

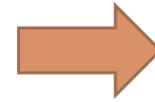
# MATLAB EXPO

## Towards Safe Driving in Unstructured Environments

*Prof. C. V. Jawahar, IIIT Hyderabad*



# Structured to Unstructured Environments



Challenges in Perception and Reasoning

- Density
- New Objects
- Diverse Objects
- Complex Movement Patterns
- Crowd/Poor-Visibility

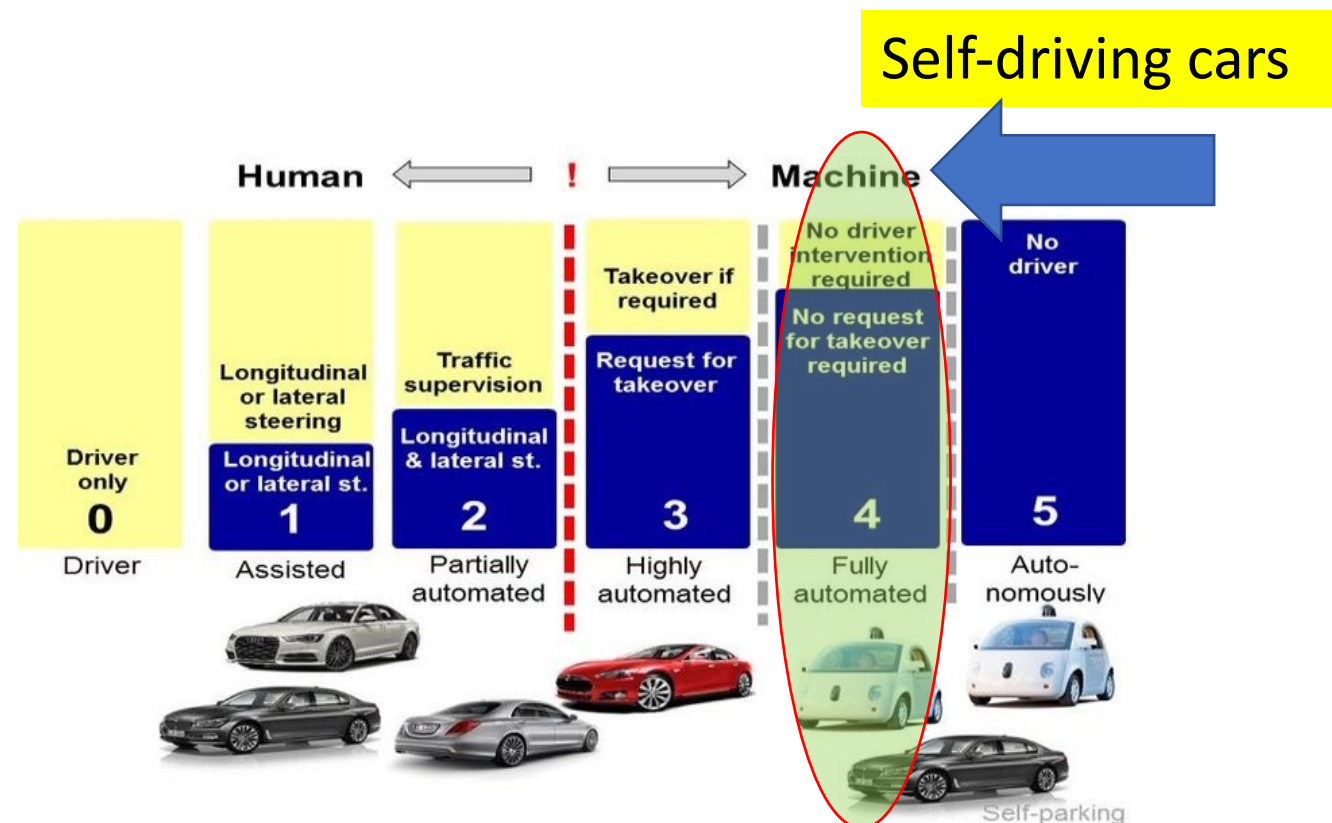
# Future of Driving – Cars with Artificial Intelligence (AI)



Source: <https://www.youtube.com/watch?v=S1DZi0x0Uhk>



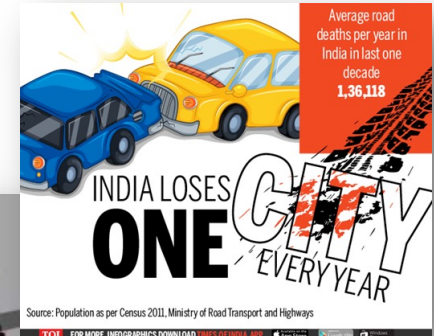
Source: <https://www.youtube.com/watch?v=HPWGFzqd7pl>



[https://www.researchgate.net/figure/Levels-of-autonomous-driving-according-to-SAE-J3016\\_fig1\\_322368082](https://www.researchgate.net/figure/Levels-of-autonomous-driving-according-to-SAE-J3016_fig1_322368082)

# How Safe are Indian Roads ?

- Enhancing road safety is an important mission for India
  - One death every 4 minutes
  - 17 deaths every hour in India
  - India loses 3% GDP every year to road deaths

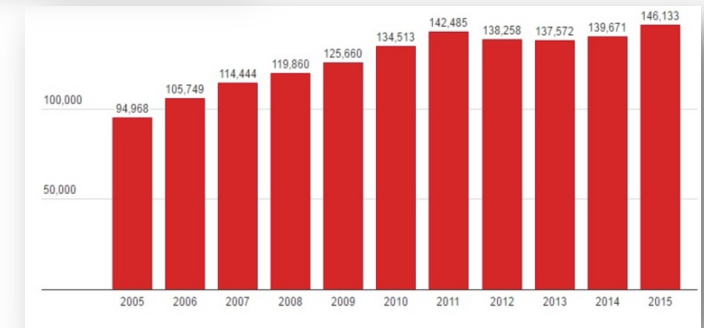


**India way behind 2020 target, road accidents still kill over a lakh a year**

Priya Kapoor | TIMESOFINDIA.COM | Updated: Oct 4, 2018, 20:55 IST

**India tops in road deaths; Globally fatalities increase by 1 lakh in 3 years: WHO report**

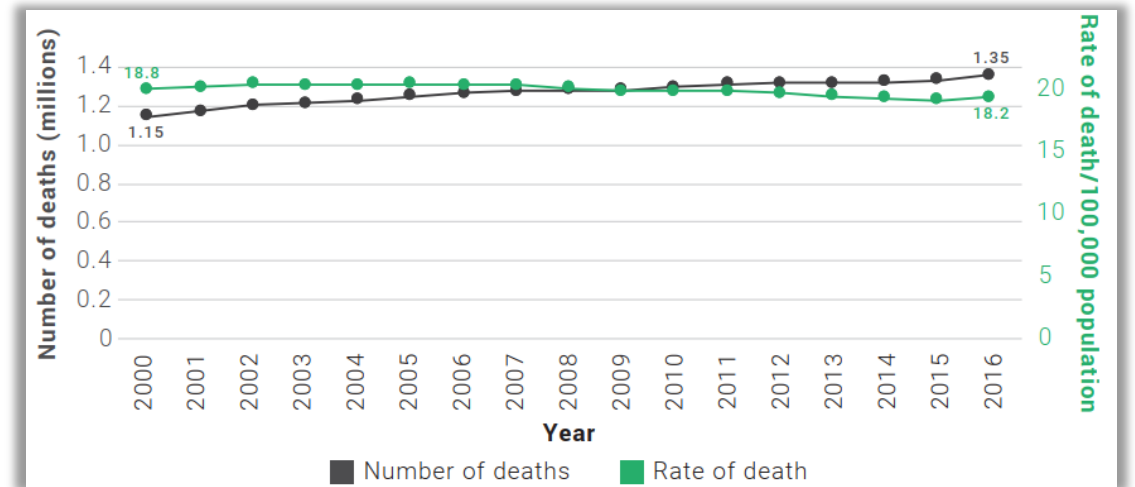
Dipak K Dash | TNN | Dec 7, 2018, 13:07 IST



# Road Safety – Big Societal Problem

- Worldwide

- 1.35 million deaths per year
- Leading killer in age group 5-29

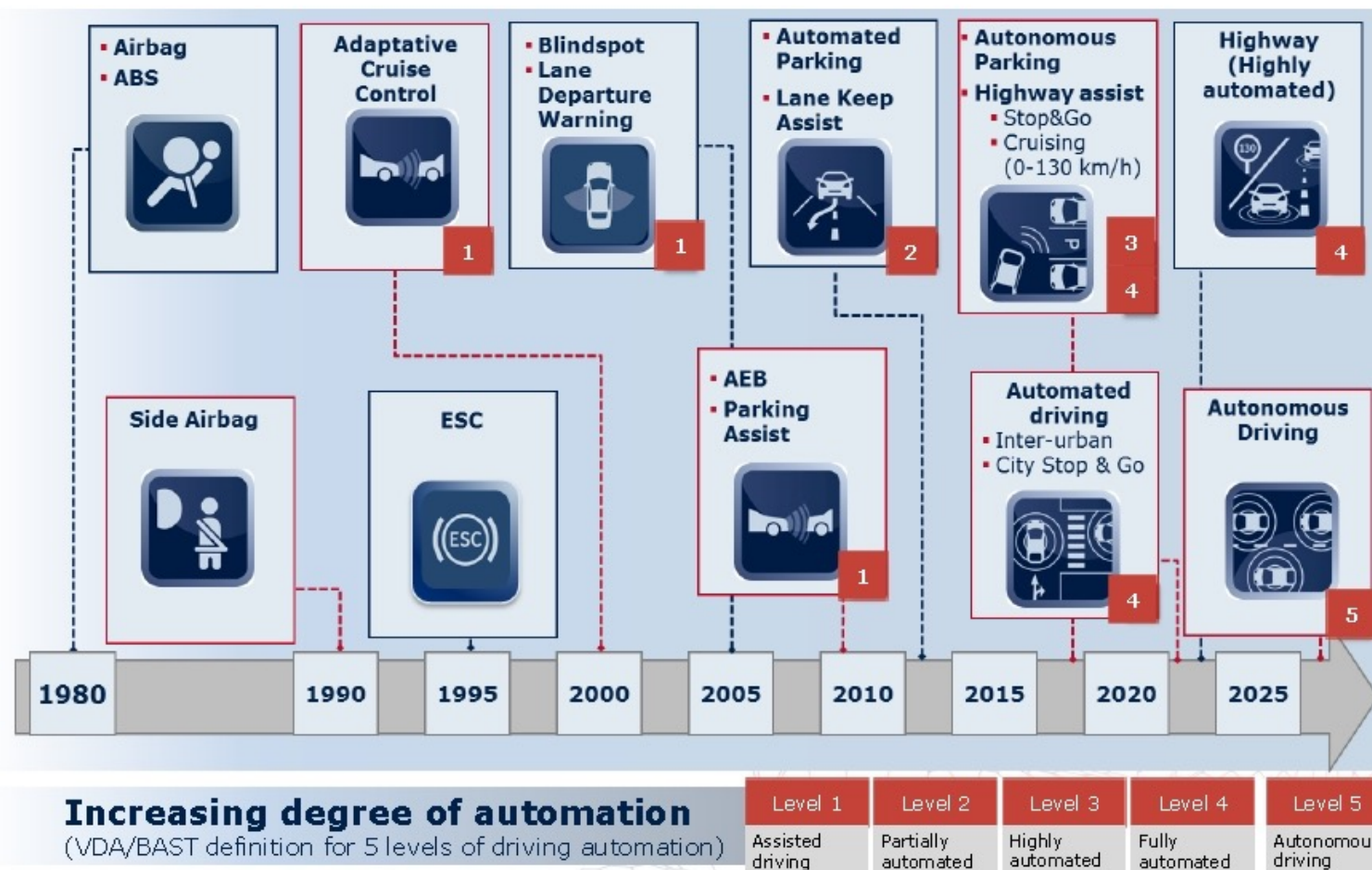


- India

- 150,000 people killed every year, 450,000 crippled every year
  - 70% of death in age group 18-45
- Cost: Rs. 91 lakhs/death, Rs. 3.64 lakhs/injured person
  - 3.14% of GDP (Rs. 4.3 lakh crores)
- 1% of world vehicles but 11% of all road deaths

# Automobile Safety – Evolution

Safety evolves towards automated and autonomous driving



Source: Infineon

# What Makes Indian Situation Different/Challenging?



Density, Diversity, Unstructured Movement Patterns



Traffic Signs, Enforcement, Regulating large population



Road Surface: Diversity, Quality, Cost in Establishing



Lack of Technology, Cost of Technology, Adoption

# AD in India – First Brainstorming Meet

- Organized at IIIT-Hyderabad (December 2017)
- 30+ attendees
  - Academia
  - Industry

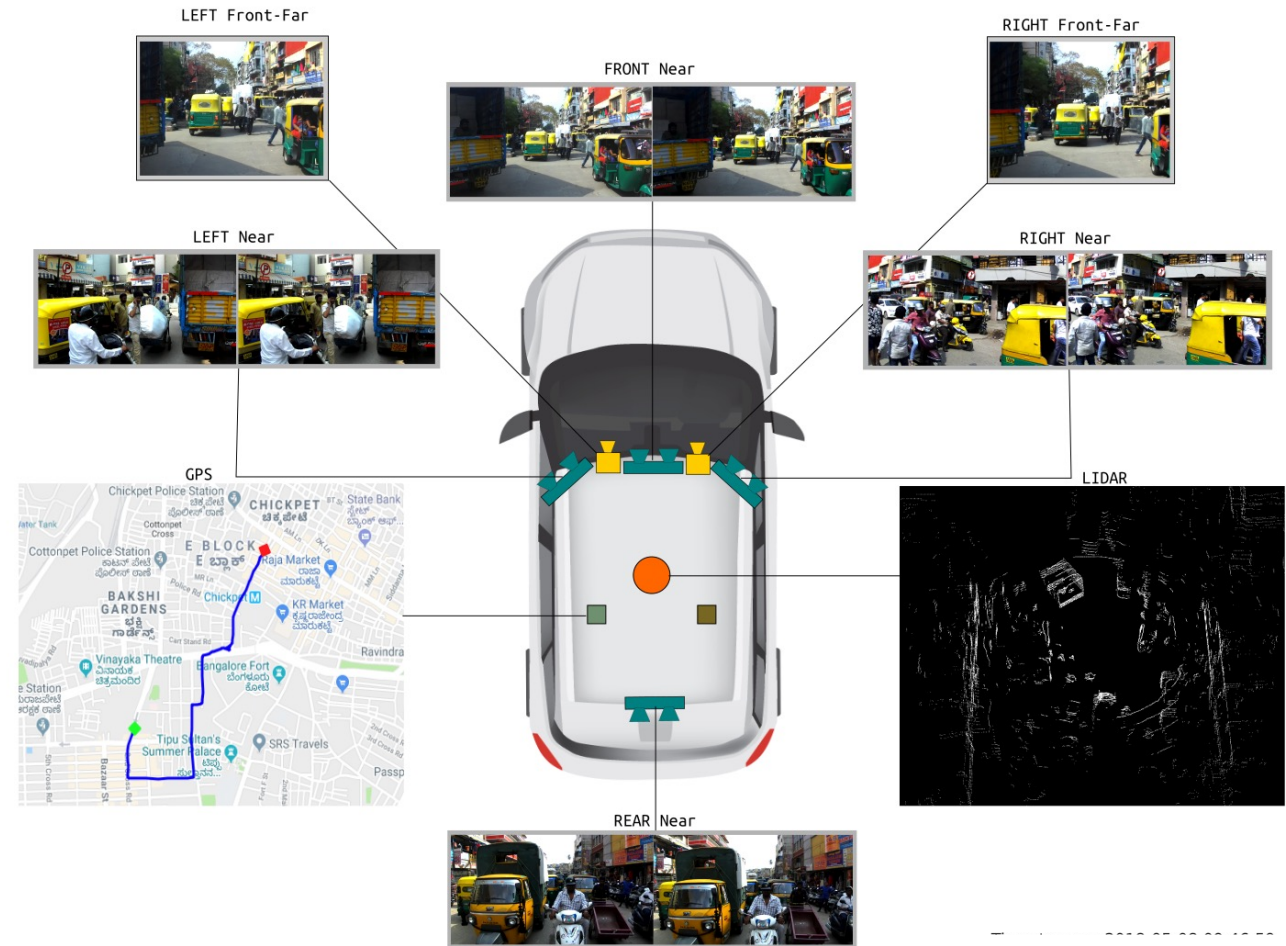


Brainstorming on Autonomous Navigation and Indian Setting 20 <sup>th</sup> December 2017 Venue: KCIS Meeting Room, IIIT Hyderabad		
Program Schedule		
Time	Event	
08:30 - 09:30	Breakfast & Informal interaction	
09:30 - 10:15	<b>Session 1: Setting the Context</b> Introduction & Background : C.V. Jawahar, IIIT-H Opening Remark : Manmohan Chandrasekar, UCSD/NEC	
10:15 - 10:30	Tea Break	
10:30 - 12:00	<b>Session 2: Panel on Problems and Challenges</b> Moderator: Vineeth Balasubramanian, IIT-H Discussions: <ul style="list-style-type: none"> <li>• What are the challenging and emerging technical problems in autonomous navigation?</li> <li>• What are the secondary benefits that the society looks forward (eg. Safety of people)?</li> <li>• What are the India specific challenges in this broad space? (Specially Technical, Social and Cultural)</li> <li>• Other related topics.</li> </ul>	<b>Panelists:</b> <ul style="list-style-type: none"> <li>• Amit Kale, Bosch</li> <li>• Anoop Nambodiri, IIIT H</li> <li>• Chetan Arora, IIIT D</li> <li>• Natraj J, Intel</li> <li>• Shanti Swarup, Mathworks</li> <li>• Dipindar, Kritikal</li> </ul>
12:00 - 13:00	<b>Session 3: Experience Sharing</b> Experience on automated navigation, driver assistance and related areas. Discussions: <ul style="list-style-type: none"> <li>• Brief presentation (5 - 10 Mins) from different groups/activities.</li> </ul>	<b>Presenters:</b> <ul style="list-style-type: none"> <li>• Akshay Uttamanambi, MSR</li> <li>• Gaurav Aggarwal, Ola</li> <li>• Madhava Krishna and IIIT H team</li> <li>• Prabhavathy Adavikolanu, Intel</li> <li>• Saket Anand and IIIT D Team</li> <li>• Vinoth Ponnuswamy, Mahindra</li> <li>• Presentations from other participants</li> </ul>



# Multi-Sensor Data Collection for IDD

- 4 stereo cameras
  - 1920 x 1080 pixels each
  - 15 frames per second
- LIDAR (16-channel)
- GPS

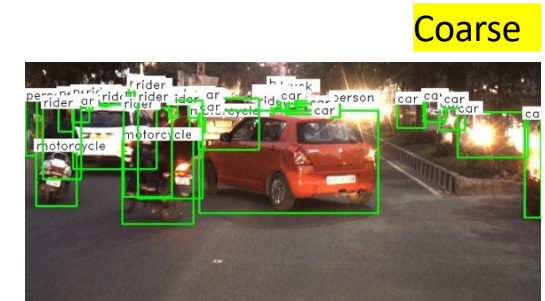


# IDD – A Snapshot of First Release (2018)

Annotated dataset – 50,000 frames (2x Cityscapes dataset)

- 10,000 fine annotations
- 40,000 coarse annotations
- 30 classes
- 4-level class hierarchy

	Image	Drive sequences
Full	10,003	182
Train	6993	120
Val	981	22
Test	2029	40



Dataset	Calibration	Nearby frames / Video	Distortion /Night	#Images/ #Sequences	#Labels Train/Total	Average Resolution
Cityscapes [5]	✓	✓		5K / 50	19/34	2048x1024
IDD	✓	✓		10K / 180	30/34	1678x968
BDD100K [26]		✓	✓	10K / 10K	19/30	1280x720
MVD [16]				25K / -	65/66	>1920x1080

Table 1. Comparison of semantic segmentation datasets for autonomous navigation.

# IDD – A Long Journey



2017

2018

2019

2020

2021

**Dec**

- First brain-storming at IIIT-H
- Autorickshaw detection challenge at **NCVPRIPG 2017**

**Aug**

- IDD in **Govt. of India's (NITI Aayog)** - Global Move Hackathon

**Sep**

- **IDD released**
- **AutoNUE @ ECCV**
- 2 data challenges

**Nov**

- IDD website launched
- ICTAI mobility workshop

**Nov**

- **AutoNUE 2 @ ICCV**
- Released **IDD-2, IDD-Multimodal, IDD-Temporal**
- 4 data challenges

**Dec**

- **IDD-Lite released**
- Data challenge at **NCVPRIPG 2019**

**Dec**

- Data challenge at **ICVGIP 2020**

**Jun**

- **AutoNUE 3 @ CVPR**
- 5 data challenges



Brainstorming On Autonomous Navigation And Indian Setting



Keynote Speakers



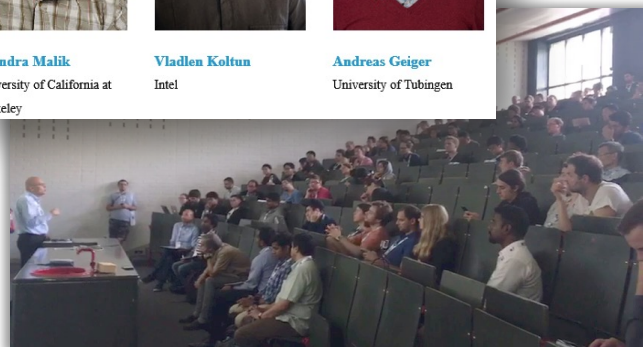
**Jitendra Malik**  
University of California at Berkeley



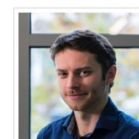
**Vladlen Koltun**  
Intel



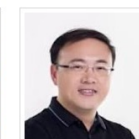
**Andreas Geiger**  
University of Tubingen



**Ayoung Kim**  
Korea Advanced Institute of Science Technology (KAIST)



**Adrien Gaidon**  
Machine Learning Lead at Toyota Research Institute (TRI)



**Kai Yu**  
CEO Horizon Robotics, Founder of Baidu IDL



**Li Erran Li**  
Head of Machine Learning, Scale AI



**Raquel Urtasun**  
University of Toronto



**Torsten Sattler**  
Chalmers University of Technology



INVITED SPEAKERS



**Henrik I. Christensen**  
University of California San Diego, USA



**Ang Marcelo H. Jr**  
National University of Singapore



**Kate Saenko**  
Boston University, USA



**Alexandre Massoud Alahi**  
EPFL, Switzerland



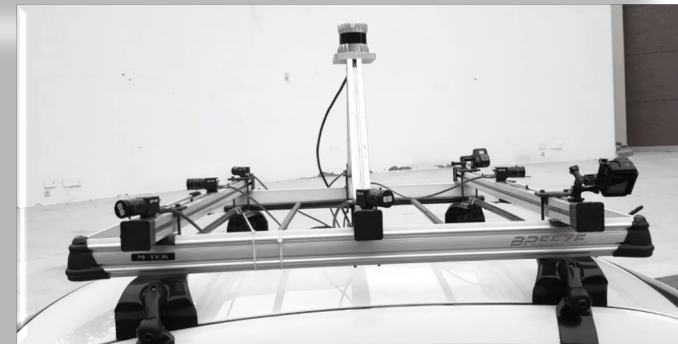
**Ruilong Yang**  
University of Kentucky, USA



**Kris Kitani**  
Carnegie Mellon University, USA

# IDD Journey (Continues in 2023)

- Driver Gaze
  - Where does the driver look?
- IDD 3D (2022)
- More Challenges
  - Eg. Detect Missing Road Signs (2023)
- Platforms that can be shared
  - Students, Researchers, Startups, NGOs
- Movement Logs, Sensor Logs
- Data for bad weather
- Synthetic Data, Algorithms, Simulations for rare situations



# Can we predict potential accidents before they happen?

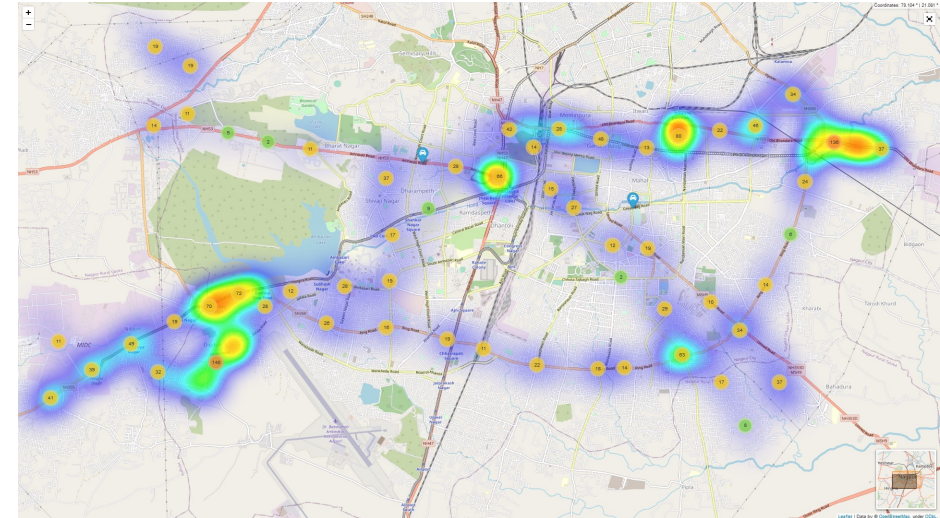
- **Blacksports:** Ministry of Road Transport & Highways (MoRTH) definition
- Locations on road network, which had 5 accidents or 10 fatalities, in the last 3 calendar years
- Today: **It takes 3 years or more**



# Grey spots: predict before it become black – Help Prevent Accidents

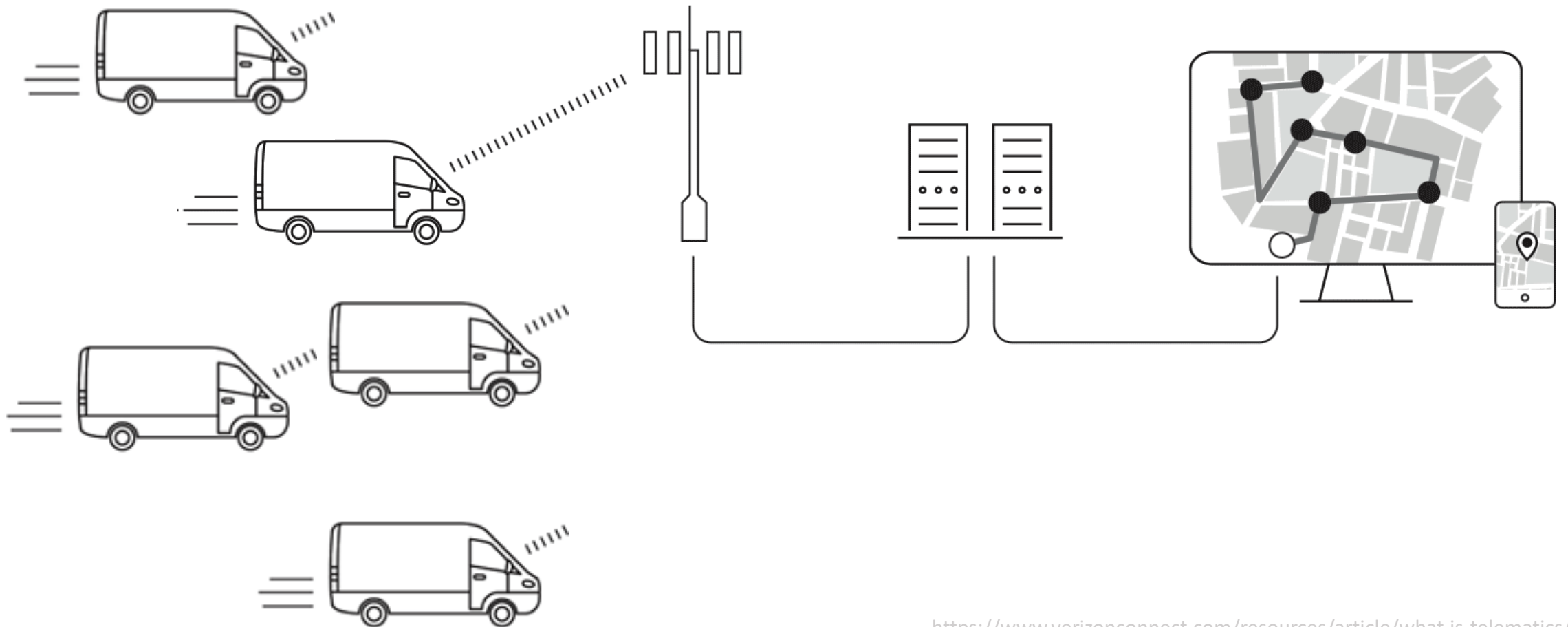


Source: [https://twitter.com/inai\\_ai/status/1655924802731876352](https://twitter.com/inai_ai/status/1655924802731876352)



- Locations on road network, which have a potential to become Blackspots sometime in future, if no corrective road-safety measures are taken at these locations to prevent accidents

# AI for Road Safety – Large Data Analysis



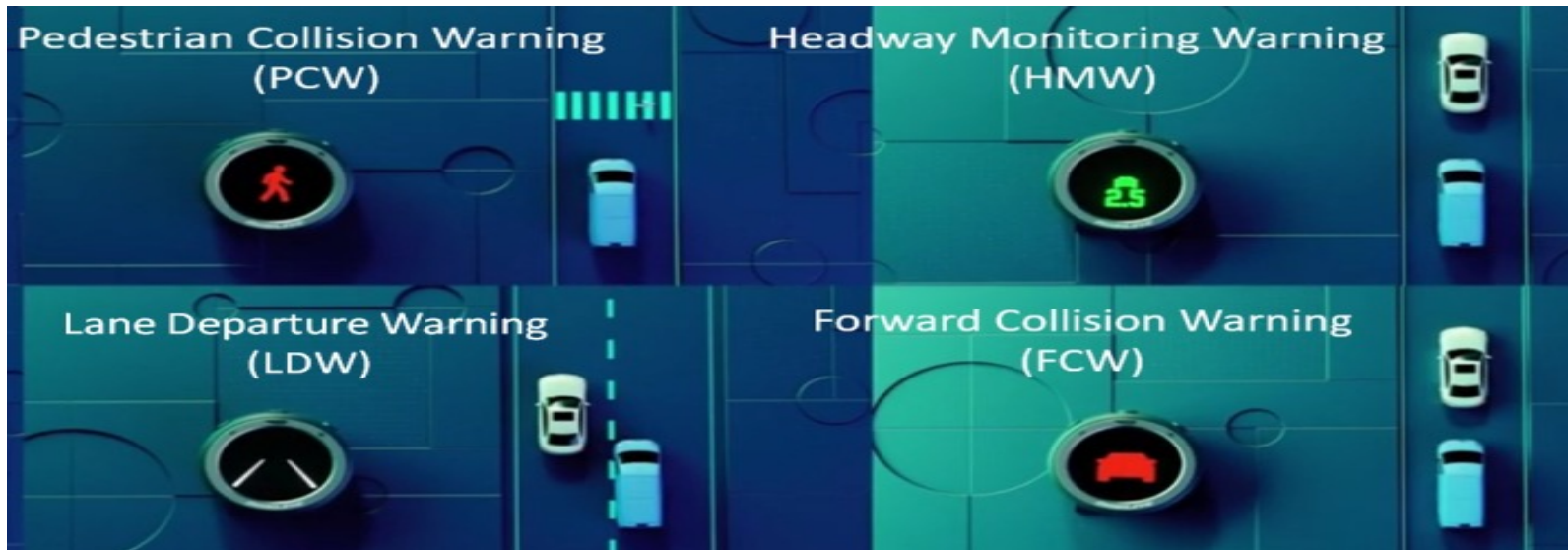
<https://www.verizonconnect.com/resources/article/what-is-telematics/>

# Participatory Road Safety

Camera focused on road



Display unit (audio + visual alerts)



Road Safety



ADAS



Autonomous Driving



# Project: iRASTE



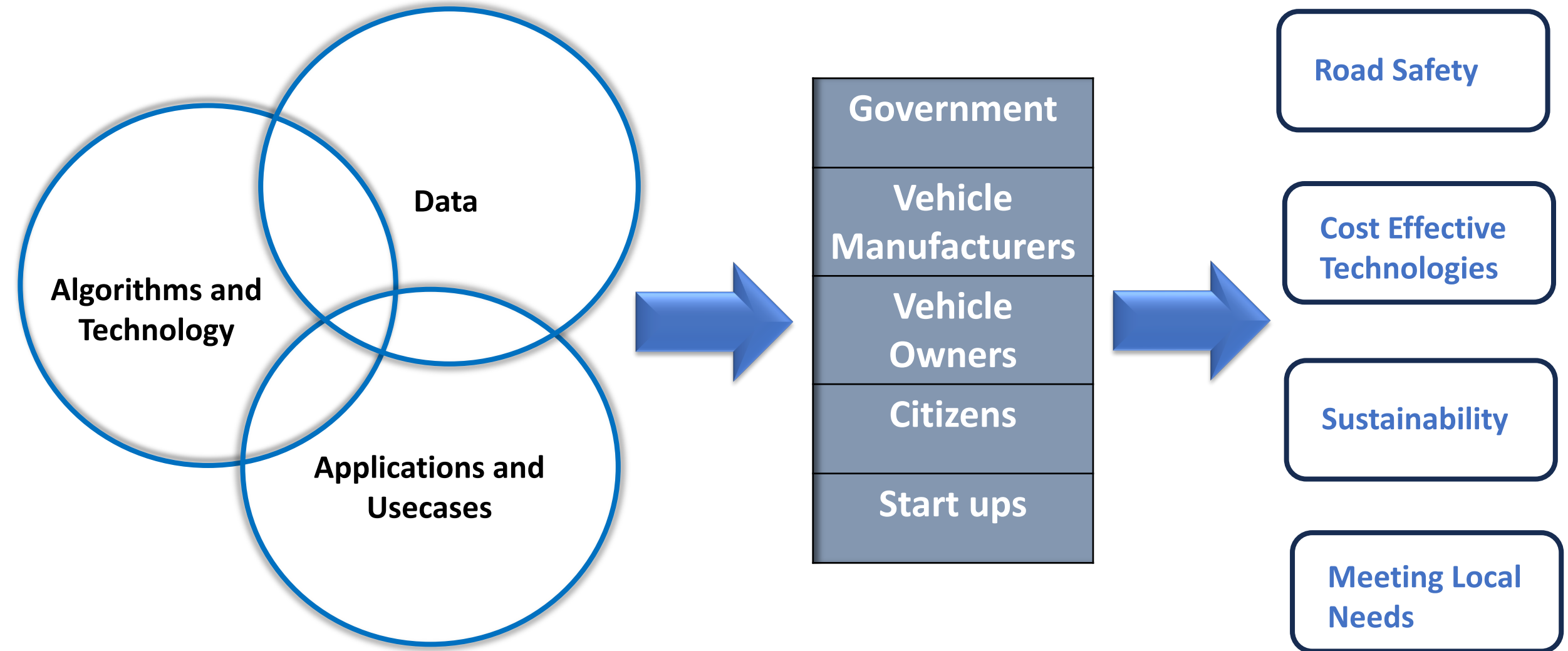
Project  
**iRASTE**

Re-imagine Road Safety with the predictive power of AI



- Academia and Industry partnership in solving real world problems
- Project getting extended to Telangana
  - Focus on Highways
- A working example of how can technology (AI, Data, Algorithms) work with engineering.

# Summary and Directions



# MATLAB EXPO

Thank you



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