MATLAB EXPO

Formalizing Requirements and Generating Requirements-Based Test Cases

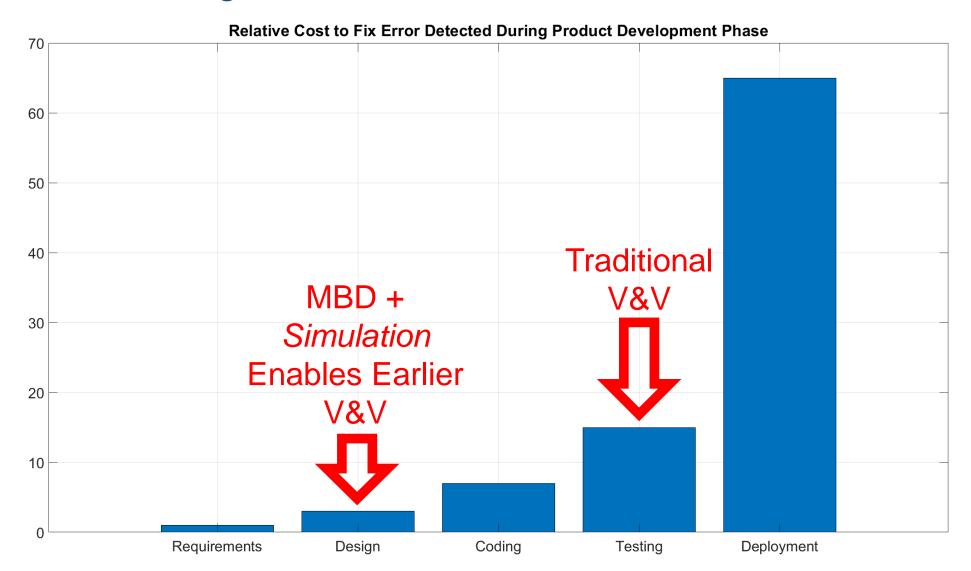
Dalton L'Heureux, MathWorks





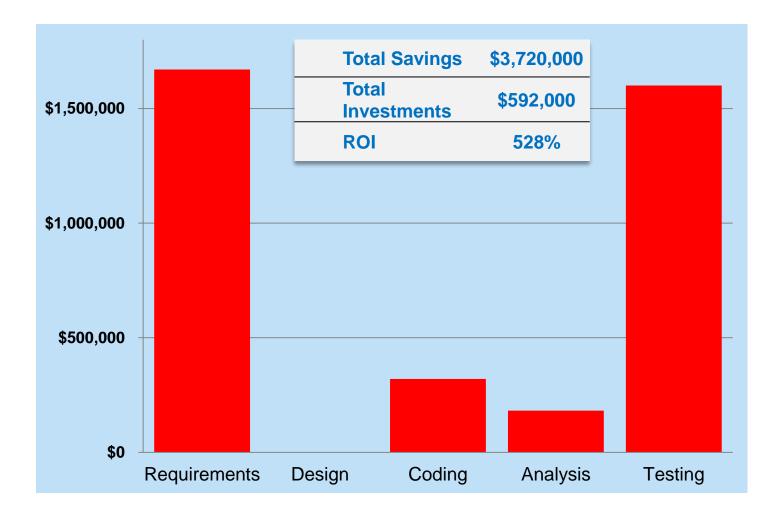
Why Model-Based Design Anything?

Model-Based Design: Detect Error Earlier to Minimize Costs

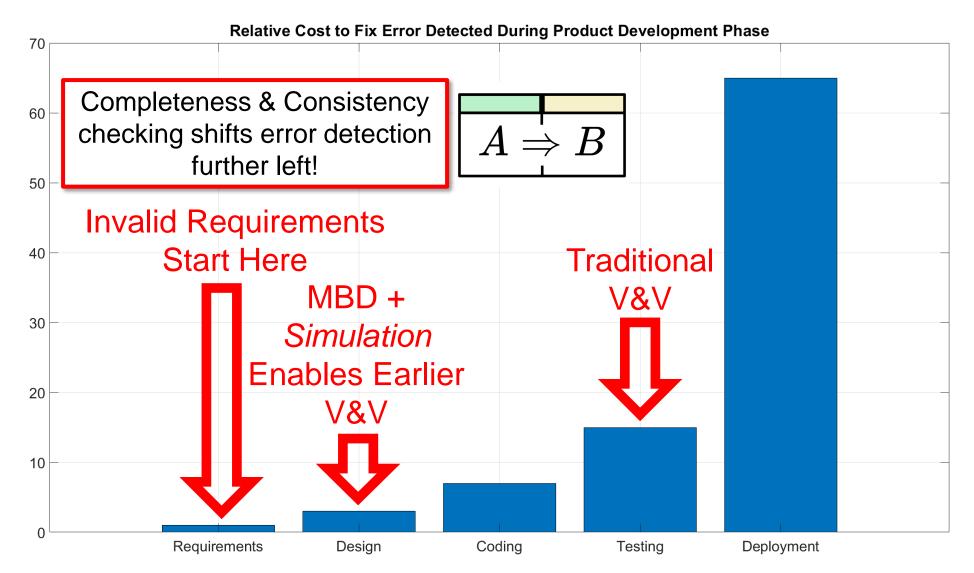


Data gathered by Hewlett Packard referred by XB in 2017 https://xbsoftware.com/blog/why-should-testing-start-early-software-project-development/

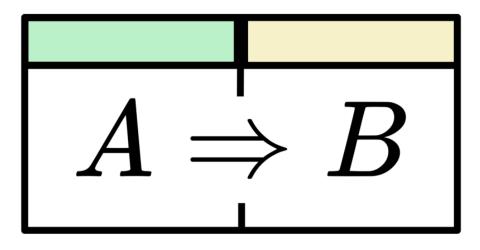
Model-Based Design ROI Calculation for Aerospace Applications



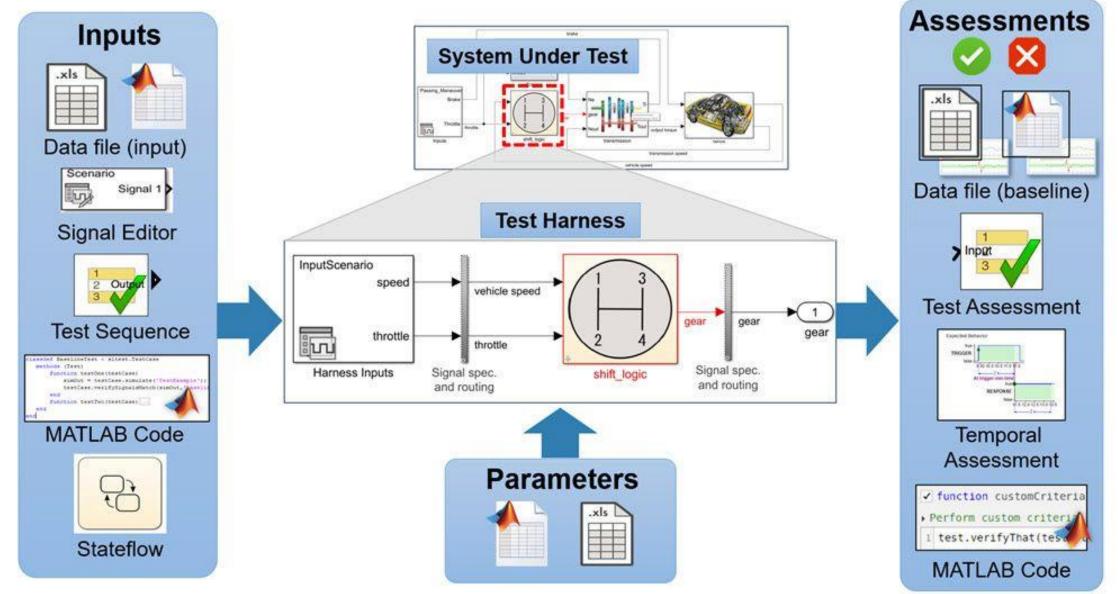
Can we Detect Errors Even Earlier?



Let's Look at an Example!

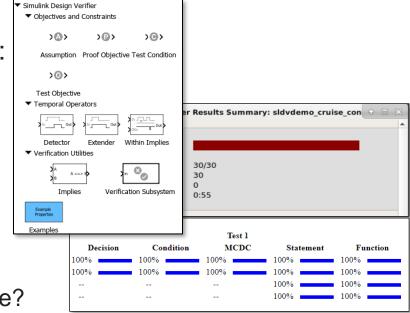


#1: Manually Author Tests with Simulink Test



#2: Generate Tests off Requirement Models Using Simulink Design Verifier Blocks

- Simulink Design Verifier can generate test cases that satisfy coverage objectives for your model, including Decision, Condition, MCDC, Relational Boundary, and Custom Objectives.
- Custom Objectives are modeled using the following constructs:
 - <u>Test Objective</u> Define values of a signal a test case must satisfy
 - Test Condition Constrain values of a signal
 - <u>Verification Subsystem</u> Conceals logic/objectives from analysis
- What do your test cases ACTUALLY mean?
 - Structural Coverage Based Tests?
 - Low-Level Requirements Based Tests used to test generated code?
 - Requirements Based Tests generated from an *Independently* developed requirement model?
 - Requirements Based Tests generated from a Design Model? What about with *Independently* defined expected outputs?



#3: Generate Tests off Requirement Models Using the Requirements Table Block

N	odeLogicSpec	Requirements Table														
Re	quirements	Assumptions														
_	Index	Summary	Precondition										-		Postcondition	
0	Index		getSimulationTime()	== 0	getPrevi	ous(Mo	ode)							Duration Mode		
1															WaitForComms	
2			false													
			14100													
2	.1			WaitFo	ns	GCSCmds.WIFIconnected && GCSCmds.BTconnected							Init			
2	.2					GCSCmds.CalibrateCmd							Calibration			
2	.3					bration	GCSCmds.GCS_MissionMode = State.CalibrationDo							ReadyForTO		
2	.4		Inconsistent with requirement 2.7		Read	1.5			-	1000	la de O		Orred		O - l'har tie e	
2	.4	Time 0-0.2 Step 1-3				0.3	0.4 5	0.5	0.6	0.7			Cmd		Calibration	
2	.5		GCSCmds.EMERGENCY_OFF		Read	4 6-0110	0	6 1 0	0	8 0 0	9 0 ISB	10 0			TrackAlt	
2	.6		GCSCmds.BTconnected	1	Tra	o Igkait	0	0	0	0 toe.A	•	0 0- Sing 0	e(0.1)		Track3D	
2	.7	A	GCSCmds.CalibrateCmd GCSCmds.GCS_MissionMode	0	Tra	o okait	0	0	0	1	o ~ise	0			LostBall	
2	.8	٨	IsBall State.CalibrationDone State.V_BODY	1	Tra 509 0.54371]	0	0	0	0	0	1 0] [000]	0	== uint8(2) ingle(3)		Land	
2	.9		State.Angles State.Altitude	[-0.00363 7.1 [2.9851 -1.37 -1.3077			[0 0 0] [-1.3963 2.3963 0 0	-			0	10001	/		LostBall	
				2.5219		0	0	0	0	0	-	0				

Additional Resources

Product Page:

Requirements Toolbox - MATLAB & Simulink (mathworks.com)

Documentation:

- <u>Requirements Toolbox Documentation (mathworks.com)</u>
- <u>Requirements Definition (mathworks.com)</u>
- <u>Requirements Table Block (mathworks.com)</u>
 - Use a Requirements Table Block to Create Formal Requirements (mathworks.com)

Examples:

- <u>Requirements Toolbox Examples (mathworks.com)</u>
- Formalize Requirements in Simulink Models Examples (mathworks.com)

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Thank you



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