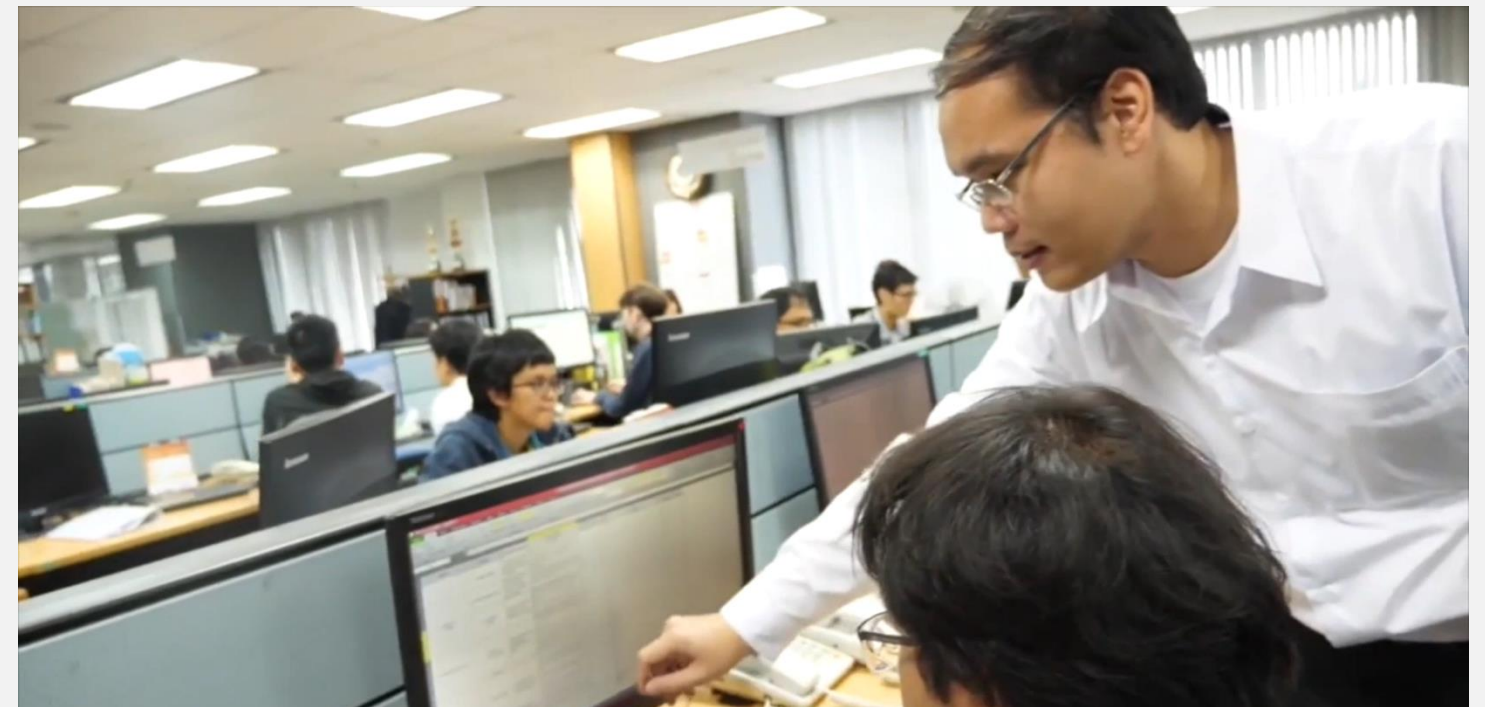
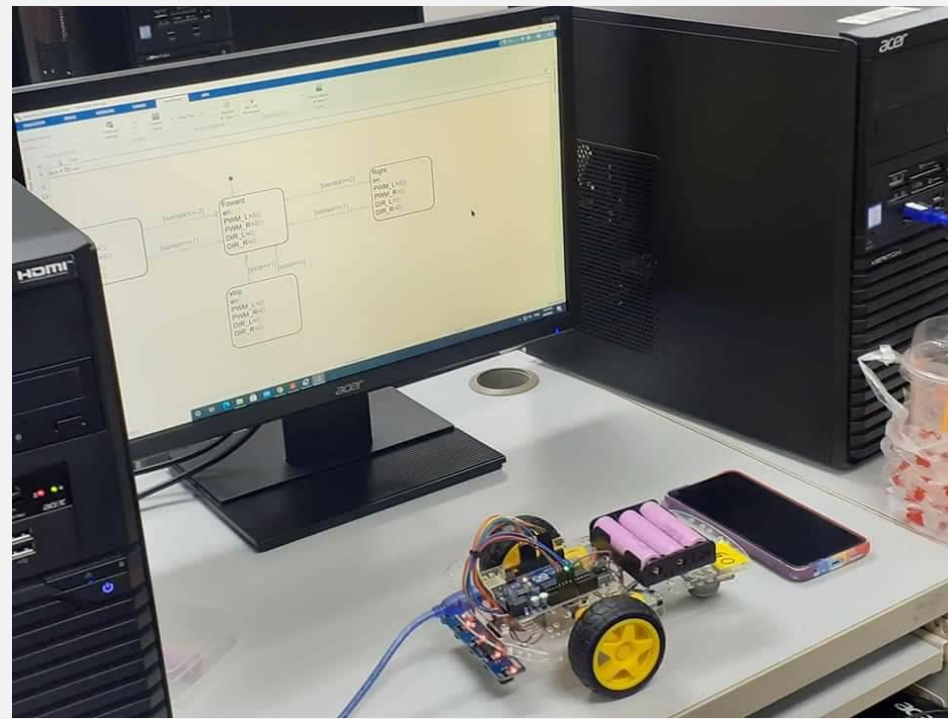


NETH talent workforce development program with university collaboration

NETH Career Identity Program



May 11, 2023 @ MATLAB EXPO 2023

TOYOTA TSUSHO NEXTY ELECTRONICS (THAILAND): NETH
PRINCE OF SONGKLA UNIVERSITY (HAT-YAI CAMPUS):PSU

KOSIN PATTANON
NATTHA JINDAPETCH

Organization overview

Prince of Songkla University (PSU) was established in 1967 as the first university in southern Thailand. The original aims of the university were to raise the general education standards and support regional industry and development.

Today, PSU is a leading public university, committed to academic excellence, reputable research and innovation. PSU is one of top 10 national research universities in Thailand by Quacquarelli Symonds'(QS) ranking.



Toyota Tsusho NEXTY Electronics, Thailand (NETH) was established in April 2005 as an offshore location for in-Vehicle embedded software development.

Since then, thanks to support from our customers, we have been growing steadily. At the same time, we have been expanding our business into various fields such as sales of car-mounted electronic devices (parts and semiconductors) and development and distribution of contents for automobiles.



Company view

- Develop talent workforce.
- Increase number of company culture compliance workforce.
- Develop training curriculum based on automotive SW development business.
- Accelerate the pace of learning for fresh graduates.

NETH Career Identity



Academic view

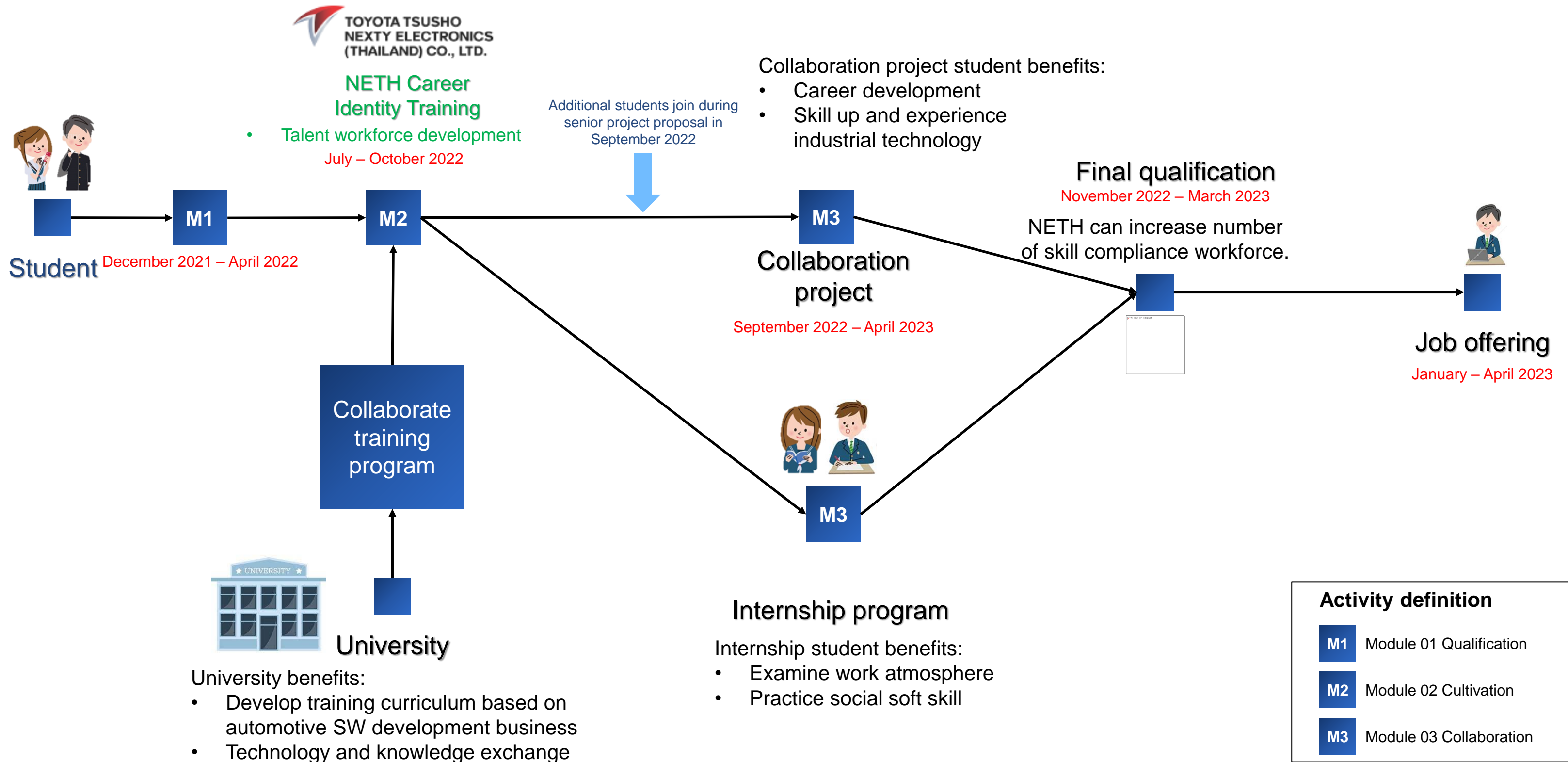
- Develop training curriculum based on industrial requirement.
- Provide skills to undergraduate students that match with industrial expectations
- Deliver **work integrated learning*** to students.
- Technology and knowledge exchange.

***Work integrated learning** is a form of curricular experiential education that integrates a student's academic studies with experiences within an industrial workplace.

Student view

- Motivate and develop student's career match with student opinion.
- Introduce industrial standard workflows in academic curriculum.
- Examine work atmosphere and company culture fit.
- Learn team collaboration with co-workers.

NETH Career Identity Activity

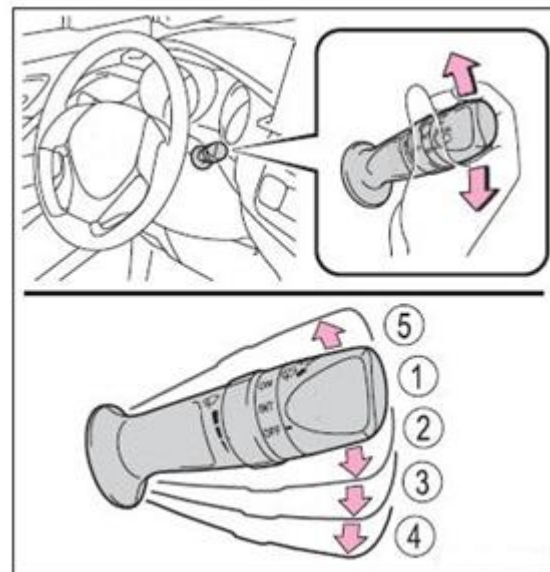


Why we develop training curriculum with MBD ?

- Easy to visualize the system operation concept with graphical simulation result
- Software functional design concept with less coding skill in beginner level
- Software product quality characteristics can applied in learning such as:
Learnability, modularity, maintainability, reusability etc. with less coding idea



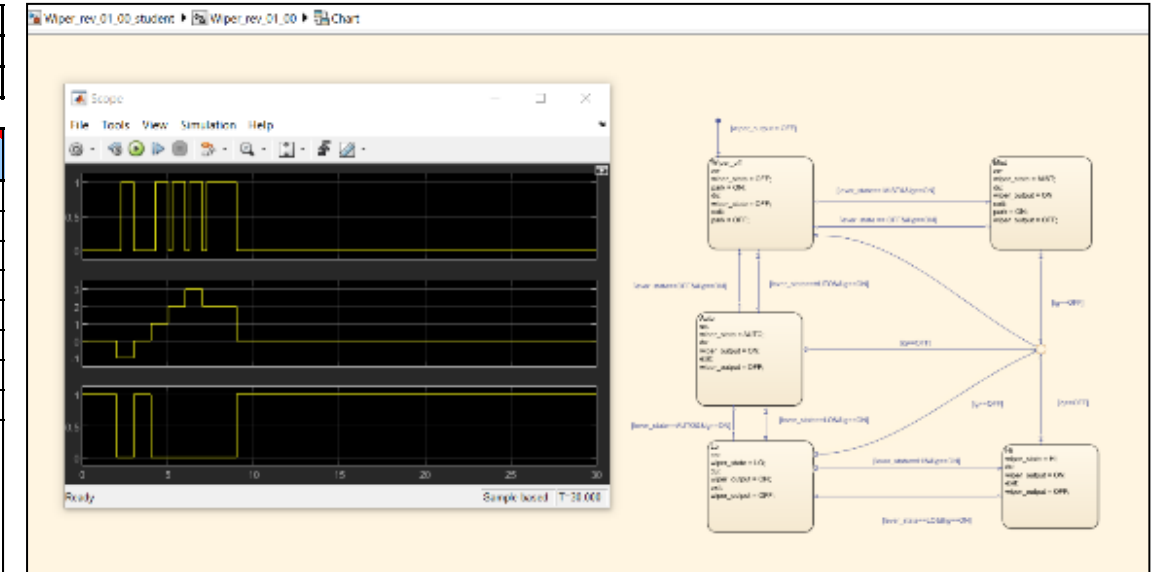
System operation



System functionality

Project Name:		Wiper	
Model name:		Wiper_rev_01_00.slx	
Project Manager Name:		-	
Project Description:		Automatic Rain Sensing Wipers	
ID	Requirement ID	Type	Functional Requirement
001	SWR-WP-00100	Overview	Wiper has inputs as follow:
001-01	SWR-WP-00101	Input	Ignition [Range OFF or ON]
001-02	SWR-WP-00102	Input	Lever [Range MIST, OFF, AUTO, LO, HI]
001-03	SWR-WP-00103	Input	Auto sensitivity [Range LOW, MED, HI]
001-04	SWR-WP-00104	Input	Washer pump spray [Range OFF or ON]
002	SWR-WP-00200	Overview	Wiper has outputs as follow:
002-01	SWR-WP-00201	Output	Wiper control [Range , WIPE_ON, WIPE_OFF]
002-02	SWR-WP-00202	Output	Wiper park
003	SWR-WP-00300	Overview	Wiper has 5 control states as follow: - off state - mist state - auto state - lo state - hi state

Functional requirement

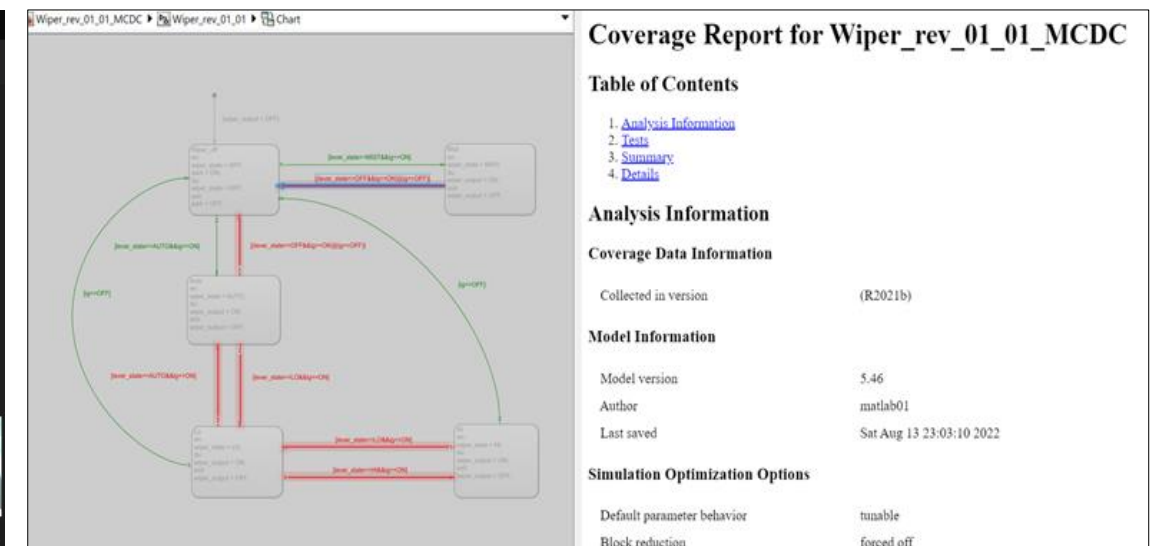


Modeling and functional test

- Use Simulink Stateflow and Simulink coverage for develop logic control system based on requirement, including model scenario test and coverage analysis to ensure correct operation based on specification and defined standard.
- Further design and verification assignment can continuously contribute to university students after company training class by a campus-wide license support from each university.



Assignment is easy to provide



Analytical skill can practice at home

Module 01 Qualification Basic MBD with MATLAB/Simulink

Specification model SW Requirement:

Variable	Quantity	Description	Type	Data type
Sensors1	1	Objects detection sensor	Input	uint8
Sensors2	1	Objects detection sensor	Input	uint8
Sensors3	1	Objects detection sensor	Input	uint8
Alarm	1	Fail state control	Input	uint8
Light	1	Operating status update	Output	uint8
PartFed	1	Output counter	Output	uint8

Light status definition:
GREEN is 2
ORANGE is 1
RED is 0

Sensors behavior:
3 sensors are generated by using Switch on hardware that can control on/off independently. When push switch is sensor ON.
ON is 1
OFF is 0

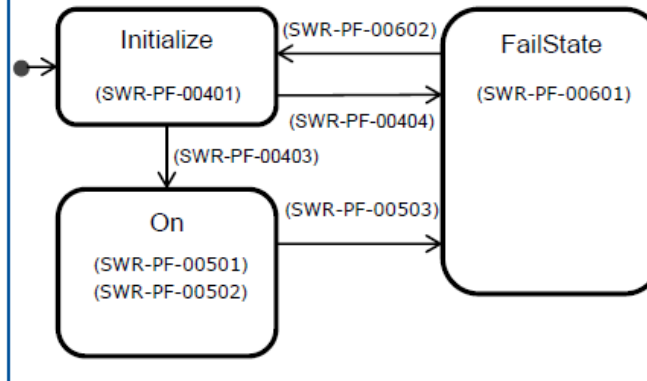
Alarm:
Alarm ON when push switch on hardware.
ON is 1
OFF is 0

Part Feeder System

Conveyor Belt, Proximity Sensor (Objects Detection), Motor 1, Counter reset, Total Objects: 5, Start, Fail

Requirement analysis

State and transition requirements



Initialize:
(SWR-PF-00401) Set Light status to **ORANGE**.
(SWR-PF-00403) All Sensors are set to **ON**, go to **On** state.
(SWR-PF-00404) If operated in **Initialize** state more than 5 sec → **FailState**.

On:
(SWR-PF-00501) Set Light status to **GREEN**.
(SWR-PF-00502) While **On** state and all of sensors set to **ON**, PartFed count up.
(SWR-PF-00503) When Alarm **ON** → **FailState**.

FailState:
(SWR-PF-00601) Set Light status to **RED**
(SWR-PF-00602) When Alarm **OFF** → **Initialize**.

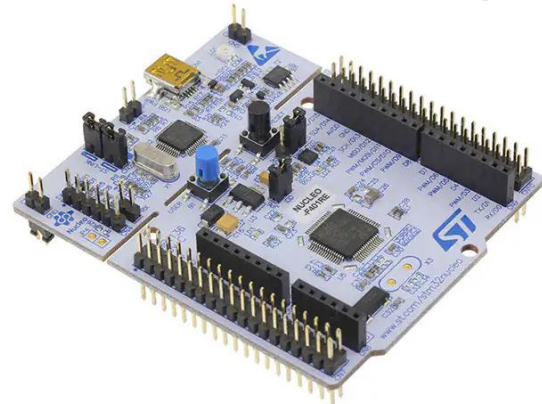
Modeling/ Requirement traceability

Circuit board diagram showing various components like sensors, a motor, and control logic.

Test and HW implementation

Module 02 Cultivation

① Embedded SW Development



- Introduction to Embedded Systems
- Interfacing
- Basic Digital Input/Output
- Serial Communications
- Analog-Digital Conversion
- Event Counters, Timers, and PWMs etc.

② Automotive SW development with MBD

- Automotive SW development overview
- Car functionality vs software module
- Model-Based Development Process
 - MBD process and process definition
 - Type of model development in MBD
 - Difference between MiL, SiL, PiL
- Model functionality test
- Model coverage verification

Simulation results showing waveforms and a coverage report.

Coverage Report for Wiper_rev_01_01_MCDC

Table of Contents

- Analysis Information
- Summary
- Details

Analysis Information

Coverage Data Information

Collection in version: (R30013)

Model Information

Model version: 3.46

Author: muelab61

Last saved: Sat Aug 13 20:08:10 2011

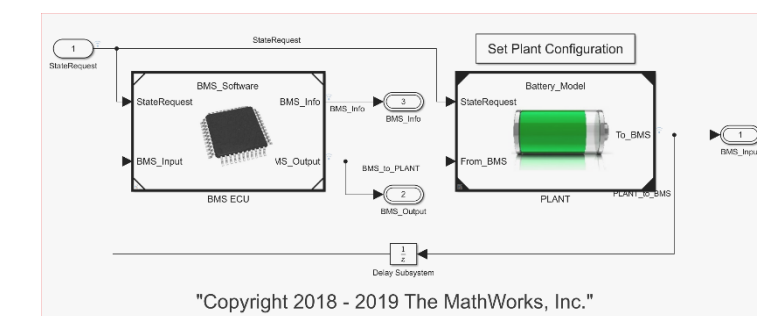
Simulation Optimization Options

Default parameter behavior: enable

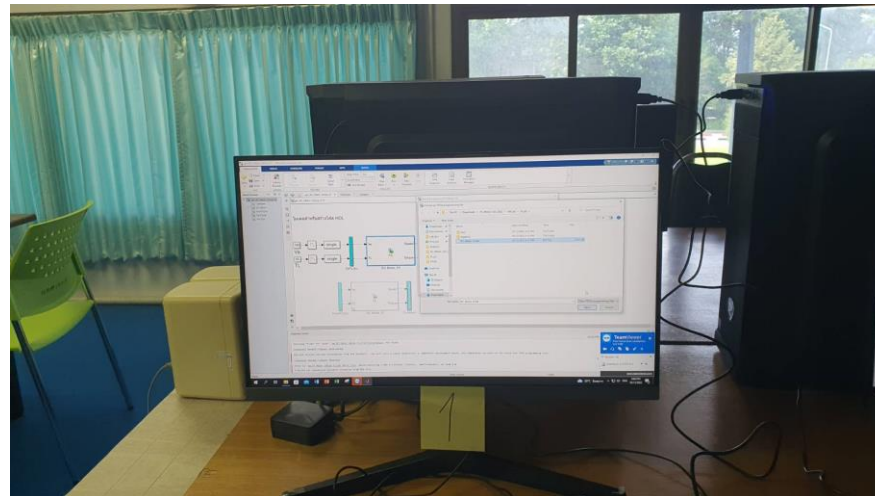
Block reduction: keep all

③ Deploying Battery Management System Algorithms

- Overview of the basic BMS operation and functionality
- Simulink for BMS application covering:
 - Cell Voltage Measurement
 - SoC Main Operation
 - State of Health
 - Cell Voltage Balancing
- BMS Safety and Protection Function
- Development BMS with MBD until HW
- Implementation and typical specification example



- **Module 02 Cultivation (Cont.)**
 - ④ **DC Motor Hardware in the Loop with FPGA (By PSU)**
 - Principle and operation overview of DC motor
 - DC motor characteristic and its mathematical model
 - DC motor modeling in s-domain
 - DC motor modeling with Simulink
 - FPGA in the Loop
 - System response and result analysis



DC motor modeling with Simulink



Workshop both online and hand-on in PSU

NETH Career Identity Program

Let's cultivate automotive software development skill and career opportunity

วันพฤหัสบดีที่ 13 ตุลาคม พ.ศ. 2565 เวลา 13:00 – 17:00 (Online)

“การสร้างแบบจำลอง **HiL** สำหรับมอเตอร์ไฟฟ้ากระแสตรงบน **FPGA**”
(ดำเนินการสอนโดยภาควิชาวิศวกรรมไฟฟ้า มหาวิทยาลัยสงขลานครินทร์)

หัวข้อฝึกอบรม

1. หลักการของมอเตอร์ไฟฟ้ากระแสตรง
2. การเขียนสมการคุณลักษณะของมอเตอร์ไฟฟ้ากระแสตรงบน s-domain
3. การสร้างแบบจำลองของมอเตอร์ไฟฟ้ากระแสตรงด้วย Simulink
4. การนำแบบจำลองที่สร้างขึ้นไปใช้จำลองการทำงานบน FPGA (FPGA in the Loop: **FiL**)
5. การวิเคราะห์ผลการตอบสนองของระบบจำลองฮาร์ดแวร์ที่สร้างขึ้น

สามารถลงทะเบียนเพื่อยืนยันการเข้าร่วมกิจกรรมได้
โดยสแกน **QR-Code** ด้านล่าง

*หมดเขตลงทะเบียน 11 ต.ค. นี้

Embedded Software & System

Battery Management System

Model-Based Development

Set Plant Configuration

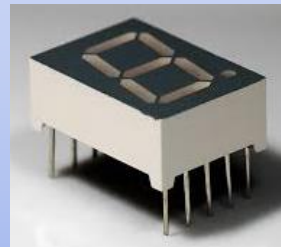
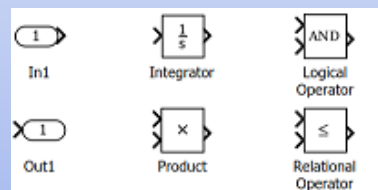
Battery Model

Module 03 Collaboration and its outcome

March 2022

Module 01 Basic MBD course

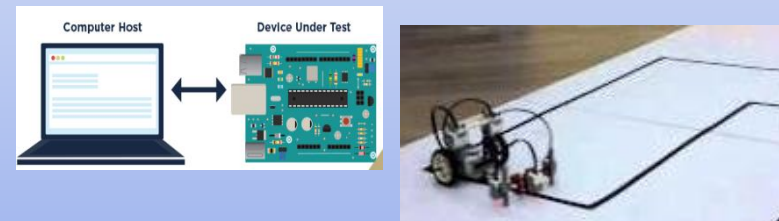
- Understand what MBD is
- Learning how to use Simulink block
- Practise MBD with 7 segment simple model



June 2022

Next Gen Higher Education MBD course

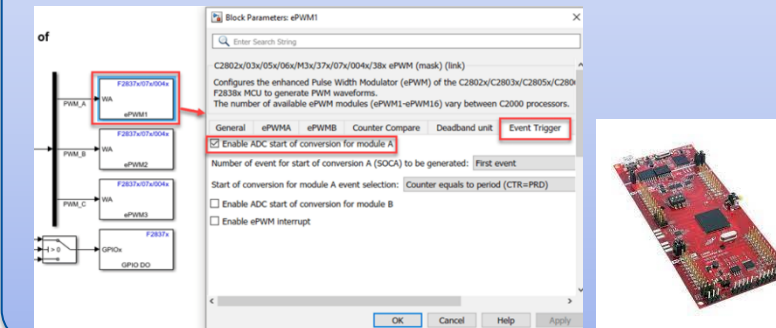
- Learning how to build and deploy model to hardware
- Learning how to use hardware in the loop
- Adaptation MBD with line following robot



December 2022

New staff Co-operation training

- Learning back to back test
- Learning hardware support package Simulink blockset
- C language and embedded system



Mr. Muhammad Samoh
Cooperative Internship student
Walailak university

"I have done PMSM motor drive by using a Rapid Control Prototype concept. A lot of hardware blockset included in MATLAB/Simulink helped to reduce manual coding to control hardware."



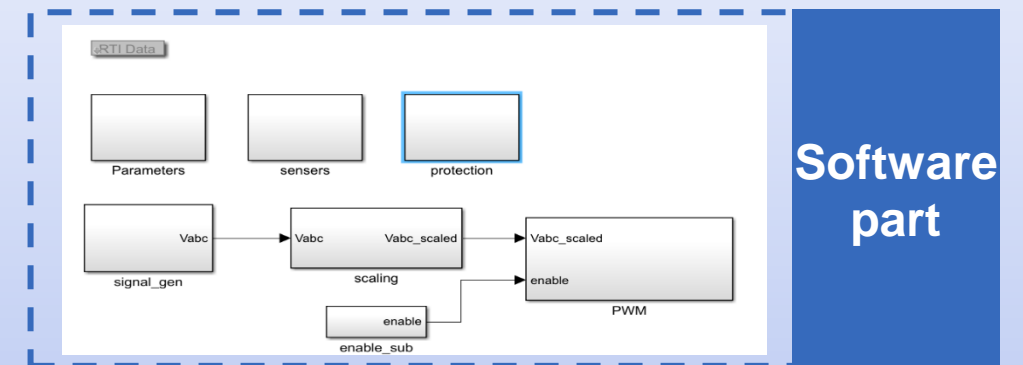
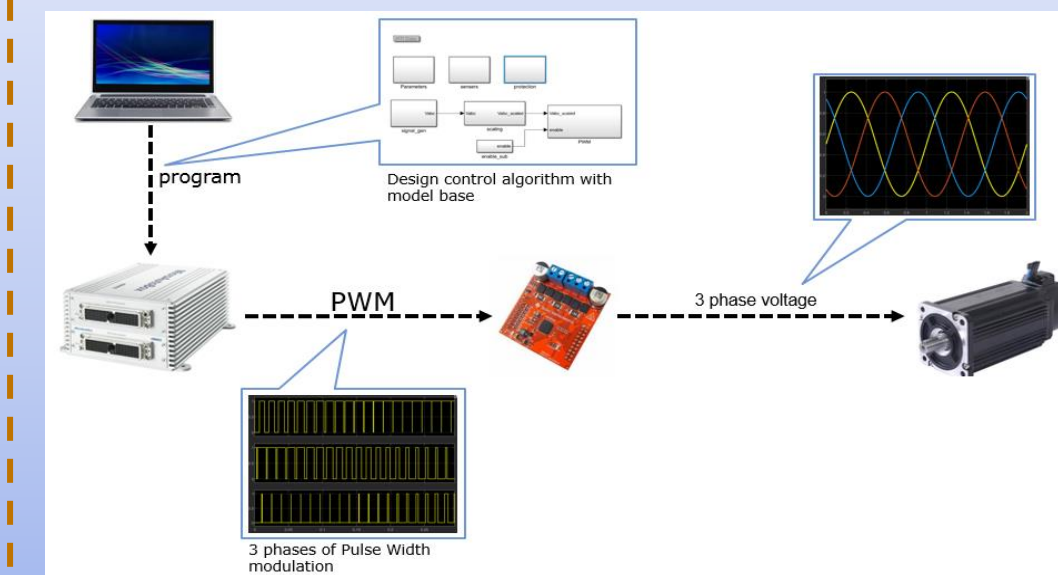
Mr. Patompong Musika
Cooperative Internship student
Prince of Songkla university

"According to COVID-19 pandemic, I have to apply a lot of online learning session however this activity fulfilled my practical skill for measurement and instrument usage also improved my analytical and problem solving skill."

January – February 2023

Co-operation project: PMSM motor drive by adaptation rapid control prototype (RCP) concept

Concept

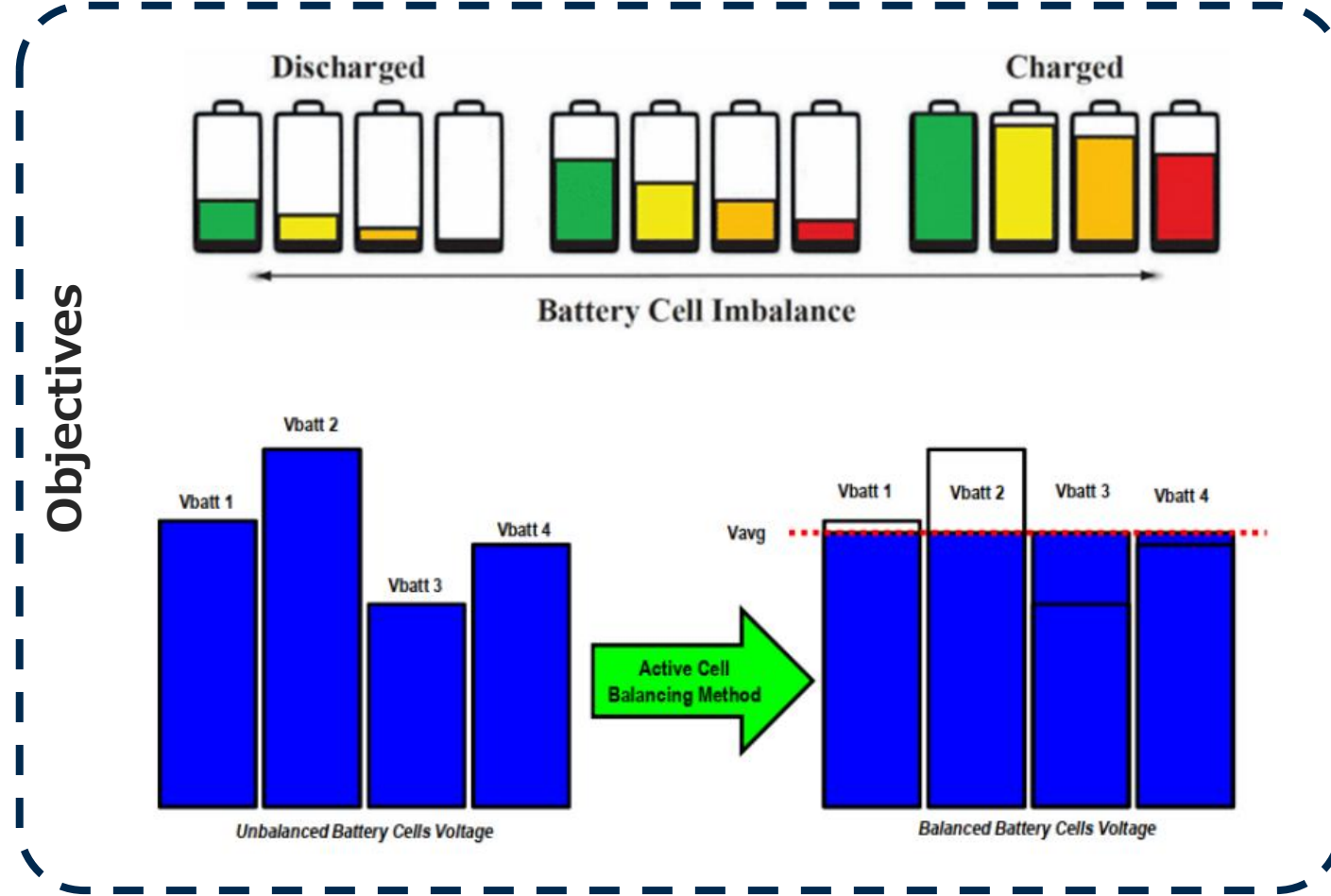


NETH-PSU Collaboration Program since 2016

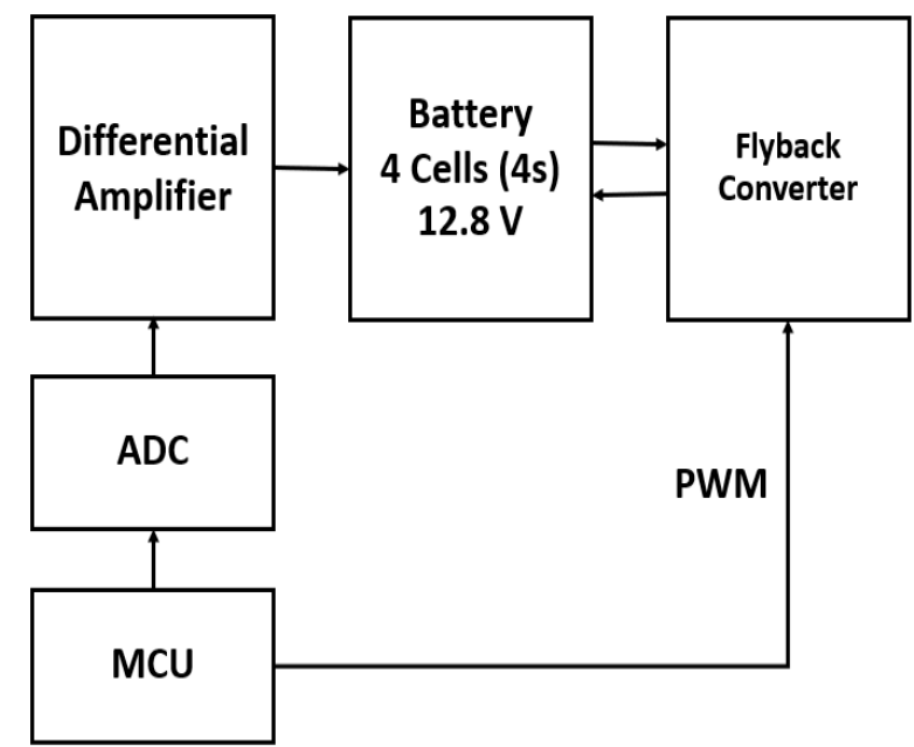


NETH – PSU Student Senior Project Collaboration

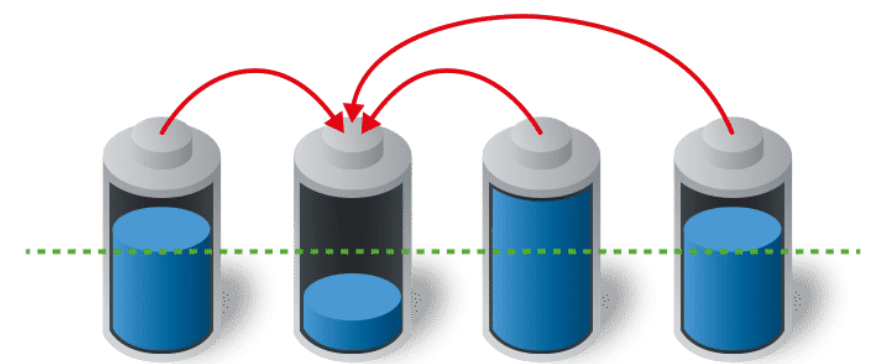
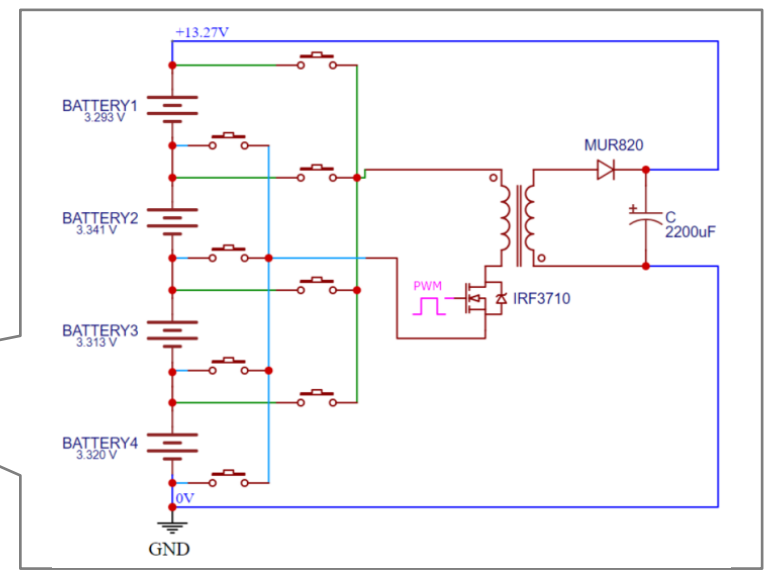
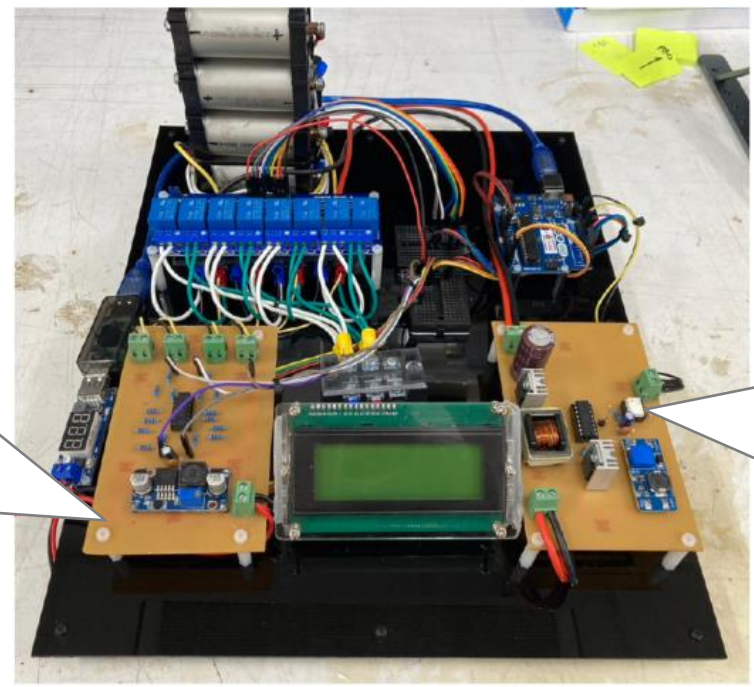
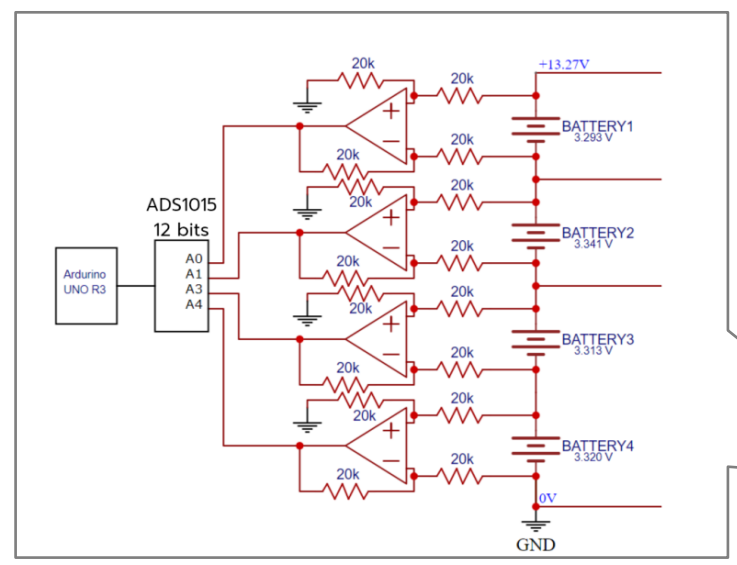
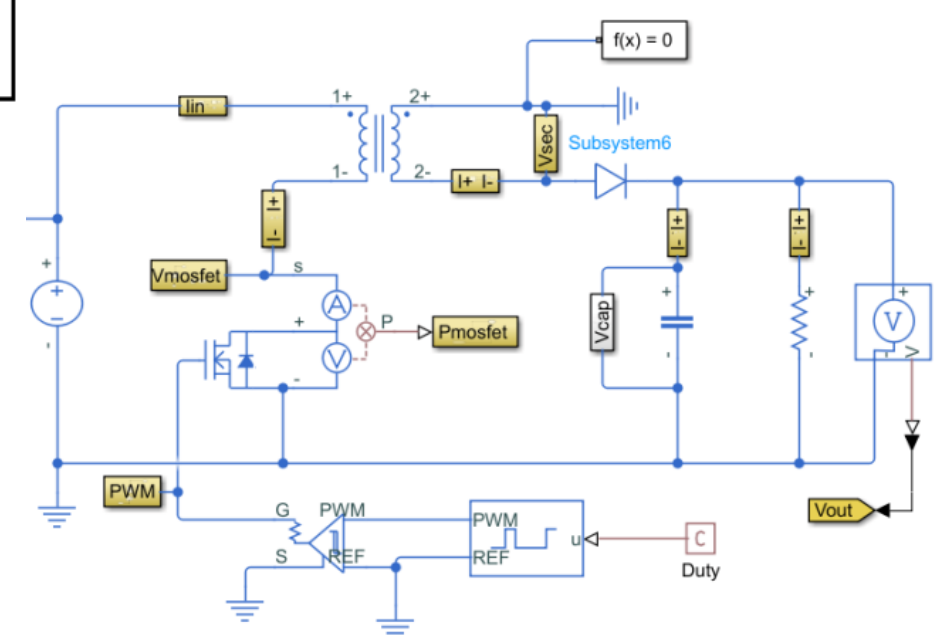
Battery Cell Active Balancer



Block Diagram



Flyback converter in Simulink

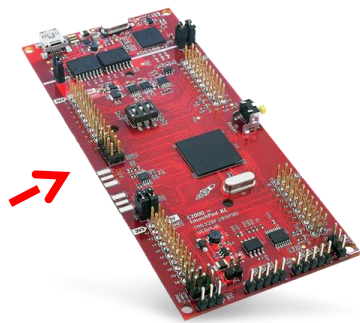


Voltage Measurement

Active Balance

3-Phase Motor Drive for Electric Shuttle Bus

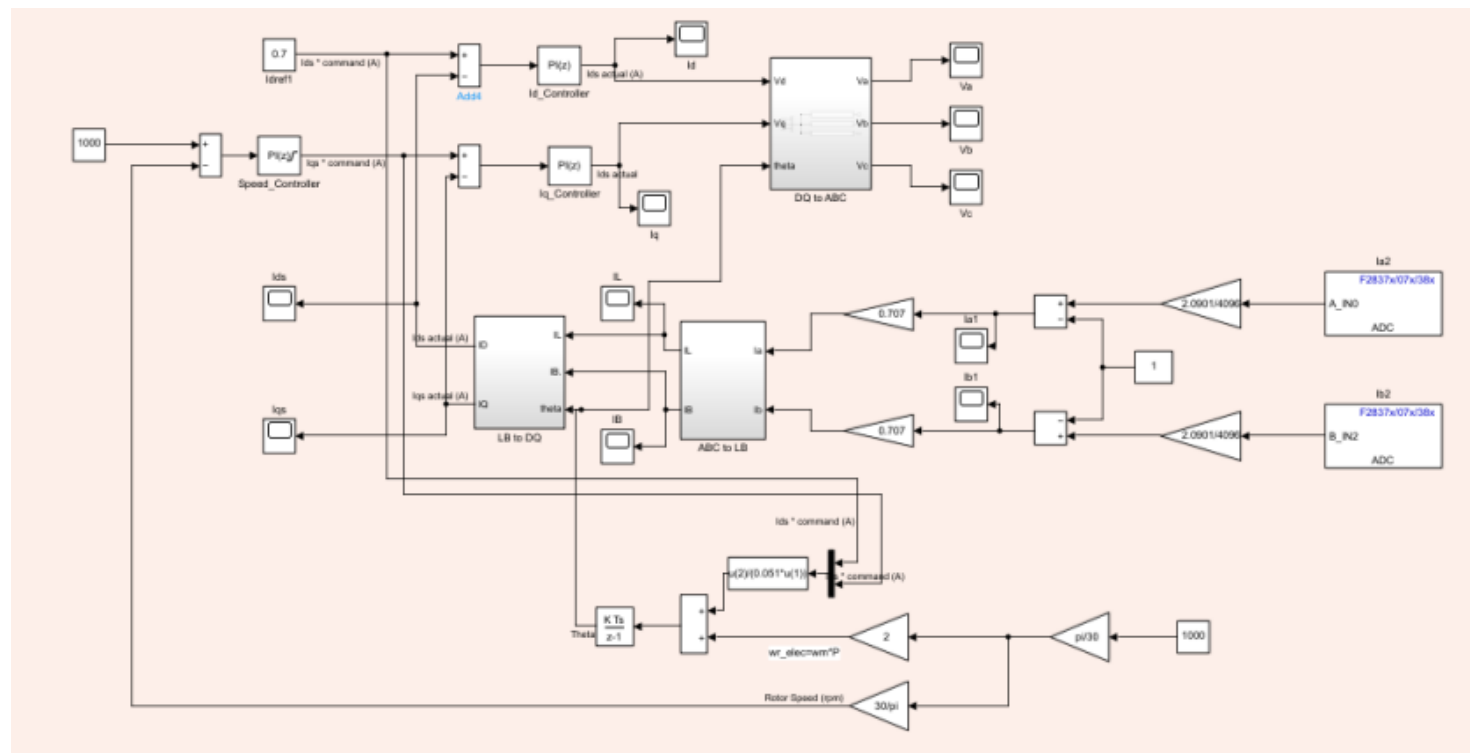
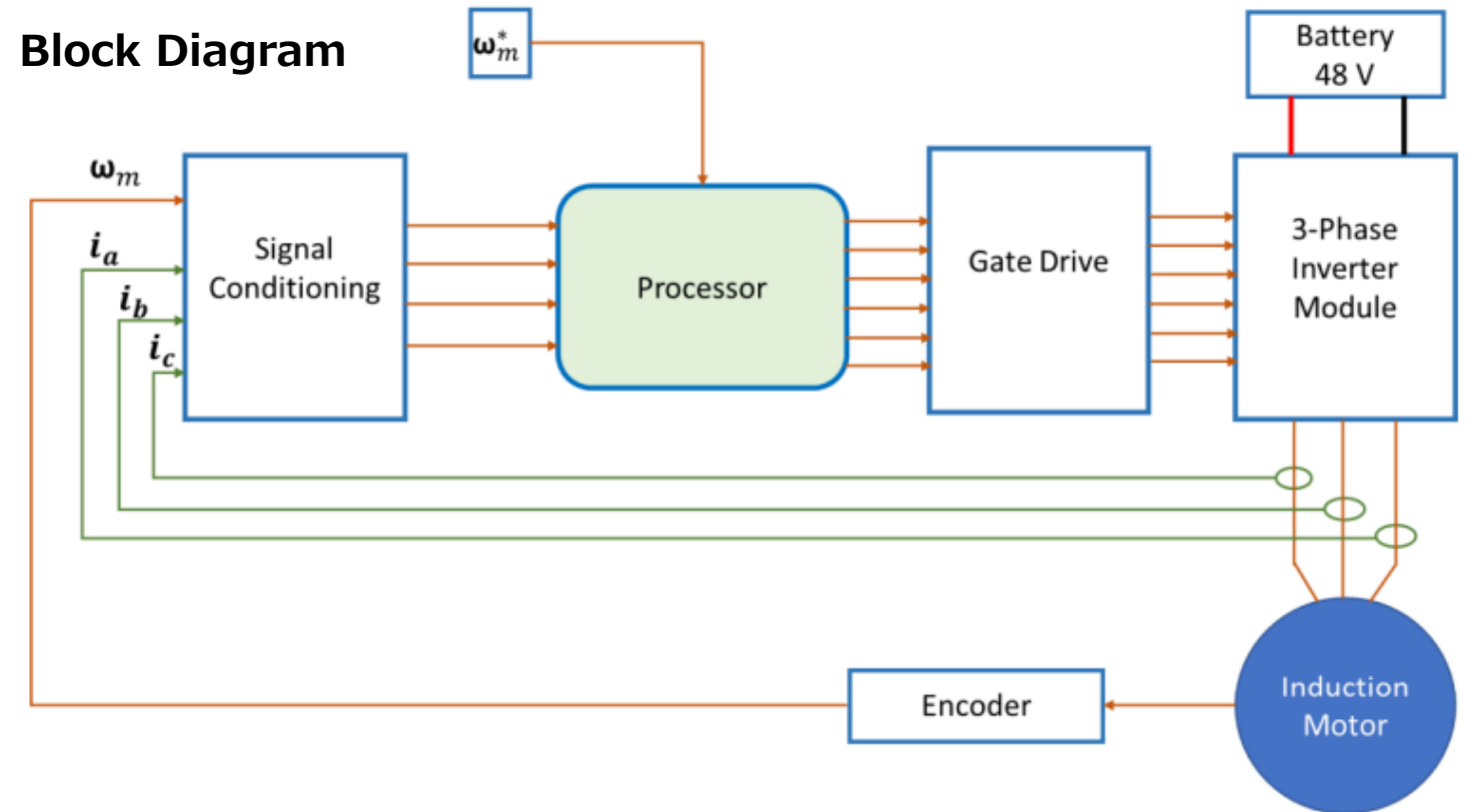
Objectives



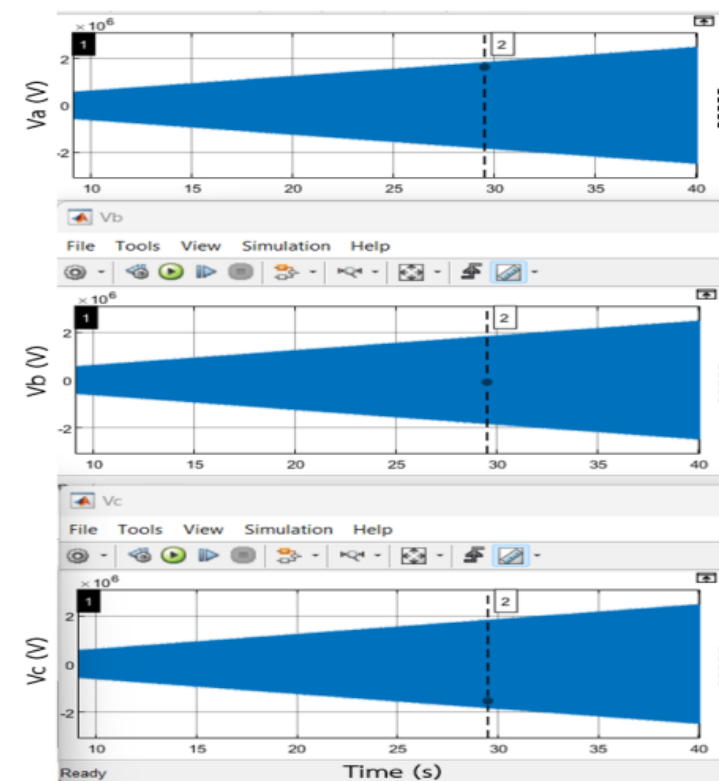
TI C2000

FOC MOTOR DRIVE BOARD

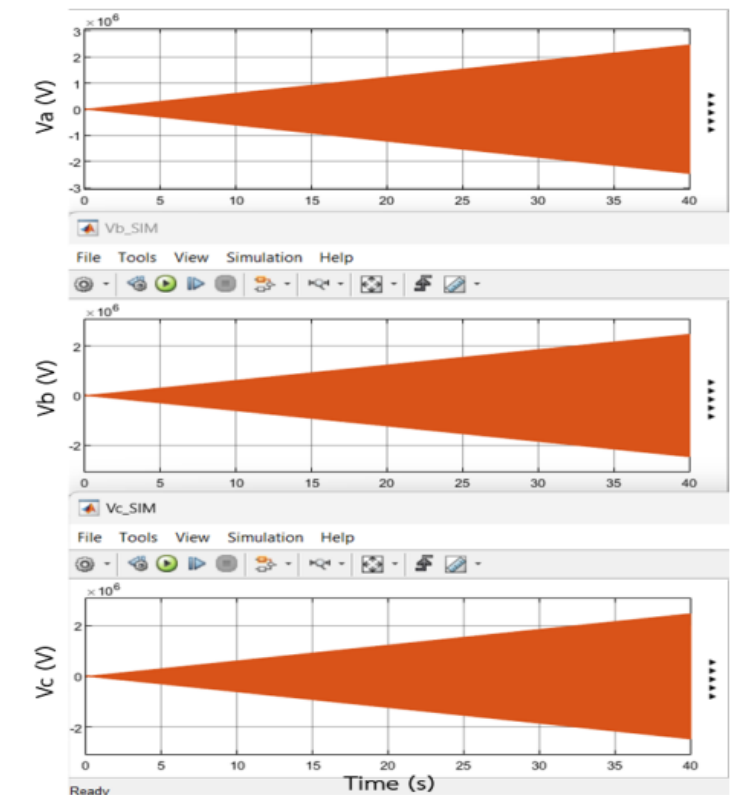
Block Diagram



Field Oriented Control Model

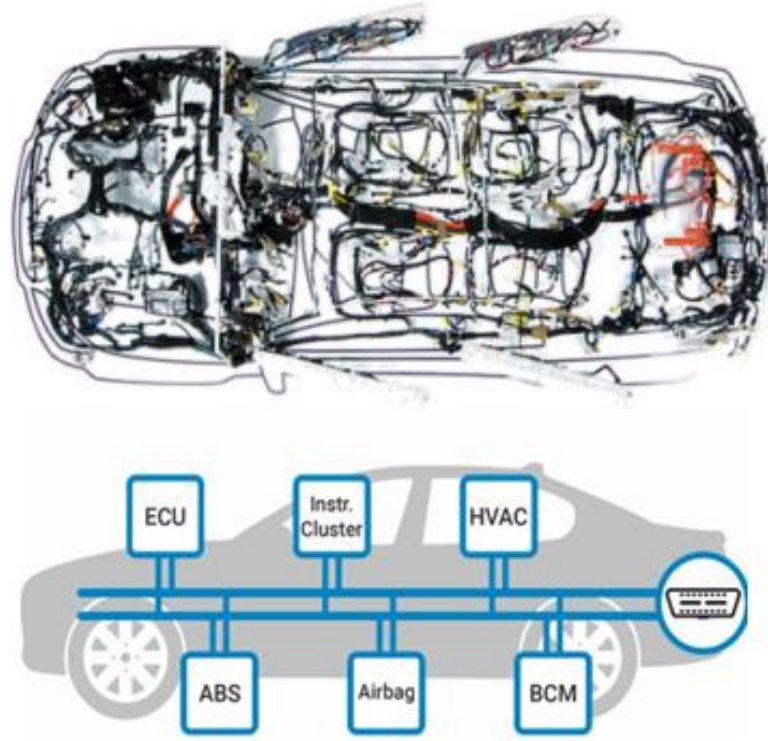


Result: TI C2000

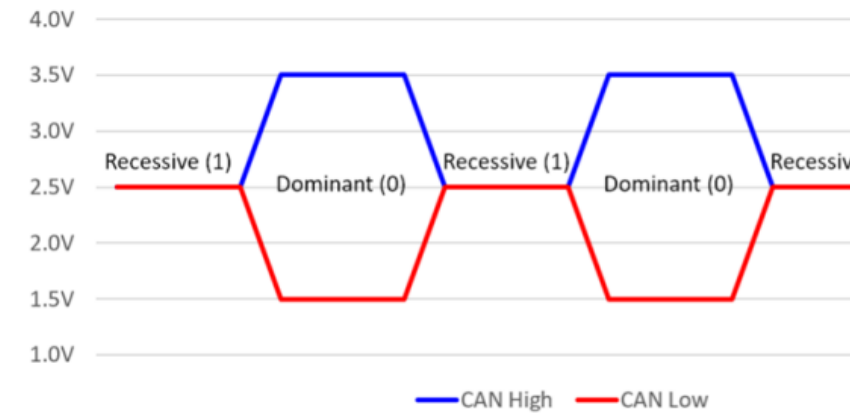
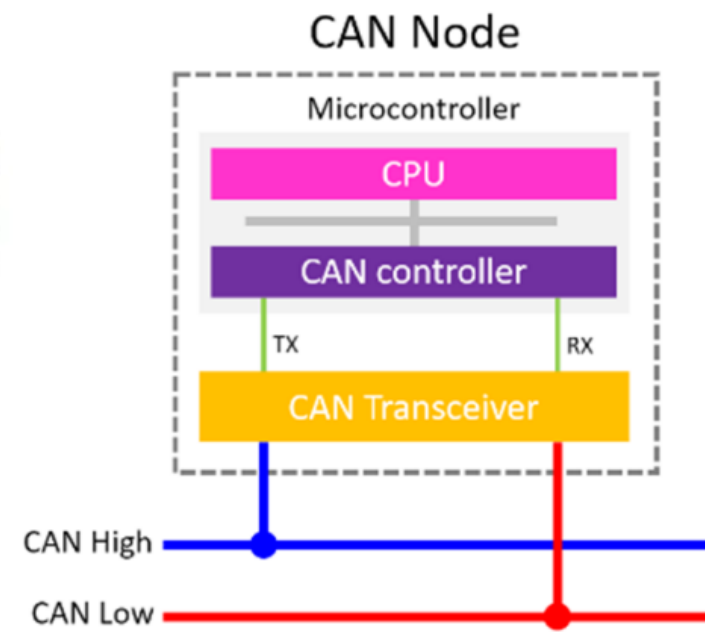


Result: MATLAB & Simulink

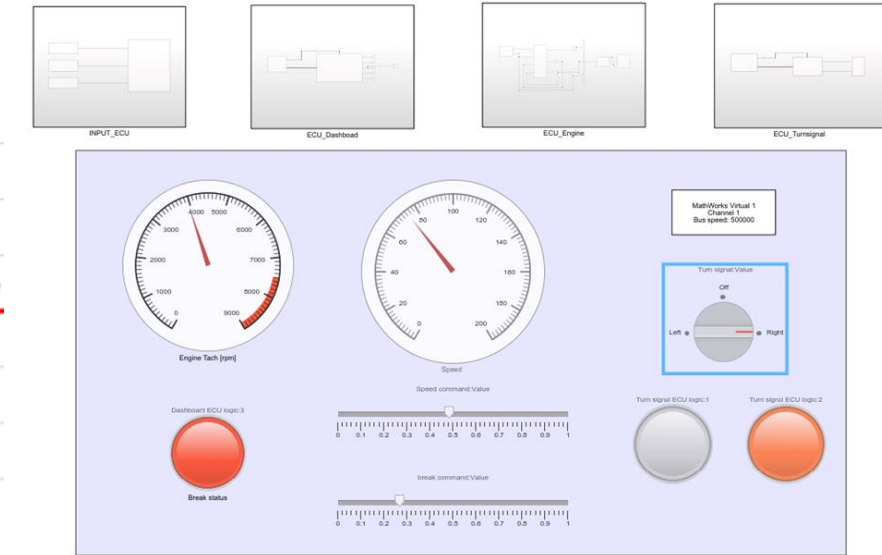
Design of a CAN Bus Communication in Electric Vehicles



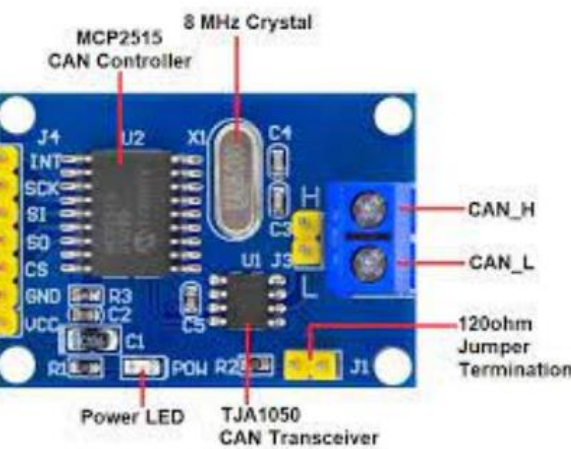
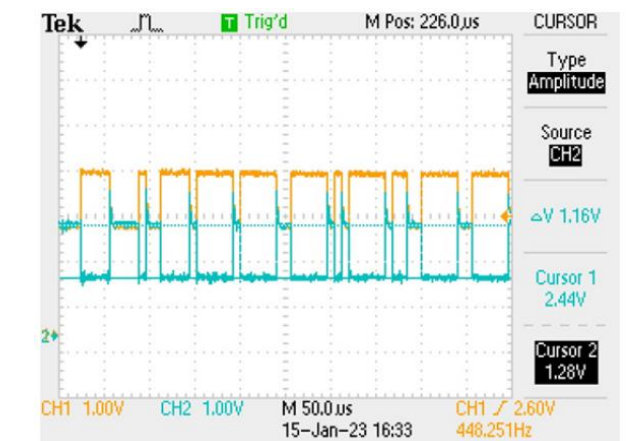
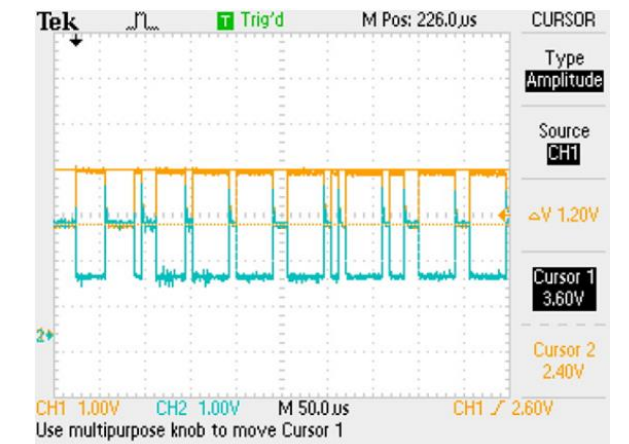
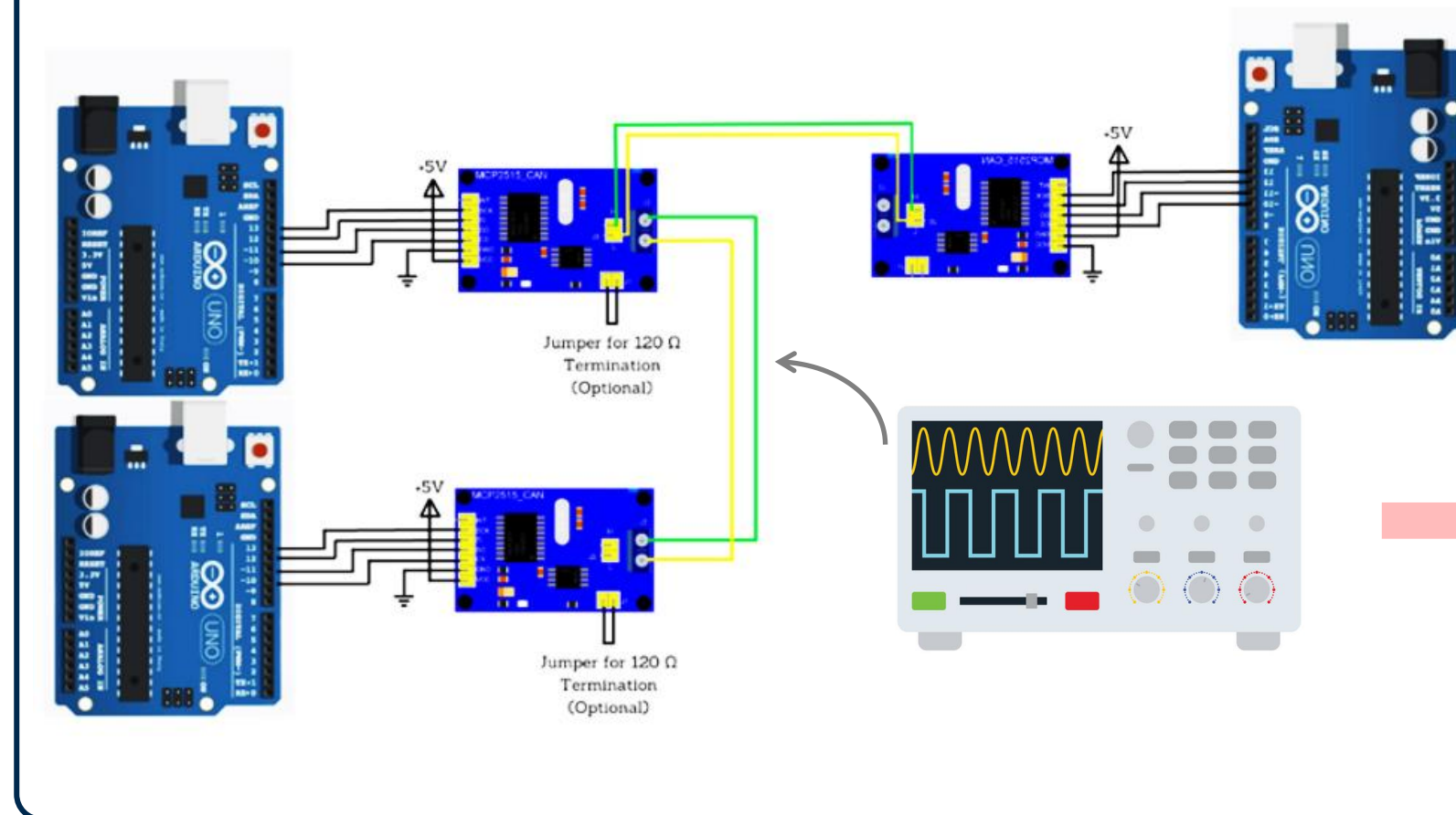
Communication in Electric Vehicles



CAN model in Simulink



CAN Bus Communication



CAN Bus Module



Mr. Pisit Palasinmongkol, 4th year Electrical Engineering (Power), PSU

“My project is Battery Cell Active Balancer. I learn battery behaviour and design flyback converter on MATLAB/Simulink before designing the real hardware.”



Mr. Pongpon Poonpakdee, 4th year Electrical Engineering (Power), PSU

“ My project is 3-Phase Motor Drive for Electric Shuttle Bus. I build MBD (Model Based Design) for PI control in MATLAB/Simulink. The signals can be real-time display in computer. This helps me easily fine-tune the PI coefficients. ”



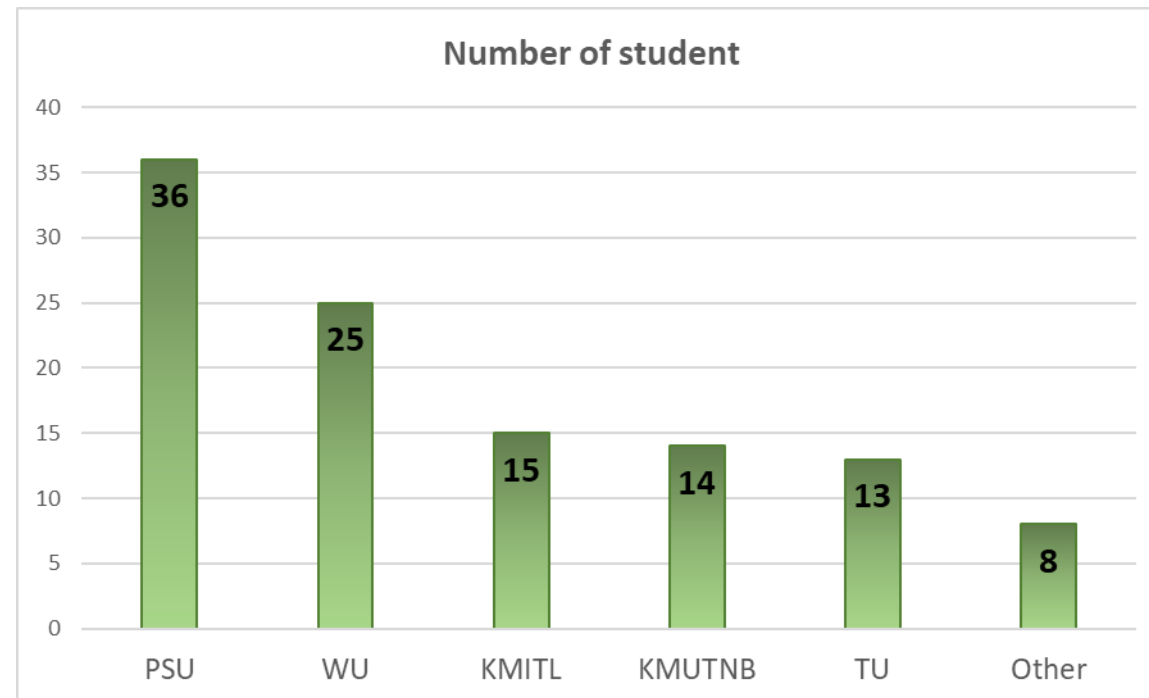
Mr. Pannatorn Khansai, 4th year Electrical Engineering (Electronics), PSU

“ My project is Design of a CAN Bus Communication in Electric Vehicles. MBD (Model Based Design) in MATLAB/Simulink can create the systematic thinking in design of CAN bus. ”

Collaboration Outcome: NETH

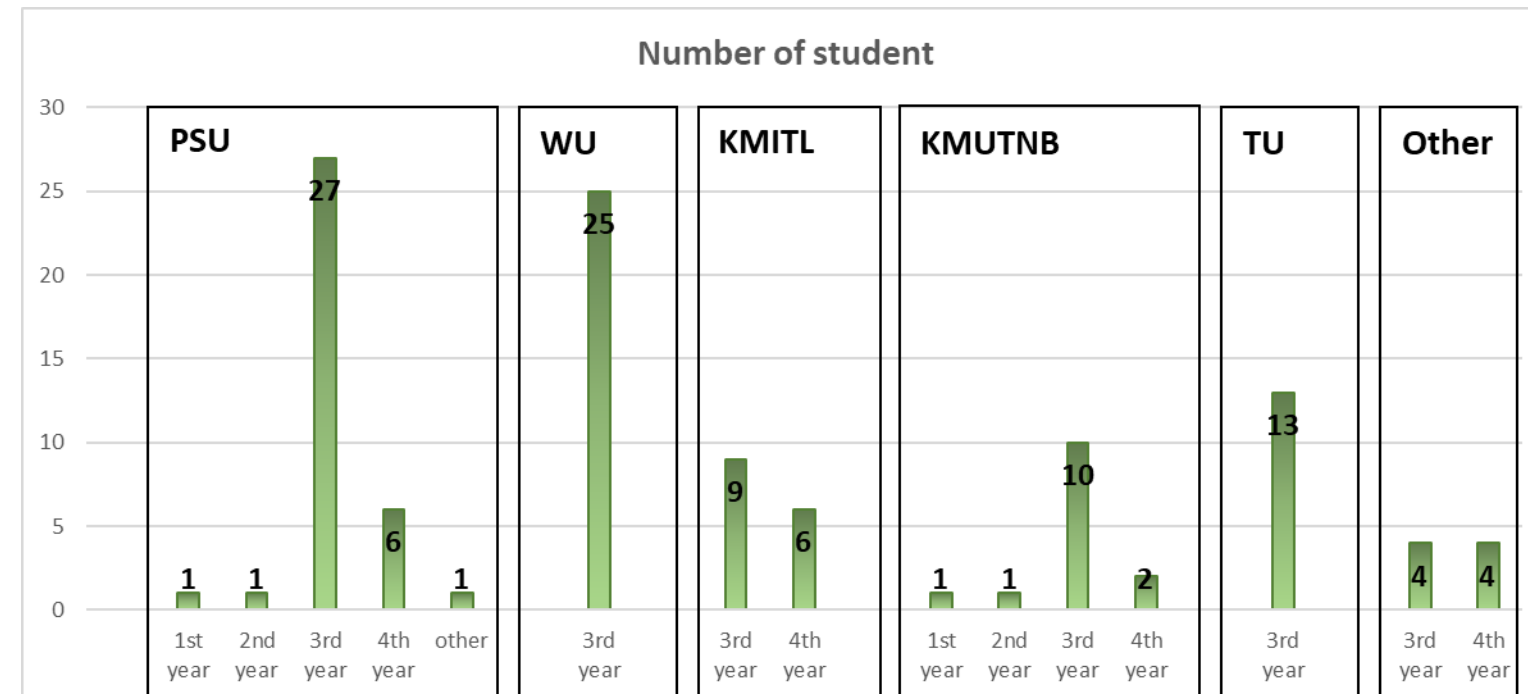
- In fiscal year 2022, number of undergraduate students who join NETH training shown as below:

By University



University	Number of student
PSU	36
WU	25
KMITL	15
KMUTNB	14
TU	13
Other university	8
Total	111

By Year of studying



- The most student joined training program is the 3rd year undergraduate students.

Abbreviation:

PSU: Prince of Songkla University

WU: Walailak University

KMITL: King Mongkut's Institute of Technology Ladkrabang

KMUTNB: King Mongkut's University of Technology North Bangkok

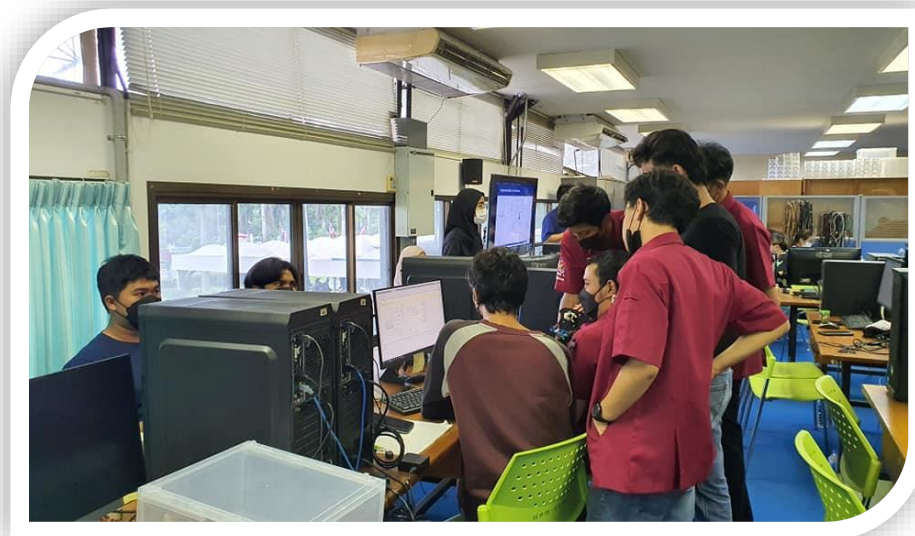
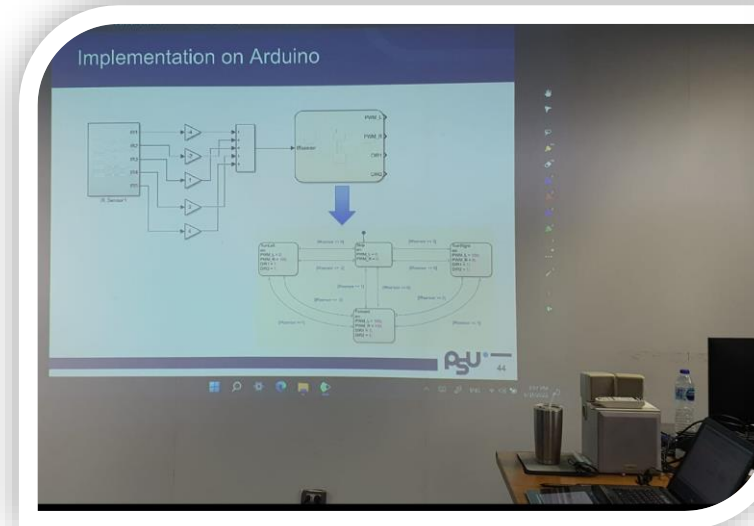
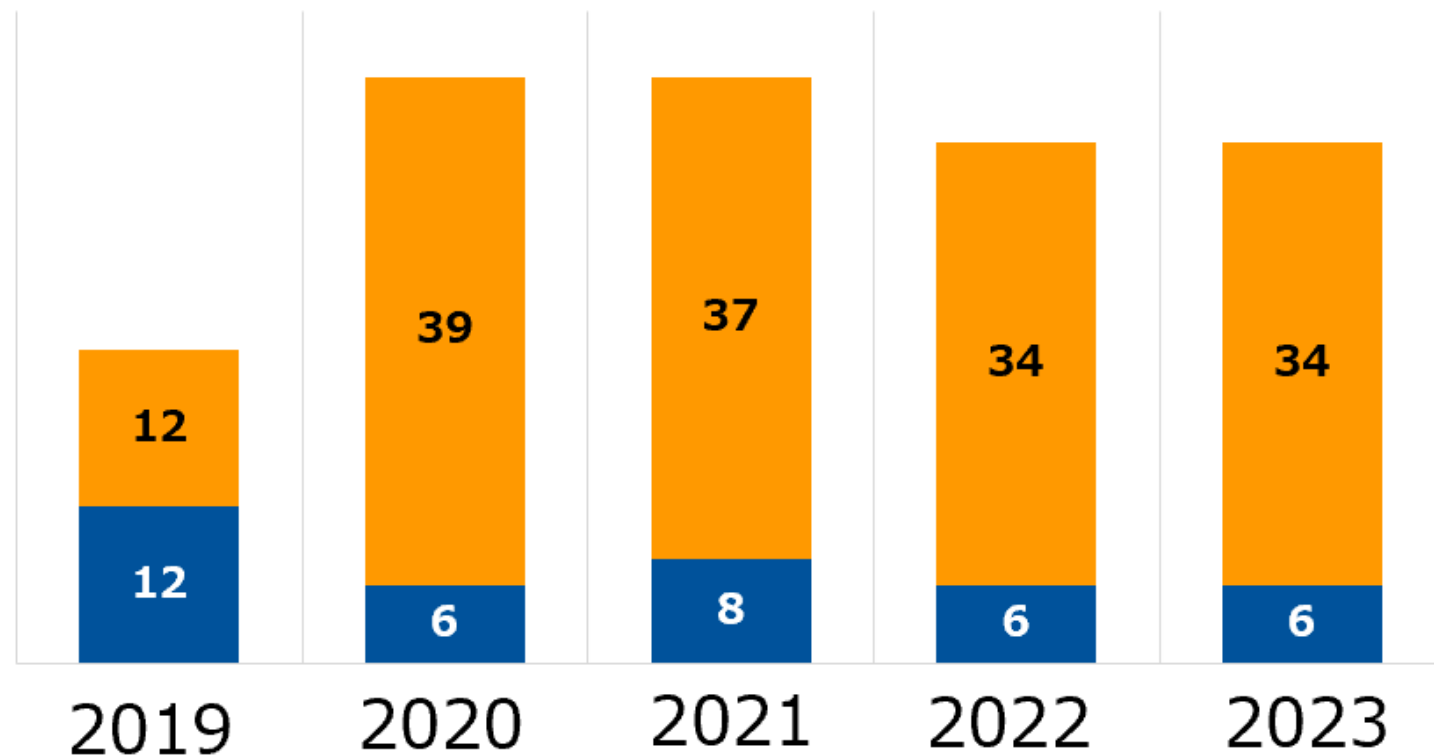
TU: Thammasat University

Collaboration Outcome: PSU

- Next Generation Higher Education funding from Ministry of Higher Education, Science, Research and Innovation

MBD TRAINED ENGINEERS

■ NETH hiring ■ Others



Benefit to Academia

- Training curriculum based on industrial requirement.
- Undergraduate student's skill matched with industrial expectations.
- Technology and knowledge exchange between university and industrial organization.

Benefit to Toyota Tsusho NEXTY Electronics, Thailand

- Skill and knowledge compliance workforce.
- To accelerate the pace of learning for fresh graduate staff.
- Training curriculum based on automotive SW development business.



FACULTY OF
ENGINEERING
PRINCE OF SONGKLA UNIVERSITY

Thank you for your collaboration

TOYOTA TSUSHO
NEXTY ELECTRONICS
(THAILAND) CO., LTD.

TOYOTA TSUSHO
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