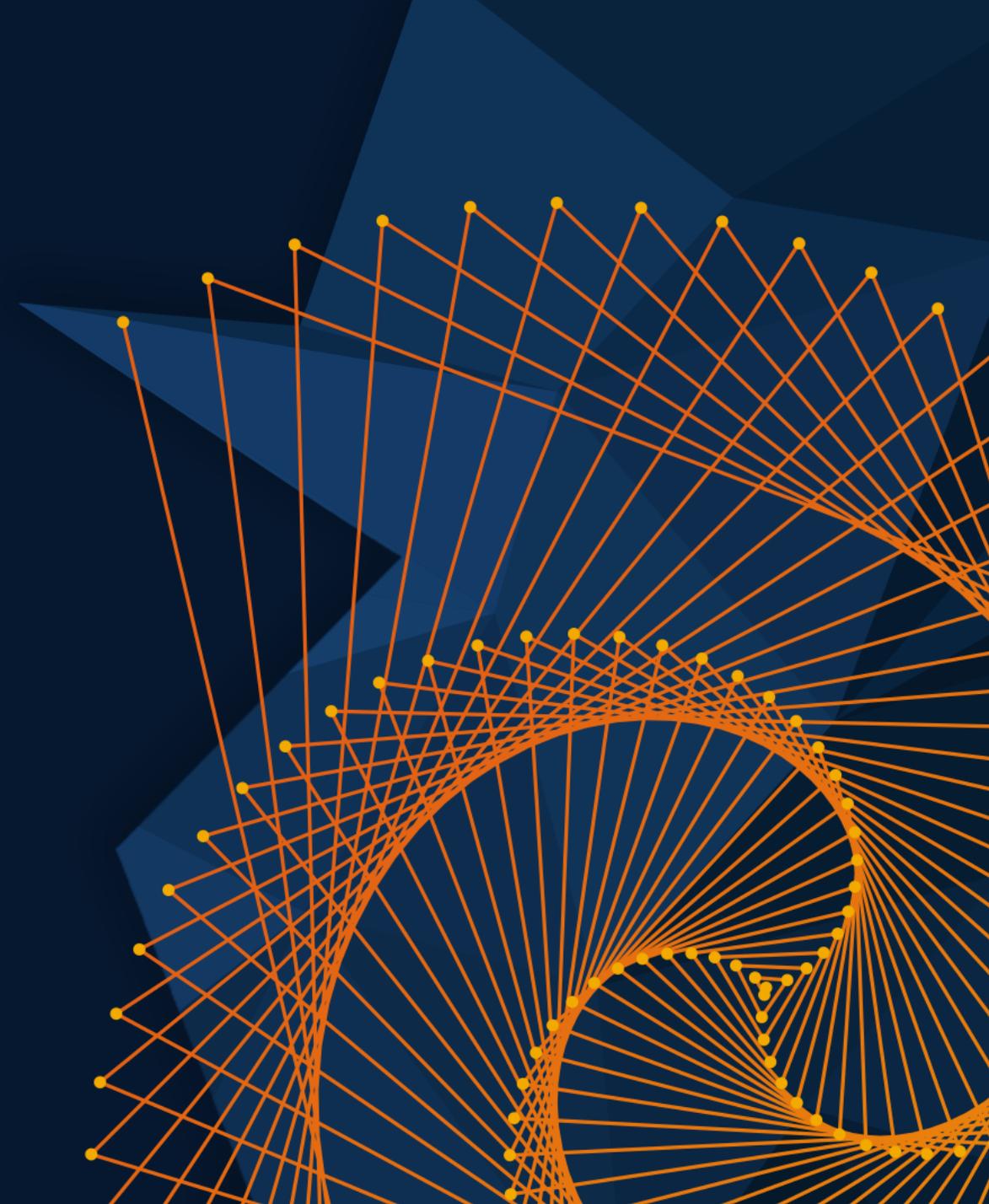
MATLAB EXPO

May 28, 2024 | Beijing

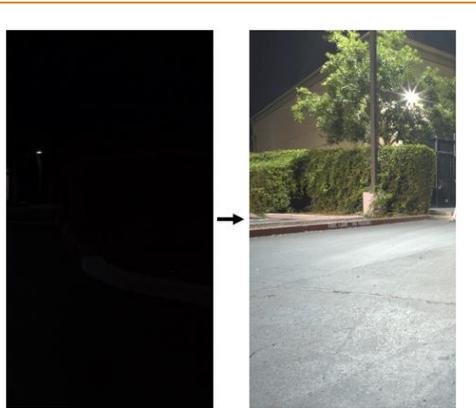
探索光影魔术：

MATLAB数字成像与显示技术创新

Qian Zhang, MathWorks



Agenda



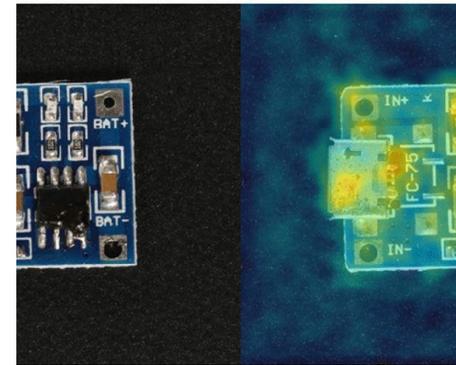
Imaging

Camera Pipeline



Display

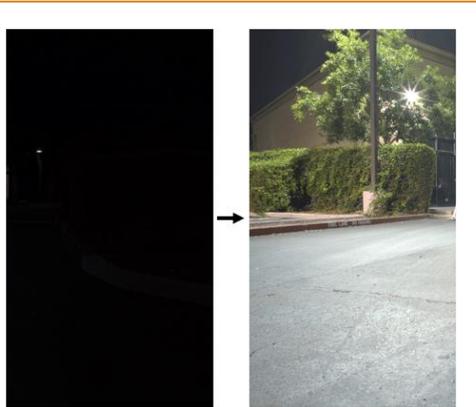
Image Quality & Enhancement



Manufacturing

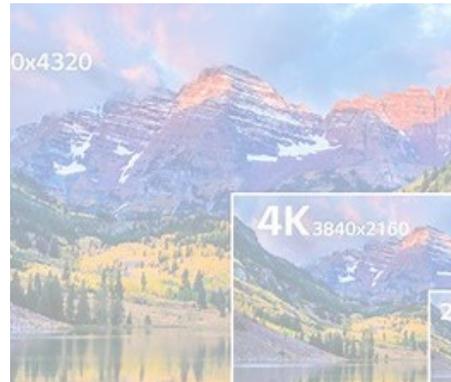
Visual Inspection

Agenda



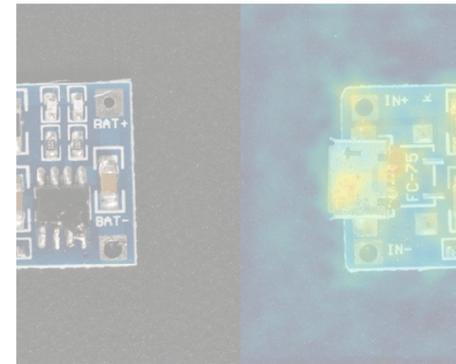
Imaging

Camera Pipeline



Display

Image Quality & Enhancement



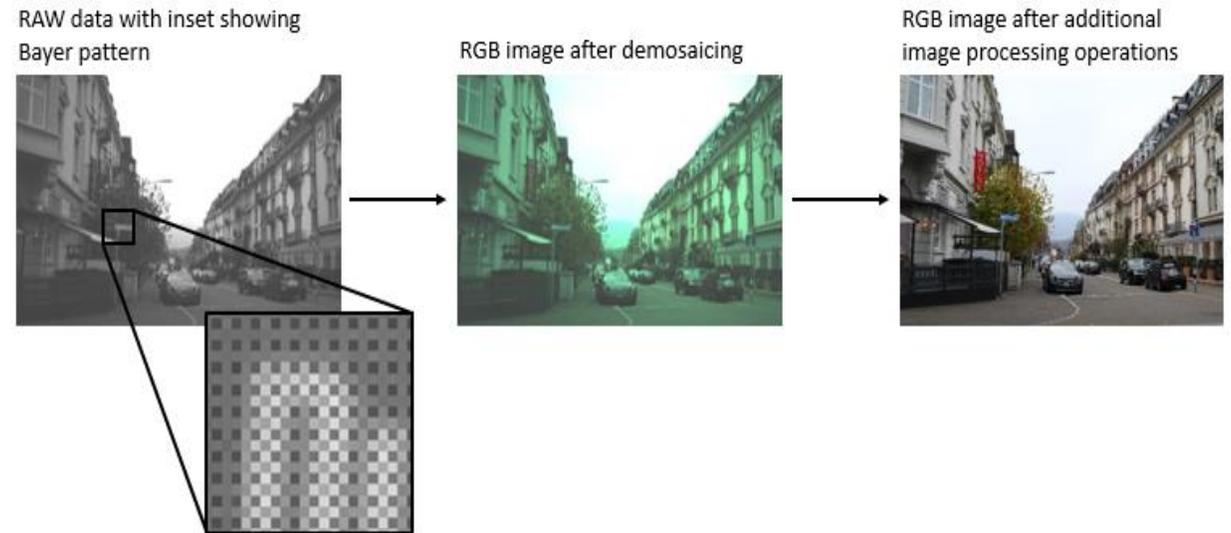
Manufacturing

Visual Inspection

Camera Pipeline Design – Traditional and Deep Learning



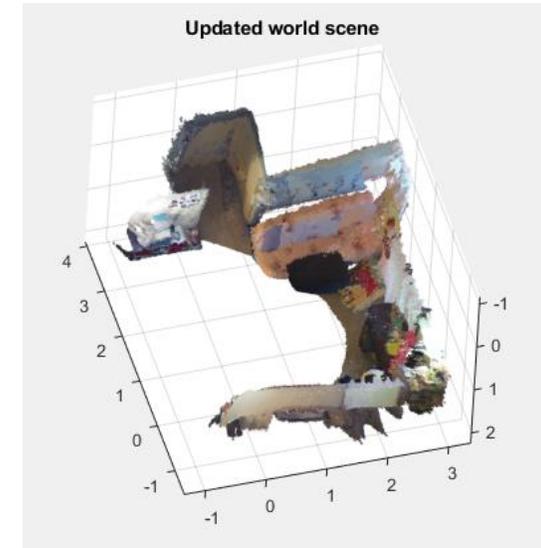
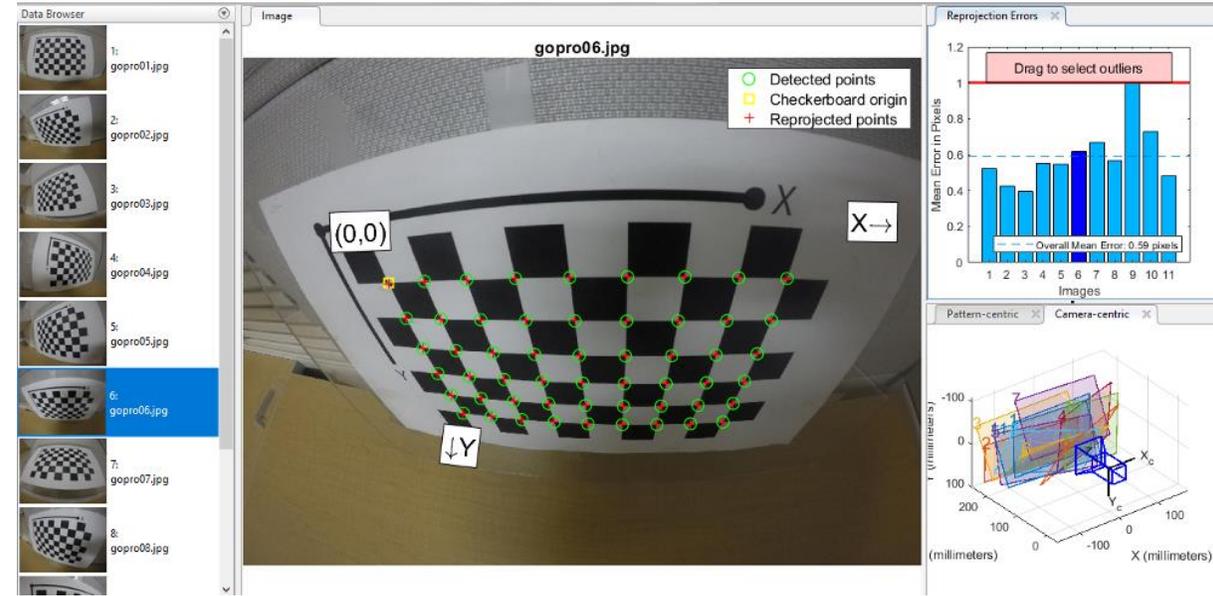
Implement Digital Camera Processing Pipeline



Develop Camera Processing Pipeline Using Deep Learning

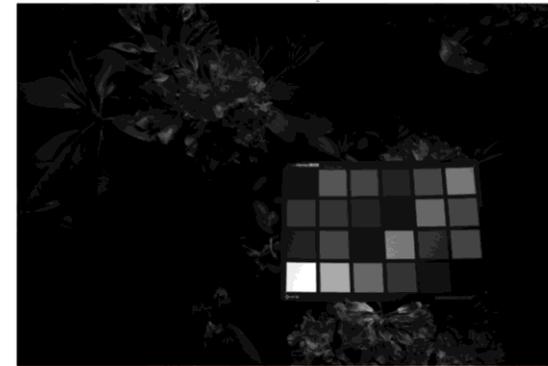
Camera Calibration

- Estimate camera intrinsic and extrinsic parameters (including fisheye)
- Remove the effects of lens distortion
- Measure sizes of real-world objects
- Compute stereo disparity and depth
- Structure from motion



RAW to RGB Camera Pipeline

- Import RAW files formats such as Nikon NEF, Canon CRW and Adobe DNG, and read CFA image
- Linearize CFA image data
- Scale the images and apply white-balance adjustment
- Demosaic and Rotate image
- Convert CFA Image to RGB image (or sRGB)



Linear CFA Image



Rendered Image in Linear Color Space



Rendered RGB Image in sRGB Color Space

Functions	
<i>rawinfo</i>	Read information about color filter array (CFA) images in RAW files
<i>rawread</i>	Read CFA images from RAW files
<i>demosaic</i>	Convert Bayer pattern encoded image to truecolor image
<i>lin2rgb</i>	Apply gamma correction to convert linear sRGB to sRGB color space
<i>raw2planar</i>	Separate a Bayer-patterned CFA image into individual, sensor-element
<i>planar2raw</i>	Combine planar sensor images into a full Bayer-pattern CFA image
<i>raw2rgb</i>	Convert a RAW file into an RGB file in one step

White Balance Algorithms

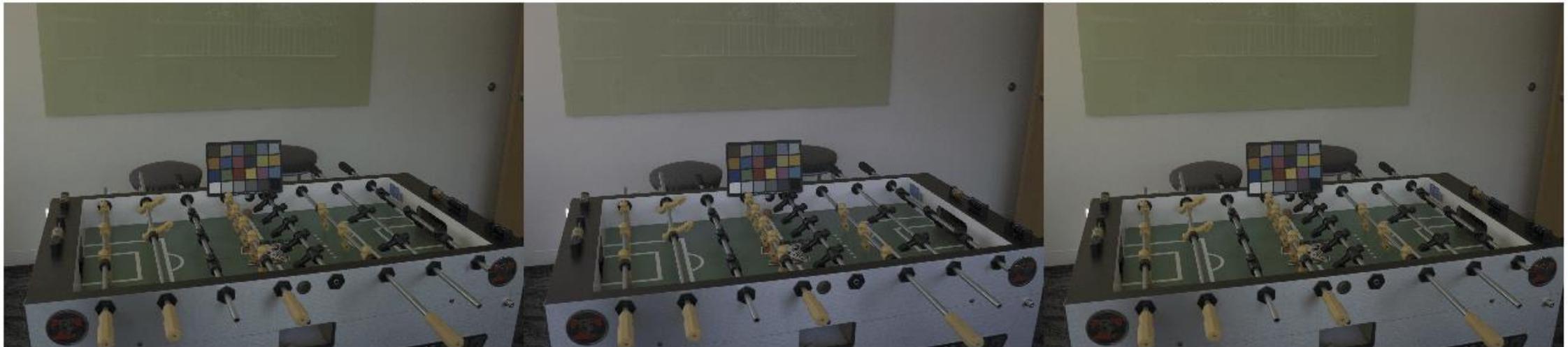
Automatic white balancing is done in two steps:

- Step 1: Estimate the scene illuminant
- Step 2: Correct the color balance of the image

Algorithms to estimate scene illuminant

<i>illumwhite</i>	Estimate illuminant using White Patch Retinex algorithm
<i>illumgray</i>	Estimate illuminant using gray world algorithm
<i>illumzca</i>	Estimate illuminant using principal component analysis (PCA)

Montage of Best White-Balanced Images: White Point, Gray World, Cheng



Recover Low Light Images Using Deep Learning

- Recover RAW images taken in low light with short exposure times using deep learning network
- Pretrained low-light recovery U-Net deep learning network



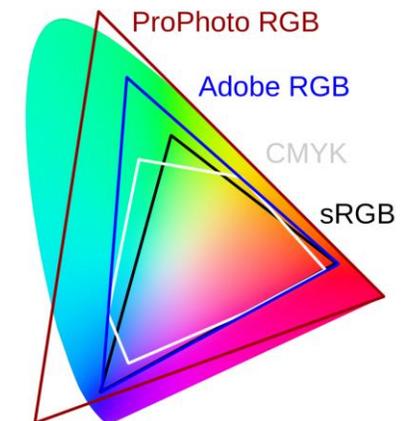
Conversion Between Color Spaces

Support for wide-gamut color spaces

- BT.2020 (Ultra High Definition, UHD)
- BT.2100 (High Dynamic Range, HDR)
- ProPhoto (ROMM RGB) color space



Function	
<code>rgbwide2ycbcr</code>	Convert wide-gamut RGB color values to YCbCr color values
<code>ycbcr2rgbwide</code>	Convert YCbCr color values to wide-gamut RGB color values
<code>xyz2rgbwide</code>	Convert CIE 1931 XYZ color values to wide-gamut RGB color values
<code>rgbwide2xyz</code>	Convert wide-gamut RGB color values to CIE 1931 XYZ color values



Agenda



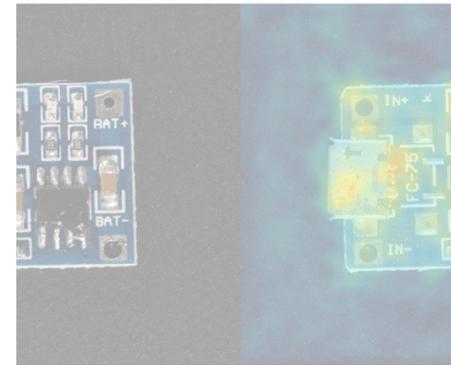
Imaging

Camera Pipeline



Display

Image Quality & Enhancement



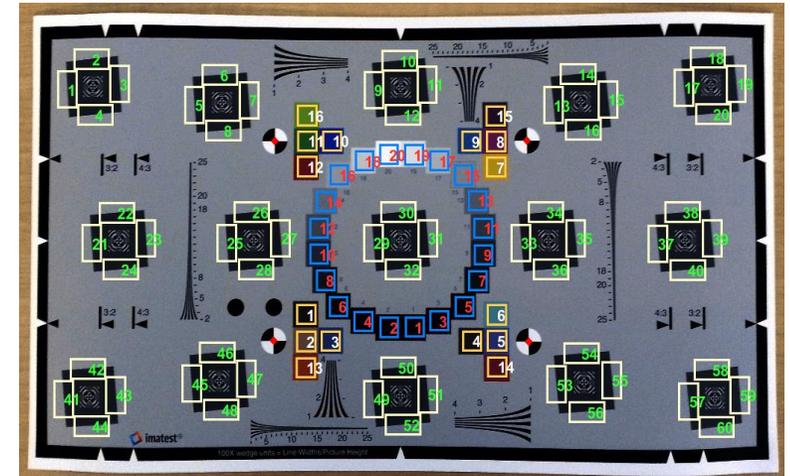
Manufacturing

Visual Inspection

Test Charts Support

- Detection and analysis of enhanced, wedge enhanced, and wedge extended versions of Imatest eSFR test charts (ISO 12233)
- Support for X-Rite® (Gretag Macbeth®) ColorChecker® test charts

Function	
<i>measureIlluminant</i>	Measure scene illuminant of test chart
<i>colorChecker</i>	Identifies the color patch ROI in test chart
<i>displayChart</i>	Display test chart with ROI
<i>measureColor</i>	Measure colors in test chart
<i>displayColorPatch</i>	Display measured and reference color as color patches
<i>plotChromaticity</i>	



Enhanced, Wedge Enhanced, and Wedge Extended eSFR test chart



X-Rite ColorChecker

Quality Measurement by Image Comparison

- Measure color deviations in test charts
- Compare color difference between 2 images in RGB or L*a*b color space

Function	
<i>deltaE</i>	Color difference based on CIE76 standard
<i>imcolordiff</i>	Color difference based on CIE94/CIE2000 standard

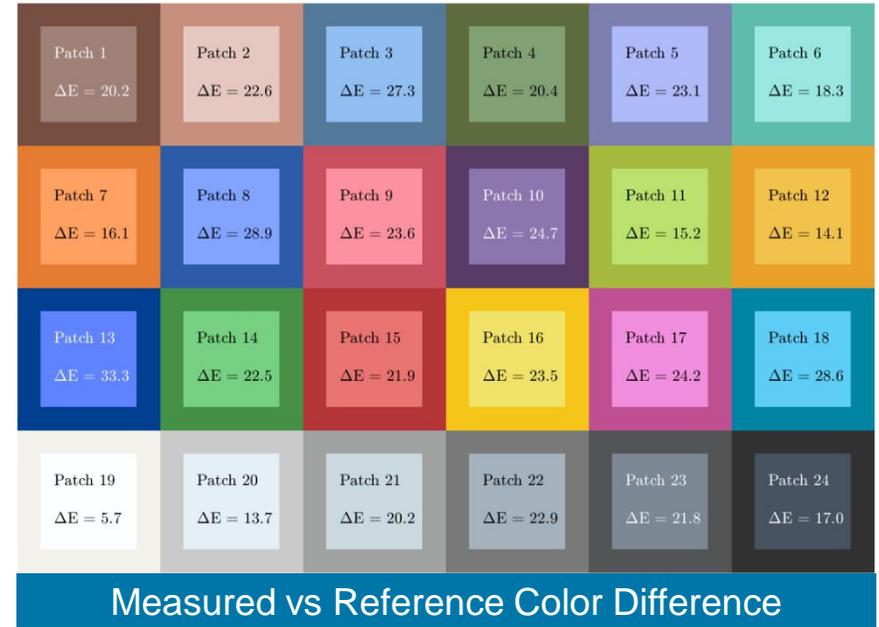


Image Quality Metrics

Full Reference Techniques Function

<i>immse</i>	Mean squared error
<i>psnr</i>	Peak signal-to-noise
<i>ssim</i>	Structural similarity metric
<i>multissim</i>	MS-SSIM index for image quality
<i>multissim3</i>	MS-SSIM index for volume quality

No-Reference Techniques Function

<i>nique</i>	Naturalness Image Quality Evaluator
<i>brisque</i>	Blind Reference-less Image Spatial Quality Evaluator
<i>piqe</i>	Perception-based Image Quality Evaluator

Original Image: PIQE score = 24.8481 | Noisy Image: PIQE score = 72.3643 | Blurred Image: PIQE score = 85.7362

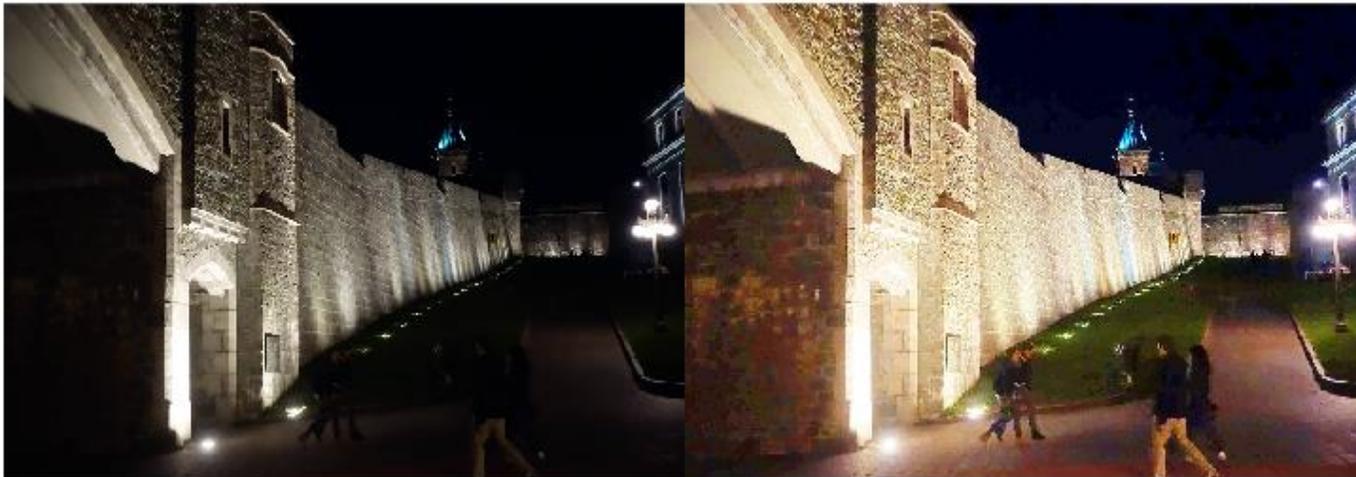


PIQE No-Reference Techniques

Enhance Low Light Image using Dehazing Algorithm

Using haze removal techniques to enhance low-light images comprises three steps:

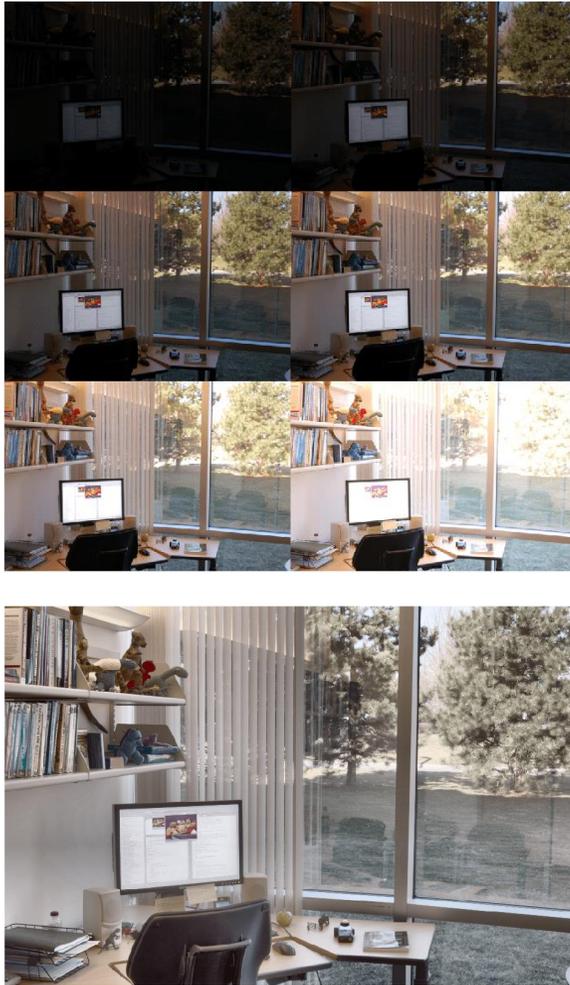
- Step 1: Invert the low-light image
- Step 2: Apply the haze removal algorithm to the inverted low-light image
- Step 3: Invert the enhanced image



Neural Style Transfer Using Deep Learning



High Dynamic Range (HDR) Images



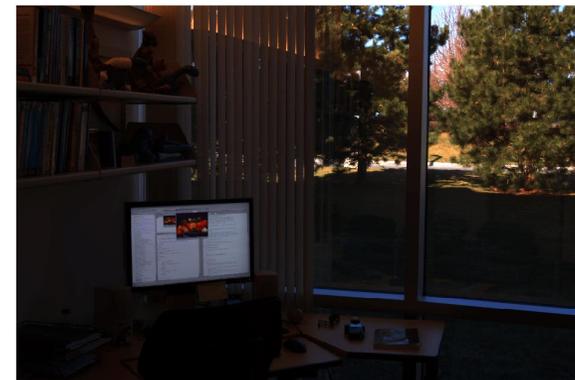
makehdr

Create the HDR from the set of LDR



tonemap

Convert HDR to LDR



Support EXR and HDR files

Increase Image Resolution

Set of Low-Resolution Burst Mode Images



High-Resolution Image



Create high-resolution image
from set of low-resolution
burst mode images

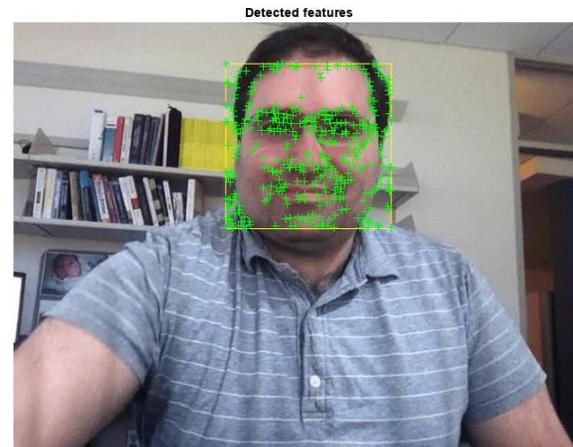
High-Resolution Results Using Bicubic Interpolation (Left) vs. VDSR (Right)



Single image super-resolution (SISR) using a very-
deep super-resolution (VDSR) neural network

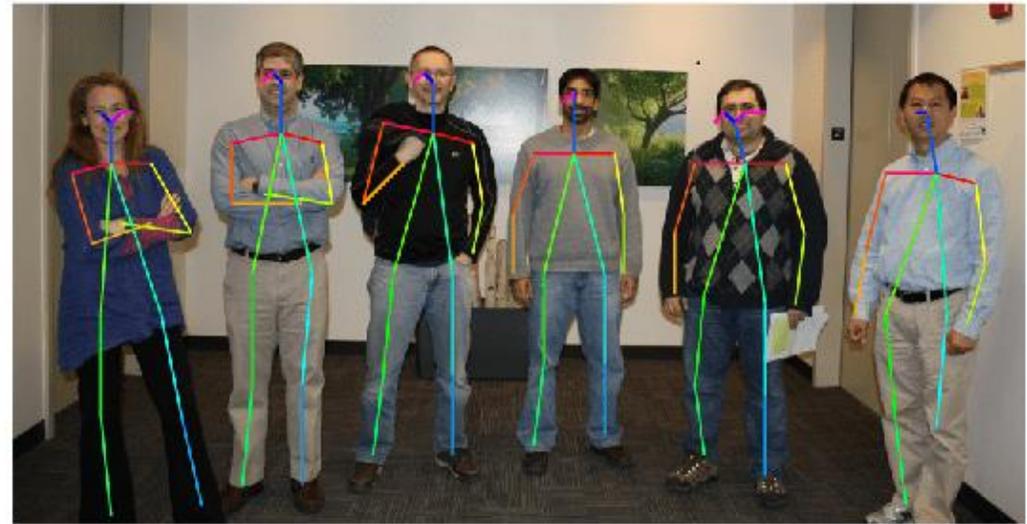
Face Detection and Tracking

- Figure out where people are to make localized adjustments (accentuate the person and minimize the background, auto-focus assistance)
- Develop the system in three steps:
 - Step 1: Detect a face
 - Step 2: Identify facial features to track
 - Step 3: Track the face



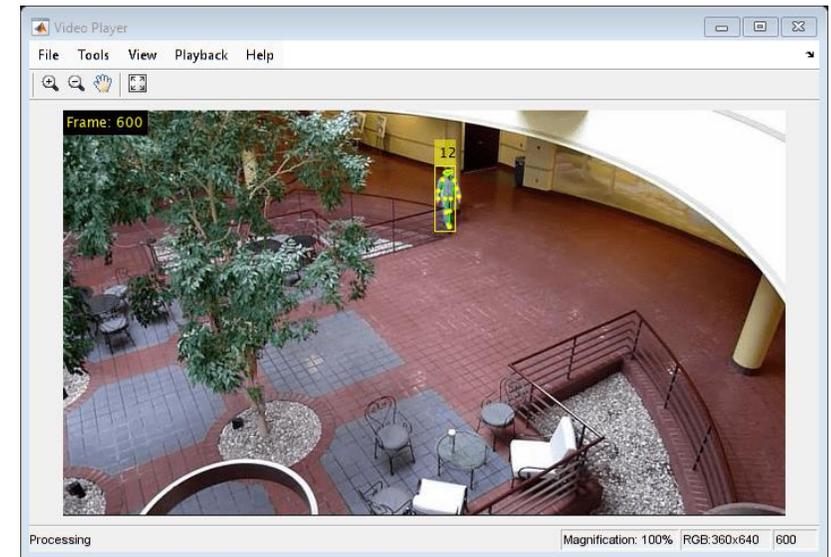
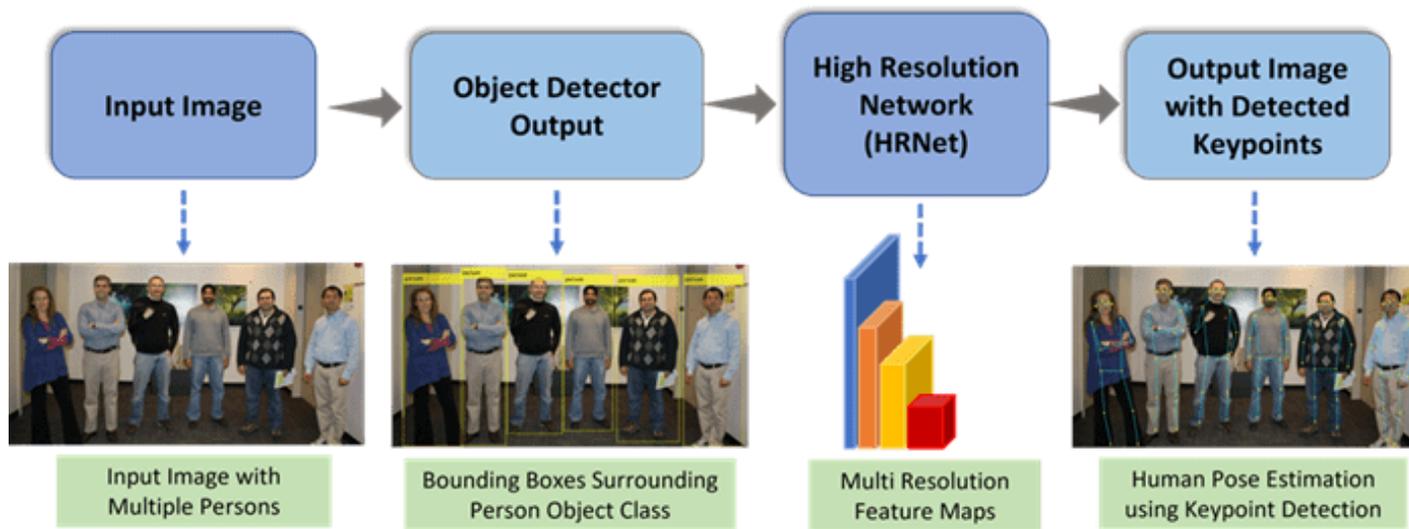
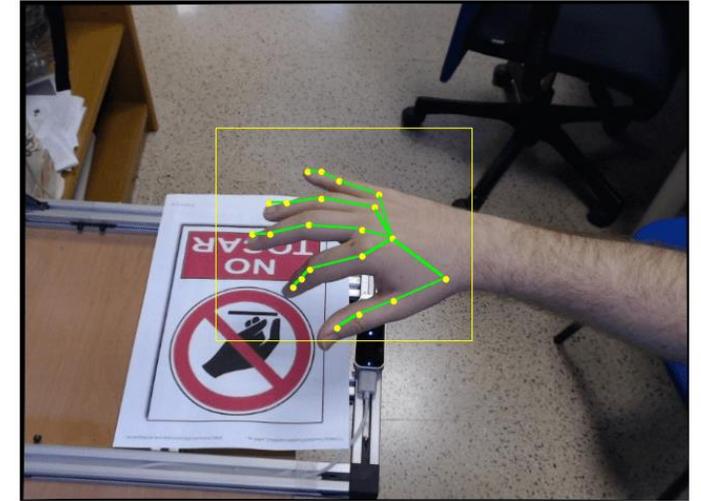
Pose Estimation

- Identify the location of people in an image and the orientation of their body parts.
- OpenPose is a multi-person human pose estimation algorithm that uses a bottom-up strategy.
- A bottom-up strategy first identifies body parts in an image, such as noses and left elbows, and then assembles individuals based on likely pairings of body parts.



Multi-Object Tracking and Human/Hand Pose Estimation

- **Detect** people in each video frame using a YOLO v4
- **Track** the detected people across frames using trackerGNN uses linear Kalman filter
- **Identify** keypoints and estimate body/hand poses using HRNet

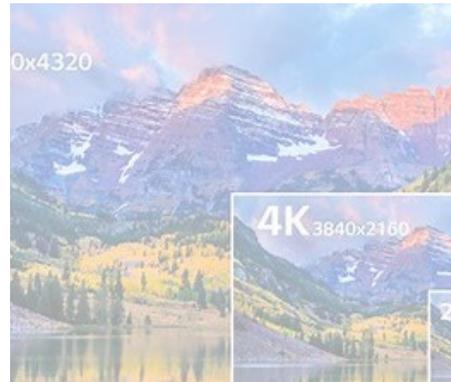


Agenda



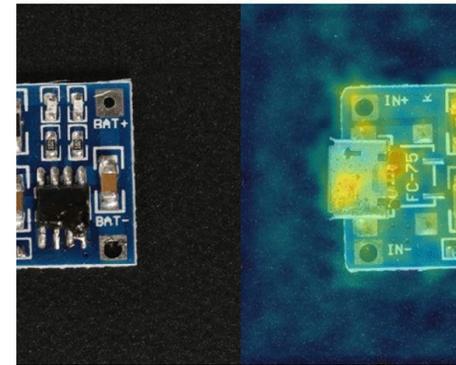
Imaging

Camera Pipeline



Display

Image Quality & Enhancement



Manufacturing

Visual Inspection

What is Automated Visual Inspection?

*“ Automated optical inspection is the **image-based** or **visual inspection** of manufacturing parts where a camera scans the device under test for both **failures** and **quality defects**”*

Automated Defect Detection

Machine Vision

Optical Inspection

Automated Inspection

Typical Visual Inspection System

Inspection Cameras

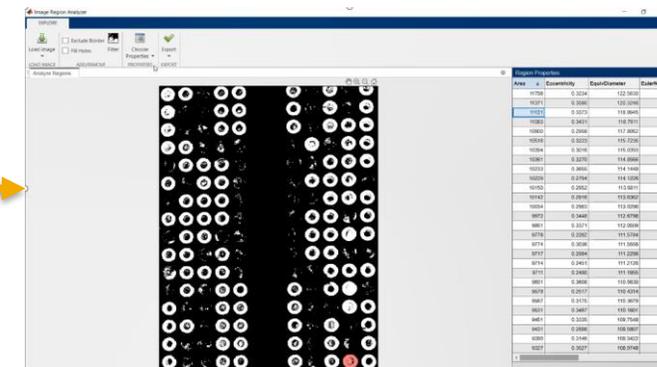
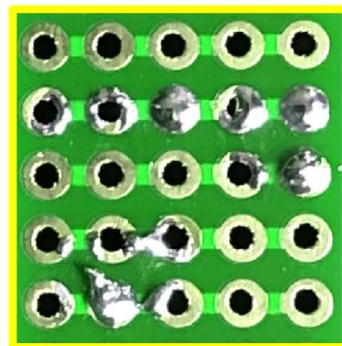
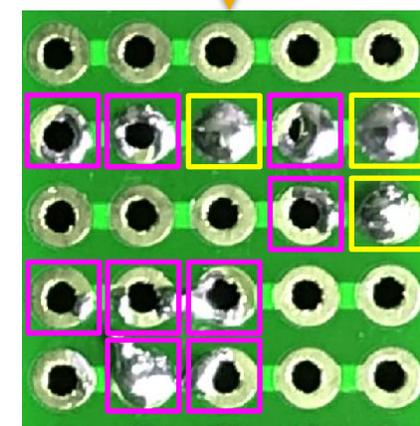
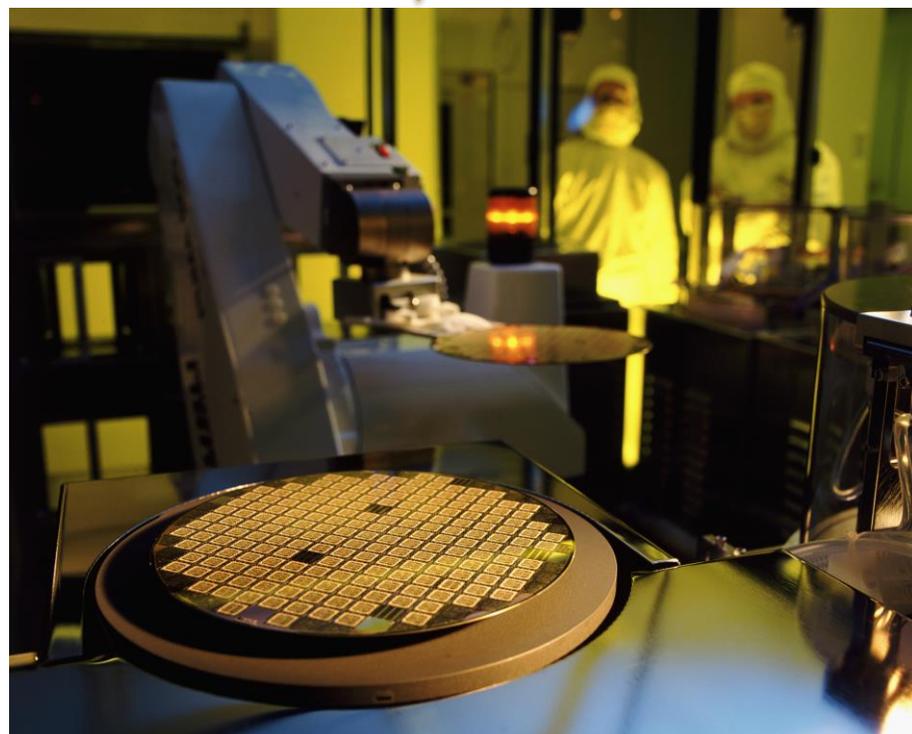
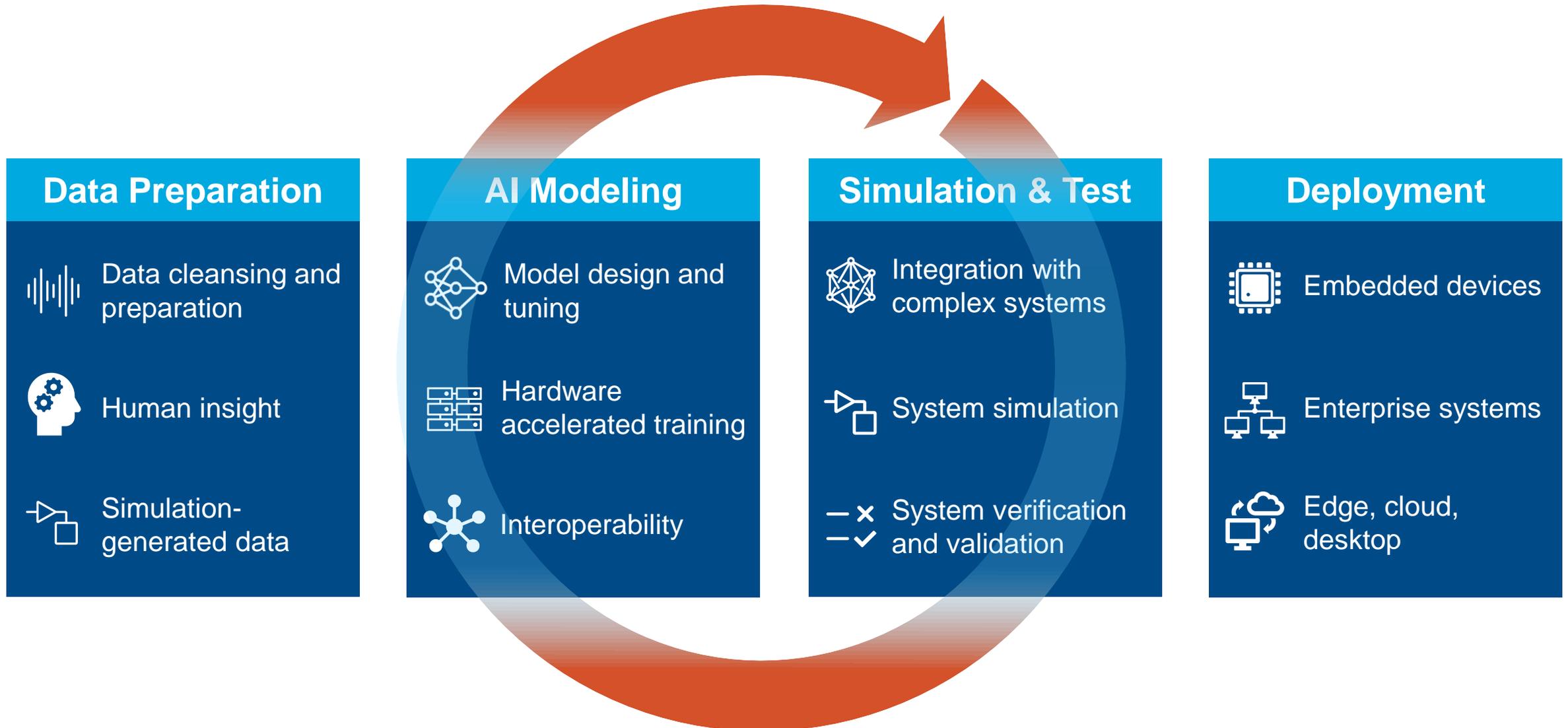


Image Analysis

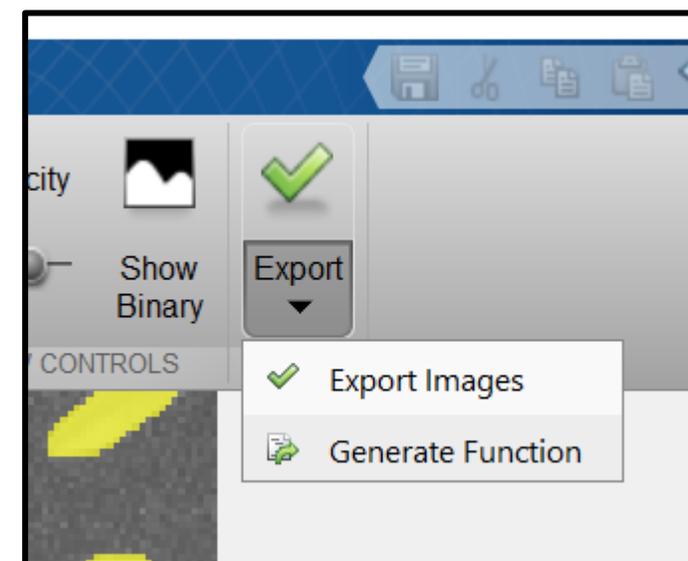
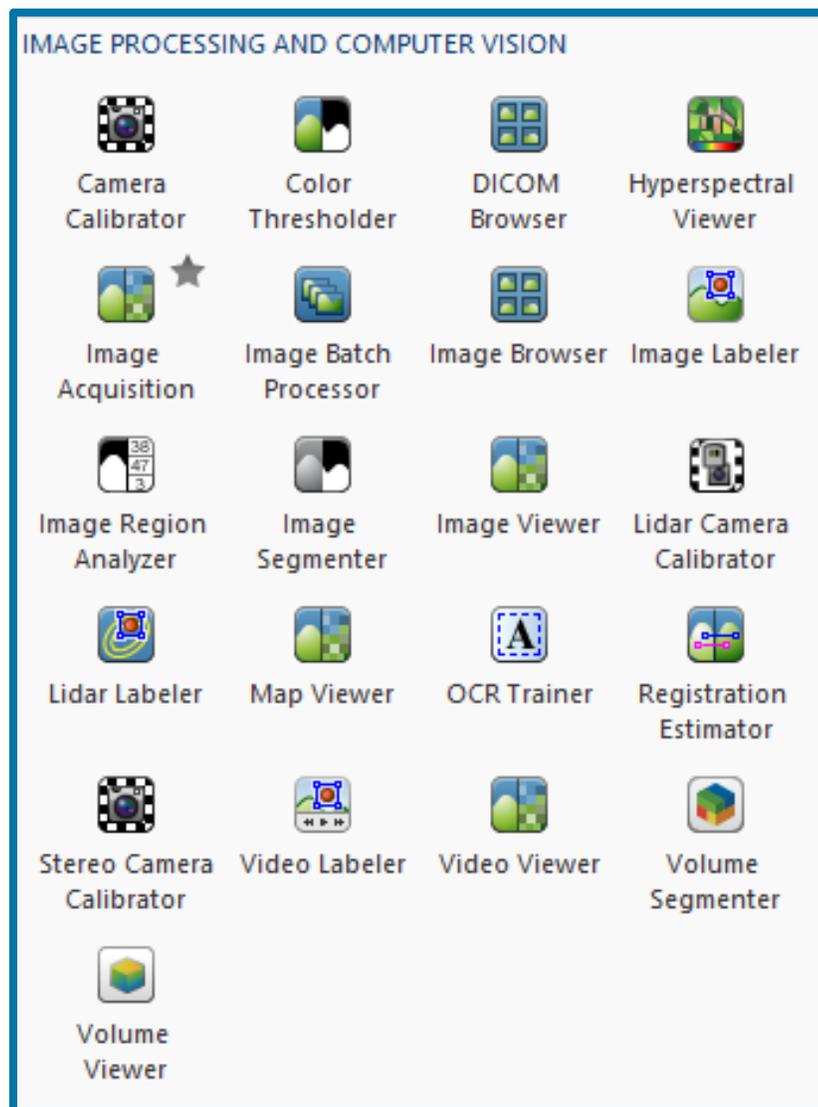


Defective Parts

AI-based Visual Inspection Workflow

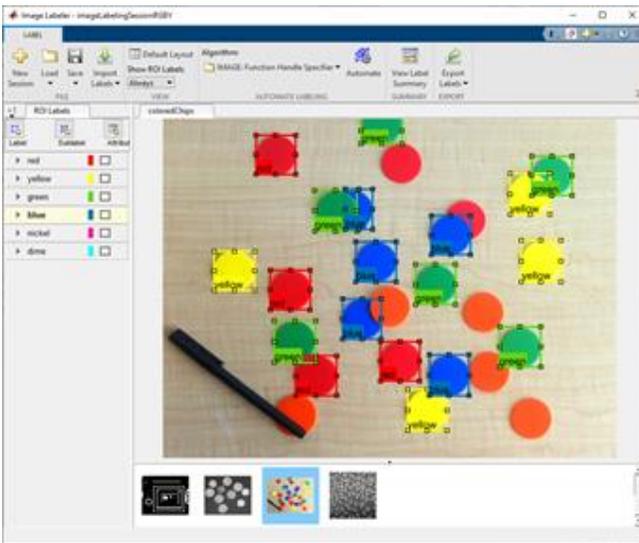


Apps Accelerate Workflow

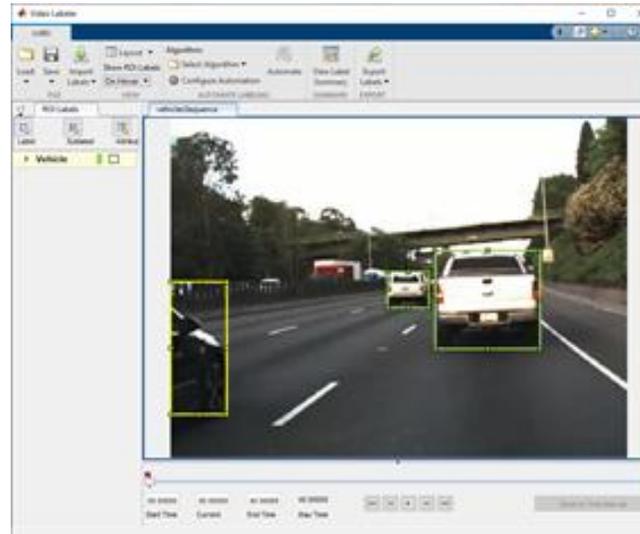


Data Labeling

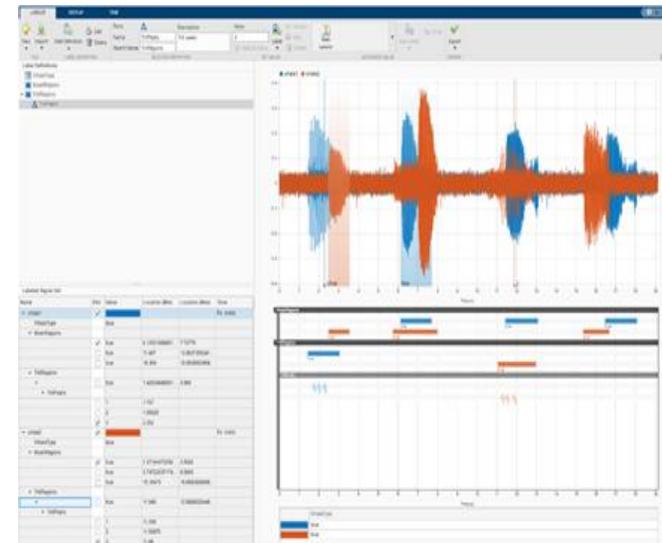
Image Labeler



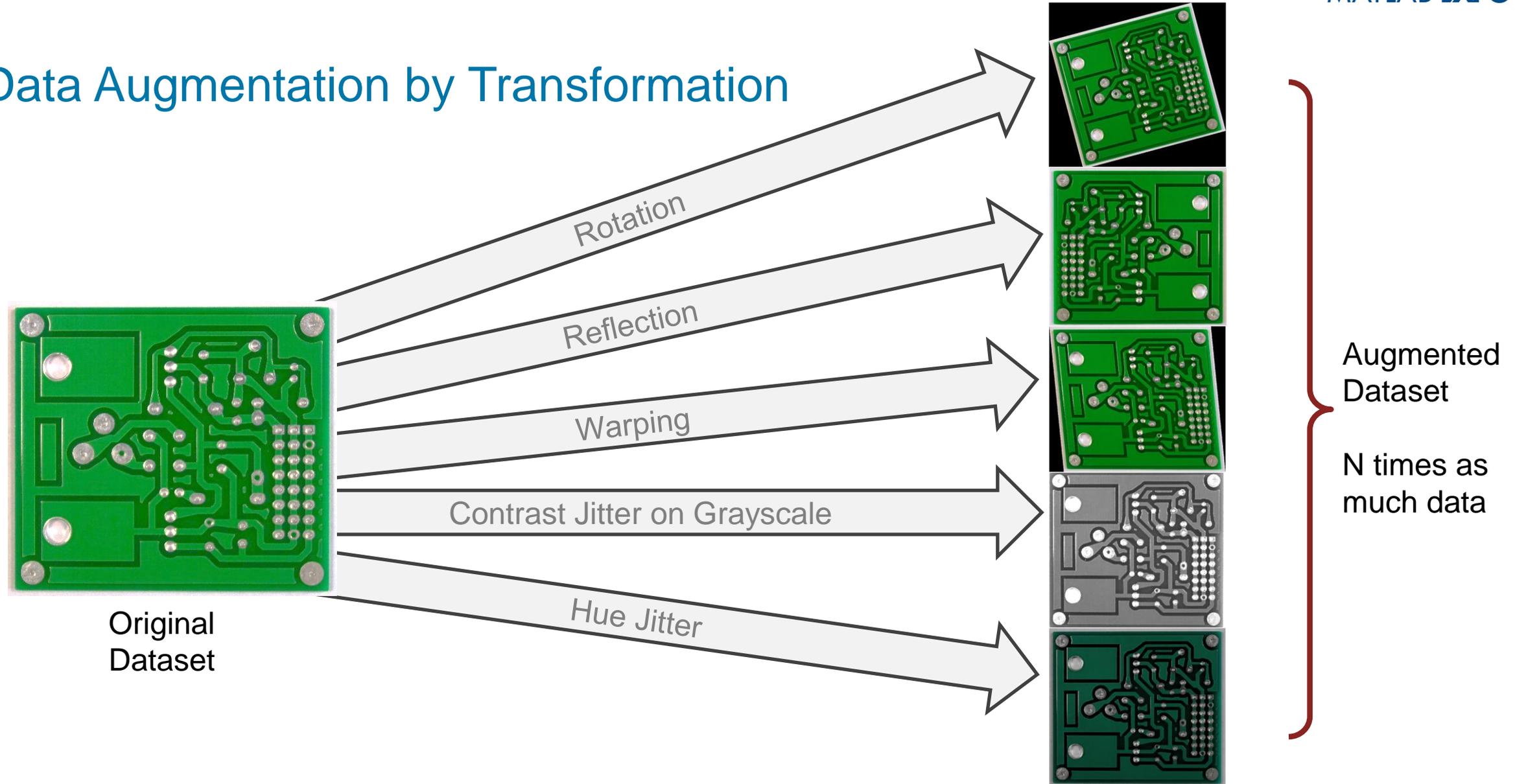
Video Labeler



Signal Labeler



Data Augmentation by Transformation



Data augmentation allows building more complex and more robust models

Data Augmentation using Generative Adversarial Networks (GANs)

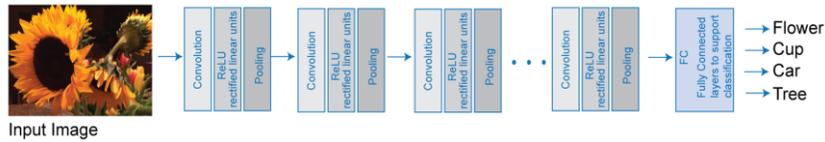


Images of digits generated from noise.

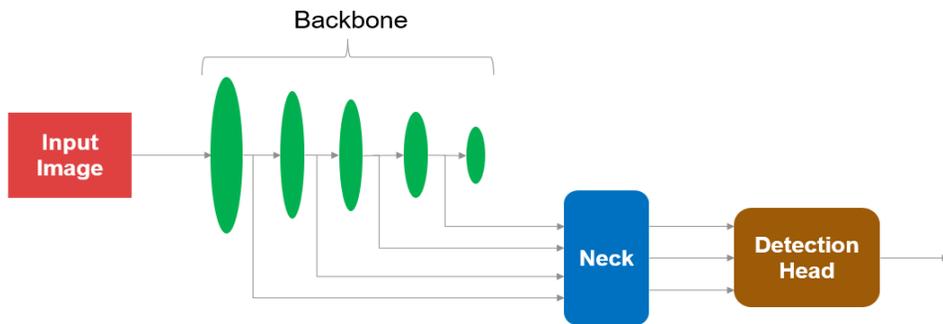
[File Exchange: Conditional GAN \(Generative Adversarial Network\) with MNIST](#)

Architectures for Visual Inspection

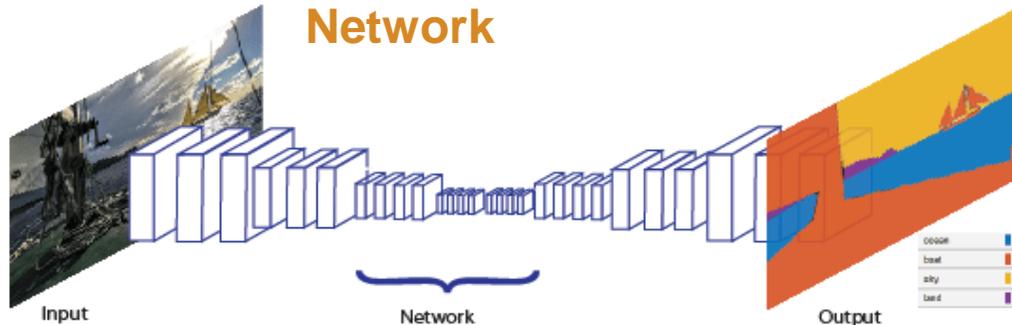
Convolutional Neural Networks



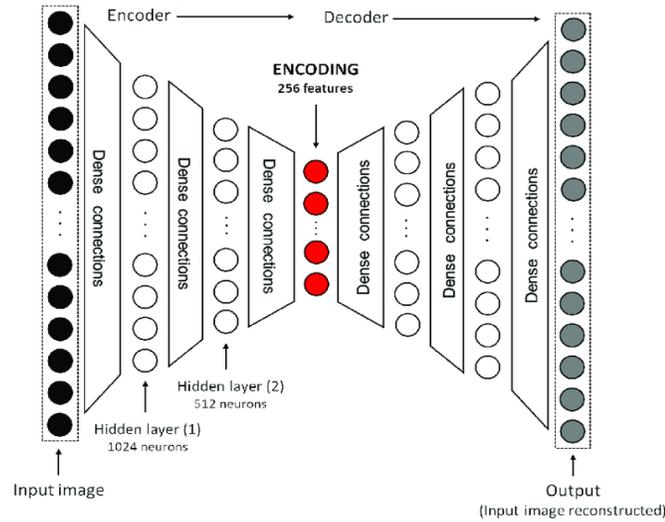
YOLO – Object Detector



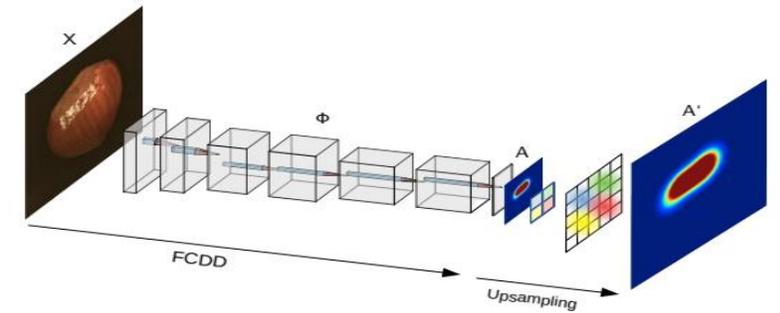
Semantic Segmentation Network



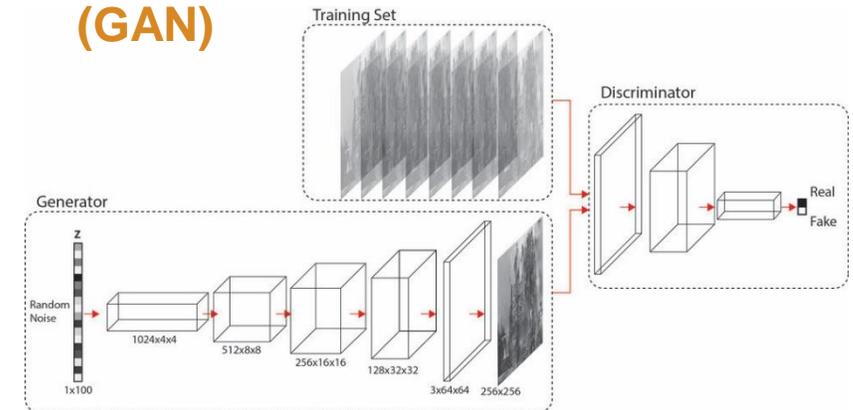
Deep Autoencoder



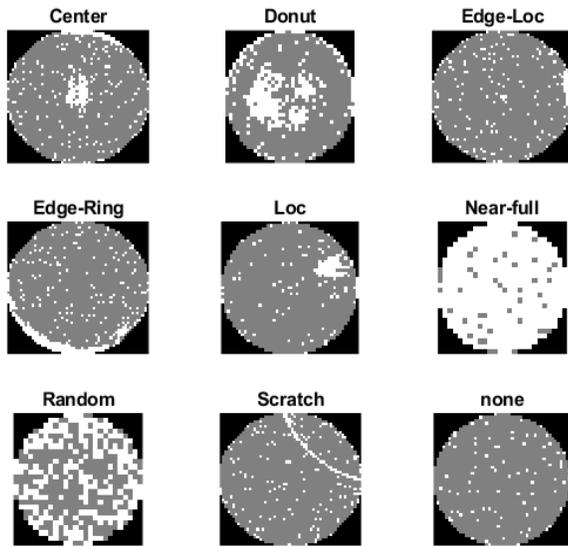
Fully Convolutional Data Description (FCDD) – Anomaly Detector



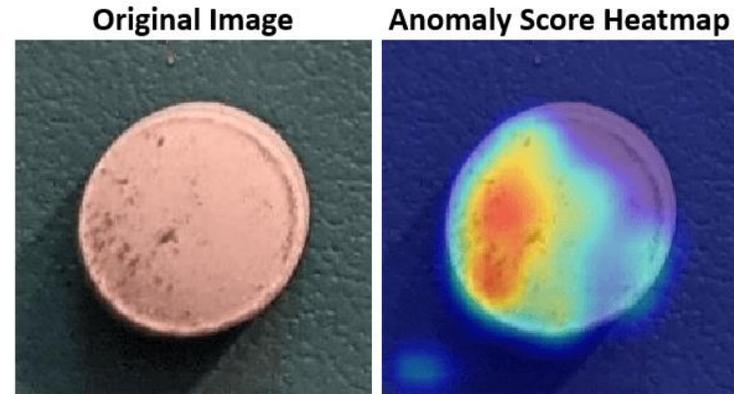
Generative Adversarial Network (GAN)



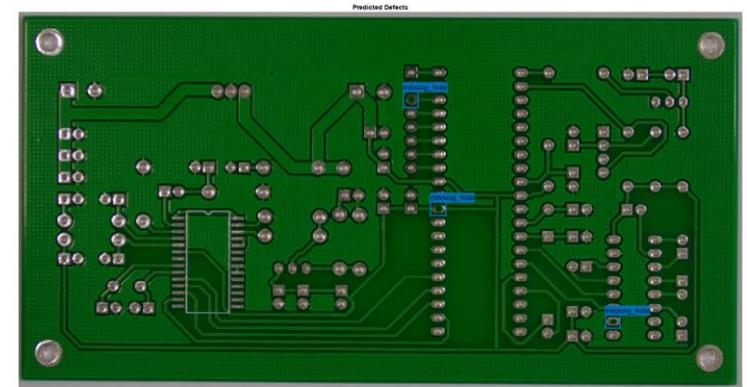
Visual Inspection Examples



Defect Classification



Anomaly Detection

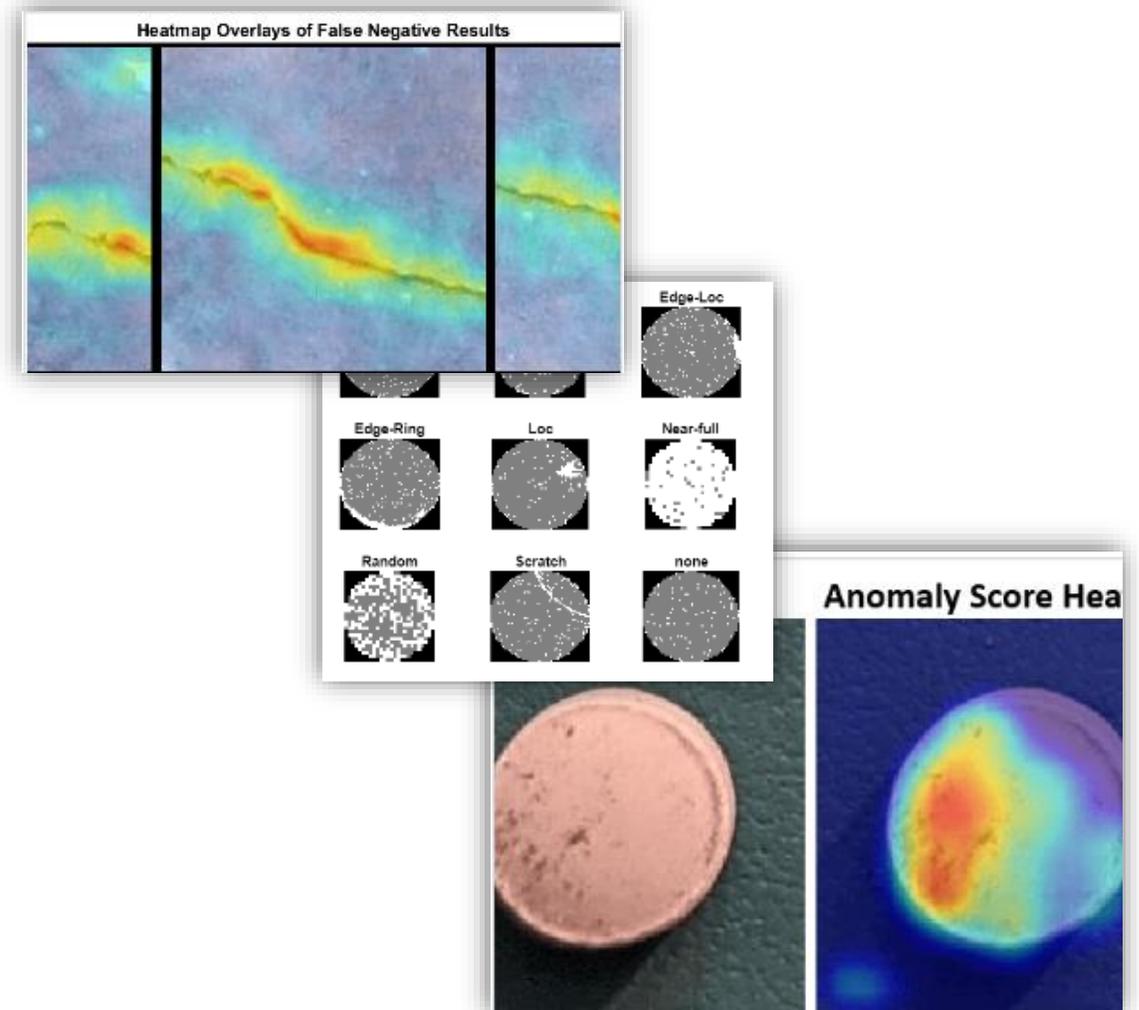


Localization and Classification
on PCBs

Visual Inspection Support package

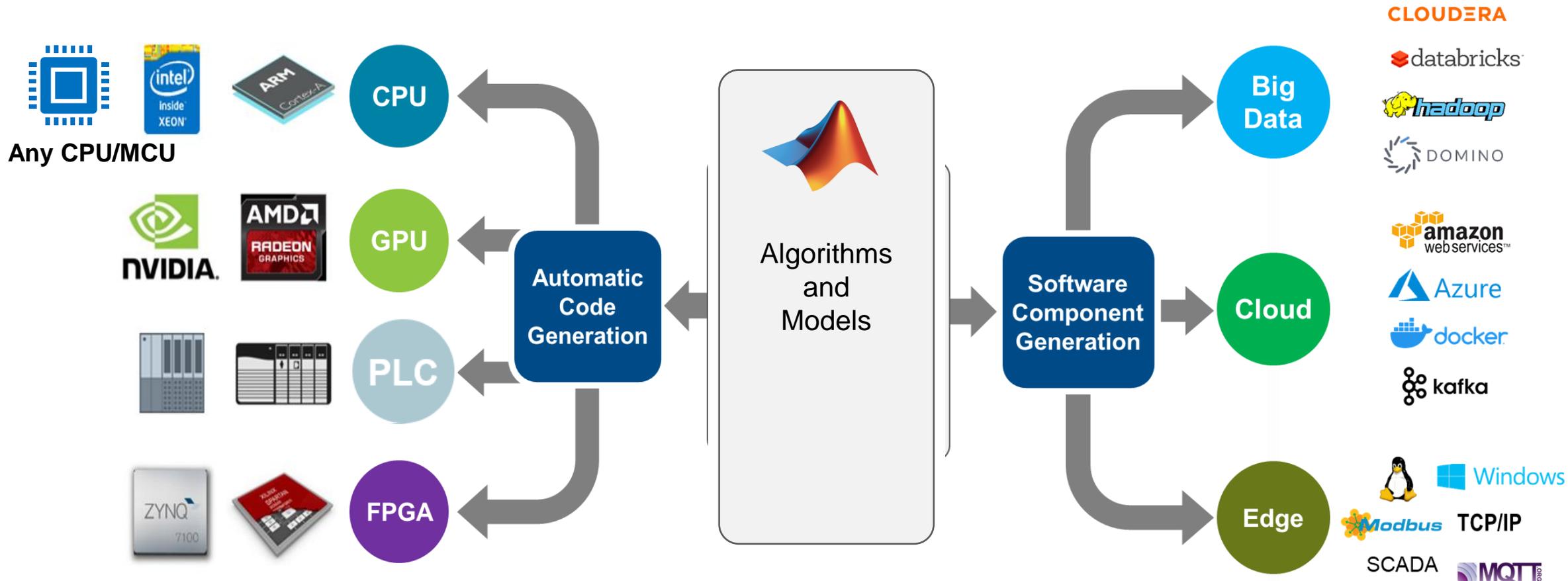
[Computer Vision Toolbox Automated Visual Inspection Library](#)

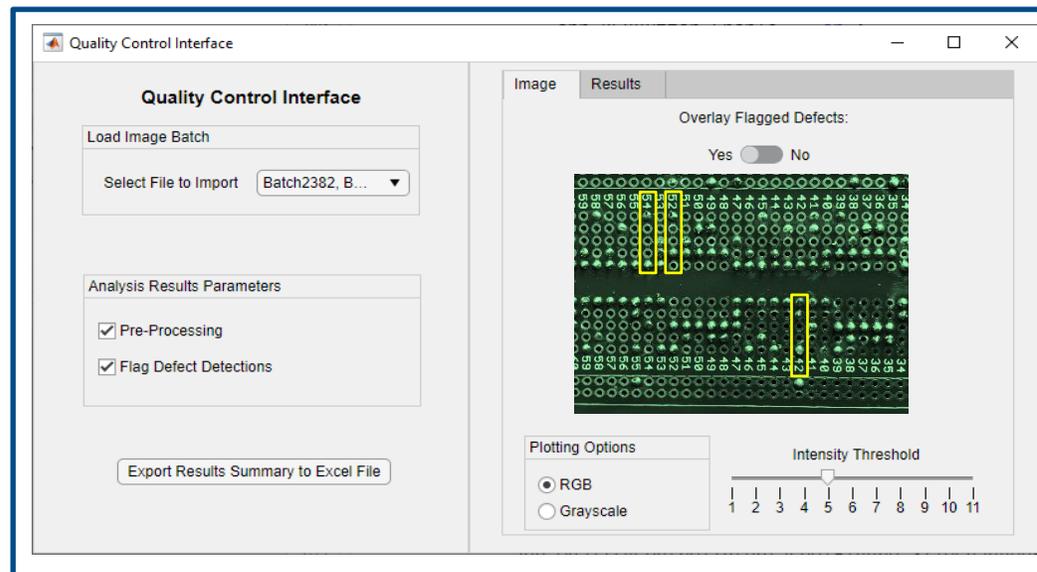
- Anomaly detector
- Parameter optimization
- Visualization and evaluation tools
- Dedicated examples
 - [Detect Image Anomalies Using Pretrained ResNet-18 Feature Embeddings](#)
 - [Classify Defects on Wafer Maps Using Deep Learning](#)
 - [Detect Image Anomalies Using Explainable One-Class Classification Neural Network](#)



Deploy to Enterprise Infrastructure or Embedded Systems

AI models in MATLAB and Simulink can be deployed on enterprise systems or the cloud, or on embedded devices.



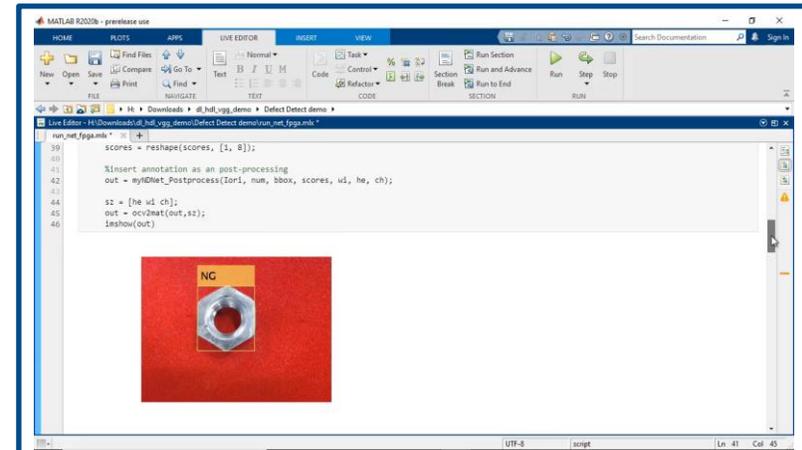
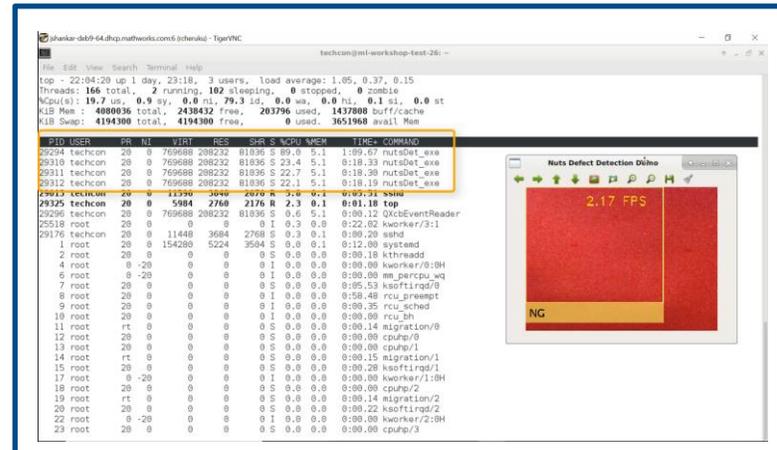


Deploy as Desktop or Web App

Deploy to Jetson AGX Xavier

Deploy to ARM Cortex-A microprocessor

Deploy to ZCU102 board from Xilinx





Wuhan JINGCE Electronic: Rapid Development of Model-Based Display Measuring Instruments

Challenge

Rapidly develop high-precision measurement instruments for display devices based on complex image processing and deep learning, measure and debug a series of optical parameters such as flicker, chromaticity and color uniformity, and spectrum.

Solution

Use MATLAB to develop image processing algorithms, create and train neural networks, and use GPU Coder for automatic code generation to quickly implement productization.

Result

- The automatically generated CUDA code is 23.6% faster than the manually optimized code
- From algorithm prototype to product prototype, the development time is shortened by 35%~50%
- Product Engineering Quality Assurance (Gold Reference, SIL, PIL)
- Simplified processes and smaller teams, 30% reduction



精测电子用于显示屏高精量测的谱系化产品



MATLAB EXPO

Thank you



© 2024 The MathWorks, Inc. MATLAB and Simulink are registered trademarks of The MathWorks, Inc. See [mathworks.com/trademarks](https://www.mathworks.com/trademarks) for a list of additional trademarks. Other product or brand names may be trademarks or registered trademarks of their respective holders.

